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ARTICULATED TOTAL BODY MODEL ENHANCEMENTS,  
Volume 3: Programmer's Guide



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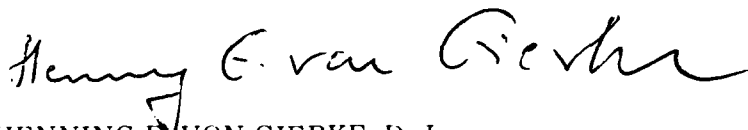
## TECHNICAL REVIEW AND APPROVAL

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This report has been reviewed by the Office of Public Affairs (PA) and is releasable to the National Technical Information Service (NTIS). At NTIS, it will be available to the general public, including foreign nations.

This technical report has been reviewed and is approved for publication.

**FOR THE COMMANDER**



HENNING E. VON GIERKE, Dr Ing  
Director  
Biodynamics and Bioengineering Division  
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<p>The Articulated Total Body (ATB) Model is used at the Armstrong Aerospace Medical Research Laboratory (AAMRL) to study human body biomechanics in various dynamic environments, especially aircraft ejection with windblast exposure. In order to improve the model's predicted results and capabilities, a number of modifications have been made. These modifications include the capability to have segment contact ellipsoids block the wind from other segments, an option to prescribe velocity dependent wind forces, a correction to prevent angular drift in the joints, improved contact force calculations for segment contact near a plane's edge, the capability to specify as input multi-axis angular displacements to describe the vehicle motion, a sliding joint capability and a hyperellipsoid option. Along with these major changes, a number of minor corrections and clarifications have been included to form the ATB-IV version. The results of these modifications have been documented in three volumes of which this is Volume 3, the</p>					
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Programmer's Guide. It contains a complete listing of the ATB-IV program with designation of coding modifications from previous versions. Volume 1 contains a technical description of the ATB-IV modifications and Volume 2 is an updated User's Guide containing the new input description.

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## PREFACE

This report incorporates the work done in a number of different efforts to improve the Articulated Total Body (ATB) model's capability to simulate human body biomechanics in various dynamic environments, especially aircraft ejection with windblast exposure.

The majority of modifications to the model fall into six categories:

- wind force option
- joint drift correction
- edge effect option
- multi-axis angular displacement vehicle motion prescription
- slip joint option
- hyperellipsoid option

These improvements have been combined to form the ATB-IV version on the Armstrong Aerospace Medical Research Laboratory's (AAMRL) Concurrent computer system at Wright Patterson Air Force Base. AAMRL, Systems Research Laboratories, Inc. and J&J Technologies Inc. and the National Highway Traffic Safety Administration have all contributed to the technical work described herein.



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## 1.0 INTRODUCTION

The Articulated Total Body (ATB) Model is used at the Armstrong Aerospace Medical Research Laboratory (AAMRL) for predicting gross human body response in various dynamic environments, especially aircraft ejection with windblast exposure. Aerodynamic force application and a harness belt capability were added to the Crash Victim Simulation (CVS) Program (Ref 1) by Calspan Corporation in 1975 for AMRL (Ref 2), and the resulting program became known as the ATB model. In 1980, Calspan made a number of modifications to the ATB model combining it with the then current 3-D Crash Victim Simulation program to form the ATB-II model (Ref 3). Complete documentation of the ATB-II program was performed by Calspan Corp. (Ref 4). A new version, ATB-III, was generated which included the improvements made by J&J Technologies Inc to model the body response to windblast for AMRL (Ref 5).

A number of efforts have been made to improve various aspects of the ATB-III model, with emphasis on its capability to simulate aircraft ejection with windblast exposure and complex automobile accidents.

This volume, Programmer's Guide, contains a complete listing of the ATB-IV.0 source code and other information about the FORTRAN program. Much of this volume is a reprinting with modifications and updates of Volume 4 of Calspan's report on the CVS (Ref 4).

A list of the variables contained in the labeled COMMON blocks and a brief description of each variable are in section Two of this volume. Cross reference charts for the subroutines and COMMON blocks are in Section Three, while a list of all the subroutines is in Section Four. Section Five contains a complete listing of the ATB-IV.0 source code.

## 2.0 COMMON BLOCK VARIABLES

This section contains a list of all of the variables contained in the labeled COMMON blocks of the ATB program. They are listed in the alphabetical order of the COMMON block names. Following each variable is its dimension, if any, and a short definition. If the variable is supplied as ATB program input, references are indicated to the input card number and a more complete definition may be found in the input description contained in Volume 2.

<u>COMMON</u>	<u>/AB DATA/</u>	
ZDEP	(3,5)	Deployment point of airbag in local reference of 1st reaction panel (Card D.4.c)
DBR	(3,3,5)	Direction cosine matrix of airbag relative to vehicle
DPVCTR	(3,5)	Vector along which airbag c.g. lies during bag inflation
DEPLOY	(3,5)	Location of deployment point
AB	(3,5)	Semiaxes of fully inflated ellipsoid airbag (Cards D.4.b)
B	(9,4,5)	3 X 3 matrix defining ellipsoid $X^T B X = 1$ for reaction panel
ZR	(3,4,5)	Location of panel c.g. in vehicle reference (Card D.4.h)
BFB	(3,4,5)	c.g. offset of reaction panel (Card D.4.g)
DRR	(9,4,5)	Direction cosine matrix of reaction panel relative to inertial reference
VBAGG	(5)	Geometric volume of fully inflated airbag
VSCS	(5)	Coefficient of sliding friction of the airbag (Card D.4.f)
SPRK	(5)	Spring constant of a linear spring used to stipulate attachment of the airbag at the deployment point (Card D.4.f)

CK	(5)	Parameter used to stabilize airbag numerical integration (Card D.4.f)
CMASS	(5)	Multiplier to increase or decrease the mass of the airbag to artificially dampen the integrated airbag motion (Card D.4.f)
CYMIN	(5)	Mass flow into the airbag
CYMOUT	(5)	Mass flow out of the airbag
BAGPV	(5)	Undeformed airbag volume
PD	(5)	Airbag pressure differential
VBAG	(5)	Airbag volume
VOLBP	(5)	Total volume of intersection of airbag with contacting segments and panels
PCYV	(5)	Volume of mass flow into airbag at atmospheric pressure at time of initial inflation
PCYMIN	(5)	Mass flow into airbag at time of initial full inflation
PVBAG	(5)	Airbag volume at time of initial inflation
TV1	(3,4,5)	Memory for Subroutines INTERS and EDEPTH for airbag-panel ellipsoid contacts
TV2	(3,10,5)	Memory for Subroutines INTERS and EDEPTH for airbag-segment ellipsoid contacts
SWITCH	(5)	Reciprocal density of airbag at time of initial full inflation

PYMOUT	(5)	Mass flow out of airbag at time of initial full inflation
SCALE	(5)	Ratio (0-1) of linear dimensions of airbag to fully inflated airbag
PREVT		Value of TIME at previous airbag integration step
IFULL	(6)	Indicates that airbag is fully inflated

COMMON    /CDINT/

UU	(4)	} Constants computed by Subroutine TRIGFS valid for the upcoming integrator time step
GH	(3,4)	

E	(3,240)	} Intermediate storage of function evaluations in Subroutine DINT
FF	(5,240)	
GG	(5,240)	
Y	(5,240)	
U	(5,240)	

H		Current value of the independent variable step size in Subroutine DINT
---	--	---

HPRINT		Saved value of H while integrating to print point only
TSAVE		Set to zero or H to reset integrator
TPRINT		Value of next print time point
TSTART		Start time of an integration step
ICNT		Count of successive integration steps for which convergence has been successful
IDBL		Maximum value for ICNT before test to double step size is performed
IFLAG		Currently not used by program

COMMON     /CEULER/

IEULER	(30)	Current lock-unlock conditions for an Euler joint (see identification under IPIN on Cards B.2)
HIR	(3,3,90)	Direction cosine matrix defining orientation of axes of an Euler joint
ANG	(3,30)	Angles of orientation of an Euler joint
ANGD	(3,30)	Time derivative of orientation angles of an Euler joint
FE	(3,30)	Components of torque acting on an Euler joint in joint reference



TQE	(3,30)	Components of torque acting on an Euler joint in inertial reference
CONST	(5,30)	Memory of previous angles of orientation of an Euler joint
<u>COMMON</u>	<u>/CMATRIX/</u>	
V1	(3,30)	Right hand side of system of equations $B_{11}\ddot{x} + B_{12}\dot{w} + B_{13} f = V_1$
V2	(3,30)	Right hand side of system of equations $B_{22}\ddot{x} + B_{24} t = v_2$
V3	(3,12)	Right hand side of system of equations $B_{31} \ddot{x} + B_{32}\dot{w} + B_{35} q = V_3$
B12	(3,3,60)	Subarray elements of $B_{12}$
A22	(3,3,60)	Subarray elements of $A_{22}$
F	(3,30)	Components of force acting on the joints from the solution of system equations
TQ	(3,30)	Components of torque acting on the joints from the solution of system equations
WJ	(30)	Relative angular velocity of each joint
A11	(3,3,30)	Subarray elements of $A_{11}$

COMMON    /CNSNTS/

PI		FORTTRAN Subroutine Library value for Pi, computed by $PI = \text{DATAN2}(0.0D0, -1.0D0)$
RADIAN		Number of radians per degree ( $PI/180$ )
G		Resultant of gravity vector (Card A.3)
THIRD		Double precision value for $1/3$
EPS	(24)	Values of negative powers of ten, computed by $EPS(I) = 10.0D0^{*(-I)}$
UNITL		I/O unit of length (Card A.3)
UNITM		I/O unit of force of mass (Card A.3)
UNITT		I/O unit of time (Card A.3)
GRAVITY	(3)	Components of gravity vector (Card A.3)
TWOPI		$2.0*PI$

COMMON    /CNTSRF/

PL	(24,30)	Array of parameters that define each plane (See Table 1 in Volume 1)
BELT	(20,8)	Array of parameters that define each belt (Cards D.3.b-D.3.c)
TPTS	(6,8)	Location of belt tangent points in inertial reference

BD	(24,40)	Array of parameters that define each ellipsoid
<u>COMMON</u>	<u>/COMAIN/</u>	
VAR	(240)	Integrated function values supplied by Subroutine DINT to Subroutine PDAUX
DER	(240)	Function derivatives supplied by Subroutine PDAUX to Subroutine DINT
DT		Time interval for main program output time points (Card A.4)
H0		Initial integrator step size (Card A.4)
HMAX		Maximum integrator step size (Card A.4)
HMIN		Minimum integrator step size (Card A.4)
RSTIME		Restart time (Card A.1.a)
ISTEP		Current integration step number
NSTEPS		No. of integration steps for duration of simulation (Card A.4)
NDINT		No. of iterations for convergence test for Subroutine DINT (Card A.4)
NEQ		Total number of functions integrated by Subroutine DINT

IRSIN	Restart input unit no. (Card A.1.a)
IRSOUT	Restart output unit no. (Card A.1.a)
<u>COMMON</u>	<u>/CONTRL/</u>
TIME	Current simulation time
NSEG	Number of body segments of crash victim, max=30 (Card B.1)
NJNT	Number of joints, max=30 (Card B.1)
NPL	Number of plane definitions supplied on Cards D.2, max=30 (Card D.1)
NBLT	Number of belt definitions supplied on Cards D.3, max=8 (Card D.1)
NBAG	Number of airbag definitions supplied Cards D.4, max=5 (Card D.1)
NVEH	Segment identification number for the vehicle (NVEH=NSEG+number of vehicles)
NGRND	Segment identification number for the ground (NGRND=NSEG+NBAG+number of vehicles+1)
NS	Number of singular segments, i.e., W or at least one component of PHI is zero
NQ	Number of constraints supplied on Cards D.6, final max = 12 (Card D.1)

NSD		Number of spring dampers supplied on Cards D.8, max=20 (Card D.1)
NFLX		Total number of interior segments of all flexible elements.
NHRNSS		Number of harness-belt systems supplied on Cards F.8, max=5 (Card D.1)
NWINDF		Number of wind force functions supplied on Cards E.6 (Card D.1)
NJNTF		Number of joint restoring force functions supplied on Cards E.7 (Card D.1)
NPRT	(36)	Indicators that control optional output of the program (Card A.5)
NPG		Current page number of main output

COMMON      /CSTRNT/

A13	(3,3,24)	Subarray elements of A <sub>13</sub> for system of equations $\ddot{M}\ddot{x} + A_{11}f + A_{13}q = U_1$
A23	(3,3,24)	Subarray elements of A <sub>23</sub> for system of equations $\phi\dot{w} + A_{21}f + A_{22}t + A_{23}q = U_2$
B31	(3,3,24)	Subarray elements of B <sub>31</sub> for system of equations defining constraints

B32	(3,3,24)	Subarray elements of $B_{32}$ for system of equations defining constraints
HHT	(3,3,12)	Array $hh^T$ or $I-hh^T$ for each constraint
RK1	(3,12)	Specified point on segment number KQ1 (Card D.6)
RK2	(3,12)	Specified point on segment number KQ2 (Card D.6)
QQ	(3,12)	Computed force necessary to maintain each constraint
TQQ	(3,12)	Normal vector at the point of contact for each constraint
RQQ	(3,12)	R dot term for constraint equation
HQQ	(3,12)	Reference vector at point of constraint
SQQ	(3,12)	R term for constraint equation
CFQQ	(12)	Coefficient of friction for each constraint
KQ1	(12)	Segment identification number of the 1st specified point (Card D.6)
KQ2	(12)	Segment identification number of the 2nd specified point (Card D.6)
KQTYPE	(12)	Constraint type number (Card D.6)

COMMON      /CYDATA/

CYTD	(5)	Gas supply actuator firing time (Card D.4.d)
CYPA	(5)	Atmospheric pressure (Card D.4.d)
CYSP	(5)	Initial gas supply pressure (Card D.4.d)
CYTO	(5)	Initial gas supply temperature (Card D.4.d)
CYVO	(5)	Gas supply reservoir volume (Card D.4.d)
CYCD	(5)	Sonic throat discharge coefficient (Card D.4.e)
CYK	(5)	Ratio of specific heats of supply gas (Card D.4.e)
CYR	(5)	Specific gas constant (Card D.4.e)
CYAT	(5)	Sonic throat area (Card D.4.e)
CYPV	(5)	Vent pressure of the exhaust orifice
CYCDO	(5)	Exhaust orifice discharge coefficient (Card D.4.e.)
CYAO	(5)	Exhaust orifice area (Card D.4.f)
CYPO	(5)	Initial air cylinder gauge supply pressure
CYSS	(5)	Speed of sound
CYLO	(5)	Characteristic length

CYC	(5)	Air cylinder gas constant
CYRHOO	(5)	Initial air cylinder density
CYVMAX	(5)	Air cylinder maximum volume
CYORFC	(5)	Air cylinder exhaust orifice constant
CYRHO	(5)	Density of air cylinder gas supply
CYT	(5)	Temperature of air cylinder gas supply
CYP	(5)	Pressure of air cylinder gas supply
CYV	(5)	Volume of air cylinder gas supply at standard atmospheric pressure

COMMON    /DAMPER/

APSDM	(3,20)	Attachment point in local reference of segment M for spring dampers (Card D.8)
APSDN	(3,20)	Attachment point in local reference of segment N for spring dampers (Card D.8)
ASD	(5,20)	Spring and viscous force function coefficients (Card D.8)
MSDM	(20)	Identification number of segment M (Card D.8)
MSDN	(20)	Identification number of segment N (Card D.8)



<u>COMMON</u>	<u>/DESCRP/</u>	
PHI	(3,30)	Segment principal moments of inertia (Cards B.2)
W	(30)	Segment weight (Cards B.2)
RW	(30)	Reciprocal mass (g/w) for each segment
SR	(4,60)	Joint locations in local reference of adjacent segments (Cards B.3)
HA	(3,60)	Principal line of joint from which flexure angle is measured
HB	(4,60)	Perpendicular to HA (pin axis if joint is pinned)
RPHI	(3,30)	Reciprocal moments of inertia for each segment
HT	(3,3,60)	Principal axes of the joints
SPRING	(5,90)	Flexural and torsional spring characteristics (Cards B.4)
VISC	(7,90)	Flexural and torsional viscous characteristics (Cards B.5)
JNT	(30)	Magnitude indicates the segment identification number that is connected to segment J+1 by joint J (Cards B.3)
IPIN	(30)	Indicator of joint type (Card B.3)

ISING	(30)	Indicator (value=1) that segment is singular
IGLOB	(30)	Input indicator (Card F.4.a) to signify that joint J is to use the globalgraphic option. A nonzero value will be set to index of function to be used.
JOINTF	(30)	The function identification number used to compute the joint restoring force (Card F.5)

COMMON    /FLXBLE/

HF	(4,12,8)	Coefficients of quadratic function defining relative orientation of interior segments of flexible elements
B42	(3,3,24)	Subarray elements of matrix $B_{42}$ in the constraint equations for flexible elements
V4	(3,8)	Right hand side of the constraint equations for flexible elements.
NFLEX	(3,8)	The identification numbers of reference, interior and terminating segments for each interior segment.

<u>COMMON</u>	<u>/FORCES/</u>	
PSF	(7,70)	Array of output values for plane-segment contacts
BSF	(4,20)	Array of output values for belt-segment contacts
SSF	(10,40)	Array of output values for segment-segment contacts
BAGSF	(3,20)	Array of output values for airbag-segment contacts
PRJNT	(7,30)	Output arrays for joint parameters
NPANEL	(5)	Number of reaction panels for each airbag (J=1, NBAG)
NPSF		Number of plane-segment contact (Max=70)
NBSF		Number of belt-segment contacts (Max=20)
NSSF		Number of segment-segment contacts (Max=40)
NBGSF		Number of items to be printed for airbag-segment contacts (Max=20)

COMMON    /HRNESS/

BAR	(15,100)	Coordinates of points in local reference (Cards F.8.d)
BB	(100)	Lengths of individual belt segments between reference points
BBDOT	(100)	Time derivative of belt segment lengths
PLOSS	(2,100)	Energy loss of individual belt segments
XLONG	(20)	The initial slack of each belt (Cards F.8.c)
HTIME	(2)	Previous value of TIME for Subroutine HPTURB
IBAR	(5,100)	Array of indicators containing KS, KE, NF index, NPD and NPR (Cards F.8.d) for each point
NL	(2,100)	Pointers to the IBAR and NTHRNS arrays for each point in play
NPTSPB	(20)	Number of points per belt (Cards F.8.b)
NPTPLY	(20)	Number of points in play per belt
NTHRNS	(20)	Index to NTAB array defining the force deflection functions for each belt
NBLTPH	(5)	Number of belts per harness (Card F.8.a)

COMMON     /INTEST/

SGTEST	(3,4,30)	Integrator convergence test input numbers (Cards B.6)
XTEST	(3,120)	Integrator convergence test numbers setup by PDAUX for DINT
SEGT	(120)	Segment identification of integrator variable
REGT	(120)	Identification (ANG VEL, ANG ACC, LIN VEL or LIN ACC) of type of integrator variable

COMMON     /JBARTZ/

MNPL	(30)	Number of segments to contact each plane (Card F.1.a)
MNBLT	(8)	Number of segments to contact each belt (Card F.2.a)
MNSEG	(30)	Number of segments to contact each segment (Card F.3.a)
MNBAG	(6)	Number of segments to contact each airbag
MPL	(3,5,30)	Segment and ellipsoid identification numbers for each plane-segment contact
MBLT	(3,5,8)	Segment and ellipsoid identification numbers for each belt-segment contact

MSEG	(3,5,30)	Segment and ellipsoid identification numbers for each segment-segment contact
MBAG	(3,10,6)	Segment and ellipsoid identification numbers for each airbag-segment contact (Cards F.4)
NTPL	(5,30)	Index to NTAB array for each plane-segment contact
NTBLT	(5,8)	Index to NTAB array for each belt-segment contact
NTSEG	(5,30)	Index to NTAB array for each segment-segment contact
 <u>COMMON</u> <u>/RSAVE/</u>		
XSG	(3,20,3)	Points in local segment reference for first three types of time history output (Cards H.1-H.3)
DPMI	(3,3,30)	Direction cosine matrix of principal moment of inertia to local geometric reference coordinate system for each segment
LPMI	(30)	Indicator that local geometric does not correspond to principal moment of inertia reference coordinate system for each segment (Cards B.2.i1)
NSG	(9)	Number of segments for each type of time history output (Max=20) (Cards H.1-H.9)

MSG	(20,9)	The segment identification numbers for each type of time history output (Cards H.1-H.9)
MCG		Number of bodies for body property time history output (Max=5) (Cards H.10)
MCGIN	(24,5)	Body characteristics for body property time history output (Cards H.10)
KREF	(20,9)	The reference segment numbers for each time history output (Cards H.1-H.9)

COMMON /SGMNTS/

D	(3,3,30)	Segment direction cosine matrix
WMEG	(3,30)	Segment angular velocity in local reference
WMEGD	(3,30)	Segment angular acceleration in local reference
U1	(3,30)	Total external forces on each segment
U2	(3,30)	Total external torques on each segment
SEGLP	(3,30)	Segment c.g. linear position in inertial reference
SEGLV	(3,30)	Segment c.g. linear velocity in inertial reference

SEGLA           (3,30)       Segment c.g. linear acceleration in inertial  
reference

NSYM           (30)       Indicators that control the symmetry options  
for body segments (Cards D.7)

COMMON       /TABLES/

MXNTI                       Dimension (50) of NTI array

MXNTB                       Number of elements in the NTAB array

MXTB1                       Number of elements in TAB array used  
to define functions

MXTB2                       Total number of elements in TAB array

NTI           (50)       Index pointers to the TAB array for data  
defining function no. 1.

NTAB           (1250)      Index pointers to TAB array for each  
function used for allowed contacts

TAB           (4500)      Subdivided into arrays containing function  
definitions and update information for each  
allowed contact

COMMON       /TEMPVI/

CREST                       Coefficient of restitution for current impulse

TTI           (3)       Value of U1 array for impulse



R1I	(3)	Value of RK1 for current constraint or impulse
R2I	(3)	Value of RK2 for current constraint or impulse
JSTOP	(4,2,30)	Indicators to signify joint is in joint stop

COMMON    /TEMPVS/

Variables in this labeled common block are temporary for each subroutine that refers to it.

COMMON    /TITLES/

DATE	(3)	Date of computer run in 12 alphanumeric characters (Card A.1.a)
COMENT	(40)	160 character description of the run (Cards A.1.b- A.1.c)
VPSTTL	(20)	80 character description of the crash vehicle deceleration (Card C.1)
BDYTTL	(5)	20 character description of the crash victim (Card B.1)
BLTTTL	(5,8)	20 character description of each belt (Cards D.3)
PLTTTL	(5,30)	20 character description of each plane (Cards D.2)

BAGTTL	(5,6)	20 character description of each airbag (Cards D.4)
SEG	(30)	4 character segment nomenclature (Cards B.2)
JOINT	(30)	4 character joint nomenclature (Cards B.3)
CGS	(30)	1 character plot symbol of the segment C.G. (Cards B.2)
JS	(30)	1 character plot symbol of the joint location (Cards B.3)

COMMON /VPOSTN/

ZPLT	(3)	Printer plot coordinates of the vehicle reference origin (Card G.1.a)
SPLT	(3)	Scale factors for the printer plot axes (Card G.1.b)
AXV	(3,6)	Unit vector of deceleration impulse direction
VATAB	(6,501,6)	Tables of computed or supplied (Cards C.3 or C.4) values of linear (1-3) and angular accelerations (4-6) of vehicle motion
VT0	(6)	Beginning time point      he deceleration table input (Card C.2)
VDT	(6)	Fixed time interval for deceleration table input (Card C.2)

TIMEV	(6)	Time duration of the deceleration impulse (Card C.2)
OMEGAV	(6)	Frequency of the half-sine wave deceleration type (Card C.2)
NVTAB	(6)	Number of points in deceleration table. Sign determines type (Card C.2)
INDXV	(6)	Segment identification number for each specified motion definition (MSEG on Card C.2.a or NVEH)

COMMON     /WINDFR/

WTIME	(30)	Initial time that segment penetrates wind
QFU	(3,5)	Unit vector for force application
QFV	(3,5)	Vector for torque application
WF	(3,30)	Wind force vectors applied to segments (local)
IWIND	(30)	Indicator that wind has been penetrated
MWSEG	(7,30)	Identification numbers for the application of wind forces on each segment (Cards F.7)
NFVSEG	(6)	Segment identification number for each force function (Cards D.9)

NFVNT	(5)	Function identification number for each force function (Cards D.9)
MOWSEG	(30,30)	Contact ellipsoid numbers and segment identification numbers of blocking segments (Cards F.7)

### 3.0 CROSS REFERENCE CHARTS

The first two cross reference charts list the COMMON blocks used by each subroutine. The remaining ten charts list the subroutines called by each subroutine.

## CALLING SUBROUTINES

## CALLLED COMMON BLOCKS

[illegible]

# SUBROUTINE CROSS REFERENCE

## CALLING SUBROUTINES

MAAAA	BBBB	CCCC	DDDD	DDDD	DDDD	DDDD	EEEE	FFFF	FFFF	HHHH	HHHH
ADIII	EEGIL	FHIMOR	AAAA	AAAA	AAAA	AAAA	DFJLL	QUV	DILN	RSL	BBEE
IJRRRR	LLGNK	AANPNO	UUUU	UUUU	UUUU	UUUU	HNTTT	CCCC	IEEMP	EUOOT	ULAN
NUBBBB	TT PD	CIPUTS	XXXX	XXXX	XXXX	XXXX	PT33	TTI	QYFTTS	PNINI	IRL
ASAGGG	GR UT	TNUTCS	1123	3334	51	1333	JUPT	DQO	TCNG	MLAF	IUER
TG13G	T TA	T TET	1221	2345	N	13KAR	L	HTT	EBDD	TTGP	LLL
YGNITB											
MAIN A											
ADJUST	1					*					
AIRBAG	1			*							
AIRBG1	1										
AIRBG3	1										
AIRBGG	2			*							
BELTG	1			*							
BELTRT	1			*							
BGG	1			*							
BINPUT	1	*									
BLKDTA	1	*									
CFACCT	3										
CHAIN	3			*							
CINPUT	1	*									
CMPUTE	1			*							
CONTC	1			*							
CROSS	28	*		***	*			*	*	*	**
DAUX	5										
DAUX11	1			*					*		
DAUX12	1			*							
DAUX22	1			*							
DAUX31	1			*							
DAUX32	1			*							
DAUX33	1			*							
DAUX44	1			*							
DAUX55	1			*							

C A L L E D S U B R O U T I N E S



MAAAA:BBBB:CCCC:DDDDDDDDDDDDDD:EEEEEEEE:FFFFFFF:HHHHHHH  
ADIII:EEGIL:FHIMOR:AAAAAAA:HIOOORRRSSZ:DFJLLQUV:DILNRS:L:BEEIIPS:  
IJRRRR:LLGNK:AANPNO:UUUUUUUU:HNTTTCCEIEEMP:EUOOTULA:INXTCMO:EPDRCNTE:  
NUBBB:TT PD:CIPUTS:XXXXXXX:PT33TTIQYFTTS :PNINIIRL:NPSSEDSB:LLIRCPUT:  
ASAGGG:GR UT:TNUCTS: 112333345:I 13333JUPTDQO :TCNGMLAF:IUERFOA:TANOSURC:  
TG13G: T TA:T TET : 12212345:N 13KAR L :HTT EBDD:TTGPLLL: YGNITB

## CALLED SUBROUTINES

## CALLING SUBROUTINES

[illegible]

## CALLLED SUBROUTINES



## CALLING SUBROUTINES

[illegible]

C A L L E D     S U B R O U T I N E .

[illegible]

37

[illegible]

38

```

HHHHHHHHHHHHHHHH : I I I : K L L L : M M O O : P P P P P P P P : Q Q R R R R : S S S S S S S S : T U U U : V V V V : W X Y :
YYYYYYYYYYYYYYYY : M M N N : I I O T : A A R U : A D L L L L O R R : S U C O O S : E E E E I L O O P P : R N P P : E I I I : I D P :
A B D E F L L N P R S V V : P P I T : N N G I : T T T T : N A E E R S T S I I : E A R T T T : A G T N P L L D L : I I D D : H N S S : N Y R :
B N O A S C I P T E E O A B F : L U T E : P A A M : 3 3 H P : E U D L E E X T N P : T T T A A : R S U P L V V A I : G T A F : P P C P : D D :
F D X D T N M R X R N A L L X N : S L A R : U X X E : 1 3 O U : L X G P A G Y P T L : T R : C E P P U O A R M N : F I T D : O U O R : Y E :
: 2 S L S : T S S : T : F Z R T : E T : H G 1 2 T T P E : S E C : S T S : G :

```

## CALLLED SUBROUTINES

[illegible]

40



[illegible]

41

#### 4.0 LIST OF 130 SUBROUTINES THAT COMPRISE THE ATB-IV MODEL COMPUTER PROGRAM

The first subroutine is a list of the common blocks used by the program, the second is the main program followed by all of the remaining subroutines in alphabetical order. Each subroutine name is appended with its revision number followed by the date of the latest change to the subroutine. This same data and revision number appears on the second line of each subroutine in Section 5.

SUBPROGRAM & REV. NO.			SUBPROGRAM & REV. NO.		
		DATE			DATE
BDATA	IV	07/23/86	MAIN	IV	07/23/86
ADJUST	IV	07/23/86	AIRBAG	IV	07/24/86
AIRBGG	III.5	10/17/85	AIRBG1	IV	07/24/86
AIRBG3	IV	07/23/86	BELTG	IV	07/23/86
BELTRT	IV	07/23/86	BGG	IV	07/23/86
BINPUT	IV	07/24/86	BLKDTA	IV	07/23/86
CFACCT	3	05/31/73	CHAIN	IV	07/24/86
CINPUT	III.2	08/08/84	CMPUTE	III.2	08/08/84
CONTCT	III.2	08/08/84	CROSS	3	05/31/73
DAUX	IV	07/24/86	DAUX11	IV	07/24/86
DAUX12	IV	07/24/86	DAUX22	IV	07/24/86
DAUX31	IV	07/24/86	DAUX32	IV	07/24/86
DAUX33	IV	07/24/86	DAUX44	IV	07/24/86
DAUX55	IV	07/24/86	DHHPIN	IV	07/24/86
DINT	IV	07/23/86	DOTT31	17	12/20/76
DOTT33	17	01/03/77	DOT31	17	01/03/77
DOT33	17	01/03/77	DRCIJK	18	02/24/78
DRCQUA	III.5	07/31/85	DRCYPR	IV	07/23/86
DRIFT	IV	07/24/86	DSETD	IV	07/23/86
DSETQ	IV	07/23/86	DSMSOL	3	07/08/74
DZP	IV	07/23/86	EDEPTH	IV	07/23/86
EFUNCT	20	04/29/80	EJOINT	IV	07/24/86
ELONG	1	10/05/72	ELTIME	III.2	08/08/84
EQUILB	IV	02/01/88	EULRAD	IV	07/23/86
EVALFD	IV	07/23/86	FDINIT	III.2	08/08/84
FINPUT	IV	02/01/88	FLXSEG	IV	07/23/86
FNTERP	IV	04/10/87	FRCDFL	III.2	08/08/84
FSMSOL	III.2	08/08/84	GLOBAL	IV	07/24/86
HBELT	IV	02/01/88	HBPLAY	III.5	10/17/85
HEDING	IV	02/01/88	HERRON	IV	07/23/86
HICCSI	IV	10/08/87	HINPUT	IV	07/23/86
HPTURB	IV	07/23/86	HSETC	III.2	08/08/84
HYABF	IV	02/07/87	HYBND	IV	02/07/87
HYBOX	IV	02/07/87	HYDAD	IV	02/07/87
HYEST	IV	02/07/87	HYFCN	IV	02/07/87
HYLIM	IV	12/11/87	HYLPR	IV	02/07/87
HYLPX	IV	02/07/87	HYNTR	IV	02/07/87
HYPEN	IV	02/07/87	HYREA	IV	12/11/87
HYSOL	IV	02/01/88	HYVAL	IV	12/11/87
HYVBX	IV	02/07/87	HYVFN	IV	12/11/87
IMPLS2	IV	07/24/86	IMPULS	IV	07/24/86
INITIAL	IV	07/24/86	INTERS	IV	02/23/86
KINPUT	IV	07/23/86	LINAXS	18	02/28/78

SUBPROGRAM & REV NO.			DATE	SUBPROGRAM & REV NO.			DATE
LOGAXS	19		09/18/79	LTIME	III.2		08/08/84
MAT31	17		01/03/77	MAT33	17		01/03/77
ORTHO	3		05/31/73	OUTPUT	IV		02/01/88
PANEL	III.2		08/08/84	PDAUX	IV		07/24/86
PLEDG	IV		02/07/87	PLELP	IV		02/07/87
PLREA	IV		12/11/87	PLSEGF	III.5		09/03/85
PLTXYZ	III.5		05/30/85	POSTPR	IV		02/01/88
PRINT	IV		07/24/86	PRIPLT	IV		07/24/86
QSET	III.3		10/01/84	QUAT	IV		07/23/86
RCRT	3		07/19/73	ROT	IV		07/23/86
ROTATE	IV		02/20/87	RSTART	IV		07/24/86
SEARCH	IV		07/24/86	SEGSEG	IV		02/07/87
SETUP1	IV		07/24/86	SETUP2	IV		07/24/86
SINPUT	IV		02/20/87	SLPLOT	III.2		08/08/84
SOLVA	III.2		08/08/84	SOLVR	III.2		08/08/84
SPDAMP	IV		07/24/86	SPLINE	19		05/14/79
SPRNGF	IV		07/23/86	TRIGFS	19		08/05/78
UNIT1	IV		02/20/87	UPDATE	IV		07/24/86
UPDFDC	III.2		08/08/84	VEHPOS	IV		07/23/86
VINPUT	IV		07/24/86	VISCOS	19		10/23/78
VISPR	IV		02/01/88	WINDY	IV		07/23/86
XDY	IV		07/23/86	YPRDEG	IV		11/26/86

## 5.0 FORTRAN SOURCE CODE OF THE ATB-IV.0 PROGRAM

Each of the 130 ATB-IV subroutines are listed in this section. The second line of each subroutine contains the subroutine revision number and the date of the latest change to the subroutine. Columns 72-80 of each line contain the subroutine name unless the line is a new or changed line from the listing in Ref. 4. In these cases the name of the latest change is in columns 72-80. The first subroutine is the BLOCKDATA containing the COMMON blocks used by the program. The second routine is the MAIN program which controls the flow of the program. The remaining subroutines are listed alphabetically.

	BLOCK DATA		DECKA
C	IMPLICIT REAL*8 (A-H,O-Z)	REV IV 07/23/86	TWOPI
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		DECKA
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		DECKA
*	UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),		DECKA
*	MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),		DECKA
*	NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)		DECKA
	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),		DECKA
*	BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30),		DECKA
*	JOINT(30),CGS(30),JS(30)		DECKA
	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT		DECKA
	LOGICAL*1 CGS,JS		DECKA
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),		NCFORC
*	PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF		DECKA
	COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),		ATBIII
*	NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)		TTHKREF
	COMMON/CDINT/ UU(4),GH(3,4),		DECKA
*	E(3,240),FF(5,240),GG(5,240),Y(5,240),U(5,240),		DECKA
*	H,HPRINT,TSAVE,TPRINT,TSTART,ICNT,IDBL,IFLAG		DECKA
	COMMON/DAMPER/ APSDM(3,20),APSDN(3,20),ASD(5,20),MSDM(20),MSDN(20)		DECKA
	COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),FLOSS(2,100),		DECKA
*	XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),		DECKA
*	NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)		DECKA
C	NOTE: FF REPLACES F.		DECKA
	LOGICAL*1 FREE		SLIP
	COMMON/TEMPVS/ JTMPVS(24000),FREE(30)		SLIP
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		DECKA
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		DECKA
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		DECKA
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		DECKA
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)		EDGE
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)		BUTLER2
	COMMON/VPOSTN/ ZPLT(3),SPLT(3),AXV(3,6),VATAB(6,501,6),		VEHICL
*	VTO(6),VDT(6),TIMEV(6),OMEGV(6),NVTAB(6),INDXV(6)		DECKA
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		DECKA
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),		JDRIFT
*	FE(3,30),TQE(3,30),CONST(5,30)		JDRIFT
	COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)		DECKA
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		DECKA
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		DECKA
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		DECKA
*	KQ1(12),KQ2(12),KQTYPE(12)		DECKA
	COMMON/TEMPVI/ CREST,TTI(3),RII(3),R2I(3),JSTOP(4,2,30)		DECKA
	COMMON/INTEST/ SGTEST(3,4,30),XTEST(3,120),SEGT(120),REGT(120)		DECKA
	REAL SEGT		DECKA

COMMON/COMAIN/	VAR(240),DER(240),DT,H0,HMAX,HMIN,RSTIME,	DECKA
*	ISTEP,NSTEPS,NDINT,NEQ,IRSIN,IRSOUT	DECKA
COMMON/ABDATA/	ZDEP(3,5),DBR(3,3,5),DPVCTR(3,5),DEPLOY(3,5),	DECKA
*	AB(3,5),B(9,4,5),ZR(3,4,5),BFB(3,4,5),DRR(9,4,5),	DECKA
*	VBAGG(5),VSCS(5),SPRK(5),CK(5),CMASS(5),CYMIN(5),	DECKA
*	CYMOUT(5),BAGPV(5),PD(5),VBAG(5),VOLBP(5),	DECKA
*	PCYV(5),PCYMIN(5),PVBAG(5),TV1(3,4,5),TV2(3,10,5),	DECKA
*	SWITCH(5),PYMOUT(5),SCALE(5),PREVT,IFULL(6)	DECKA
COMMON/CYDATA/	CYTD(5),CYPA(5),CYSP(5),CYT0(5),CYV0(5),CYCD(5),	DECKA
*	CYK(5),CYR(5),CYAT(5),CYPV(5),CYCD0(5),CYA0(5),	DECKA
*	CYP0(5),CYSS(5),CYL0(5),CYC(5),CYRHO0(5),CYVMAX(5),	DECKA
*	CYORFC(5),CYRHO(5),CYT(5),CYP(5),CYV(5)	DECKA
COMMON/WINDFR/	WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30),	WINDOP
*	MWSEG(7,30),NFVSEG(6),NFVNT(5),MOWSEG(30,30)	WINDOP
END		DECKA

C		MAINA
C	AAMRL ARTICULATED TOTAL BODY (ATBIV) MODEL COMPUTER PROGRAM	ATBIV
C	DEVELOPED BY CALSPAN CORP. AND J&J TECHNOLOGIES INC.	BUTLER1
C		REV IV 07/23/86TWOPI
C	MAIN PROGRAM	MAINA
C		MAINA
C	PERFORMS CARD INPUT, PROGRAM INITIALIZATION,	MAINA
C	CONTROL OF INTEGRATION LOOP AND OPTIONAL OUTPUT.	MAINA
C		MAINA
	IMPLICIT REAL*8(A-H,O-Z)	MAINA
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	MAINA
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),	MAINA
*	BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30),	MAINA
*	JOINT(30),CGS(30),JS(30)	MAINA
	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT	MAINA
	LOGICAL*1 CGS,JS	MAINA
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	MAINA
*	UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
	COMMON/COMAIN/ VAR(240),DER(240),DT,H0,HMAX,HMIN,RSTIME,	MAINA
*	ISTEP,NSTEPS,NDINT,NEQ,IRSIN,IRSOUT	MAINA
	LOGICAL NPRT1,NPRT2,NPRT3	MAINA
	CALL ELTIME(1, 1)	MAINA
C		PECONV
C	MAKE THE OUTPUT FILES PRINTER CONTROL FILES FOR THE P&E	PECONV
C		PECONV
	CALL CARCON(6,1)	PECONV
	CALL CARCON(2,1)	PECONV
C		MAINA
C	WRITE PROLOGUE ON PRIMARY OUTPUT UNIT.	MAINA
C		MAINA
	NPG=2	PAGE
	WRITE(6,11)	MAINA
	11 FORMAT(1H1,30X,'AAMRL ARTICULATED TOTAL BODY (ATB) MODEL',52X,	ATBIV
	* 'PAGE 1'////	PAGE
	* 31X,'DEVELOPED BY CALSPAN CORP., P.O. BOX 400, BUFFALO NY 14225'//	BUTLER1
	* 31X,'AND BY J&J TECHNOLOGIES INC., ORCHARD PARK, NY 14127' //	EDGE
	* 31X,'FOR THE AIR FORCE ARMSTRONG AEROSPACE MEDICAL RESEARCH ' /	VEHICL
	* 31X,'LABORATORY, WRIGHT PATTERSON AIR FORCE BASE ' /	ATBIV
	* 31X,'UNDER CONTRACTS F33615-75C-5002,-78C-0516 AND -80C-05117' //	BUTLER1
	* 31X,'AND FOR THE NATIONAL HIGHWAY TRAFFIC SAFETY ADMINISTRATION,'	BUTLER1
	*/31X,'U.S. DEPARTMENT OF TRANSPORTATION, UNDER CONTRACTS' /	BUTLER1
	* 31X,'FH-11-7592, HS-053-2-485, HS-6-01300 AND HS-6-01410.' ////	BUTLER1
	* 31X,'PROGRAM DOCUMENTATION: NHTSA REPORT NOS. DOT-HS-801-507' /	BUTLER1
	* 31X,'THROUGH 510 (FORMERLY CALSPAN REPORT NO. ZQ-5180-L-1),' /	BUTLER1
	* 31X,'AVAILABLE FROM NTIS (ACCESSION NOS. PB-241692,3,4 AND 5),'	BUTLER1
	* 31X,'APPENDIXES A-J TO THE ABOVE (AVAILABLE FROM CALSPAN),' /	BUTLER1
	* 31X,'AND REPORT NOS. AMRL-TR-75-14 (NTIS NO. AD-A014 816),/'	ATBIV
	* 31X,'AFAMRL-TR-80-14 (NTIS NO. AD-A088 029), AND' /	ATBIV
	* 31X,'AFAMRL-TR-83-073 (NTIS NO. AD-B079 184).'////	



	* 31X,'PROGRAM ATB-IV, EXECUTED ON THE AAMBL/BB CONCURRENT'/	ATBIV
	* 31X,'3250 COMPUTER, WRIGHT-PATTERSON AFB, OHIO'////)	ATBIV
C		MAINA
C	INPUT CARDS A.1 AND A.2, TEST FOR RESTART.	MAINA
C		MAINA
	CALL BLKDTA	MAINA
	READ(5,12) DATE,IRSIN,IRSOUT,RSTIME,COMENT	MAINA
	12 FORMAT(3A4,2I4,F8.0/20A4/20A4)	MAINA
	WRITE(6,13) DATE,IRSIN,IRSOUT,RSTIME,COMENT	MAINA
	13 FORMAT(////4X,3A4,' IRSIN=',I4,' IRSOUT=',I4,' RSTIME =',F8.4,	MAINA
	* 61X,'CARDS A'//1X,20A4/1X,20A4//)	MAINA
	IF (IRSIN.NE.0) GO TO 18	MAINA
C		MAINA
C	INPUT CARDS A.3,A.4 AND A.5.	MAINA
C		MAINA
	READ(5,14) UNITL,UNITM,UNITT,GRAVTY,G	MAINA
	14 FORMAT(3A4,4F12.0)	MAINA
	IF (G.EQ.0.0) G = DSQRT(GRAVTY(1)**2+GRAVTY(2)**2+GRAVTY(3)**2)	MAINA
	READ(5,15) NDINT,NSTEPS,DT,H0,HMAX,HMIN,NPRT	MAINA
	15 FORMAT(2I4,4F8.0/36I2)	MAINA
	WRITE(6,16) UNITL,UNITM,UNITT,GRAVTY,G,	CHGIII
	* NDINT,NSTEPS,DT,H0,HMAX,HMIN	MAINA
	16 FORMAT(5X,'UNITL = ',A4,5X,'UNITM = ',A4,5X,'UNITT = ',A4,	CHGIII
	* 5X,'GRAVITY VECTOR = (',F9.4,',',F9.4,',',F9.4,',')',5X,'G ='	CHGIII
	*F9.4,/,5X,'NDINT = ',I4,5X,'NSTEPS = ',I5,5X,'DT = ',F8.6,	MAINA
	* 5X,'H0 = ',F8.6,5X,'HMAX = ',F8.6,5X,'HMIN = ',F8.6)	MAINA
	WRITE(6,17) (I,I=1,36),NPRT	MAINA
	17 FORMAT('0 NPRT ARRAY'/3X,36I3/3X,36I3)	MAINA
	NPRT4 = NPRT(4)	MAINA
	IF(NPRT(26).GT.6) STOP 93	TGMOD1
	IF (NPRT(4).LT.0) GO TO 50	MAINA
C		MAINA
C	CALL INPUT ROUTINES	MAINA
C		MAINA
	CALL BINPUT	MAINA
	CALL VINPUT	MAINA
	CALL SINPUT	MAINA
	CALL CINPUT	MAINA
C		MAINA
C	PROGRAM INITIALIZATION	MAINA
C		MAINA
	TIME = 0.0	MAINA
	CALL INITAL	MAINA
	GO TO 19	MAINA
C		MAINA
C	READ INPUT DATA FROM RESTART TAPE AND WRITE NEW TAPE.	MAINA
C	THE FIVE FUNCTIONS OF SUBROUTINE RSTART ARE:	MAINA
C	1. READ INPUT & INITIALIZATION RECORD FROM OLD RESTART TAPE.	MAINA
C	2. WRITE INPUT & INITIALIZATION RECORD ONTO NEW RESTART TAPE.	MAINA
C	3. READ TIME POINT RECORD FROM OLD RESTART TAPE.	MAINA

C	4. READ NEW INPUT DATA FROM INPUT STREAM FOR RESTART.	MAINA
C	5. WRITE TIME POINT RECORD ONTO NEW RESTART TAPE.	MAINA
C		MAINA
	18 CALL RSTART(1,IRSIN)	MAINA
	CALL RSTART(4,5)	MAINA
	NPRT4 = NPRT(4)	MAINA
	19 IF (IRSOUT.NE.0) CALL RSTART(2,IRSOUT)	MAINA
C		MAINA
C	INTEGRATION LOOP - ADVANCE TIME BY EITHER INTEGRATING THROUGH	MAINA
C	SUBROUTINE DINT OR BY FETCHING TIME POINT RECORD FROM RESTART TAPE	MAINA
C		MAINA
	TIME = 0.0	MAINA
	ISTEP = 0	MAINA
	20 IF (IRSIN.EQ.0) GO TO 23	MAINA
	IF (TIME.GT.RSTIME+0.5*DT) GO TO 23	MAINA
	IF (DABS(TIME-RSTIME).LT.0.5*DT) GO TO 21	MAINA
	CALL RSTART(3,IRSIN)	MAINA
	GO TO 24	MAINA
	21 CALL RSTART(4,5)	MAINA
	IF (NPRT(4).LT.0) GO TO 50	MAINA
	23 CALL DINT	MAINA
C		MAINA
C	OPTIONAL OUTPUT	MAINA
C	1. PRINTER PLOT ON OUTPUT UNIT 2 CONTROLLED BY NPRT(5) & (6).	MAINA
C		MAINA
	24 CALL PRIPLT	MAINA
C		MAINA
C	2. RESTART DATA ON UNIT IRSOUT CONTROLLED BY IRSOUT * 0.	MAINA
C		MAINA
	IF (IRSOUT.NE.0) CALL RSTART(5,IRSOUT)	MAINA
C		MAINA
C	3. SUBROUTINE PRINT ON PRIMARY OUTPUT UNIT CONTROLLED BE NPRT(3).	MAINA
C		MAINA
	NPRT3 = (NPRT(3).EQ.1)	MAINA
	IF (NPRT(3).GT.1) NPRT3 = (MOD(ISTEP,NPRT(3)).EQ.0)	MAINA
	IF (NPRT3) CALL PRINT(6HMAIN3D)	MAINA
C		MAINA
C	4. PROGRAM VIEW PLOT DATA ON UNIT 1 CONTROLLED BY NPRT(1).	MAINA
C		MAINA
	NPRT1 = (NPRT(1).EQ.1)	MAINA
	IF (NPRT(1).GT.1) NPRT1 = (MOD(ISTEP,NPRT(1)).EQ.0)	MAINA
	IF (NPRT1) CALL UNIT1(0)	MAINA
C		MAINA
C	5. SUBROUTINE ELTIME ON PRIMARY OUTPUT UNIT CONTROLLED BY NPRT(2).	MAINA
C		MAINA
	NPRT2 = (NPRT(2).EQ.1)	MAINA
	IF (NPRT(2).GT.1) NPRT2 = (MOD(ISTEP,NPRT(2)).EQ.0)	MAINA
	IF (NPRT2) CALL ELTIME(NPG,1)	MAINA
C		PAGE
C	END OF INTEGRATION LOOP.	MAINA

C	ISTEP = ISTEP+1	MAINA
	IF (ISTEP.LE.NSTEPS) GO TO 20	MAINA
C		MAINA
C	6. SUBROUTINE POSTPR ON PRIMARY OUTPUT UNIT CONTROLLED BY NPRT(4).	MAINA
C		MAINA
50	IF (NPRT4.GT.0) END FILE 8	MAINA
	IF (NPRT(4).EQ.0 .OR. NPRT(4).EQ.4) GO TO 60	MAINA
	PRDT = 1000.0*DT	MAINA
	CALL POSTPR (PRDT)	MAINA
	IF (NPRT2) CALL ELTIME(NPG,1)	PAGE
C		MAINA
C	7. END OF RUN - CALL ELTIME IF NOT CALLED ABOVE.	MAINA
C		MAINA
60	IF (.NOT.NPRT2) CALL ELTIME(NPG,1)	PAGE
	STOP 1	MAINA
	END	MAINA

	SUBROUTINE ADJUST (M,D1)		ADJUST
C		REV IV 07/23/86	TWOPI
	IMPLICIT REAL*8 (A-H,O-Z)		ADJUST
	COMMON/CMSNTS/ PI,RADIAN,G,THIRD,EPS(24),		ADJUST
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	COMMON/CDINT/ UU(4),GH(3,4),		ADJUST
	* E(3,240), F(5,240),GG(5,240),Y(5,240),U(5,240),		ADJUST
	* H,HPRINT,HS,TPRINT,TSTART,ICNT,IDBL,IFLAG		ADJUST
	COMMON/COMAIN/ VAR(240),DER(240),DT,H0,EMAX,HMIN,RSTIME,		ADJUST
	* ISTEP,NSTEPS,NDINT,NEQ,IRSIM,IRSOUT		ADJUST
	IF (M.NE.1) GO TO 12		ADJUST
C			ADJUST
C	M = 1:		ADJUST
C			ADJUST
	DO 11 I=1,NEQ		ADJUST
	W = VAR(I) - GG(1,I)		ADJUST
	Z = DER(I) - GG(2,I)		ADJUST
	ZZ = Z - GG(5,I)*W - GG(3,I)*UU(3) - GG(4,I)*UU(4)		ADJUST
	GG(3,I) = GG(3,I) + ZZ*UU(1)		ADJUST
	GG(4,I) = GG(4,I) + ZZ*UU(2)		ADJUST
	Y(1,I) = VAR(I)		ADJUST
11	Y(2,I) = DER(I)		ADJUST
	GO TO 99		ADJUST
12	IF (M.EQ.3) GO TO 23		ADJUST
C			ADJUST
C	M = 2,4,5:		ADJUST
C			ADJUST
	H1 = EPS(1)/H		ADJUST
	N2 = NEQ/2		ADJUST
	DO 20 I=1,NEQ,3		ADJUST
	ZA = 0.0		ADJUST
	IF (I.LE.N2) GO TO 20		ADJUST
	IF (M.EQ.4) GO TO 16		ADJUST
	VARX = VAR(I) - Y(1,I)		ADJUST
	VARY = VAR(I+1) - Y(1,I+1)		ADJUST
	VARZ = VAR(I+2) - Y(1,I+2)		ADJUST
	DERX = DER(I) - Y(2,I)		ADJUST
	DERY = DER(I+1) - Y(2,I+1)		ADJUST
	DERZ = DER(I+2) - Y(2,I+2)		ADJUST
	GO TO 17		ADJUST
16	VARX = VAR(I) - U(1,I)		ADJUST
	VARY = VAR(I+1) - U(1,I+1)		ADJUST
	VARZ = VAR(I+2) - U(1,I+2)		ADJUST
	DERX = DER(I) - U(2,I)		ADJUST
	DERY = DER(I+1) - U(2,I+1)		ADJUST
	DERZ = DER(I+2) - U(2,I+2)		ADJUST
17	U(3,I) = U(3,I) + VARX*DERX + VARY*DERY + VARZ*DERZ		ADJUST
	U(4,I) = U(4,I) + VARX**2 + VARY**2 + VARZ**2		ADJUST
	IF (U(4,I).EQ.0.0) GO TO 18		FIXADJ
	ZA = H1		FIXADJ

	IF (U(3,I).LT.H1*U(4,I)) ZA = U(3,I)/U(4,I)	FIXADJ
18	GG(5,I+2) = ZA	FIXADJ
	GG(5,I+1) = ZA	ADJUST
20	GG(5,I) = ZA	ADJUST
	GO TO (99,21,99,23,25),M	ADJUST
C		ADJUST
C	M = 2:	ADJUST
C		ADJUST
21	DO 22 I=1,NEQ	ADJUST
	ZA = GG(5,I)	ADJUST
	Y1 = Y(4,I) - ZA*Y(3,I)	ADJUST
	Y2 = GG(2,I) - ZA*GG(1,I)	ADJUST
	Y3 = DER(I) - ZA*VAR(I)	ADJUST
	GG(3,I) = -Y1*GH(1,1) + Y2*GH(2,1) + Y3*GH(3,1)	ADJUST
	GG(4,I) = Y1*GH(1,2) - Y2*GH(2,2) + Y3*GH(3,2)	ADJUST
	Y(1,I) = 0.5*(Y(1,I)+VAR(I))	ADJUST
22	Y(2,I) = 0.5*(Y(2,I)+DER(I))	ADJUST
	GO TO 99	ADJUST
C		ADJUST
C	M = 3,4:	ADJUST
C		ADJUST
23	DO 24 I=1,NEQ	ADJUST
	ZA = GG(5,I)	ADJUST
	Y1 = GG(2,I) - ZA*GG(1,I)	ADJUST
	Y2 = Y(2,I) - ZA*Y(1,I)	ADJUST
	Y3 = DER(I) - ZA*VAR(I)	ADJUST
	GG(3,I) = -Y1*GH(1,3) + Y2*GH(2,3) - Y3*GH(3,3)	ADJUST
	GG(4,I) = Y1*GH(1,4) - Y2*GH(2,4) + Y3*GH(3,4)	ADJUST
	U(1,I) = VAR(I)	ADJUST
24	U(2,I) = DER(I)	ADJUST
	GO TO 99	ADJUST
C		ADJUST
C	M = 5:	ADJUST
C		ADJUST
25	DO 26 I=1,NEQ	ADJUST
	ZA = GG(5,I)	ADJUST
	Y1 = GG(2,I) - ZA*GG(1,I)	ADJUST
	Y2 = DER(I) - ZA*VAR(I)	ADJUST
	Y3 = U(2,I) - ZA*U(1,I)	ADJUST
	GG(3,I) = -Y1*GH(1,3) + Y2*GH(2,3) - Y3*GH(3,3)	ADJUST
	GG(4,I) = Y1*GH(1,4) - Y2*GH(2,4) + Y3*GH(3,4)	ADJUST
	Y(1,I) = VAR(I)	ADJUST
26	Y(2,I) = DER(I)	ADJUST
99	RETURN	ADJUST
	END	ADJUST

```

C      SUBROUTINE  AIRBAG
C
C      REV IV      07/24/86SLIP
C
C      AIRBAG ROUTINE CALLED BY SUBROUTINE CONTCT TO DETERMINE THE INTER-AIRBAG
C      ACTION OF THE BAG WITH REACTION PANELS AND BODY SEGMENTS BY USE OFAIRBAG
C      SUBROUTINE BGG. THE DIFFERENTIAL PRESSURE, FORCE AND TORQUE ON THE AIRBAG
C      BAG IS EVALUATED AND THE RESULTING FORCE AND TORQUE ON THE BODY
C      SEGMENTS ARE ADDED TO THE U1 AND U2 ARRAYS.
C
C      IMPLICIT REAL*8 (A-H,O-Z)
C      COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,
C      *              NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG
C      COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),
C      *              SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)
C      COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),
C      *              RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),
C      *              JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)
C      COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),
C      *              MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),
C      *              NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)
C      COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),
C      *              PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF
C      COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)
C      COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),
C      *              UNITL,UNITM,UNITT,GRAVITY(3),TWOPI
C      COMMON/ABDATA/ ZDEP(3,5),DBR(3,3,5),DPVCTR(3,5),DEPLOY(3,5),
C      *              AB(3,5),B(9,4,5),ZR(3,4,5),BFB(3,4,5),DRR(9,4,5),
C      *              VBAGG(5),VSCS(5),SPRK(5),CK(5),CMASS(5),CYMIN(5),
C      *              CYMOUT(5),BAGPV(5),PD(5),VBAG(5),VOLBP(5),
C      *              PCYV(5),PCYMIN(5),PVBAG(5),TV1(3,4,5),TV2(3,10,5),
C      *              SWITCH(5),PYMOUT(5),SCALE(5),PREVT,IFULL(6)
C      COMMON/CYDATA/ CYTD(5),CYP(5),CYSP(5),CYT0(5),CYV0(5),CYCD(5),
C      *              CYK(5),CYR(5),CYAT(5),CYPV(5),CYCD0(5),CYA0(5),
C      *              CYP0(5),CYSS(5),CYL0(5),CYC(5),CYRHO0(5),CYVMAX(5),
C      *              CYORFC(5),CYRHO(5),CYT(5),CYP(5),CYV(5)
C      COMMON/TEMPVS/ TMP(9),TMP1(3),TORQ(3),FORCE(3,5),TORA(3,5),
C      *              TQB(3,10),FRB(3,10),VOL(10),DELF(3),VOLP(4,5),FRA(4,5)
C      NOTE: THIS COMMON/TEMPVS/ IS SHARED BY AIRBAG AND AIRBGG.
C      CALL ELTIME(1,24)
C      DELT = TIME-PREVT
C      NBGSF = 0
C      DO 70 J=1,NBAG
C      IF (MNBAG(J).EQ.0) GO TO 70
C      IF (IFULL(J).LE.0) GO TO 69
C      CALL AIRBGG(J)
C
C      COMPUTE CMOUT: MASS FLOW OUT OF BAG
C      BAGPV: UNDISTORTED BAG VOLUME
C
C      IF (PD(J).GT.CYPV(J)) CYMOUT(J) = PYMOUT(J)
C      *      + DELT*CYORFC(J)*DSQRT(PD(J))

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	BAGPV(J) = CYPA(J)*((CYMIN(J)-CYMOUT(J))*SWITCH(J))*CYK(J)	AIRBAG
C		AIRBAG
C	BAG IS FULLY INFLATED, COMPUTE DIFFERENTIAL PRESSURE	AIRBAG
C		AIRBAG
	PD(J) = BAGPV(J)/(VBAG(J)-VOLBP(J))*CYK(J) - CYPA(J)	AIRBAG
	JB = NVEH + J	AIRBAG
	KP = NPANEL(J)	AIRBAG
	KBAG = MNBAG(J)	AIRBAG
C		AIRBAG
C	OPTIONAL DIAGNOSTIC OUTPUT	AIRBAG
C		AIRBAG
	IF (NPRT(21).NE.0) WRITE(6,41)	AIRBAG
	* ((FRB(I,K),I=1,3),(TQB(I,K),I=1,3),K=1,KBAG),(FORCE(I,J),I=1,3),	AIRBAG
	* (TORA(I,J),I=1,3),TORQ,((FRA(I,K),I=1,3),VOLP(K,J),K=1,KP),	AIRBAG
	* (VOL(K),K=1,KBAG),VOLBP(J),CYMOUT(J),BAGPV(J),PD(J)	AIRBAG
41	FORMAT ('OAIRBAG CONTACT'/(1X,9G14.6))	AIRBAG
	IF (PD(J).LT.0.0) PD(J) = 0.0	AIRBAG
	IF (PD(J).EQ.0.0) GO TO 46	AIRBAG
C		AIRBAG
C	SET UP BAGSF ARRAY FOR OUTPUT ROUTINE	AIRBAG
C		AIRBAG
	KBGSF = NBGSF+5	AIRBAG
	DO 42 K=1,KP	AIRBAG
	KBGSF = KBGSF+1	AIRBAG
	DO 42 I=1,3	AIRBAG
42	BAGSF(I,KBGSF) = PD(J)*FRA(I,K)	AIRBAG
	DO 45 I=1,KBAG	AIRBAG
	KBGSF = KBGSF+1	AIRBAG
	IF (VOL(I).EQ.0.0) GO TO 45	AIRBAG
	M = MBAG(2,I,J)	AIRBAG
C		AIRBAG
C	FINAL COMPUTATIONS OF FORCE AND TORQUE ON AIRBAG	AIRBAG
C		AIRBAG
	DO 44 K=1,3	AIRBAG
	FRB(K,I) = PD(J)*FRB(K,I)	AIRBAG
	BAGSF(K,KBGSF) = FRB(K,I)	AIRBAG
	U1(K,M) = U1(K,M) - FRB(K,I)	AIRBAG
44	U2(K,M) = U2(K,M) + PD(J)*TQB(K,I)	AIRBAG
45	CONTINUE	AIRBAG
46	DO 47 K=1,3	AIRBAG
	FORCE(K,J) = PD(J)*FORCE(K,J)	AIRBAG
47	TORA (K,J) = PD(J)*TORA (K,J)	AIRBAG
	IF (VOLP(1,J).NE.0.0) GO TO 55	AIRBAG
C		AIRBAG
C	AIRBAG IS NOT INTERSECTING PRIMARY REACTION PANEL.	AIRBAG
C	COMPUTE ARTIFICIAL FORCE AND TORQUE WITH A LINEAR SPRING FUNCTION	AIRBAG
C	IN AN ATTEMPT TO TIE +X SEMIAXIS ENDPOINT OF AIRBAG TO DEPLOYMENT	AIRBAG
C	POINT ON REACTION PANEL.	AIRBAG
C		AIRBAG
	DO 51 K=1,3	AIRBAG

51	TMP(K) = BFB(K,1,J) + ZDEP(K,J)	AIRBAG
	CALL DOT31 (D(1,1,NVEH),TMP,TMP1)	AIRBAG
	DO 52 K=1,3	AIRBAG
	DELF(K) = TMP1(K) + SEGLP(K,NVEH) - SEGLP(K,JB)	AIRBAG
52	TMP(K) = BD(K+3,JB)	AIRBAG
	TMP(1) = TMP(1) + BD(1,JB)	AIRBAG
	CALL DOT31 (D(1,1,JB),TMP,TMP1)	AIRBAG
	DO 53 K=1,3	AIRBAG
	DELF(K) = SPRK(J)*(DELF(K)-TMP1(K))	AIRBAG
	BAGSF(K,NBGSF+5) = DELF(K)	AIRBAG
53	FORCE(K,J) = FORCE(K,J) + DELF(K)	AIRBAG
	CALL MAT31 (D(1,1,JB),DELF,TMP1)	AIRBAG
	CALL CROSS (TMP,TMP1,DELF)	AIRBAG
	DO 54 K=1,3	AIRBAG
54	TORA(K,J) = TORA(K,J) + DELF(K)	AIRBAG
55	XDD = CYMIN(J) - CYMOUT(J) + W(JB)	AIRBAG
	FMASS = CMASS(J)*XDD/G	AIRBAG
	TMASS = CMASS(J)*(XDD+W(JB)*2.0/3.0)/G	AIRBAG
	DO 56 I=1,3	AIRBAG
56	TMP(I) = WMEG(I,JB)*PHI(I,JB)	AIRBAG
	CALL CROSS (WMEG(1,JB),TMP,TMP1)	AIRBAG
	DO 57 I=1,3	AIRBAG
	SEGLA(I,JB) = FORCE(I,J)/FMASS + GRAVITY(I)	AIRBAG
57	WMEGD(I,JB) = (TORA(I,J)/TMASS-TMP1(I))*RPHI(I,JB)	AIRBAG
69	NBGSF = NBGSF + 5 + NPANEL(J) + MNBAG(J)	AIRBAG
70	CONTINUE	AIRBAG
	CALL ELTIME(2,24)	AIRBAG
	RETURN	AIRBAG
	END	AIRBAG





	CYMIN(J) = CYV0(J)*(CYRH00(J)-CYRHO(J))	AIRBGG
	CYV(J) = CYVMAX(J)*(1.0-Q2)	AIRBGG
	IF (TIME.LT.CYTD(J)) GO TO 31	AIRBGG
	IF (BD(1,JB).EQ.0.0) GO TO 31	AIRBGG
	IF (TIME.LE.0.0) GO TO 31	AIRBGG
	VOLB = 0.0	AIRBGG
C		AIRBGG
C	COMPUTE AIRBAG ELLIPSOID MATRIX AND ZERO BAG FORCE AND TORQUE.	AIRBGG
C		AIRBGG
	IF (IFULL(J).NE.0) GO TO 21	AIRBGG
	SAB = SCALE(J)*AB(1,J)	AIRBGG
	DO 19 I=1,3	AIRBGG
19	TMP(I) = DEPLOY(I,J) + SAB*DPVCTR(I,J)	AIRBGG
	CALL DOT31 (D(1,1,NVEH),TMP,SEGLP(1,JB))	AIRBGG
	DO 20 I=1,3	AIRBGG
20	SEGLP(I,JB) = SEGLP(I,JB) + SEGLP(I,NVEH)	AIRBGG
21	DO 23 I=1,3	AIRBGG
	FORCE(I,J) = 0.0	AIRBGG
23	TORA (I,J) = 0.0	AIRBGG
C		AIRBGG
C	COMPUTE FORCE,TORQUE AND VOLUME OF INTERSECTION	AIRBGG
C	OF AIRBAG WITH REACTION PANEL ELLIPSOIDS.	AIRBGG
C		AIRBGG
	KP = NPANEL(J)	AIRBGG
	DO 26 K=1,KP	AIRBGG
	CALL BGG(	AIRBGG
	* BD(7,JB),SEGLP(1,JB),D(1,1,JB),BD(4,JB),SEGLV(1,JB),WMEG(1,JB),	AIRBGG
	* B(1,K,J),SEGLP(1,NVEH),D(1,1,NVEH),BFB(1,K,J),SEGLV(1,NVEH),	AIRBGG
	* WMEG(1,NVEH),VSCS(J),IFULL(J),TV1(1,K,J),	AIRBGG
	* FRA(1,K),TORQ,TQB,VOLP(K,J))	AIRBGG
	VOLBP(J) = VOLBP(J) + VOLP(K,J)	AIRBGG
	DO 26 I=1,3	AIRBGG
	FORCE(I,J) = FORCE(I,J) + FRA(I,K)	AIRBGG
26	TORA (I,J) = TORA (I,J) + TORQ(I)	AIRBGG
C		AIRBGG
C	COMPUTE FORCE,TORQUE AND VOLUME OF INTERSECTION	AIRBGG
C	OF AIRBAG WITH CONTACTING SEGMENT ELLIPSOIDS.	AIRBGG
C		AIRBGG
	KBAG = MNBAG(J)	AIRBGG
	DO 30 I=1,KBAG	AIRBGG
	M = MBAG(2,I,J)	AIRBGG
	MM = MBAG(3,I,J)	AIRBGG
	CALL BGG(	AIRBGG
	* BD(7,JB),SEGLP(1,JB),D(1,1,JB),BD(4,JB),SEGLV(1,JB),WMEG(1,JB),	AIRBGG
	* BD(7,MM),SEGLP(1,M),D(1,1,M),BD(4,MM),SEGLV(1,M),WMEG(1,M),	AIRBGG
	* VSCS(J),IFULL(J),TV2(1,I,J),FRB(1,I),TORQ,TQB(1,I),VOL(I))	AIRBGG
	IF (VOL(I).EQ.0.0) GO TO 30	AIRBGG
	VOLB = VOLB + VOL(I)	AIRBGG
	DO 28 K=1,3	AIRBGG
	FORCE(K,J) = FORCE(K,J) + FRB(K,I)	AIRBGG

28 TORA (K,J) = TORA (K,J) + TORQ(K)  
30 CONTINUE  
VOLBP(J) = VOLBP(J) + VOLB  
31 RETURN  
END

AIRBGG  
AIRBGG  
AIRBGG  
AIRBGG  
AIRBGG

	SUBROUTINE AIRBG1		AIRBG1
		REV IV 07/24/86SLIP	
C	READS AND PRINTS THE INPUT CARDS THAT DESCRIBE THE PHYSICAL		AIRBG1
C	DIMENSIONS AND GAS DYNAMICS OF THE AIRBAG RESTRAINTS AND		AIRBG1
C	PERFORMS INITIALIZATION REQUIRED BY THE AIRBAG ROUTINE.		AIRBG1
C			AIRBG1
	IMPLICIT REAL*8 (A-H,O-Z)		AIRBG1
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		AIRBG1
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		AIRBG1
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		AIRBG1
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		AIRBG1
	* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		AIRBG1
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),		NCFORC
	* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF		AIRBG1
	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),		AIRBG1
	* BLTTTL(5,8),PLTTTL(5,30),BAGTTL(5,6),SEG(30),		AIRBG1
	* JOINT(30),CGS(30),JS(30)		AIRBG1
	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTTL,BAGTTL,SEG,JOINT		AIRBG1
	LOGICAL*1 CGS,JS		AIRBG1
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		AIRBG1
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)		EDGE
	COMMON/INTEST/ SGTEST(3,4,30),XTEST(3,120),SEGT(120),REGT(120)		AIRBG1
	REAL SEGT		AIRBG1
	COMMON/ABDATA/ ZDEP(3,5),DBR(3,3,5),DPVCTR(3,5),DEPLOY(3,5),		AIRBG1
	* AB(3,5),B(9,4,5),ZR(3,4,5),BFB(3,4,5),DRR(9,4,5),		AIRBG1
	* VBAGG(5),VSCS(5),SPRK(5),CK(5),CMASS(5),CYMIN(5),		AIRBG1
	* CYMOUT(5),BAGPV(5),PD(5),VBAG(5),VOLBP(5),		AIRBG1
	* PCYV(5),PCYMIN(5),PVBAG(5),TV1(3,4,5),TV2(3,10,5),		AIRBG1
	* SWITCH(5),PYMOUT(5),SCALE(5),PREVT,IFULL(6)		AIRBG1
	COMMON/CYDATA/ CYTD(5),CYPA(5),CYSP(5),CYT0(5),CYV0(5),CYCD(5),		AIRBG1
	* CYK(5),CYR(5),CYAT(5),CYPV(5),CYCD0(5),CYA0(5),		AIRBG1
	* CYP0(5),CYSS(5),CYL0(5),CYC(5),CYRHO0(5),CYVMAX(5),		AIRBG1
	* CYORFC(5),CYRHO(5),CYT(5),CYP(5),CYV(5)		AIRBG1
	COMMON/TEMPVS/ TMP(9),TMP1(3)		AIRBG1
	DIMENSION YB(3),YP(3),IDYPR(3)		AIRBG1
	REAL BAG(6)		AIRBG1
	DATA BAG/4HBAG1,4HBAG2,4HBAG3,4HBAG4,4HBAG5,4HBAG /		AIRBG1
	DATA IDYPR/3,2,1/		AIRBG1
	DATA MAXNPL/4/,MAXSEG/30/		CHGIII
C			AIRBG1
C	MAKE ROOM FOR BAG DATA IN SEGMENT ARRAYS BETWEEN VEH AND GRND.		AIRBG1
C			AIRBG1
	MSEG = 0		CHGIII
	IF (NVEH.GT.NSEG) MSEG = NVEH - NSEG		CHGIII
	L = NSEG + NBAG + MSEG + 1		CHGIII
	K = NSEG + MSEG + 1		CHGIII
	W(L) = W(K)		AIRBG1

RW(L)	= RW(K)	AIRBG1
SEG(L)	= SEG(K)	AIRBG1
ISING(L)	= ISING(K)	AIRBG1
IF (L-1.GT.NJNT)	JNT (L-1) = 0	AIRBG1
IF (L-1.GT.NJNT)	IPIN(L-1) = 0	AIRBG1
DO 19 I=1,3		AIRBG1
SEGLP(I,L)	= SEGLP(I,K)	AIRBG1
SEGLV(I,L)	= SEGLV(I,K)	AIRBG1
SEGLA(I,L)	= SEGLA(I,K)	AIRBG1
WMEG(I,L)	= WMEG(I,K)	AIRBG1
WMEGD(I,L)	= WMEGD(I,K)	AIRBG1
PHI(I,L)	= PHI(I,K)	AIRBG1
RPHI(I,L)	= RPHI(I,K)	AIRBG1
DO 18 J=1,3		AIRBG1
D(I,J,L)	= D(I,J,K)	AIRBG1
18 SGTEST(I,J,L)	= SGTEST(I,J,K)	AIRBG1
19 SGTEST(I,4,L)	= SGTEST(I,4,K)	AIRBG1
NGRND	= NSEG + NBAG + MSEG + 1	CHGIII
IF (NGRND.GT.MAXSEG)	STOP 75	CHGIII
DO 40 J=1,NBAG		AIRBG1
JB	= NVEH + J	AIRBG1
C		AIRBG1
C		AIRBG1
C		AIRBG1
READ AND PRINT CARDS D.4.A -D.4.F FOR THE JTH AIRBAG.		AIRBG1
READ(5,13) (BAGTTL(I,J),I = 1,5),NPANEL(J),		AIRBG1
*	(AB(I,J),I=1,3) , (BD(I,JB),I=4,6) ,	AIRBG1
*	YB,(ZDEP(I,J),I=1,3) ,	AIRBG1
*	W(JB),CYTD(J),CYP A(J),CYSP(J),CYT0(J),CYV0(J) ,	AIRBG1
*	CYCD(J),CYK(J),CYR(J),CYAT(J),CYPV(J),CYCD0(J) ,	AIRBG1
*	CYA0(J),SPRK(J),VSCS(J),CK(J),CMASS(J)	AIRBG1
13	FORMAT (5A4,14/(6F12.0))	AIRBG1
	IF (NPANEL(J).GT.MAXNPL) STOP 76	CHGIII
	IF (MOD(J,2).EQ.1) WRITE(6,15) NPG	PAGE
	IF (MOD(J,2).EQ.1) NPG=NPG+1	PAGE
15	FORMAT('1',122X,'PAGE',15/' AIRBAG INPUTS',105X,'CARDS D.4')	PAGE
	WRITE(6,14) J,(BAGTTL(I,J),I = 1,5) ,	AIRBG1
*	(AB(I,J),I=1,3) , (BD(I,JB),I=4,6) ,	AIRBG1
*	YB,(ZDEP(I,J),I=1,3) ,	AIRBG1
*	W(JB),CYTD(J),CYP A(J),CYSP(J),CYT0(J),CYV0(J) ,	AIRBG1
*	CYCD(J),CYK(J),CYR(J),CYAT(J),CYPV(J),CYCD0(J) ,	AIRBG1
*	CYA0(J),SPRK(J),VSCS(J),CK(J),CMASS(J)	AIRBG1
14	FORMAT('0 AIRBAG NO.',14,4X,5A4//	AIRBG1
*	29X,'AIR BAG SEMIAXES',46X,'C.G. OFFSET'/6X,6G20.9//	AIRBG1
*	15X,'YAW',16X,'PITCH',15X,'ROLL',30X,'DEPLOYMENT POINT'	AIRBG1
*	/6X,6G20.9//	AIRBG1
*	15X,'XBM',16X,'CYTD',16X,'CYP A',16X,'CYSP',16X,'CYT0',16X,'CYV0'	AIRBG1
*	/6X,6G20.9//	AIRBG1
*	14X,'CYCD',17X,'CYK',17X,'CYR',16X,'CYAT',16X,'CYPV',16X,'CYCD0'	AIRBG1
*	/6X,6G20.9//	AIRBG1
*	14X,'CYA0',16X,'SPRK',16X,'VSCS',17X,'CK',17X,'CMASS'/6X,5G20.9)	AIRBG1

	KP = NPANEL(J)	AIRBG1
	DO 25 K=1,KP	AIRBG1
C		AIRBG1
C	READ AND PRINT CARDS D.4.G AND D.4.H FOR THE KTH PANEL TO	AIRBG1
C	CONTACT THE JTH AIRBAG. THESE PANELS ARE APPROXIMATED BY	AIRBG1
C	ELLIPSOIDS. THE FIRST PANEL (K=1) IS THE REACTION PANEL THAT	AIRBG1
C	INCLUDES THE DEPLOYMENT POINT.	AIRBG1
C		AIRBG1
	READ(5,11) (B(I,K,J),I=1,3),(BFB(I,K,J),I=1,3),	AIRBG1
	* (ZR(I,K,J),I=1,3),YP	AIRBG1
11	FORMAT(6F12.0)	AIRBG1
	WRITE(6,12) K,(B(I,K,J),I=1,3),(BFB(I,K,J),I=1,3),	AIRBG1
	* (ZR(I,K,J),I=1,3),YP	AIRBG1
12	FORMAT('O PANEL NO.',I4//	AIRBG1
	* 24X,'PANEL ELLIPSOID SEMIAXES',43X,'C.G. OFFSET'/6X,6G20.9//	AIRBG1
	* 29X,'PANEL LOCATION',32X,'YAW',16X,'PITCH',15X,'ROLL'/6X,6G20.9)	AIRBG1
C		AIRBG1
C	CONVERT B FROM ELLIPSOID SEMIAXES TO MATRIX	AIRBG1
C		AIRBG1
	DO 21 I=1,3	AIRBG1
21	TMP(I) = B(I,K,J)	AIRBG1
	DO 22 I=1,9	AIRBG1
22	B(I,K,J) = 0.0	AIRBG1
	DO 23 I=1,3	AIRBG1
23	B(4*I-3,K,J) = 1.0/TMP(I)**2	AIRBG1
	CALL DRCYPR (DRR(1,K,J),YP,IDYPR)	AIRBG1
	CALL MAT33 (B(1,K,J),DRR(1,K,J),TMP)	AIRBG1
	CALL DOT33 (DRR(1,K,J),TMP,B(1,K,J))	AIRBG1
	CALL DOT31 (DRR(1,K,J),BFB(1,K,J),TMP)	AIRBG1
	DO 24 I=1,3	AIRBG1
24	BFB(I,K,J) = TMP(I) + ZR(I,K,J)	AIRBG1
25	CONTINUE	AIRBG1
C		AIRBG1
C	COMPUTE GEOMETRY OF DEPLOYMENT POINT ON FIRST PANEL.	AIRBG1
C		AIRBG1
	CALL DRCYPR (DBR(1,1,J),YB,IDYPR)	AIRBG1
	CALL DOT31 (DRR(1,1,J),ZDEP(1,J),DEPLOY(1,J))	AIRBG1
	DO 31 I=1,3	AIRBG1
	DPVCTR(I,J) = -DBR(1,I,J)	AIRBG1
31	DEPLOY(I,J) = DEPLOY(I,J) + BFB(I,1,J)	AIRBG1
	CALL PANEL (DBR(1,1,J),DEPLOY(1,J),JB)	AIRBG1
C		AIRBG1
C	INITIALIZATION OF AIRBAG GEOMETRY.	AIRBG1
C		AIRBG1
	VBAGG(J) = 4.0/3.0*PI*AB(1,J)*AB(2,J)*AB(3,J)	AIRBG1
	PHI(1,JB) = (AB(2,J)**2+AB(3,J)**2)/5.0	AIRBG1
	PHI(2,JB) = (AB(3,J)**2+AB(1,J)**2)/5.0	AIRBG1
	PHI(3,JB) = (AB(1,J)**2+AB(2,J)**2)/5.0	AIRBG1
	JNT(JB-1) = 0	AIRBG1
	IPIN(JB-1) = 0	AIRBG1

	SEG(JB) = BAG(J)	AIRBG1
	IF (NBAG.EQ.1) SEG(JB) = BAG(6)	AIRBG1
	ISING(JB) = -1	AIRBG1
	RW(JB) = G/W(JB)	AIRBG1
	DO 36 I=1,3	AIRBG1
	BD(I,JB) = 0.0	AIRBG1
	RPHI(I,JB) = 1.0/PHI(I,JB)	AIRBG1
	DO 38 K=1,4	AIRBG1
36	SGTEST(I,K,JB) = 0.0	AIRBG1
	DO 35 I=7,24	AIRBG1
35	BD(I,JB) = 0.0	AIRBG1
	IFULL(J) = 0	AIRBG1
	CYMOUT(J) = 0.0	AIRBG1
	PYMOUT(J) = 0.0	AIRBG1
	DO 38 I=1,3	AIRBG1
	DO 37 K=1,4	AIRBG1
37	TV1(I,K,J) = 0.0	AIRBG1
	DO 38 K=1,10	AIRBG1
38	TV2(I,K,J) = 0.0	AIRBG1
C		AIRBG1
C	AIR CYLINDER INITIALIZATION	AIRBG1
C		AIRBG1
	CYP0(J) = CYSP(J)+CYP A(J)	AIRBG1
	CYSS(J) = DSQRT(CYK(J)*CYR(J)*CYT0(J)*G)	AIRBG1
	CYL0(J) = CYV0(J)/CYAT(J)	AIRBG1
	CYK1 = CYK(J)-1.0	AIRBG1
	CYK2 = 0.5*(CYK(J)+1.0)	AIRBG1
	CYK3 = CYK2**(-CYK2/CYK1)	AIRBG1
	CYC(J) = 0.5*CYK1*CYSS(J)*CYCD(J)/CYL0(J)*CYK3	AIRBG1
	CYRH00(J) = CYP0(J)/(CYR(J)*CYT0(J))	AIRBG1
	CYVMAX(J) = CYV0(J)/CYK(J)*CYP0(J)/CYP A(J)	AIRBG1
	CYORFC(J) = CYCD0(J)*CYA0(J)*G*DSQRT(2.0*CYP A(J)*CYK(J))/CYSS(J)	AIRBG1
	IF (NPRT(22).NE.0) WRITE(6,39)	AIRBG1
	* (SEGLP(I,JB),I=1,3),(SEGLV(I,JB),I=1,3),(WMEG(I,JB),I=1,3),	AIRBG1
	* VBAGG(J),CYP0(J),CYSS(J),CYC(J),CYRH00(J),CYVMAX(J),CYORFC(J)	AIRBG1
39	FORMAT('0 AIRBAG SINPUT'/(1X,9G14.6))	AIRBG1
40	CONTINUE	AIRBG1
	PREVT = 0.0	AIRBG1
	RETURN	AIRBG1
	END	AIRBG1

	SUBROUTINE AIRBG3(IRESET)		AIRBG3
		REV IV	07/23/86TWOPI
C			AIRBG3
C	THIS SUBROUTINE IS CALLED BY SUBROUTINE UPDATE AT START (IRESET=1)		AIRBG3
C	AND END (IRESET=2) OF EACH INTEGRATION STEP TO DETERMINE IF EACH		AIRBG3
C	AIRBAG HAS BEEN FULLY INFLATED.		AIRBG3
C			AIRBG3
	IMPLICIT REAL*8 (A-H,O-Z)		AIRBG3
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		AIRBG3
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		AIRBG3
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		AIRBG3
	COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),		AIRBG3
	* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),		AIRBG3
	* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)		AIRBG3
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),		NCFORC
	* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF		AIRBG3
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)		EDGE
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		AIRBG3
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	COMMON/ABDATA/ ZDEP(3,5),DBR(3,3,5),DPVCTR(3,5),DEPLOY(3,5),		AIRBG3
	* AB(3,5),B(9,4,5),ZR(3,4,5),BFB(3,4,5),DRR(9,4,5),		AIRBG3
	* VBAGG(5),VSCS(5),SPRK(5),CK(5),CMASS(5),CYMIN(5),		AIRBG3
	* CYMOUT(5),BAGPV(5),PD(5),VBAG(5),VOLBP(5),		AIRBG3
	* PCYV(5),PCYMIN(5),PVBAG(5),TV1(3,4,5),TV2(3,10,5),		AIRBG3
	* SWITCH(5),PYMOUT(5),SCALE(5),PREVT,IFULL(6)		AIRBG3
	COMMON/CYDATA/ CYTD(5),CYPA(5),CYSP(5),CYTO(5),CYVO(5),CYCD(5),		AIRBG3
	* CYK(5),CYR(5),CYAT(5),CYPV(5),CYCDO(5),CYAO(5),		AIRBG3
	* CYP0(5),CYSS(5),CYLO(5),CYC(5),CYRHO0(5),CYVMAX(5),		AIRBG3
	* CYORFC(5),CYRHO(5),CYT(5),CYP(5),CYV(5)		AIRBG3
	COMMON/TEMPVS/ TMP(9),TMP1(3)		AIRBG3
	CALL ELTIME(1,29)		AIRBG3
	JRESET = IRESET		AIRBG3
	IF (JRESET.EQ.1) PREVT = TIME		AIRBG3
	NBGSF = 0		AIRBG3
	DO 50 J=1,NBAG		AIRBG3
	IF (MNBAG(J).EQ.0) GO TO 50		AIRBG3
	JB = NVEH + J		AIRBG3
	JFULL = IFULL(J) + 2		AIRBG3
	IF (JFULL.LT.1 .OR. JFULL.GT.3) GO TO 11		AIRBG3
	IF (JRESET-1) 13,13,14		BUTLER1
11	WRITE(6,12) TIME		AIRBG3
12	FORMAT ('0 ERROR IN SUBROUTINE AIRBG3 AT TIME =',F10.6)		AIRBG3
	STOP 32		AIRBG3
13	IF (JFULL-2) 41,49,49		BUTLER1
14	IF (JFULL-2) 11,21,31		BUTLER1
C			AIRBG3
C	END OF INTEGRATION STEP WHEN IFULL=0. TEST FOR FULL INFLATION.		AIRBG3
C			AIRBG3
21	PD(J) = 0.0		AIRBG3



	PCYV(J) = CYV(J)	AIRBG3
	PCYMIN(J) = CYMIN(J)	AIRBG3
	PVBAG(J) = VBAG(J)	AIRBG3
22	CALL AIRBGG(J)	AIRBG3
	VBAG(J) = CYV(J) + VOLBP(J)	AIRBG3
	IF (SCALE(J).EQ.1.0) GO TO 23	AIRBG3
	SCALE(J) = (VBAG(J)/VBAGG(J))*THIRD	AIRBG3
	IF (SCALE(J).LT.1.0) GO TO 24	AIRBG3
	SCALE(J) = 1.0	AIRBG3
	GO TO 22	AIRBG3
23	IFULL(J) = -1	AIRBG3
	CYMOUT(J) = 0.0	AIRBG3
	PSW1 = (VBAG(J)-VBAGG(J))*PCYV(J)/PCYMIN(J)	AIRBG3
	PSW2 = (VBAGG(J)-PVBAG(J))*CYV(J)/CYMIN(J)	AIRBG3
	SWITCH(J) = (PSW1+PSW2)/(VBAG(J)-PVBAG(J))	AIRBG3
	BAGPV(J) = CYP(J)*(CYMIN(J)*SWITCH(J))*CYK(J)	AIRBG3
	PD(J) = BAGPV(J)/(CYV(J)*CYK(J)) - CYP(J)	AIRBG3
24	DO 25 K=1,3	AIRBG3
	BD(K,JB) = SCALE(J)*AB(K,J)	AIRBG3
	IF (SCALE(J).EQ.0.0) GO TO 25	AIRBG3
	BD(4*K+12,JB) = BD(K,JB)**2	AIRBG3
	BD(4*K+ 3,JB) = 1.0/BD(4*K+12,JB)	AIRBG3
25	TMP(K) = DEPLOY(K,J) + BD(1,JB)*DPVCTR(K,J)	AIRBG3
	CALL PANEL (DBR(1,1,J),TMP,JB)	AIRBG3
C		AIRBG3
C	SET UP BAGSF ARRAY FOR OUTPUT.	AIRBG3
C		AIRBG3
31	BAGSF(1,NBGSF+1) = CYP(J)	AIRBG3
	BAGSF(2,NBGSF+1) = CYT(J)	AIRBG3
	BAGSF(3,NBGSF+1) = PD(J)	AIRBG3
	CALL DOT31 (D(1,1,JB),BD(4,JB),TMP)	AIRBG3
	DO 32 K=1,3	AIRBG3
	BAGSF(K,NBGSF+3) = BD(K,JB)	AIRBG3
32	TMP(K) = TMP(K) + SEGLP(K,JB) - SEGLP(K,NVEH)	AIRBG3
	CALL MAT31 (D(1,1,NVEH),TMP,BAGSF(1,NBGSF+2))	AIRBG3
	CALL YPRDEG (D(1,1,JB),BAGSF(1,NBGSF+4))	AIRBG3
	NBGSF = NBGSF + 5 + NPANEL(J) + MNBAG(J)	AIRBG3
	GO TO 50	AIRBG3
C		AIRBG3
C	START OF INTEGRATION STEP WITH IFULL = -1, RESET INTEGRATOR.	AIRBG3
C		AIRBG3
41	IFULL(J) = 1	AIRBG3
	IRESET = -1	AIRBG3
49	PYMOUT(J) = CYMOUT(J)	AIRBG3
50	CONTINUE	AIRBG3
	CALL ELTIME(2,29)	AIRBG3
	RETURN	AIRBG3
	END	AIRBG3

	SUBROUTINE BELTG (ZA,ZB,ZC,BD)	BELTG
C		REV IV 07/23/86TWOPI
C	COMPUTE TANGENT POINTS, UNIT VECTORS FROM TANGENT POINTS TO	BELTG
C	ANCHOR POINTS AND LENGTHS OF THE BELT SEGMENTS.	BELTG
C		BELTG
C	ARGUMENTS:	BELTG
C		BELTG
C	ZA,ZB - ANCHOR POINTS RELATIVE TO ELLIPSOID CENTER.	BELTG
C	ZC - FIXED POINT OF BELT ON SEGMENT ELLIPSOID.	BELTG
C	BD - SEGMENT ELLIPSOID SEMIAXES AND CENTER.	BELTG
C		BELTG
C	RESULTS ARE RETURNED TO CALLING ROUTINE VIA COMMON/TEMPVS/.	BELTG
C		BELTG
	IMPLICIT REAL*8 (A-H,O-Z)	BELTG
	DIMENSION ZA(3),ZB(3),ZC(3),BD(24)	BELTG
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,WGRND,	BELTG
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	BELTG
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
C	NOTE: BELTRT AND BELTG SHARE FIRST PART OF TEMPVS	BELTG
	COMMON/TEMPVS/ APA(3),UVA(3),DLGA,UAA,APB(3),UVB(3),DLGB,UBB	BELTG
	* ,TA(3),TB(3),TC(3),UP(3),B(3)	BELTG
	* ,UC(3),AX(3),XE(3),BX(3),ACA(3),ACB(3)	BELTG
C		BELTG
C	COMPUTE	BELTG
C	TC: NORMALIZED VECTOR OF BELT PLANE DETERMINED	BELTG
C	BY ANCHOR POINTS AND FIXED POINT.	BELTG
C		BELTG
	DO 10 K=1,3	BELTG
	TA(K) = ZC(K)-ZA(K)	BELTG
10	TB(K) = ZC(K)-ZB(K)	BELTG
	CALL CROSS(TB,TA,TC)	BELTG
	S = DSQRT(TC(1)**2 + TC(2)**2 + TC(3)**2)	BELTG
	TC(1) = TC(1)/S	BELTG
	TC(2) = TC(2)/S	BELTG
	TC(3) = TC(3)/S	BELTG
C		BELTG
C	GET DISTANCE OF BELT PLANE TO CENTER OF ELLIPSIOD.	BELTG
C		BELTG
	BET = TC(1)*ZC(1)+TC(2)*ZC(2)+TC(3)*ZC(3)	BELTG
C		BELTG
C	COMPUTE	BELTG
C	XE: CENTER OF ELLIPSE DETERMINED BY INTERSECTION	BELTG
C	OF BELT PLANE AND SEGMENT ELLIPSOID.	BELTG
C		BELTG
	CALL MAT31 (BD(16),TC,XE)	BELTG
	GG = BET/(TC(1)*XE(1)+TC(2)*XE(2)+TC(3)*XE(3))	BELTG
	DLGA = 0.0	BELTG
	DLGB = 0.0	BELTG
	DO 15 K=1,3	BELTG

	XE(K) = XE(K)*GG	BELTG
	UC(K) = ZC(K)-XE(K)	BELTG
	APA(K) = UC(K)	BELTG
15	APB(K) = UC(K)	BELTG
	YAY = GG*BET	BELTG
	YAY1 = 1.0-YAY	BELTG
	IF (YAY1.LE.EPS(6)) GO TO 70	BELTG
C		BELTG
C	CALCULATE POSSIBLE TANGENT POINTS FROM	BELTG
C	UVA,UVB: VECTORS FROM ELLIPSE CENTER TO MIDPOINT OF	BELTG
C	LINE CONNECTING POSSIBLE TANGENT POINTS.	BELTG
C	ACA,ACB: VECTORS FROM UVA,UVB TO TANGENT POINTS (POSITIVE).	BELTG
C		BELTG
	CALL MAT31 (BD(7),ZA,AX)	BELTG
	CALL MAT31 (BD(7),ZB,BX)	BELTG
	ZZA = AX(1)*ZA(1)+AX(2)*ZA(2)+AX(3)*ZA(3)	BELTG
	IF( ZZA.LE.1.0) STOP 88	CHGIII
	ZZB = BX(1)*ZB(1)+BX(2)*ZB(2)+BX(3)*ZB(3)	BELTG
	IF( ZZB.LE.1.0) STOP 89	CHGIII
	C2A = YAY1/(ZZA-YAY)	BELTG
	C2B = YAY1/(ZZB-YAY)	BELTG
	CALL CROSS(TC,AX,ACA)	BELTG
	CALL CROSS(TC,BX,ACB)	BELTG
	TTA = 0.0	BELTG
	TTB = 0.0	BELTG
	DO 21 I=1,3	BELTG
	DO 21 J=1,3	BELTG
	K = 3*J+I+3	BELTG
	TTA = TTA + ACA(I)*BD(K)*ACA(J)	BELTG
21	TTB = TTB + ACB(I)*BD(K)*ACB(J)	BELTG
	C3A = DSQRT((1.0 - C2A)*YAY1/TTA)	CHGIII
	C3B = DSQRT((1.0 - C2B)*YAY1/TTB)	CHGIII
	TT = DSQRT(UC(1)**2 + UC(2)**2 + UC(3)**2)	BELTG
	DO 24 K=1,3	BELTG
	UVA(K) = C2A*(ZA(K)-XE(K))	BELTG
	UVB(K) = C2B*(ZB(K)-XE(K))	BELTG
	ACA(K) = C3A*ACA(K)	BELTG
	ACB(K) = C3B*ACB(K)	BELTG
	UC(K) = UC(K)/TT	BELTG
24	B(K) = 0.0	BELTG
C		BELTG
C	OBTAIN EQUATION OF ELLIPSE	BELTG
C	B1*X**2 + 2*B2*X*Y + B3*Y**2 = 1	BELTG
C	IN UC,UP COORDINATES WHERE UC POINTS TO FIXED POINT.	BELTG
C		BELTG
	CALL CROSS(TC,UC,UP)	BELTG
	DO 22 I=1,3	BELTG
	DO 22 J=1,3	BELTG
	K = 3*J+I+3	BELTG
	B(1) = B(1) + UC(I)*BD(K)*UC(J)	BELTG

	B(2) = B(2) + UC(1)*BD(K)*UP(J)	BELTG
22	B(3) = B(3) + UP(1)*BD(K)*UP(J)	BELTG
	B(1) = B(1)/YAY1	BELTG
	B(2) = B(2)/YAY1	BELTG
	B(3) = B(3)/YAY1	BELTG
C		BELTG
C	COMPUTE ANGLES FROM FIXED POINT TO POSSIBLE TANGENT POINTS.	BELTG
C		BELTG
	UCUVA = UC(1)*UVA(1) + UC(2)*UVA(2) + UC(3)*UVA(3)	BELTG
	UCUVB = UC(1)*UVB(1) + UC(2)*UVB(2) + UC(3)*UVB(3)	BELTG
	UCACA = UC(1)*ACA(1) + UC(2)*ACA(2) + UC(3)*ACA(3)	BELTG
	UCACB = UC(1)*ACB(1) + UC(2)*ACB(2) + UC(3)*ACB(3)	BELTG
	UPUVA = UP(1)*UVA(1) + UP(2)*UVA(2) + UP(3)*UVA(3)	BELTG
	UPUVB = UP(1)*UVB(1) + UP(2)*UVB(2) + UP(3)*UVB(3)	BELTG
	UPACA = UP(1)*ACA(1) + UP(2)*ACA(2) + UP(3)*ACA(3)	BELTG
	UPACB = UP(1)*ACB(1) + UP(2)*ACB(2) + UP(3)*ACB(3)	BELTG
	TH1 = DATAN2(UPUVA-UPACA,UCUVA-UCACA)	BELTG
	TH2 = DATAN2(UPUVA+UPACA,UCUVA+UCACA)	BELTG
	TH3 = DATAN2(UPUVB-UPACB,UCUVB-UCACB)	BELTG
	TH4 = DATAN2(UPUVB+UPACB,UCUVB+UCACB)	BELTG
	IF (TH1.LT.0.0) TH1 = TWOPI + TH1	BELTG
	IF (TH2.LT.0.0) TH2 = TWOPI + TH2	BELTG
	IF (TH3.LT.0.0) TH3 = TWOPI + TH3	BELTG
	IF (TH4.LT.0.0) TH4 = TWOPI + TH4	BELTG
C		BELTG
C	CHOOSE PROPER TANGENT POINTS AND BELT ARC LENGTHS.	BELTG
C		BELTG
	THMIN = DMIN1(TH1,TH2,TH3,TH4)	BELTG
	IF (THMIN.EQ.TH1.AND.DMIN1(TH2,TH3,TH4).NE.TH4) GO TO 61	BELTG
	IF (THMIN.EQ.TH2.AND.DMAX1(TH1,TH3,TH4).EQ.TH4) GO TO 61	BELTG
	IF (THMIN.EQ.TH3.AND.DMIN1(TH1,TH2,TH4).NE.TH2) GO TO 63	BELTG
	IF (THMIN.EQ.TH4.AND.DMAX1(TH1,TH2,TH3).EQ.TH2) GO TO 63	BELTG
	GO TO 70	BELTG
61	THA = TH1	BELTG
	THB = TWOPI-TH4	BELTG
	DO 62 K=1,3	BELTG
	APA(K) = UVA(K)-ACA(K)	BELTG
62	APB(K) = UVB(K)+ACB(K)	BELTG
	GO TO 65	BELTG
63	THA = TWOPI-TH2	BELTG
	THB = TH3	BELTG
	DO 64 K=1,3	BELTG
	APA(K) = UVA(K)+ACA(K)	BELTG
64	APB(K) = UVB(K)-ACB(K)	BELTG
65	CONTINUE	BELTG
	EPS1 = EPS(1)	BELTG
	DLGA = DABS(ELONG(B(1),B(2),B(3),EPS1,THA))	BELTG
	DLGB = DABS(ELONG(B(1),B(2),B(3),EPS1,THB))	BELTG
C		BELTG
C	CALCULATE BELT LENGTHS AND UNIT VECTORS	BELTG



	SUBROUTINE BELTRT(I,II,MM,M,NT)	BELTRT
C		REV IV 07/23/86TWOPI
C	THE ROUTINE CALLS SUBROUTINE BELTG TO COMPUTE THE TANGENT POINTS	BELTRT
C	AND BELT LENGTHS AND APPLIES THE RESTRAINT FORCES TO THE U1 ARRAY	BELTRT
C	AND BELT TORQUES TO THE U2 ARRAY FOR ELLIPSOID(II) ATTACHED TO	BELTRT
C	BODY SEGMENT (I) BY BELT (M) ATTACHED TO SEGMENT (MM).	BELTRT
C		BELTRT
	IMPLICIT REAL*8(A-H,O-Z)	BELTRT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	BELTRT
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	BELTRT
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	BELTRT
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)	EDGE
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	DIMENB
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),	NCFORC
	* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF	BELTRT
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	BELTRT
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
	COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),	TGMOD4
	* NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)	TTHKREF
C	NOTE: BELTRT AND BELTG SHARE FIRST PART OF TEMPVS	BELTRT
	COMMON/TEMPVS/ APA(3),UVA(3),DLGA,UAA,APB(3),UVB(3),DLGB,UBB	BELTRT
	DIMENSION TA(3),TB(3),ZA(3),ZB(3),TT(3),TTT(3),TA1(3),TB1(3)	TGMOD4
C		BELTRT
	CALL ELTIME(1,22)	BELTRT
C		BELTRT
C	CONVERT SEGMENT POSITION TO SEGMENT REFERENCE.	BELTRT
C		BELTRT
	MA = MOD(MM,100)	JTF984
	MB = MM/100	JTF984
	IF (MB.EQ.0) MB=MA	JTF984
	CALL DOT31 (D(1,1,MA),BELT(1,M),TA)	BELTRT
	CALL DOT31 (D(1,1,MB),BELT(4,M),TB)	BELTRT
	DO 10 K=1,3	BELTRT
	TA(K) = SEGLP(K,MA) + TA(K) - SEGLP(K,I)	BELTRT
10	TB(K) = SEGLP(K,MB) + TB(K) - SEGLP(K,I)	BELTRT
	CALL MAT31 (D(1,1,I),TA,ZA)	BELTRT
	CALL MAT31 (D(1,1,I),TB,ZB)	BELTRT
	DO 13 K=1,3	BELTRT
	ZA(K) = ZA(K) - BD(K+3,II)	BELTRT
13	ZB(K) = ZB(K) - BD(K+3,II)	BELTRT
C		BELTRT
C	COMPUTE NEW BELT LENGTHS AND EXPANSION.	BELTRT
C		BELTRT
	CALL BELTG (ZA, ZB, BELT(7,M), BD(1,II))	BELTRT
	TLA = DLGA+UAA	BELTRT
	TLB = DLGB+UBB	BELTRT
	TL = TLA+TLB	BELTRT
	IF (TIME.NE.0.0) GO TO 11	BELTRT
C		BELTRT

C	IF TIME=0, COMPUTE INITIAL BELT LENGTHS	BELTRT
C	AND STORE RESULTS IN BELT ARRAY.	BELTRT
C		BELTRT
	IF (BELT(11,M).LT.0.0) BELT(11,M) = -BELT(11,M)-TL	BELTRT
	IF (BELT(11,M).LT.0.0) BELT(11,M)=0.0	BELTRT
	BELT(12,M) = TLA+TLA/TL*BELT(11,M)	BELTRT
	BELT(13,M) = TLB+TLB/TL*BELT(11,M)	BELTRT
	B1213 = BELT(12,M) + BELT(13,M)	BELTRT
	BELT(10,M) = B1213	BELTRT
	DO 305 LL=1,3	TGMOD4
	TA1(LL) = APA(LL)	TGMOD4
305	TB1(LL) = APB(LL)	TGMOD4
	IF(LPMI(I).EQ.0) GO TO 306	TGMOD4
	CALL DOT31(DPMI(1,1,I),APA,TA1)	TGMOD4
	CALL DOT31(DPMI(1,1,I),APB,TB1)	TGMOD4
306	CONTINUE	TGMOD4
	WRITE (6,14) M, B1213, BELT(12,M), BELT(13,M), UNITL,I,TA1, TB1	TGMOD4
14	FORMAT('0 INITIAL LENGTHS OF BELT NO.',I3,' AND ITS SEGMENTS ARE',	BELTRT
	* 3F12.4,1X,A4/'0 INITIAL TANGENT POINTS IN LOCAL REFERENCE	TGMOD4
	*OF SEGMENT ',I2,' ARE:',/,2(3X,3F12.3))	TGMOD4
C		BELTRT
C	CONVERT TANGENT POINTS TO INERTIAL REFERENCE AND STORE.	BELTRT
C		BELTRT
11	CALL DOT31 (D(1,1,I),APA,TPTS(1,M))	BELTRT
	CALL DOT31 (D(1,1,I),APB,TPTS(4,M))	BELTRT
	DO 12 K=1,3	BELTRT
	TPTS(K ,M) = TPTS(K ,M) + SEGLP(K,I)	BELTRT
12	TPTS(K+3,M) = TPTS(K+3,M) + SEGLP(K,I)	BELTRT
	SDOT = 0.0	BELTRT
	NCF = NTAB(NT+5)	BELTRT
	IF (NCF.NE.0) GO TO 15	BELTRT
C		BELTRT
C	ZERO BELT FRICTION, COMPUTE STRAIN AND FORCE OF ENTIRE BELT.	BELTRT
C		BELTRT
	B1213 = BELT(12,M)+BELT(13,M)	BELTRT
	S = (TL-B1213)/B1213	BELTRT
	SA = S	BELTRT
	SB = S	BELTRT
	IF (S.LT.0.0) S = 0.0	BELTRT
	CALL FRCDFL (S,SDOT,NT,1,FA,ELOSS)	BELTRT
	FB = FA	BELTRT
	GO TO 17	BELTRT
C		BELTRT
C	FULL BELT FRICTION, COMPUTE STRAIN AND FORCE OF EACH PART OF BELT.	BELTRT
C		BELTRT
15	IF (TL.GT.BELT(10,M)) GO TO 16	BELTRT
	FA = 0.0	BELTRT
	FB = 0.0	BELTRT
	SA = (TL-BELT(10,M))/BELT(10,M)	BELTRT
	SB = SA	BELTRT

BELT(12,M) = TLA	BELTRT
BELT(13,M) = TLB	BELTRT
GO TO 17	BELTRT
16 S = (TLA-BELT(12,M))/BELT(12,M)	BELTRT
SA = S	BELTRT
IF (S.LT.0.0) S = 0.0	BELTRT
CALL FRCDFL (S,SDOT,NT,1,FA,ELOSS)	BELTRT
S = (TLB-BELT(13,M))/BELT(13,M)	BELTRT
SB = S	BELTRT
IF (S.LT.0.0) S = 0.0	BELTRT
CALL FRCDFL (S,SDOT,NT+6,1,FB,ELOSS)	BELTRT
BELT(10,M) = 0.0	BELTRT
17 BSF(1,NBSF) = SA	BELTRT
BSF(2,NBSF) = FA	BELTRT
BSF(3,NBSF) = SB	BELTRT
BSF(4,NBSF) = FB	BELTRT
IF (FA+FB.LE.0.0) GO TO 31	BELTRT
C	BELTRT
C COMPUTE FORCE VECTORS.	BELTRT
C	BELTRT
DO 20 K=1,3	BELTRT
UVA (K) = FA*UVA(K)	BELTRT
20 UVB(K) = FB*UVB(K)	BELTRT
C	BELTRT
C CONVERT FORCES TO INERTIAL REFERENCE AND ADD TO U1 ARRAY.	BELTRT
C	BELTRT
CALL DOT31(D(1,1,I),UVA,TT )	BELTRT
CALL DOT31(D(1,1,I),UVB,TTT)	BELTRT
DO 30 K=1,3	BELTRT
U1(K,MA) = U1(K,MA) - TT(K)	JTF984
U1(K,MB) = U1(K,MB) - TTT(K)	JTF984
30 U1(K,I) = U1(K,I)+TTT(K) + TT(K)	JTF984
C	BELTRT
C CONVERT TORQUES TO LOCAL REFERENCE AND ADD TO U2 ARRAY.	BELTRT
C	BELTRT
CALL MAT31(D(1,1,MA),TT,ZA)	JTF984
CALL MAT31(D(1,1,MB),TTT,ZB)	JTF984
CALL CROSS(BELT(1,M),ZA,TA)	JTF984
CALL CROSS(BELT(4,M),ZB,TB)	JTF984
CALL CROSS(APA,UVA,TT)	BELTRT
CALL CROSS(APB,UVB,TTT)	BELTRT
DO 40 K=1,3	BELTRT
U2(K,MA) = U2(K,MA) - TA(K)	JTF984
U2(K,MB) = U2(K,MB) - TB(K)	JTF984
40 U2(K,I) = U2(K,I)+(TT(K)+TTT(K))	BELTRT
31 CONTINUE	BELTRT
CALL ELTIME(2,22)	BELTRT
RETURN	BELTRT
END	BELTRT



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SUBROUTINE BGG(A,ZA,DA,BFA,VA,WA,          BGG
*      B,ZB,DB,BFB,VB,WB,                BGG
*      VSCS,IFULL,TV,FRA,TORQ,TQB,VOL)     BGG

C
C                                     REV IV 07/23/86TWOPI
C      COMPUTES THE VOLUME OF INTERSECTION OF AN ELLIPSOIDAL AIRBAG BGG
C      WITH AN ELLIPSOIDAL BODY SEGMENT OR REACTION PANEL. BGG
C      ALSO COMPUTES THE FORCE PER UNIT PRESSURE AND TORQUE PER UNIT BGG
C      PRESSURE ON BOTH THE BAG AND THE INTERSECTING OBJECT. BGG
C
C      ARGUMENTS: BGG
C      AIRBAG INPUTS : A(3,3) - ELLIPSOID MATRIX BGG
C                      ZA(3) - C.G. BGG
C                      DA(3,3) - DIRECTION COSINE MATRIX BGG
C                      BFA(3) - OFFSET BGG
C                      VA(3) - CG VELOCITY(INERTIAL REF.) BGG
C                      WA(3) - ANGULAR VELOCITY (LOCAL REF.) BGG
C
C      CONTACT SURFACE B(3,3) - ELLIPSOID MATRIX BGG
C                      ZB(3) - C.G. BGG
C                      DB(3,3) - DIRECTION COSINE MATRIX BGG
C                      BFB(3) - OFFSET BGG
C                      VB(3) - CG VELOCITY (INERTIAL REF.) BGG
C                      WB(3) - ANGULAR VELOCITY (LOCAL REF.) BGG
C                      VSCS - COEFFICIENT OF SLIDING FRICTION BGG
C                      IFULL - IF ZERO, COMPUTE VOL ONLY. BGG
C                      TV(3) - MEMORY FOR SUBROUTINES INTERS & EDEPTH. BGG
C
C      OUTPUT : FRA(3) - FORCE ON BAG BGG
C               TORQ(3) - TORQUE ON BAG BGG
C               TOB(3) - TORQUE ON CONTACT SURFACE BGG
C               VOL - VOLUME OF INTERSECTION BGG
C
C      IMPLICIT REAL*8 (A-H,O-Z) BGG
C      DIMENSION A(3,3),ZA(3),DA(3,3),BFA(3),VA(3),WA(3),B(3,3),ZB(3), BGG
C      *      DB(3,3),BFB(3),VB(3),WB(3),FRA(3),TORQ(3),TQB(3),TV(3) BGG
C      COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24), BGG
C      *      UNITL,UNITM,UNITT,GRAVITY(3),TWOPI TWOPI
C      COMMON/TEMPVS/ DUMMY(200),DAB(3,3),BA(3,4),TEMP(3,3),Y(3),CPA(3), BGG
C      *      CPB(3),PLANE(4,3),FORCE(3),CBB(3),VLM(3),FRB(3), BGG
C      *      YFA(3),YFB(3),ZBB(3),T1(3),T2(3),T3(3),T4(3),T5(3),T6(3) BGG
C      NOTE: DUMMY IS USED BY SUBROUTINES AIRBAG AND AIRBGG. BGG
C
C      INITIALIZATION BGG
C
C      S3TEST = 10.0 BGG
C      VOL=0. BGG
C      DO 5 I=1,3 BGG
C      FRA(I) = 0.0 BGG
C      TORQ(I) = 0.0 BGG
C      TQB (I) = 0.0 BGG
C      BA(I,4)=-BFA(I) BGG

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	DO 5 J=1,3	BGG
	BA(I,4)=BA(I,4)+DA(I,J)*(ZB(J)-ZA(J))	BGG
	DAB(I,J)=0.	BGG
	DO 5 K=1,3	BGG
	5 DAB(I,J)=DAB(I,J)+DA(I,K)*DB(J,K)	BGG
C		BGG
C	COMPUTE DISTANCE BETWEEN ELLIPSOID CENTERS AND	BGG
C	CONVERT ELLIPSOID MATRIX OF OBJECT TO AIRBAG REFERENCE.	BGG
C		BGG
	DO 10 I=1,3	BGG
	DO 10 J=1,3	BGG
	TEMP(I,J) = 0.0	BGG
	BA(I,4)=BA(I,4)+DAB(I,J)*BFB(J)	BGG
	DO 10 K=1,3	BGG
	10 TEMP(I,J) = TEMP(I,J) + B(I,K)*DAB(J,K)	BGG
	CALL MAT33(DAB,TEMP,BA)	BGG
C		BGG
C	CHECK FOR INTERSECTION AND DETERMINE POINTS OF MAXIMUM PENETRATION	BGG
C		BGG
	TB = 1.0	BGG
	CALL INTERS (A,BA,BA(1,4),TB,Y,TV(1),T1)	BGG
	IF (TB.GT.1.0) RETURN	BGG
	CALL EDEPTH (A,BA,BA(1,4),TB,Y,CPA,CPB,TV(2),TV(3))	BGG
C		BGG
C	SET UP ORTHOGONAL SYSTEM USING VECTOR BETWEEN POINTS	BGG
C	OF MAXIMUM PENETRATION AS ONE AXIS.	BGG
C		BGG
	P = 0.	BGG
	DO 20 I=1,3	BGG
	PLANE(I,3) = CPA(I)-CPB(I)	BGG
	20 P = PLANE(I,3)**2+P	BGG
	IF (P.LT.EPS(6)) GO TO 99	BGG
	PP = DSQRT(P)	BGG
	DO 25 I=1,3	BGG
	25 TEMP(I,1) = PLANE(I,3)/PP	BGG
	CALL ORTHO(PLANE,TEMP,4)	BGG
C		BGG
C	DEFINE PLANES AT MAXIMUM PENETRATION POINTS.	BGG
C		BGG
	DO 40 I=1,3	BGG
	PLANE(4,I) = 0.0	BGG
	DO 40 J=1,3	BGG
	40 PLANE(4,I) = PLANE(4,I)+PLANE(J,I)*CPB(J)	BGG
	DO 45 K=1,3	BGG
	45 CBB(K)=CPB(K)-BA(K,4)	BGG
C		BGG
C	ESTIMATES OF VOLUME AND AREA BASED ON RADII OF CURVATURE	BGG
C	AND PENETRATION.	BGG
C		BGG
	IP=2	BGG

AREA=PI	BGG
DO 70 L=1,2	BGG
RA=RCRT(A,PLANE,CPA,L)	BGG
RB=RCRT(BA,PLANE,CBB,L)	BGG
IF (PP.GT.RA) RA=PP	BGG
R=(RA-RB)*.5	BGG
RC=(RA+RB)*.5	BGG
VP=PP/(RA+RB)	BGG
VD=VP	BGG
ALP=RC*DSQRT(VP*(2.-VP))	BGG
IF (R.GE.0.) GO TO 60	BGG
AB=RA+RB-PP	BGG
BET=(RA**2-RB**2+AB**2)*.5/AB	BGG
ALP=DSQRT(RA**2-BET**2)	BGG
R=0.	BGG
VD=1.-BET/RA	BGG
VP=(PP+BET-RA)/RB	BGG
60 VLM(L)=RB*(RB*VP)**2*(1.-VP/3.)+RA*(RA*VD)**2*(1.-VD/3.)	BGG
IF (R.GT.0.) VLM(L)=VLM(L)-ALP*R*R*(PI-2.*(DASIN(1.-VP)+	BGG
* (1.-VP)*ALP/RC))	BGG
VLM(L)=VLM(L)*PI	BGG
AREA=AREA*ALP	BGG
70 IP=1	BGG
VOL=(VLM(1)+VLM(2))*5	BGG
IF (IFULL.EQ.0) GO TO 99	BGG
C	BGG
C	BGG
C	BGG
SET UP FORCE VECTOR ALONG LINE OF MAXIMUM PENETRATION.	BGG
CALL DOT31(DAB,CBB,ZBB)	BGG
DO 76 K=1,3	BGG
YFA(K)=CPB(K)+BFA(K)	BGG
YFB(K)=ZBB(K)+BFB(K)	BGG
FORCE(K) = -AREA*PLANE(K,3)	BGG
76 T1(K) = VA(K)-VB(K)	BGG
C	BGG
C	BGG
C	BGG
C	BGG
COMPUTE ANGULAR VELOCITY COMPONENTS,RELATIVE VELOCITY, COMPONENTS	BGG
OF RELATIVE VELOCITY ALONG MAX PENETRATION LINE AND MAGNITUDE OF	BGG
FORCE.	BGG
CALL MAT31(DA,T1,T2)	BGG
CALL CROSS(WA,YFA,T1)	BGG
CALL CROSS(WB,YFB,T3)	BGG
CALL MAT31(DAB,T3,T4)	BGG
FM = 0.0	BGG
SUM = 0.0	BGG
DO 77 K=1,3	BGG
T5(K) = T2(K)+T1(K)-T4(K)	BGG
SUM = SUM+T5(K)*PLANE(K,3)	BGG
77 FM = FM+FORCE(K)**2	BGG
C	BGG

C	COMPUTE COMPONENTS OF RELATIVE VELOCITY IN TANGENT PLANE,	BGG
C	FRICTION FORCE AND TOTAL FORCE VECTOR.	BGG
C		BGG
	S3 = 0.0	BGG
	DO 78 K=1,3	BGG
	T6(K) = T5(K)-SUM*PLANE(K,3)	BGG
78	S3 = S3+T6(K)**2	BGG
	SQ3 = DSQRT(S3)	BGG
	IF (SQ3.LT.S3TEST) SQ3=S3TEST/(2.0-SQ3/S3TEST)	BGG
	FF = VSCS*DSQRT(FM)/SQ3	BGG
	DO 79 K=1,3	BGG
79	FORCE(K) = FORCE(K)-FF*T6(K)	BGG
C		BGG
C	COMPUTE FRB: FORCE ON REACTION SURFACE IN ITS LOCAL REFERENCE.	BGG
C	TORQ: TORQUE ON AIRBAG IN AIRBAG REFERENCE.	BGG
C	TQB: TORQUE ON REACTION SURFACE IN ITS LOCAL REFERENCE.	BGG
C	FRA: FORCE ON AIRBAG IN INERTIAL REFERENCE.	BGG
C		BGG
	CALL DOT31(DAB,FORCE,FRB)	BGG
	CALL CROSS(YFA,FORCE,TORQ)	BGG
	CALL CROSS(FRB,YFB,TQB)	BGG
	CALL DOT31(DA,FORCE,FRA)	BGG
99	RETURN	BGG
	END	BGG

	SUBROUTINE BINPUT		BINPUT
C		REV IV 07/24/86	SLIP
C	READS THE INPUT CARDS THAT CONTAINS THE PHYSICAL DIMENSIONS AND		BINPUT
C	CHARACTERISTICS OF THE CRASH VICTIM'S BODY SEGMENTS AND JOINTS.		BINPUT
C			BINPUT
	IMPLICIT REAL*8(A-H,O-Z)		BINPUT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		BINPUT
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		BINPUT
	* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		BINPUT
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)		EDGE
	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),		BINPUT
	* BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30),		BINPUT
	* JOINT(30),CGS(30),JS(30)		BINPUT
	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT		BINPUT
	LOGICAL*1 CGS,JS		BINPUT
	COMMON/INTEST/ SGTEST(3,4,30),XTEST(3,120),SEGT(120),REGT(120)		BINPUT
	REAL SEGT		BINPUT
	COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)		BINPUT
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),		JDRIFT
	* FE(3,30),TQE(3,30),CONST(5,30)		JDRIFT
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		BINPUT
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	COMMON/RSAGE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),		ATBIII
	* NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)		TTHKREF
	LOGICAL*1 EULER,SLIP		SLIP
	COMMON/TEMPVS/ YPR1(3,30),YPR2(3,30),YPR3(3,30),YPRPMI(3,30),		BINPUT
	* T1(6),TMP1(3,3),TMP2(3,3),KNT(30),IDYPR(6,30),		SLIP
	* EULER(30)		SLIP
	DATA MXNSEG/30/,MXNJNT/30/,MNFLX/8/		MISC
	CALL ELTIME(1, 2)		BINPUT
	IDYPRT = 0		TGMOD5
C			BINPUT
C	INPUT CARD B.1		BINPUT
C			BINPUT
	READ (5,11) NSEG,NJNT,BDYTTL		BINPUT
11	FORMAT (2I6,8X,5A4)		BINPUT
	IF (NSEG.GT.MXNSEG) STOP 77		MISC
	IF (NJNT.GT.MXNJNT) STOP 78		MISC
C			BINPUT
C	INPUT CARDS B.2.I FOR EACH SEGMENT.		BINPUT
C			BINPUT
	DO 12 I=1,NSEG		BINPUT
	READ (5,13) SEG(I),CGS(I),W(I),(PHI(J,I),J=1,3),		BINPUT
	* (BD(J,I),J=1,6),LPMI(I)		BINPUT
13	FORMAT(A4,1X,A1,10F6.0,I4)		BINPUT
	DO 81 J=1,3		BINPUT
	IDYPR(J,I) = 4-J		BINPUT
81	YPRPMI(J,I) = 0.0		BINPUT

	IF (LPMI(I).EQ.0) GO TO 12	BINPUT
	READ (5,82) (YPRPMI(J,I),J=1,3)	BINPUT
	82 FORMAT(12X,3F6.0)	BINPUT
	12 CALL DRCYPR (DPMI(1,1,I),YPRPMI(1,I),IDYPR(1,I))	BINPUT
C		BINPUT
C	INPUT CARDS B.3.J FOR EACH JOINT.	BINPUT
C		BINPUT
	NFLX = 0	BINPUT
	IF (NJNT.EQ.0) GO TO 27	BINPUT
	SLIP = .FALSE.	SLIP
	DO 14 J=1,NJNT	BINPUT
	READ (5,15) JOINT(J),JS(J),JNT(J),IPIN(J),(SR(I,2*J-1),I=1,3),	BINPUT
	* (SR(I,2*J),I=1,3),IEULER(J),CONST(1,J),CONST(2,J),	SLIP
	* (YPR1(I,J),I=1,3),(YPR2(I,J),I=1,3),	SLIP
	* (YPR3(I,J),I=1,3),(IDYPR(I,J),I=1,6)	BINPUT
	ID1 = IDYPR(1,J)	BINPUT
	ID4 = IDYPR(4,J)	BINPUT
	EULER(J) = .FALSE.	SLIP
	IF (IPIN(J).EQ.4) EULER(J) = .TRUE.	SLIP
	IF (IEULER(J).EQ.0.AND.IPIN(J).LE.-4) EULER(J) = .TRUE.	SLIP
	IF (.NOT.EULER(J).AND.IABS(IPIN(J)).GE.5) SLIP = .TRUE.	SLIP
	IF(ID1.NE.0.OR.ID4.NE.0) IDYPRT = 1	TGMOD5
	DO 479 II=1,6	TGMOD5
	479 IF(IABS(IDYPR(II,J)).GT.3) STOP 101	TGMOD5
	DO 14 I=1,3	BINPUT
	IF (ID1.EQ.0) IDYPR(I,J) = 4-I	BINPUT
	14 IF (ID4.EQ.0) IDYPR(I+3,J) = 4-I	BINPUT
	15 FORMAT(A4,1X,A1,2I4,6F6.0,I4,2F6.0/14X,9F6.0,6I2)	SLIP
C		BINPUT
C	COMPUTE NFLX AND NFLEX ARRAY FROM NEGATIVE VALUES OF JNT(J).	BINPUT
C	NFLX WILL BE NUMBER OF CONSTRAINT TORQUES FOR FLEXIBLE SEGMENTS.	BINPUT
C	NFLEX(1, ) REFERENCE SEGMENT (LOWEST NUMBERED SEGMENT OF CHAIN)	BINPUT
C	NFLEX(2, ) INTERIOR SEGMENT NUMBERS	BINPUT
C	NFLEX(3, ) TERMINATING SEGMENT (HIGHEST NUMBERED SEGMENT IN CHAIN)	BINPUT
C	VALUES OF NFLEX NEED NOT BE SEQUENTIAL BUT MUST BE ORDERED.	BINPUT
C	FLEXIBLE SEGMENT MUST BE SIMPLE CHAIN, I.E., BRANCHING SEGMENTS	BINPUT
C	CANNOT BE ATTACHED TO INTERIOR SEGMENTS BUT MAY BE ATTACHED TO	BINPUT
C	REFERENCE OR TERMINATING SEGMENTS.	BINPUT
C		BINPUT
	DO 16 J=1,NJNT	BINPUT
	16 KNT(J) = JNT(J)	BINPUT
	DO 22 J=1,NJNT	BINPUT
	IF (KNT(J).GE.0) GO TO 22	BINPUT
	NFA = NFLX+1	BINPUT
	IT = J+1	BINPUT
	IF (IT.GT.NJNT) GO TO 18	BINPUT
	JPl = J+1	BINPUT
	DO 17 L=JPl,NJNT	BINPUT
	IF (IABS(KNT(L)).NE.IT) GO TO 17	BINPUT
	KL = KNT(L)	BINPUT

KNT(L) = 0	BINPUT
IF (KL.GT.0) GO TO 18	BINPUT
NFLX = NFLX+1	BINPUT
NFLEX(1,NFLX) = IAPS(KNT(J))	BINPUT
NFLEX(2,NFLX) = IT	BINPUT
IT = L+1	BINPUT
17 CONTINUE	BINPUT
18 IF (NFLX.GE.NFA) GO TO 20	BINPUT
WRITE (6,19)	BINPUT
19 FORMAT('OERROR IN DEFINING FLEXIBLE SEGMENTS, ONLY ONE NEGATIVE JNB	BINPUT
*T IN STRING. PROGRAM TERMINATED.')	BINPUT
STOP 3	BINPUT
20 DO 21 K=NFA,NFLX	BINPUT
21 NFLEX(3,K) = IT	BINPUT
22 CONTINUE	BINPUT
C	BINPUT
C INPUT CARDS B.4.J FOR EACH JOINT.	BINPUT
C	BINPUT
DO 23 J=1,NJNT	BINPUT
READ (5,24) (SPRING(I,3*J-2),I=1,5),(SPRING(I,3*J-1),I=1,5)	BINPUT
23 IF (EULER(J)) READ(5,24) (SPRING(I,3*J),I=1,5),(ANG(I,J),I=1,3)	SLIP
24 FORMAT(2(4F6.0,F12.0))	BINPUT
C	BINPUT
C INPUT CARDS B.5.J FOR EACH JOINT.	BINPUT
C	BINPUT
DO 25 J=1,NJNT	BINPUT
READ (5,26) (VISC(I,3*J-2),I=1,7)	BINPUT
IF (.NOT.EULER(J)) GO TO 25	SLIP
READ (5,26) (VISC(I,3*J-1),I=1,7)	BINPUT
READ (5,26) (VISC(I,3*J),I=1,7)	BINPUT
25 CONTINUE	BINPUT
26 FORMAT(5F6.0,18X,2F6.0)	BINPUT
C	BINPUT
C INPUT CARDS B.6.I FOR EACH SEGMENT.	BINPUT
C	BINPUT
27 DO 28 I=1,NSEG	BINPUT
29 READ (5,29) ((SGTEST(J,K,I),J=1,3),K=1,4)	BINPUT
29 FORMAT(12F6.0)	BINPUT
C	BINPUT
C PRINT CARD B.1	BINPUT
C	BINPUT
WRITE (6,30) BDYTTL,NSEG,NJNT,NPG,UNITM,UNITT,UNITL,UNITL,	PAGE
* UNITL,UNITM	PAGE
NPG=NPG+1	PAGE
30 FORMAT('1 CRASH VICTIM',5X,5A4,I5,' SEGMENTS',I5,' JOINTS',58X,	PAGE
* 'PAGE',I5/120X,'CARD B.1'/25X,'PRINCIPAL MOMENTS OF INERTIA',	PAGE
* 14X,'SEGMENT CONTACT ELLIPSOID',28X,'CARDS B.2'/'	BINPUT
* 3X,'SEGMENT',6X,'WEIGHT',7X,'(',A4,'-',A4,'**2-',A4,')',	BINPUT
* 11X,'SEMIAXES (' ,A4,')',12X,'CENTER (' ,A4,')',	BINPUT
* 11X,'PRINCIPAL AXES (DEG)'/	BINPUT

	*        ' I SYM PLOT (' ,A4,')' ,7X,'X',8X,'Y',8X,'Z' ,	BINPUT
	*        2(9X,'X',7X,'Y',7X,'Z') ,8X,'YAW',5X,'PITCH',5X,'ROLL' /)	BINPUT
C		BINPUT
C	PRINT CARDS B.2.I FOR EACH SEGMENT.	BINPUT
C		BINPUT
	DO 31 I=1,NSEG	BINPUT
	31 WRITE (6,32) I,SEG(I),CGS(I),W(I), (PHI(J,I),J=1,3),	BINPUT
	*        (BD(J,I),J=1,6), (YPRPMI(J,I),J=1,3)	BINPUT
	32 FORMAT(I3,1X,A4,2X,A1,F11.3,2X,3F9.4,2(2X,3F8.3),1X,3F9.2)	BINPUT
	IF (NJNT.EQ.0) GO TO 50	BUTLER1
C		BINPUT
C	PRINT CARDS B.3.J FOR EACH JOINT.	BINPUT
C		BINPUT
	IF(IDYPRT.EQ.0) WRITE(6,33) UNITL,UNITL	TGMOD5
	IF(IDYPRT.EQ.1) WRITE(6,733) UNITL,UNITL	TGMOD5
	33 FORMAT(///120X,'CARDS B.3' /	BINPUT
	* 3X,'JOINT',15X,'LOCATION(' ,A4,') - SEG(JNT)' ,	BINPUT
	*        3X,'LOCATION(' ,A4,') - SEG(J+1)' ,	BINPUT
	*        2X, 'PRIN. AXIS(DEG) - SEG(JNT)' ,	BINPUT
	*        2X, 'PRIN. AXIS(DEG) - SEG(J+1)' /	BINPUT
	* ' J SYM PLOT JNT PIN' , 2(6X,'X',8X,'Y',8X,'Z',3X),	BINPUT
	*        2(5X,'YAW',5X,'PITCH',5X,'ROLL',1X) /)	BINPUT
	733 FORMAT(///120X,'CARDS B.3' /	TGMOD5
	* 3X,'JOINT',15X,'LOCATION(' ,A4,') - SEG(JNT)' ,	TGMOD5
	*        3X,'LOCATION(' ,A4,') - SEG(J+1)' ,	TGMOD5
	*        2X, 'PRIN. AXIS(DEG) - SEG(JNT)' ,	TGMOD5
	*        2X, 'PRIN. AXIS(DEG) - SEG(J+1)' /	TGMOD5
	* ' J SYM PLOT JNT PIN' , 2(6X,'X',8X,'Y',8X,'Z',3X),	TGMOD5
	*        'ID1 YAW ID2 PITCH ID3 ROLL ' ,	TGMOD5
	*        'ID4 YAW ID5 PITCH ID6 ROLL ' ,/)	TGMOD5
	DO 34 J=1,NJNT	BINPUT
	IF(IDYPRT.EQ.0)	TGMOD5
	*WRITE (6,35) J,JOINT(J),JS(J),JNT(J),IPIN(J), (SR(I,2*J-1),I=1,3),	TGMOD5
	*        (SR(I,2*J),I=1,3), (YPR1(I,J),I=1,3), (YPR2(I,J),I=1,3)	BINPUT
	IF(IDYPRT.EQ.1)	TGMOD5
	*WRITE(6,735) J,JOINT(J),JS(J),JNT(J),IPIN(J), (SR(I,2*J-1),I=1,3),	TGMOD5
	*        (SR(I,2*J),I=1,3), (IDYPR(I,J),YPR1(I,J),I=1,3),	TGMOD5
	*        (IDYPR(I+3,J),YPR2(I,J),I=1,3)	TGMOD5
	IF (.NOT.EULER(J)) GO TO 34	SLIP
	IEULER(J) = 8	BINPUT
	IF (IPIN(J).EQ.4) GO TO 34	BINPUT
	IEULER(J) = 11 + IPIN(J)	BINPUT
	IPIN(J) = -4	BINPUT
	34 CONTINUE	BINPUT
	35 FORMAT(I3,1X,A4,2X,A1,2X,2I3,2(1X,3F9.3),2(1X,3F9.2) )	BINPUT
	735 FORMAT(I3,1X,A4,2X,A1,2X,2I3,2(1X,3F9.3),2(1X,3(1X,I1,F7.2)))	TGMOD5
	IF (.NOT.SLIP) GO TO 89	SLIP
	WRITE (6,83) UNITM,UNITM	SLIP
	83 FORMAT(// ' UNLOCK CONDITIONS FOR SLIP JOINTS' /	SLIP
	*        ' JOINT TENSION COMPRESSION' /	SLIP



	* 14X,(' ,A4,')',7X,(' ,A4,')')/)	SLIP
	DO 85 J = 1,NJNT	SLIP
	IF (EULER(J)) GO TO 85	SLIP
	IF (IABS(IPIN(J)).LT.5) GO TO 85	SLIP
	WRITE (6,84) J,CONST(1,J),CONST(2,J)	SLIP
	84 FORMAT(1X,I6,4X,F10.3,3X,F10.3)	SLIP
	85 CONTINUE	SLIP
C		BINPUT
C	SET UP HT MATRIX FROM YPR1 & YPR2 INPUT.	BINPUT
C	HA IS 3RD COLUMN & HB IS 2ND COLUMN OF HT.	BINPUT
C	FOR A SLIP JOINT(IPIN=7),HB IS 3RD COLUMN OF HT.	SLIP
C		BINPUT
89	IF (NPRT(23).NE.0) WRITE (6,36) NPG	SLIP
	IF (NPRT(23).NE.0) NPG=NPG+1	PAGE
36	FORMAT('1 HT ARRAY AS COMPUTED FROM YPR1 & YPR2 INPUT.',77X,	PAGE
	* 'PAGE',I5)	PAGE
	DO 38 J=1,NJNT	BINPUT
	SR(4,2*J-1) = 0.0	SLIP
	SR(4,2*J ) = 0.0	SLIP
	CALL DRCYPR (TMP1,YPR1(1,J),IDYPR(1,J))	BINPUT
	CALL DRCYPR (TMP2,YPR2(1,J),IDYPR(4,J))	BINPUT
	DO 37 I=1,3	BINPUT
	ANGD(I,J) = 0.0	BINPUT
	HA(I,2*J-1) = 0.0	BINPUT
	HA(I,2*J ) = 0.0	BINPUT
	K = 2	SLIP
	IF (IABS(IPIN(J)).EQ.7) K = 3	SLIP
	HB(I,2*J-1) = TMP1(K,I)	SLIP
	HB(I,2*J ) = TMP2(K,I)	SLIP
	DO 77 K=1,3	SLIP
	HT(I,K,2*J-1) = TMP1(K,I)	SLIP
77	HT(I,K,2*J ) = TMP2(K,I)	SLIP
	IF (.NOT.EULER(J)) GO TO 37	SLIP
	CONST(I,J) = YPR3(I,J)*RADIAN	SLIP
	ANG(I,J) = ANG(I,J)*RADIAN - CONST(I,J)	SLIP
	37 CONTINUE	SLIP
38	IF (NPRT(23).NE.0) WRITE (6,39) J,JOINT(J),	BINPUT
	* ((HT(I,K,2*J-1),K=1,3),(HT(I,K,2*J),K=1,3),I=1,3)	BINPUT
39	FORMAT('0',I4,2X,A4,3X,3F12.6,3X,3F12.6/(14X,3F12.6,3X,3F12.6))	BINPUT
C		BINPUT
C	PRINT CARDS B.4.J FOR EACH JOINT.	BINPUT
C		BINPUT
	WRITE (6,41) NPG,UNITL,UNITM,UNITL,UNITM	PAGE
	NPG=NPG+1	PAGE
41	FORMAT('1 JOINT TORQUE CHARACTERISTICS',93X,	PAGE
	* 'PAGE',I5/120X,'CARDS B.4'/	PAGE
	*23X,'FLEXURAL SPRING CHARACTERISTICS',28X,'TORSIONAL SPRING' ,	BINPUT
	* ' CHARACTERISTICS'//	BINPUT
	*15X,'SPRING COEF. (' ,2A4,'/DEG**J)',6X,'ENERGY JOINT',	BINPUT
	* 7X,'SPRING COEF. (' ,2A4,'/DEG**J)',6X,'ENERGY JOINT'/' JBINPUT	

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*OINT ',2(8X,'LINEAR    QUADRATIC    CUBIC    DISSIPATION STOP ')BINPUT
*/8X,2(8X,'(J=1)',7X,'(J=2)',7X,'(J=3)',7X,'COEF.    (DEG)')/)    BINPUT
DO 42 J=1,NJNT    BINPUT
J1 = 3*J-2    BINPUT
J2 = 3*J-1    BINPUT
J3 = 3*J    BINPUT
WRITE (6,43) J,JOINT(J),((SPRING(I,JJ),I=1,5),JJ=J1,J2)    BINPUT
42 IF (EULER(J)) WRITE (6,44) (SPRING(I,J3),I=1,5)    SLIP
43 FORMAT(I3,1X,A4,2(3X,3F12.3,2F10.3))    BINPUT
44 FORMAT(11X,3F12.3,2F10.3)    BINPUT
C    BINPUT
C    PRINT CARDS B.5.J  FOR EACH JOINT.    BINPUT
C    BINPUT
WRITE (6,46) (UNITL,UNITM,UNITT,I=1,2),(UNITL,UNITM,I=1,2),UNITT    BINPUT
46 FORMAT(///120X,'CARDS B.5'/    BINPUT
*38X,'JOINT VISCOUS CHARACTERISTICS AND LOCK-UNLOCK CONDITIONS'//    BINPUT
*14X,'VISCOUS',9X,'COULOMB',7X,'FULL FRICTION',5X,'MAX TORQUE FOR',    BINPUT
*4X,'MIN TORQUE FOR',4X,'MIN. ANG. VELOCITY',6X,'IMPULSE'/    BINPUT
*2X,'JOINT',5X,'COEFFICIENT',4X,'FRICTION COEF. ANGULAR VELOCITY',    BINPUT
*4X,'A LOCKED JOINT',4X,'UNLOCKED JOINT',4X,'FOR UNLOCKED JOINT',    BINPUT
*4X,'RESTITUTION'/    BINPUT
*8X,'('',3A4,'/DEG) ('',2A4,'')',6X,'(DEG/'',A4,'')',10X,'('',2A4,'')',    BINPUT
*8X,'('',2A4,'')',10X,'(RAD/'',A4,'')',8X,'COEFFICIENT'/)    BINPUT
DO 47 J=1,NJNT    BINPUT
J1 = 3*J-2    BINPUT
J2 = 3*J-1    BINPUT
J3 = 3*J    BINPUT
WRITE (6,48) J,JOINT(J),(VISC(I,J1),I=1,7)    BINPUT
47 IF (EULER(J)) WRITE (6,49) ((VISC(I,JJ),I=1,7),JJ=J2,J3)    SLIP
48 FORMAT(I3,1X,A4,F13.3,2F15.2,F22.2,F18.2,F20.2,F17.3)    BINPUT
49 FORMAT(      8X,F13.3,2F15.2,F22.2,F18.2,F20.2,F17.3)    BINPUT
C    BINPUT
C    PRINT CARDS B.6.I  FOR EACH SEGMENT.    BINPUT
C    BINPUT
50 WRITE (6,51) NPG,(UNITT,UNITL,UNITT,I=1,2)    PAGE
NPG=NPG+1    PAGE
51 FORMAT('1',122X,'PAGE',I5/20X,    PAGE
* 'SEGMENT INTEGRATION CONVERGENCE TEST INPUT',58X,'CARDS B.6'//PAGE
* 17X,'ANGULAR VELOCITIES', 11X,'LINEAR VELOCITIES',    BINPUT
* 10X,'ANGULAR ACCELERATIONS',9X,'LINEAR ACCELERATIONS'/    BINPUT
* 21X,'(RAD/'',A4,'')', 18X,'('',A4,'/'',A4,'')',    BINPUT
* 17X,'(RAD/'',A4,'**2)', 16X,'('',A4,'/'',A4,'**2)'/    BINPUT
* 'SEGMENT', 4('MAG. ABS. REL.') /    BINPUT
* 'NO. SYM', 4('TEST ERROR ERROR') /)    BINPUT
DO 52 I=1,NSEG    BINPUT
52 WRITE (6,53) I,SEG(I),((SGTEST(J,K,I),J=1,3),K=1,4)    BINPUT
53 FORMAT(I3,1X,A4,4(F11.3,F9.3,F9.4) )    BINPUT
IF (NFLX.EQ.0) GO TO 62    BINPUT
C    BINPUT
C    INPUT AND PRINT CARDS B.7    BINPUT

```

C	CARD B.7.A	NFX: NO. OF INTERIOR SEGMENTS OF FLEXIBLE ELEMENTS.	BINPUT
C		KNT(J),J=1,NFX: THE SEGMENT NUMBERS.	BINPUT
C			BINPUT
	READ (5,54)	NFX,(KNT(J),J=1,NFX)	BINPUT
54	FORMAT(18I4)		BINPUT
	IF (NFX.NE.NFLX)	WRITE (6,55) NFX,NFLX	BINPUT
55	FORMAT('OINPUT ERROR ON CARD B.7.A, NFX =',I4, ' BUT NFLX =',I4,		BINPUT
	* ' AS COMPUTED FROM CARDS B.3. PROGRAM TERMINATED.')		BINPUT
	IF (NFX.NE.NFLX)	STOP 4	BINPUT
	WRITE (6,56)	NPG	PAGE
	NPG=NPG+1		PAGE
56	FORMAT('1',122X,'PAGE',I5/121X,'CARDS B.7')		PAGE
	DO 60 JJ=1,NFX		BINPUT
	DO 57 K=1,NFLX		BINPUT
	IF (KNT(JJ).EQ.NFLEX(2,K))	GO TO 59	BINPUT
57	CONTINUE		BINPUT
	WRITE (6,58)	KNT(JJ)	BINPUT
58	FORMAT('OINPUT ERROR ON CARD B.7.J, SEGMENT NO.',I4, ' IS NOT AN		BINPUT
	*TERIOR SEGMENT OF A FLEXIBLE ELEMENT FROM DATA ON CARDS B.3.')		BINPUT
	* ' PROGRAM TERMINATED.')		BINPUT
	STOP 5		BINPUT
59	IF(NFLX.GT.MNFLX)	STOP 99	TGMOD5
C			BINPUT
C	CARDS B.7.J	HF ARRAY FOR SEGMENT KNT(JJ)	BINPUT
C			BINPUT
	READ (5,29)	((HF(I,J,K),J=1,12),I=1,4)	TGMOD5
	DO 737 LL=1,3		TGMOD5
	L = (LL-1)*4		TGMOD5
	DO 737 I=1,4		TGMOD5
	DO 737 J=1,4		TGMOD5
737	IF(HF(I,J+L,K).NE.HF(J,I+L,K))	STOP 100	TGMOD5
60	WRITE (6,61)	KNT(JJ),K,(NFLEX(I,K),I=1,3),	BINPUT
	* ((HF(I,J,K),J=1,12),I=1,4)		BINPUT
61	FORMAT('O HF ARRAY FOR INTERIOR SEGMENT NO.',I4,20X,		BINPUT
	* '(NFLEX(I,',I1,')',I=1,3) =',3I6//		BINPUT
	* (3X,4F10.4,3X,4F10.4,3X,4F10.4) )		BINPUT
62	IF (NJNT.EQ.0)	GO TO 65	BINPUT
C			BINPUT
C	CHANGE SPRING AND VISC FROM DEG TO RAD		BINPUT
C			BINPUT
	DO 64 I=1,NJNT		BINPUT
	J1 = 3*I-2		BINPUT
	J2 = 3*I-1		BINPUT
	IF (EULER(I))	J2= 3*I	SLIP
	DO 63 J=J1,J2		BINPUT
	SPRING(1,J) =	SPRING(1,J)/RADIAN	BINPUT
	SPRING(2,J) =	SPRING(2,J)/RADIAN**2	BINPUT
	SPRING(3,J) =	SPRING(3,J)/RADIAN**3	BINPUT
	SPRING(5,J) =	SPRING(5,J)*RADIAN	BINPUT
63	CONTINUE		BINPUT

	IF (.NOT.EULER(I)) J2 = J1	SLIP
	DO 64 J=J1,J2	BINPUT
	VISC (1,J) = VISC (1,J)/RADIAN	BINPUT
64	VISC (3,J) = VISC (3,J)*RADIAN	BINPUT
C		BINPUT
C	W ARRAY HAS BEEN SUPPLIED IN LBS. SET UP RECIPROCAL MASS (RW)	BINPUT
C	AND MOMENT OF INERTIA (RPHI) ARRAYS. HOWEVER, IF W OR ANY ELEMENT	BINPUT
C	OF PHI IS ZERO, SEGMENT WILL BE CONSIDERED SINGULAR (ISING=1) AND	BINPUT
C	ALL RECIPROCAL WILL BE ZERO SO AS TO NULLIFY COMPUTATIONS IN THE	BINPUT
C	DAUX ROUTINES. NS IS THE NUMBER OF SINGULAR SEGMENTS.	BINPUT
C		BINPUT
65	NS = 0	BINPUT
	DO 68 I=1,NSEG	BINPUT
	ISING(I) = 0	BINPUT
	RW(I) = 0.0	BINPUT
	IF (W(I).EQ.0.0) ISING(I) = 1	BINPUT
	DO 66 K=1,3	BINPUT
	IF (PHI(K,I).EQ.0.0) ISING(I) = 1	BINPUT
66	RPHI(K,I) = 0.0	BINPUT
	IF (ISING(I).EQ.1) NS = NS+1	BINPUT
	IF (ISING(I).EQ.1) GO TO 68	BINPUT
	RW(I) = G/W(I)	BINPUT
	DO 67 K=1,3	BINPUT
67	RPHI(K,I) = 1.0/PHI(K,I)	BINPUT
68	CONTINUE	BINPUT
C		BINPUT
C	SET UP ELLIPSOID MATRIX AND INVERSE (ASSUME YAW,PITCH,ROLL = 0)	BINPUT
C	FOR 1ST NSEG ELLIPSOIDS IN BD(7-15) AND BD(16-24).	BINPUT
C		BINPUT
	DO 71 J=1,NSEG	BINPUT
	DO 70 I=7,24	BINPUT
70	BD(I,J) = 0.0	BINPUT
	DO 71 I=1,3	BINPUT
	BD(4*I+3,J) = 1.0/BD(I,J)**2	BINPUT
71	BD(4*I+12,J) = BD(I,J)**2	BINPUT
	RETURN	BINPUT
	END	BINPUT

	SUBROUTINE BLKDTA		BLKDTA
		REV IV 07/23/86	TWOPI
C			BLKDTA
C	THIS SUBROUTINE REPLACES THE BLOCK DATA SUBPROGRAM OF PREVIOUS		BLKDTA
C	VERSIONS OF CVS-III TO INITIALIZE COMMON/CNSMTS/ IN A MANNER		BLKDTA
C	THAT IS INDEPENDENT OF THE COMPUTER SYSTEM BEING UTILIZED.		BLKDTA
C			BLKDTA
	IMPLICIT REAL*8 (A-H,O-Z)		BLKDTA
	COMMON/CNSMTS/ PI,RADIAN,G,THIRD,EPS(24),		BLKDTA
	* UNITL,UNITM,UNITT,GRAVTY(3),TWOPI		TWOPI
	COMMON/TEMPVS/ ZERO,ONE,THREE,TEN,ONE80		BLKDTA
	DATA UM/8H LBS / , UT/8H SEC / , UL/8H IN /		BLKDTA
	ZERO = 0.0		BLKDTA
	ONE = 1.0		BLKDTA
	UNITM = UM		BLKDTA
	UNITT = UT		BLKDTA
	UNITL = UL		BLKDTA
	G = 386.088D0		BLKDTA
	GRAVTY(1) = ZERO		BLKDTA
	GRAVTY(2) = ZERO		BLKDTA
	GRAVTY(3) = G		BLKDTA
	THREE = 3.0		BLKDTA
	TEN = 10.0		BLKDTA
	ONE80 = 180.0		BLKDTA
	PI = DATAN2(ZERO,-ONE)		BLKDTA
	TWOPI = 2.0*PI		TWOPI
	RADIAN = PI/ONE80		BLKDTA
	THIRD = ONE/THREE		BLKDTA
	EPS(1) = ONE/TEN		BLKDTA
	DO 10 I=2,24		BLKDTA
10	EPS(I) = EPS(I-1)/TEN		BLKDTA
	RETURN		BLKDTA
	END		BLKDTA

	SUBROUTINE CFACTT(A,B,D)		REV 03	05/31/73	CFACTT
C					CFACTT
C	GIVEN 3X3 MATRIX A				CFACTT
C	COMPUTE B TRANSPOSE OF COFACTORS (SIGNED MINORS)				CFACTT
C	AND D THE VALUE OF THE DETERMINANT OF A.				CFACTT
C	INVERSE OF A IS B(J,K)/D				CFACTT
C					CFACTT
	IMPLICIT REAL*8 (A-H,O-Z)				CFACTT
	DIMENSION A(3,3),B(3,3)				CFACTT
	M = 4				CFACTT
	L = 2				CFACTT
	N = 3				CFACTT
	D = 0.0				CFACTT
	DO 20 J=1,3				CFACTT
	B(J,J) = A(L,L)*A(N,N)-A(L,N)*A(N,L)				CFACTT
	IF (J.EQ.3) GO TO 20				CFACTT
	L = N				CFACTT
	N = J				CFACTT
	KK = J+1				CFACTT
	DO 15 K=KK,3				CFACTT
	M = M-1				CFACTT
	B(K,J) = A(K,M)*A(M,J)-A(K,J)*A(M,M)				CFACTT
15	B(J,K) = A(J,M)*A(M,K)-A(J,K)*A(M,M)				CFACTT
20	D = D+A(1,J)*B(J,1)				CFACTT
	RETURN				CFACTT
	END				CFACTT

	SUBROUTINE CHAIN(ISKIP)		JDRIFT
C		REV IV	07/24/86SLIP
C	COMPUTES THE LINEAR POSITION AND VELOCITY IN INERTIAL REFERENCE		CHAIN
C	OF BODY SEGMENTS FROM THOSE OF THE REFERENCE SEGMENTS		CHAIN
C	(I.E., SEGMENT NO. 1 AND EACH SEGMENT J FOR WHICH JNT(J)=0).		CHAIN
C			CHAIN
	IMPLICIT REAL*8(A-H,O-Z)		CHAIN
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		CHAIN
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		CHAIN
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		CHAIN
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		CHAIN
	* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		CHAIN
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),		SLIP
	* FE(3,30),TQE(3,30),CONST(5,30)		SLIP
	COMMON/TEMPVS/ T1(3),T2(3),T3(3),T4(3),T5(3),T6(3),T7(3)		SLIP
	DATA IFIRST/1/		SLIP
	CALL ELTIME (1,11)		ATBIII
	IF (NJNT.EQ.0) GO TO 71		ATBIII
	IF (ISKIP.NE.0) CALL DRIFT		JDRIFT
	DO 70 J=1,NJNT		ATBIII
	K = IABS(JNT(J))		ATBIII
	IF (K.EQ.0) GO TO 70		ATBIII
	IF (ISING(J+1).LT.0) GO TO 70		ATBIII
C			ATBIII
C	COMPUTE SEGMENT POSITIONS BY		ATBIII
C	P(J+1) = P(K) + D(K)'*R(K,J) - D(J+1)'*R(J+1,J)		ATBIII
C			ATBIII
C	COMPUTE SEGMENT VELOCITIES BY		ATBIII
C	V(J+1) = V(K) + D(K)'*W(K) X R(K,J) - D(J+1)'*W(J+1) X R(J+1,J)		ATBIII
C			ATBIII
	CALL CROSS (WMEG(1,K),SR(1,2*J-1),T1)		JDRIFT
	CALL DOT31 (D(1,1,K),T1,T3)		ATBIII
	CALL CROSS (WMEG(1,J+1),SR(1,2*J),T2)		ATBIII
	CALL DOT31 (D(1,1,J+1),T2,T4)		ATBIII
	CALL DOT31 (D(1,1,K),SR(1,2*J-1),T1)		ATBIII
	CALL DOT31 (D(1,1,J+1),SR(1,2*J),T2)		ATBIII
	IF (IABS(IPIN(J)).LT.5) GO TO 50		SLIP
	IF (IEULER(J).EQ.-1)GO TO 50		SLIP
	IF (IFIRST.EQ.1) GO TO 50		SLIP
	DO 40 I = 1,3		SLIP
	T5(I) = SEGLP(I,J+1) + T2(I) - SEGLP(I,K) - T1(I)		SLIP
40	T6(I) = SEGLV(I,J+1) + T4(I) - SEGLV(I,K) - T3(I)		SLIP
	CALL DOT31 (D(1,1,K),HT(1,3,2*J-1),T7)		SLIP
	SR(4,2*J-1) = T5(1)*T7(1) + T5(2)*T7(2) + T5(3)*T7(3)		SLIP
	SR(4,2*J ) = T6(1)*T7(1) + T6(2)*T7(2) + T6(3)*T7(3)		SLIP
	CALL CROSS (WMEG(1,K),HT(1,3,2*J-1),T5)		SLIP
	CALL DOT31 (D(1,1,K),T5,T6)		SLIP
	DO 45 I =1 ,3		SLIP

	T1(I) = T1(I) + SR(4,2*J-1)*T7(I)	SLIP
45	T3(I) = T3(I) + SR(4,2*J )*T7(I) + SR(4,2*J-1)*T6(I)	SLIP
50	DO 60 I=1,3	SLIP
	SEGLP(I,J+1) = SEGLP(I,K) + T1(I) - T2(I)	ATBIII
60	SEGLV(I,J+1) = SEGLV(I,K) + T3(I) - T4(I)	ATBIII
70	CONTINUE	CHAIN
	IFIRST = 0	SLIP
C		CHAIN
C	OPTIONAL OUTPUT	CHAIN
C		CHAIN
	71 IF (NPRT(20).NE.0) WRITE(6,90) TIME	CHAIN
	* ,((SEGLP(I,J),I=1,3),J=1,NSEG)	CHAIN
	* ,((SEGLV(I,J),I=1,3),J=1,NSEG)	CHAIN
90	FORMAT('0 LINEAR POSITIONS AND VELOCITIES OF BODY SEGMENTS FROM CH	CHAIN
	*AIN FOR TIME =' ,F12.6/(9F13.5))	CHAIN
	CALL ELTIME(2,11)	CHAIN
	RETURN	CHAIN
	END	CHAIN



	SUBROUTINE CINPUT	CINPUT
		REV III.2 08/08/84REVIII
C	INPUT CARDS E.1 - E.4 FOR THE FORCE-DEFLECTION, INERTIAL SPIKE,	CINPUT
C	R FACTOR, G FACTOR AND FRICTION COEFFICIENT FUNCTION DEFINITIONS	CINPUT
C		CINPUT
	IMPLICIT REAL*8(A-H,O-Z)	CINPUT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	PAGE
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	DIMENB
	COMMON/TEMPVS/JTITL(5,51),NF(5),NT(3),KTITLE(31)	CINPUT
	REAL JTITL,KTITLE	CINPUT
C		CINPUT
	IS = 0	CINPUT
	DO 10 I = 1,50	CINPUT
	10 NTI(I) = 0	CINPUT
	J1 = 1	CINPUT
C		CINPUT
C	INPUT CARD E.1 - FUNCTION NO. AND TITLE, IF NO. > 50 SKIP OUT.	CINPUT
C		CINPUT
	11 READ(5,12) I,(KTITLE(J),J = 1,5)	CINPUT
	12 FORMAT (I4,4X,5A4)	CINPUT
	IF (I.GT.50) GO TO 30	CINPUT
	DO 13 J = 1,5	CINPUT
	13 JTITL(J,I) = KTITLE(J)	CINPUT
C		CINPUT
C	HAS FUNCTION NO. BEEN ALREADY USED?	CINPUT
C		CINPUT
	IF (NTI(I).NE.0) WRITE(6,14) I	CINPUT
	14 FORMAT('0 FUNCTION NO.',I4,' HAS ALREADY BEEN INPUTTED AND WILL BE	CINPUT
	*REPLACED BY NEXT FUNCTION')	CINPUT
	NTI(I) = J1	CINPUT
	J2 = J1+4	CINPUT
C		CINPUT
C	INPUT CARD E.2	CINPUT
C		CINPUT
	READ(5,15) (TAB(J),J = J1,J2)	CINPUT
	15 FORMAT (6F12.0)	CINPUT
	IS = 1-IS	CINPUT
	IF (IS.EQ.0) WRITE(6,16)	CINPUT
	IF (IS.EQ.0) GOTO 40	PAGE
	WRITE(6,41) NPG	PAGE
	41 FORMAT('1',122X,'PAGE',I5)	PAGE
	NPG=NPG+1	PAGE
	16 FORMAT(//////)	CINPUT
	40 WRITE(6,17) I,(JTITL(J,I),J=1,5),I,NTI(I),(TAB(J),J=J1,J2)	PAGE
	17 FORMAT(' FUNCTION NO.',I4,4X,5A4,20X,'NTI('',I2,'') =',I5,45X,	PAGE
	* 'CARDS E'//10X,'D0',13X,'D1',13X,'D2',13X,'D3',13X,'D4'/5F15.4//)	CINPUT
	D0 = TAB(J1)	CINPUT
	D1 = TAB(J1+1)	CINPUT
	D2 = TAB(J1+2)	CINPUT

	J1 = J2+1	CINPUT
	IF (D1) 22,18,20	CINPUT
C		CINPUT
C	FUNCTION IS CONSTANT D2 FOR ALL D.	CINPUT
C		CINPUT
	18 WRITE(6,19) D2	CINPUT
	19 FORMAT(7X,'FUNCTION IS CONSTANT',F12.6)	CINPUT
	GO TO 11	CINPUT
C		CINPUT
C	5TH ORDER POLYNOMIAL ... 1ST FUNCTION	CINPUT
C	INPUT CARD E.3	CINPUT
C		CINPUT
	20 J2 = J1+5	CINPUT
	READ(5,15) (TAB(J), J = J1,J2)	CINPUT
	WRITE(6,21) (TAB(J), J = J1,J2)	CINPUT
	21 FORMAT(7X,'FIRST PART OF FUNCTION - 5TH DEGREE POLYNOMIAL'//	CINPUT
	* 8X,'A0',13X,'A1',13X,'A2',13X,'A3',13X,'A4',13X,'A5',13X/C	CINPUT
	* 6F15.6//)	CINPUT
	J1 = J2+1	CINPUT
	GO TO 25	CINPUT
C		CINPUT
C	TABLE LOAD ... 1ST FUNCTION	CINPUT
C	INPUT CARDS E.4.A-E.4.N	CINPUT
C		CINPUT
	22 READ(5,23) NPI	CINPUT
	23 FORMAT (12I6)	CINPUT
	TAB(J1) = NPI	CINPUT
	J1 = J1+1	CINPUT
	J2 = J1+2*NPI-1	CINPUT
	READ(5,15) (TAB(J), J = J1,J2)	CINPUT
	WRITE(6,24) NPI, (TAB(J), J = J1, J2)	CINPUT
	24 FORMAT(7X,'FIRST PART OF FUNCTION - ',I4,' TABULAR POINTS'//	CINPUT
	* 8X,'D',16X,'F(D)' /(F15.6,F15.4))	CINPUT
	J1 = J2+1	CINPUT
C		CINPUT
C	CHECK FOR SECOND FUNCTION	CINPUT
C		CINPUT
	25 IF(D2) 28,11,26	CINPUT
C		CINPUT
C	SECOND FUNCTION ... 5TH ORDER POLYNOMIAL	CINPUT
C	INPUT CARD E.3	CINPUT
C		CINPUT
	26 J2 = J1+5	CINPUT
	READ(5,15) (TAB(J), J = J1,J2)	CINPUT
	WRITE(6,27) (TAB(J), J = J1,J2)	CINPUT
	27 FORMAT(7X,'SECOND PART OF FUNCTION - 5TH DEGREE POLYNOMIAL'//	CINPUT
	* 8X,'B0',13X,'B1',13X,'B2',13X,'B3',13X,'B4',13X,'B5',13X/C	CINPUT
	* 6F15.6//)	CINPUT
	J1 = J2+1	CINPUT
	GO TO 11	CINPUT

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C
C      SECOND FUNCTION ... TABLE LOAD
C      INPUT CARDS E.4.A-E.4.N
```

[illegible]

28	READ(5,23) NPI	CINPUT
	TAB(J1) = NPI	CINPUT
	J1 = J1+1	CINPUT
	J2 = J1+2*NPI-1	CINPUT
	READ(5,15) (TAB(J), J = J1,J2)	CINPUT
	WRITE(6,29) NPI, (TAB(J), J = J1,J2)	CINPUT
29	FORMAT(7X,'SECOND PART OF FUNCTION - ',I4,' TABULAR POINTS'//	CINPUT
	* 8X,'D',16X,'F(D)' /(F15.6,F15.4))	CINPUT
	J1 = J2+1	CINPUT
	GO TO 11	CINPUT
30	MXTB1 = J1-1	CINPUT
	CALL KINPUT	CINPUT
	CALL FINPUT	CINPUT
	CALL HINPUT	CINPUT
	RETURN	CINPUT
	END	CINPUT



	SUBROUTINE CONTACT	CONTACT
C		REV III.2 08/08/84REVIII
C	CONTROLS THE CALLING OF SUBROUTINES REQUIRED TO COMPUTE THOSE	CONTACT
C	EXTERNAL FORCES AND TORQUES ACTING ON THE BODY SEGMENTS.	CONTACT
C		CONTACT
	IMPLICIT REAL*8 (A-H,O-Z)	CONTACT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	CONTACT
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),	CONTACT
*	MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),	CONTACT
*	NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)	CONTACT
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),	NCFORC
*	PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF	CONTACT
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	DIMENB
	COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),	CONTACT
*	XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),	CONTACT
*	NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)	CONTACT
	COMMON/WINDFR/ WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30),	WINDOP
*	MWSEG(7,30),NFVSEG(6),NFVNT(5),MOWSEG(30,30)	WINDOP
	DATA MAXPSF/70/,MAXBSF/20/,MAXSSF/46/	NCFORC
C		CHGIII
C	MAXSSF SHOULD BE 40 BUT IT IS ALLOWED TO OVERFLOW INTO BAGSF	NCFORC
C		CHGIII
	CALL ELTIME(1,12)	CONTACT
	NPSF = 0	CONTACT
	NBSF = 0	CONTACT
	NSSF = 0	CONTACT
	IF (NPL.LE.0) GO TO 21	CONTACT
C		CONTACT
C	CALL PLELP ROUTINE FOR EACH ALLOWED PLANE-SEGMENT CONTACT.	CONTACT
C		CONTACT
	DO 20 J=1,NPL	CONTACT
	IF(MNPL(J).EQ.0) GO TO 20	CONTACT
	KPL = MNPL(J)	CONTACT
	DO 19 I=1,KPL	CONTACT
	NPSF = NPSF+1	CONTACT
	IF(NPSF.GT.MAXPSF) STOP 57	CHGIII
	M1 = MPL(1,I,J)	CONTACT
	M2 = MPL(2,I,J)	CONTACT
	M3 = MPL(3,I,J)	CONTACT
	NT = NTPL(I,J)	CONTACT
	JT = NTAB(NT)	CONTACT
	TAB(JT) = 0.0	CONTACT
	19 CALL PLELP(M2,M3,M1,J,NT)	CONTACT
	20 CONTINUE	CONTACT
	21 IF(NBLT.LE.0) GO TO 41	CONTACT
C		CONTACT
C	CALL BELTRT ROUTINE FOR EACH ALLOWED BELT-SEGMENT CONTACT.	CONTACT
C		CONTACT
	DO 30 J=1,NBLT	CONTACT

	IF(MNBLT(J).EQ.0) GO TO 30	CONTCT
	KBLT = MNBLT(J)	CONTCT
	DO 29 I=1,KBLT	CONTCT
	NBSF = NBSF+1	CONTCT
	IF(NBSF.GT.MAXBSF) STOP 58	CHGIII
	M1 = MBLT(1,I,J)	CONTCT
	M2 = MBLT(2,I,J)	CONTCT
	M3 = MBLT(3,I,J)	CONTCT
	NT = NTBLT(1,J)	CONTCT
	JT = NTAB(NT)	CONTCT
	TAB(JT) = 0.0	CONTCT
	NF = NTAB(NT+5)	CONTCT
	IF (NF.NE.0) JT = NTAB(NT+6)	CONTCT
	IF (NF.NE.0) TAB(JT) = 0.0	CONTCT
	29 CALL BELTRT(M2,M3,M1,J,NT)	CONTCT
	30 CONTINUE	CONTCT
C		CONTCT
C	CALL SEGSEG ROUTINE FOR EACH ALLOWED SEGMENT-SEGMENT CONTACT.	CONTCT
C		CONTCT
	41 DO 50 J=1,NSEG	CONTCT
	IF(MNSEG(J).EQ.0) GO TO 50	CONTCT
	YSEG = MNSEG(J)	CONTCT
	DO 49 I=1,KSEG	CONTCT
	NSSF = NSSF+1	CONTCT
	IF(NSSF.GT.MAXSSF) STOP 59	CHGIII
	M1 = MSEG(1,I,J)	CONTCT
	M2 = MSEG(2,I,J)	CONTCT
	M3 = MSEG(3,I,J)	CONTCT
	NT = NTSEG(1,J)	CONTCT
	JT = NTAB(NT)	CONTCT
	TAB(JT) = 0.0	CONTCT
	49 CALL SEGSEG(J,M1,M2,M3,NT)	CONTCT
	50 CONTINUE	CONTCT
C		CONTCT
C	CALL AIRBAG ROUTINE FOR ALLOWED BAG-SEGMENT CONTACTS, IF ANY.	CONTCT
C		CONTCT
	IF (NBAG.NE.0) CALL AIRBAG	CONTCT
C		CONTCT
C	CALL WINDY ROUTINE FOR WIND FORCES ON EACH SEGMENT.	CONTCT
C		CONTCT
	DO 60 J=1,NSEG	CONTCT
	IF (MWSEG(1,J).EQ.0) GO TO 60	CONTCT
	M=MWSEG(1,J)	WINDOP
	M1 = MWSEG(2,J)	CONTCT
	M2 = MWSEG(3,J)	CONTCT
	M3 = MWSEG(4,J)	CONTCT
	NT = MWSEG(5,J)	CONTCT
	CALL WINDY (M,M1,M2,M3,NT)	WINDOP
	60 CONTINUE	CONTCT
C		CONTCT

C	CALL WINDY FOR FORCE FUNCE FUNCTION CALCULATIONS.	CONTCT
C		CONTCT
	NFORCE = NFVSEG(6)	CONTCT
	IF (NFORCE.GT.0) CALL WINDY (0,M1,M2,M3,NT)	WINDOP
C		CONTCT
C	CALL HBELT ROUTINE FOR EACH HARNESS-BELT SYSTEM.	CONTCT
C		CONTCT
	IF (NHRMSS.LE.0) GO TO 80	CONTCT
	J1 = 1	CONTCT
	KNL0 = 0	CONTCT
	DO 70 I=1,NHRMSS	CONTCT
	IF (NBLTPH(I).LE.0) GO TO 70	CONTCT
	J2 = J1 + NBLTPH(I) - 1	CONTCT
	CALL HBELT (J1,J2,KNL0,0)	CONTCT
	J1 = J2+1	CONTCT
	70 CONTINUE	CONTCT
C		CONTCT
C	CALL SPDAMP FOR SPRING DAMPER FORCES, IF ANY	CONTCT
C		CONTCT
	80 IF (NSD.NE.0) CALL SPDAMP	CONTCT
	CALL ELTIME (2,12)	CONTCT
	RETURN	CONTCT
	END	CONTCT

C	SUBROUTINE CROSS(A,B,C)		CROSS
C		REV 03	05/31/73CROSS
C	COMPUTES VECTOR CROSS PRODUCT $C = A \times B$ .		CROSS
C	ARGUMENTS		CROSS
C	A,B,C: VECTORS OF LENGTH 3 WHERE $C=AXB$ .		CROSS
C			CROSS
	IMPLICIT REAL*8 (A-H,O-Z)		CROSS
	DIMENSION A(3),B(3),C(3)		CROSS
	C(1) = A(2)*B(3) - A(3)*B(2)		CROSS
	C(2) = A(3)*B(1) - A(1)*B(3)		CROSS
	C(3) = A(1)*B(2) - A(2)*B(1)		CROSS
	RETURN		CROSS
	END		CROSS



	SUBROUTINE DAUX(11)		DAUX
		REV IV	07/24/86SLIP
C	COMPUTES DERIVATIVES FOR INTEGRATOR ROUTINE BY		DAUX
C	(1) SET UP INITIAL VALUES FOR ARRAY OF SYSTEM EQUATIONS.		DAUX
C	(2) MODIFY ARRAYS BY CONSTRAINTS.		DAUX
C	(3) SOLVE SYSTEM OF EQUATION FOR F,TQ,QQ AND V4.		DAUX
C	(4) EVALUATE DERIVATIVES SEGLA AND WMEGD.		DAUX
C			DAUX
	IMPLICIT REAL*8(A-H,O-Z)		DAUX
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		DAUX
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		DAUX
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		DAUX
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		DAUX
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		DAUX
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		DAUX
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		DAUX
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		DAUX
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		DAUX
*	KQ1(12),KQ2(12),KQTYPE(12)		DAUX
	COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)		DAUX
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		DAUX
*	UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),		ATBIII
*	NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)		TTHKREF
			DAUX
C	NOTE: DAUX SHARES /TEMPVS/ WITH DAUX11,12,22,31,32 &33.		DAUX
C			DAUX
C			DAUX
	LOGICAL*1 FREE		SLIP
	COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S,		SLIP
*	IDUM(458),FREE(30)		SLIP
	DIMENSION T1(3),T2(3),T3(3)		TGMOD2
	CALL ELTIME(1,9)		DAUX
C			DAUX
C	IF I1*0, U1 AND U2 HAVE BEEN SET UP BY CALLING ROUTINE.		DAUX
C			DAUX
	IF (I1.NE.0) GO TO 8		DAUX
C			DAUX
C	SET UP INITIAL VALUES OF A & B ARRAYS AND U & V VECTORS.		DAUX
C	MODIFY U1 & U2 ARRAYS BY CONTACT AND JOINT FORCES.		DAUX
C			DAUX
	CALL CHAIN(NPRT(36))		JDRIFT
	CALL SETUP1		DAUX
	CALL VEHPOS		DAUX
	CALL CONTCT		DAUX
	CALL VISPR(0,0)		DAUX
	CALL EJOINT(0,0)		DAUX
	CALL SETUP2		DAUX

	IF (NFLX.GT.0) CALL FLXSEG	DAUX
C		DAUX
C	MODIFY U1,U2 AND ADD G TO U1.	DAUX
C		DAUX
	DO 5 J=1,NGRND	DAUX
	IF (ISING(J)) 1,3,5	DAUX
1	DO 2 I=1,3	DAUX
	U1(I,J) = SEGLA(I,J)	DAUX
2	U2(I,J) = WMEGD(I,J)	DAUX
	GO TO 5	DAUX
3	DO 4 I=1,3	DAUX
	U1(I,J) = U1(I,J)*RW(J) + GRAVITY(I)	DAUX
4	U2(I,J) = U2(I,J)*RPHI(I,J)	DAUX
5	CONTINUE	DAUX
C		DAUX
C	SET UP BODY SEGMENT SYMMETRY	DAUX
C	NSYM(J) = 0 3D MOTION	DAUX
C	NSYM(J) = J CENTRAL SEGMENT 2D MOTION, NO LATERAL MOTION	DAUX
C	NSYM(J) = K SEGMENT J SYMMETRIC TO SEGMENT K, ALL MOTION	DAUX
C	IN THE X-Z PLANE, NO LATERAL MOTION	DAUX
C	NSYM(J) = -K SEGMENT J MIRROR SYMMETRIC TO SEGMENT K, EQUAL	DAUX
C	BUT OPPOSITE LATERAL MOTION PERMITTED	DAUX
C		DAUX
	DO 20 J=1,NGRND	DAUX
	IF (NSYM(J).EQ.0) GO TO 20	DAUX
	K = IABS(NSYM(J))	DAUX
	DO 205 L=1,3	TGMOD2
	T1(L) = U2(L,J)	TGMOD2
	T2(L) = U2(L,K)	TGMOD2
	T3(L) = U2(L,J)	TGMOD2
205	CONTINUE	TGMOD2
	IF (LPMI(J).EQ.0.AND.LPMI(K).EQ.0) GO TO 201	TGMOD2
	IF (LPMI(J).NE.0.AND.LPMI(K).EQ.0) GO TO 202	TGMOD2
	IF (LPMI(J).EQ.0.AND.LPMI(K).NE.0) GO TO 203	TGMOD2
	CALL DOT31(DPMI(1,1,J),U2(1,J),T1)	TGMOD2
	CALL DOT31(DPMI(1,1,K),U2(1,K),T2)	TGMOD2
	GO TO 201	TGMOD2
202	CALL DOT31(DPMI(1,1,J),U2(1,J),T1)	TGMOD2
	GO TO 201	TGMOD2
203	CALL DOT31(DPMI(1,1,K),U2(1,K),T2)	TGMOD2
201	CONTINUE	TGMOD2
	IF (NSYM(J).EQ.J) GO TO 19	DAUX
	IF (K.LT.J) GO TO 16	DAUX
	U1(1,J) = 0.5*(U1(1,J) + U1(1,K))	DAUX
	U1(3,J) = 0.5*(U1(3,J) + U1(3,K))	DAUX
	T3(2) = 0.5*(T1(2) + T2(2))	TGMOD2
	GO TO 17	DAUX
16	U1(1,J) = U1(1,K)	DAUX
	U1(3,J) = U1(3,K)	DAUX
	T3(2) = T2(2)	DAUX

17 IF (NSYM(J).GT.0) GO TO 19	DAUX
IF (K.LT.J) GO TO 18	DAUX
U1(2,J) = 0.5*(U1(2,J) - U1(2,K))	DAUX
T3(1) = 0.5*(T1(1) - T2(1))	TGMOD2
T3(3) = 0.5*(T1(3) - T2(3))	TGMOD2
GO TO 206	DAUX
18 U1(2,J) = -U1(2,K)	DAUX
T3(1) = -T2(1)	TGMOD2
T3(3) = -T2(3)	TGMOD2
GO TO 206	DAUX
19 U1(2,J) = 0.0	DAUX
T3(1) = 0.0	TGMOD2
T3(3) = 0.0	TGMOD2
206 IF (LPMI(J).EQ.0) GO TO 207	TGMOD2
CALL MAT31(DPMI(1,1,J),T3,U2(1,J))	TGMOD2
GO TO 20	TGMOD2
207 U2(1,J) = T3(1)	TGMOD2
U2(2,J) = T3(2)	TGMOD2
U2(3,J) = T3(3)	TGMOD2
20 CONTINUE	TGMOD2
C	DAUX
C INITIALIZE IJK ARRAY AND IJ COUNTER TO ZERO.	DAUX
C	DAUX
8 NQ2S = 2*NS + NFLX + NQ	DAUX
NJ2 = NQ2S + 2*NJNT	DAUX
IF (NJ2.GT.54) WRITE (6,11) NS,NFLX,NQ,NJNT,NJ2	DAUX
11 FORMAT('ONS=',I6,',NFLX=',I6,',NQ=',I6,',NJNT=',I6,', AND NJ2=',I6,/AFREVS	
*' THE VALUE OF NJ2 EXCEEDS THE ARRAY SIZES FOR RHS AND IJK IN SUBRDAUX	
*OUTINE DAUX. PROGRAM TERMINATED.')	DAUX
IF (NJ2.GT.54) STOP 34	DAUX
MJ2 = NJ2	DAUX
DO 10 I=1,NJ2	DAUX
DO 10 J=1,NJ2	DAUX
10 IJK(I,J) = 0	DAUX
IJ = 0	DAUX
C	DAUX
C ELMINATE SEGLA AND WMEGD FROM SYSTEM OF EQUATIONS.	DAUX
C	DAUX
IF (NS.GT.0) CALL DAUX55	DAUX
IF (NJNT.EQ.0) GO TO 12	DAUX
IF (NFLX.GT.0) CALL DAUX44	DAUX
CALL DAUX11	DAUX
CALL DAUX12	DAUX
CALL DAUX22	DAUX
12 IF (NQ.LE.0) GO TO 15	DAUX
IF (NJNT.EQ.0) GO TO 13	DAUX
CALL DAUX31	DAUX
CALL DAUX32	DAUX
13 CALL DAUX33	DAUX
DO 14 I=1,NQ	DAUX

14	IF (KQTYPE(I).GE.4) MJ2 = -NJ2	DAUX
15	IF (NPRT(8).EQ.0) GO TO 28	DAUX
21	WRITE (6,22) NPG,(J,J=1,NJ2)	PAGE
	NPG=NPG+1	PAGE
22	FORMAT('1 DAUX PRINT OF IJK MATRIX',97X,'PAGE',I5//6X,40I3)	PAGE
	DO 23 I=1,NJ2	DAUX
23	WRITE (6,24) I,(IJK(I,J),J=1,NJ2)	DAUX
24	FORMAT(I3,3X,40I3)	DAUX
	WRITE (6,29)	DAUX
29	FORMAT('0 DAUX PRINT OF RHS ARRAY'//)	DAUX
	DO 30 K=1,NJ2	DAUX
30	WRITE (6,27) K,(RHS(I,K),I=1,3)	DAUX
	WRITE (6,25) NPG	PAGE
	NPG=NPG+1	PAGE
25	FORMAT('1 DAUX PRINT OF C ARRAY ELEMENTS',91X,'PAGE',I5//)	PAGE
	DO 26 K=1,IJ	DAUX
26	WRITE (6,27) K,((C(I,J,K),J=1,3),I=1,3)	DAUX
27	FORMAT(I6,9G14.7)	DAUX
28	IF (NPRT(8).EQ.-2) GO TO 31	DAUX
C		DAUX
C	SOLVE SYSTEM OF EQUATIONS FOR F,TQ,QQ & V4.	DAUX
C		DAUX
	CALL FSMSOL (C,RHS,IJK,MJ2,IJ,54,600)	CHGIII
	IF (NPRT(8).EQ. 2) NPRT(8) = -2	DAUX
	IF (NPRT(8).EQ.-2) GO TO 21	DAUX
31	IF (NPRT(8).EQ.-2) NPRT(8) = 0	DAUX
	EPS12 = EPS(12)	JDRIFT
	IF (NJNT.EQ.0) GO TO 49	DAUX
	DO 51 I=1,NJNT	DAUX
	NJ = NQ2S + I	DAUX
	NI = NJ+NJNT	DAUX
	DO 51 K=1,3	DAUX
	IF (DABS(RHS(K,NJ)).LT.EPS12) RHS(K,NJ) = 0.0	DAUX
	IF (DABS(RHS(K,NI)).LT.EPS12) RHS(K,NI) = 0.0	DAUX
	TQ(K,I) = TQ(K,I) - RHS(K,NI)	DAUX
51	F(K,I) = RHS(K,NJ)	DAUX
49	IF (NQ.EQ.0) GO TO 53	DAUX
	DO 52 I=1,NQ	DAUX
	J = 2*NS + NFLX + I	DAUX
	DO 52 K=1,3	DAUX
	IF (KQTYPE(I).LT.0) RHS(K,J) = 0.0	DAUX
	IF (DABS(RHS(K,J)).LT.EPS12) RHS(K,J) = 0.0	DAUX
52	QQ(K,I) = RHS(K,J)	DAUX
53	IF (NFLX.EQ.0) GO TO 70	DAUX
	DO 54 I=1,NFLX	DAUX
	J = 2*NS + I	DAUX
	DO 54 K=1,3	DAUX
	IF (DABS(RHS(K,J)).LT.EPS12) RHS(K,J) = 0.0	DAUX
54	V4(K,I) = RHS(K,J)	DAUX
C		DAUX

C	BACKUP SOLUTION FOR SEGLA AND WMEGD.	DAUX
C		DAUX
70	DO 71 J=1,NGRND	DAUX
	DO 71 I=1,3	DAUX
	SEGLA(I,J) = U1(I,J)	DAUX
71	WMEGD(I,J) = U2(I,J)	DAUX
	IF (NS.EQ.0) GO TO 79	DAUX
C		DAUX
C	SET UP SEGLA & WMEGD FOR SINGULAR SEGMENTS.	DAUX
C		DAUX
	IS = 0	DAUX
	DO 78 J=1,NGRND	DAUX
	IF (ISING(J).LE.0) GO TO 78	DAUX
	IS = IS+2	DAUX
	DO 77 I=1,3	DAUX
	IF (DABS(RHS(I,IS-1)).LT.EPS12) RHS(I,IS-1) = 0.0	DAUX
	SEGLA(I,J) = SEGLA(I,J) + RHS(I,IS-1)	DAUX
	IF (DABS(RHS(I,IS)).LT.EPS12) RHS(I,IS) = 0.0	DAUX
77	WMEGD(I,J) = WMEGD(I,J) + RHS(I,IS)	DAUX
78	CONTINUE	DAUX
79	IF (NJNT.EQ.0) GO TO 80	DAUX
C		DAUX
C	ELIMINATE F	DAUX
C		DAUX
	DO 75 M=1,NJNT	DAUX
	N = IABS(JNT(M))	DAUX
	IF (N.EQ.0) GO TO 73	DAUX
	DO 72 I=1,3	DAUX
	DO 72 J=1,3	DAUX
	SEGLA(I,N) = SEGLA(I,N) - A11(I,J,M)*RW(N)*F(J,M)	SLIP
	SEGLA(I,M+1) = SEGLA(I,M+1) + A11(I,J,M)*RW(M+1)*F(J,M)	SLIP
	WMEGD(I,N) = WMEGD(I,N) - B12(J,I,2*M-1)*RPHI(I,N)*F(J,M)	DAUX
72	WMEGD(I,M+1) = WMEGD(I,M+1) - B12(J,I,2*M)*RPHI(I,M+1)*F(J,M)	DAUX
C		DAUX
C	ELIMINATE TQ	DAUX
C		DAUX
73	IF (FREE(M)) GO TO 75	SLIP
	L = NQ2S + NJNT + M	DAUX
	DO 74 I=1,3	DAUX
	DO 74 J=1,3	DAUX
	WMEGD(I,N) = WMEGD(I,N) - A22(I,J,2*M-1)*RPHI(I,N)*RHS(J,L)	DAUX
74	WMEGD(I,M+1) = WMEGD(I,M+1) + A22(I,J,2*M)*RPHI(I,M+1)*RHS(J,L)	DAUX
75	CONTINUE	DAUX
80	IF (NQ.EQ.0) GO TO 83	DAUX
C		DAUX
C	ELIMINATE QQ	DAUX
C		DAUX
	DO 82 K=1,NQ	DAUX
	IF (KQTYPE(K).LT.0) GO TO 82	DAUX
	N = KQ1(K)	DAUX

M = KQ2(K)	DAUX
DO 81 I=1,3	DAUX
DO 81 J=1,3	DAUX
SEGLA(I,N) = SEGLA(I,N) - A13(I,J,2*K-1)*RW(N) *QQ(J,K)	DAUX
SEGLA(I,M) = SEGLA(I,M) - A13(I,J,2*K )*RW(M) *QQ(J,K)	DAUX
WMEGD(I,N) = WMEGD(I,N) - A23(I,J,2*K-1)*RPHI(I,N)*QQ(J,K)	DAUX
81 WMEGD(I,M) = WMEGD(I,M) - A23(I,J,2*K )*RPHI(I,M)*QQ(J,K)	DAUX
82 CONTINUE	DAUX
83 IF (NFLX.EQ.0) GO TO 90	DAUX
C	DAUX
C ELIMINATE V4 (TORQUES FOR FLEXIBLE SEGMENTS)	DAUX
C	DAUX
DO 84 N=1,NFLX	DAUX
N1 = NFLEX(1,N)	DAUX
N2 = NFLEX(2,N)	DAUX
N3 = NFLEX(3,N)	DAUX
DO 84 I=1,3	DAUX
DO 84 J=1,3	DAUX
WMEGD(I,N1) = WMEGD(I,N1) - B42(J,I,3*N-2)*RPHI(I,N1)*V4(J,N)	DAUX
WMEGD(I,N2) = WMEGD(I,N2) - B42(J,I,3*N-1)*RPHI(I,N2)*V4(J,N)	DAUX
84 WMEGD(I,N3) = WMEGD(I,N3) - B42(J,I,3*N )*RPHI(I,N3)*V4(J,N)	DAUX
90 DO 91 J=1,NGRND	DAUX
DO 91 I=1,3	DAUX
IF (DABS(WMEGD(I,J)).LE.EPS12) WMEGD(I,J) = 0.0	DAUX
91 IF (DABS(SEGLA(I,J)).LE.EPS12) SEGLA(I,J) = 0.0	DAUX
C	DAUX
C OPTIONAL OUTPUT OF FUNCTIONS AND DERIVATIVES.	DAUX
C	DAUX
IF (NPRT(9).NE.0) CALL PRINT(6H DAUX )	DAUX
C	DAUX
CALL ELTIME(2,9)	DAUX
RETURN	DAUX
END	DAUX

	SUBROUTINE DAUX11	DAUX11
C		REV IV 07/24/86SLIP
C	CALL BY SUBROUTINE DAUX TO COMPUTE	DAUX11
C		DAUX11
C		DAUX11
C	$(C11) = (B11)(M)^{-1} (A11) + (B12)(PHI)^{-1} (A21)$	DAUX11
C		DAUX11
C	$(R1) = (B11)(M)^{-1} (U1) + (B12)(PHI)^{-1} (U2) - (V1)$	DAUX11
C		DAUX11
C	IMPLICIT REAL*8(A-H,O-Z)	DAUX11
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	DAUX11
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	DAUX11
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	DAUX11
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),	SLIP
	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),	DAUX11
	* JNT(30),IPIW(30),ISING(30),TGLOBAL(30),JOINTF(30)	DAUX11
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),	DAUX11
	* F(3,30),TQ(3,30),WJ(30),A11(3,3,30)	SLIP
	COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S	CHGIII
	* DN(3,3),DM(3,3),SN(3,3),SM(3,3),HH(3,3),BW(3)	DAUX11
	CALL ELTIME(1,14)	DAUX11
	DO 30 M=1,NJNT	DAUX11
	N = IABS(JNT(M))	DAUX11
	MQ = NQ2S + M	DAUX11
	IJ = IJ+1	DAUX11
	IJK(MQ,MQ) = IJ	DAUX11
	IF (N.GT.0) GO TO 13	DAUX11
C		DAUX11
C	IF (N < 1) SET C11(M,M) = I	DAUX11
C		DAUX11
C	AND RHS(M) = V1(M)	DAUX11
C		DAUX11
	DO 12 I=1,3	DAUX11
	DO 11 J=1,3	DAUX11
	11 C(I,J,IJ) = 0.0	DAUX11
	C(I,I,IJ) = 1.0	DAUX11
	12 RHS(I,MQ) = V1(I,M)	DAUX11
	IJK(MQ,MQ) = -IJ	DAUX11
	GO TO 30	DAUX11
C		DAUX11
C	IF (N > 0) SET RHS(M) = U1(N) - U1(M+1) - V1(M)	DAUX11
C		+ B12(M,N)U2(N) + B12(M,M+1)U2(M+1)
C		DAUX11
C	AND C11(M,N) = RW(N) + RW(M+1)	DAUX11
C		+ B12(M,N)PHI(N)'A21(N,M)
C		+ B12(M,M+1)PHI(M+1)'A21(M+1,M)
C		DAUX11
C		DAUX11
	13 DO 15 I=1,3	DAUX11

	T1 = -V1(I,M)	SLIP
	DO 15 J = 1,3	DAUX11
	T1 = T1 + B12(I,J,2*M-1)*U2(J,N) + B12(I,J,2*M)*U2(J,M+1)	DAUX11
	* + A11(I,J,M)*(U1(J,N) - U1(J,M+1))	SLIP
	IF (J.LT.I) GO TO 15	DAUX11
	T2 = 0.0	DAUX11
	IF (J.EQ.I) T2 = RW(N) + RW(M+1)	DAUX11
	DO 14 K=1,3	DAUX11
14	T2 = T2 + B12(I,K,2*M-1)*RPHI(K,N)*B12(J,K,2*M-1)	DAUX11
	* + B12(I,K,2*M)*RPHI(K,M+1)*B12(J,K,2*M)	DAUX11
	C(I,J,IJ) = T2	DAUX11
	C(J,I,IJ) = T2	DAUX11
15	RHS(I,MQ) = T1	DAUX11
	IF (ISING(N).NE.0) GO TO 30	DAUX11
	L = 0	DAUX11
	IF (N.GT.1) L = IABS(JNT(N-1))	DAUX11
	IF (L.EQ.0) GO TO 18	DAUX11
C		DAUX11
C	IF (N > 1) AND (L = JNT(N-1) > 0)	DAUX11
C		DAUX11
C	SET C11(M,N-1) = -RW(N) + B12(M,N)PHI(N)'A21(N,N-1)	DAUX11
C		DAUX11
C	AND C11(N-1,M) = C(M,N-1) <sup>T</sup>	DAUX11
C		DAUX11
	KJNT = NQ2S + N - 1	DAUX11
	IJ = IJ+1	DAUX11
	IJK(MQ,KJNT) = IJ	DAUX11
	IJK(KJNT,MQ) = IJ+1	DAUX11
	DO 17 I=1,3	DAUX11
	DO 17 J=1,3	DAUX11
	C(I,J,IJ) = 0.0	DAUX11
	DO 16 K=1,3	DAUX11
16	C(I,J,IJ) = C(I,J,IJ) + B12(I,K,2*M-1)*RPHI(K,N)*B12(J,K,2*N-2)	DAUX11
	* - A11(I,K,M)*RW(N)*A11(J,K,N-1)	SLIP
17	C(J,I,IJ+1) = C(I,J,IJ)	DAUX11
	IJ = IJ+1	DAUX11
18	IF (M.EQ.NJNT) GO TO 30	DAUX11
	M1 = M+1	DAUX11
	DO 21 L=M1,NJNT	DAUX11
	IF (IABS(JNT(L)).NE.N) GO TO 21	DAUX11
C		DAUX11
C	IF (L > M) AND (JNT(L) = N)	DAUX11
C		DAUX11
C	SET C11(M,L) = RW(N) + B12(M,N)PHI(N)'A21(N,L)	DAUX11
C		DAUX11
C	AND C11(L,M) = C11(M,L) <sup>T</sup>	DAUX11
C		DAUX11
C		DAUX11
	KJNT = NQ2S + L	DAUX11



IJ = IJ+1	DAUX11
IJK(MQ,KJNT) = IJ	DAUX11
IJK(KJNT,MQ) = IJ+1	DAUX11
DO 20 I=1,3	DAUX11
DO 20 J=1,3	DAUX11
C(I,J,IJ) = 0.0	DAUX11
DO 19 K=1,3	DAUX11
19 C(I,J,IJ) = C(I,J,IJ) + B12(I,K,2*M-1)*RPHI(K,N)*B12(J,K,2*L-1)	DAUX11
*                    + A11(I,K,M)*RW(N)*A11(J,K,L)	SLIP
20 C(J,I,IJ+1) = C(I,J,IJ)	DAUX11
IJ = IJ+1	DAUX11
21 CONTINUE	DAUX11
30 CONTINUE	DAUX11
CALL ELTIME(2,14)	DAUX11
RETURN	DAUX11
END	DAUX11

	SUBROUTINE DAUX12	DAUX12
C		REV IV 07/24/86SLIP
C	CALL BY SUBROUTINE DAUX TO COMPUTE	DAUX12
C		DAUX12
C	-1	DAUX12
C	(C12) = (B12)(PHI) (A22)	DAUX12
C		DAUX12
C	T	DAUX12
C	(C21) = (C12)	DAUX12
C		DAUX12
	IMPLICIT REAL*8(A-H,O-Z)	DAUX12
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	DAUX12
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),	SLIP
	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),	DAUX12
	* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)	DAUX12
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),	DAUX12
	* F(3,30),TQ(3,30),WJ(30),A11(3,3,30)	SLIP
	LOGICAL*1 FREE	SLIP
	COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S	CHGIII
	* ,DN(3,3),DM(3,3),SN(3,3),SM(3,3),HH(3,3),BN(3)	DAUX12
	* ,IDUM(362),FREE(30)	SLIP
	CALL ELTIME(1,15)	DAUX12
	NQSJNT = NQ2S + NJNT	DAUX12
	DO 60 M=1,NJNT	DAUX12
	N = IABS(JNT(M))	DAUX12
	IF (N.EQ.0) GO TO 60	DAUX12
	MQ = NQ2S + M	DAUX12
	IF (FREE(M)) GO TO 37	SLIP
	MJNT = NQSJNT + M	D. UX12
	IJ = IJ+1	DAUX12
	IJK(MQ,MJNT) = IJ	DAUX12
	IJK(MJNT,MQ) = IJ+1	DAUX12
	DO 36 I=1,3	DAUX12
	DO 36 J=1,3	DAUX12
	SN(I,J) = 0.0	DAUX12
	SM(I,J) = 0.0	DAUX12
	DO 35 K=1,3	DAUX12
	SN(I,J) = SN(I,J) + B12(I,K,2*M-1) * RPHI(K,N) * A22(K,J,2*M-1)	DAUX12
35	SM(I,J) = SM(I,J) + B12(I,K,2*M) * RPHI(K,M+1) * A22(K,J,2*M)	DAUX12
	C(I,J,IJ) = SN(I,J) - SM(I,J)	DAUX12
36	C(J,I,IJ+1) = C(I,J,IJ)	DAUX12
	IJ = IJ+1	DAUX12
37	IF (ISING(N).NE.0) GO TO 50	DAUX12
	IF (N.EQ.1) GO TO 43	DAUX12
	IF (FREE(N-1)) GO TO 43	SLIP
	MJNT = NQSJNT + N-1	DAUX12
	IJ = IJ+1	DAUX12
	IJK(MQ,MJNT) = IJ	DAUX12
	IJK(MJNT,MQ) = IJ+1	DAUX12

DO 42 I=1,3	DAUX12
DO 42 J=1,3	DAUX12
SN(I,J) = 0.0	DAUX12
DO 41 K=1,3	DAUX12
41 SN(I,J) = SN(I,J) + B12(I,K,2*M-1) * RPHI(K,M) * A22(K,J,2*N-2)	DAUX12
C(I,J,IJ) = -SN(I,J)	DAUX12
42 C(J,I,IJ+1) = -SN(I,J)	DAUX12
IJ = IJ+1	DAUX12
43 DO 49 L=N,NJNT	DAUX12
IF (L.EQ.M) GO TO 49	DAUX12
IF (IABS(JNT(L)).NE.N) GO TO 49	DAUX12
IF (FREE(L)) GO TO 49	SLIP
MJNT = NQSJNT + L	DAUX12
IJ = IJ+1	DAUX12
IJK(MQ,MJNT) = IJ	DAUX12
IJK(MJNT,MQ) = IJ+1	DAUX12
DO 48 I=1,3	DAUX12
DO 48 J=1,3	DAUX12
SN(I,J) = 0.0	DAUX12
DO 47 K=1,3	DAUX12
47 SN(I,J) = SN(I,J) + B12(I,K,2*M-1) * RPHI(K,M) * A22(K,J,2*L-1)	DAUX12
C(I,J,IJ) = SN(I,J)	DAUX12
48 C(J,I,IJ+1) = SN(I,J)	DAUX12
IJ = IJ + 1	DAUX12
49 CONTINUE	DAUX12
50 IF (M.EQ.NJNT) GO TO 60	DAUX12
IF (ISING(M+1).NE.0) GO TO 60	DAUX12
M1 = M+1	DAUX12
DO 59 L=M1,NJNT	DAUX12
IF (IABS(JNT(L)).NE.M1) GO TO 59	DAUX12
IF (FREE(L)) GO TO 59	SLIP
MJNT = NQSJNT + L	DAUX12
IJ = IJ+1	DAUX12
IJK(MQ,MJNT) = IJ	DAUX12
IJK(MJNT,MQ) = IJ+1	DAUX12
DO 58 I=1,3	DAUX12
DO 58 J=1,3	DAUX12
SM(I,J) = 0.0	DAUX12
DO 57 K=1,3	DAUX12
57 SM(I,J) = SM(I,J) + B12(I,K,2*M) * RPHI(K,M+1) * A22(K,J,2*L-1)	DAUX12
C(I,J,IJ) = SM(I,J)	DAUX12
58 C(J,I,IJ+1) = SM(I,J)	DAUX12
IJ = IJ + 1	DAUX12
59 CONTINUE	DAUX12
60 CONTINUE	DAUX12
CALL ELTIME(2,15)	DAUX12
RETURN	DAUX12
END	DAUX12



* + HB(J,2*M )**2 * RPHI(J,M+1)	DAUX22
IF (TEST) GO TO 64	DAUX22
CALL DOT31 (D(1,1,N),HB(1,2*M-1),BN)	DAUX22
DO 53 J=1,3	DAUX22
DO 53 I=1,3	DAUX22
53 HH(I,J) = AN*BN(I)*BN(J)	DAUX22
64 DO 67 I=1,3	DAUX22
RHS(I,MJNT) = -V2(I,M)	DAUX22
DO 66 J=1,3	DAUX22
RHS(I,MJNT) = RHS(I,MJNT) + A22(J,I,2*M-1)*U2(J,N )	DAUX22
* - A22(J,I,2*M )*U2(J,M+1)	DAUX22
SN(I,J) = 0.0	DAUX22
IF (TEST) GO TO 66	DAUX22
DO 65 K=1,3	DAUX22
65 SN(I,J) = SN(I,J) + A22(K,I,2*M-1) * RPHI(K,N ) * A22(K,J,2*M-1)	DAUX22
* + A22(K,I,2*M ) * RPHI(K,M+1) * A22(K,J,2*M )	DAUX22
66 C(I,J,IJ) = SN(I,J) + HH(I,J)	DAUX22
67 IF (TEST) C(I,I,IJ) = AN	DAUX22
IF (ISING(N).NE.0) GO TO 90	DAUX22
IF (N.EQ.1) GO TO 80	DAUX22
IF (FREE(N-1)) GO TO 80	SLIP
N1JNT = NQSJNT + N -1	DAUX22
IJ = IJ+1	DAUX22
IJK(MJNT,N1JNT) = IJ	DAUX22
IJK(N1JNT,MJNT) = IJ+1	DAUX22
DO 77 I=1,3	DAUX22
DO 77 J=1,3	DAUX22
SN(I,J) = 0.0	DAUX22
DO 76 K=1,3	DAUX22
76 SN(I,J) = SN(I,J) + A22(K,I,2*M-1) * RPHI(K,N ) * A22(K,J,2*M-2)	DAUX22
C(I,J,IJ) = -SN(I,J)	DAUX22
77 C(J,I,IJ+1) = -SN(I,J)	DAUX22
IJ = IJ+1	DAUX22
80 IF (M.EQ.NJNT) GO TO 90	DAUX22
M1 = M+1	DAUX22
DO 88 L=M1,NJNT	DAUX22
IF (IABS(JNT(L)).NE.N) GO TO 88	DAUX22
IF (FREE(L)) GO TO 88	SLIP
LJNT = NQSJNT + L	DAUX22
IJ = IJ+1	DAUX22
IJK(MJNT,LJNT) = IJ	DAUX22
IJK(LJNT,MJNT) = IJ+1	DAUX22
DO 87 I=1,3	DAUX22
DO 87 J=1,3	DAUX22
SN(I,J) = 0.0	DAUX22
DO 86 K=1,3	DAUX22
86 SN(I,J) = SN(I,J) + A22(K,I,2*M-1) * RPHI(K,N ) * A22(K,J,2*L-1)	DAUX22
C(I,J,IJ) = SN(I,J)	DAUX22
87 C(J,I,IJ+1) = SN(I,J)	DAUX22
IJ = IJ+1	DAUX22

88 CONTINUE  
90 CONTINUE  
CALL ELTIME(2,16)  
RETURN  
END

DAUX22  
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C	SUBROUTINE DAUX31	DAUX31
C		REV IV 07/24/86SLIP
C	CALLED BY SUBROUTINE DAUX TO COMPUTE	DAUX31
C		DAUX31
C	$(C13) = (B11)(M)^{-1} (A13) + (B12)(PHI)^{-1} (A23)$	DAUX31
C		DAUX31
C	$(C31) = (B31)(M)^{-1} (A11) + (B32)(PHI)^{-1} (A21)$	DAUX31
C		DAUX31
C	IMPLICIT REAL*8 (A-H,O-Z)	DAUX31
C	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	DAUX31
C	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
C	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),	SLIP
C	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),	DAUX31
C	* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)	DAUX31
C	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),	DAUX31
C	* F(3,30),TQ(3,30),WJ(30),A11(3,3,30)	SLIP
C	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),	DAUX31
C	* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),	DAUX31
C	* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),	DAUX31
C	* KQ1(12),KQ2(12),KQTYPE(12)	DAUX31
C	COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S	CHGIII
C	CALL ELTIME(1,17)	DAUX31
C	DO 30 N=1,NQ	DAUX31
C	IF (KQTYPE(N).LT.0) GO TO 30	DAUX31
C	K1 = KQ1(N)	DAUX31
C	K2 = KQ2(N)	DAUX31
C	NNS = NQ2S - NQ + N	DAUX31
C	IF (K1.LE.1) GO TO 13	DAUX31
C	IF (IABS(JNT(K1-1)).EQ.0) GO TO 13	DAUX31
C	IF (ISING(K1).NE.0) GO TO 13	DAUX31
C		DAUX31
C	$C13(K1-1,N) = B11(K1-1,K1)^{-1} M (K1) A13(K1,N)$	DAUX31
C	$+ B12(K1-1,K1)^{-1} PHI (K1) A23(K1,N)$	DAUX31
C		DAUX31
C	$C31(N,K1-1) = B31(N,K1)^{-1} M (K1) A11(K1,K1-1)$	DAUX31
C	$+ B32(N,K1)^{-1} PHI (K1) A21(K1,K1-1)$	DAUX31
C		DAUX31
C	MQ = NQ2S + K1 - 1	DAUX31
C	IJ = IJ+1	DAUX31
C	IJK(MQ,NNS) = IJ	DAUX31
C	IJK(NNS,MQ) = IJ+1	DAUX31
C	DO 12 I=1,3	DAUX31
C	DO 12 J=1,3	DAUX31
C	SUM = 0.0	SLIP







```

      C(I,J,IJ ) = 0.0
22  C(I,J,IJ+1) = 0.0
      IJ = IJ+1
23  JJ = IJK(MQ,NNS)
      DO 25 I=1,3
      DO 25 J=1,3
      SUM = C(I,J,JJ)
      TUM = C(I,J,JJ+1)
      DO 24 K=1,3
      SUM = SUM + B12(I,K,2*L-1)*RPHI(K,K2)*A23(K,J,2*N )
      *          + A11(I,K,L)*RW(K2)*A13(K,J,2*N)
24  TUM = TUM + B32(I,K,2*N )*RPHI(K,K2)*B12(J,K,2*L-1)
      *          + B31(I,K,2*N)*RW(K2)*A11(J,K,L)
      C(I,J,JJ) = SUM
25  C(I,J,JJ+1) = TUM
26  CONTINUE
30  CONTINUE
      CALL ELTIME(2,17)
      RETURN
      END

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	SUBROUTINE DAUX32	DAUX32
		REV IV 07/24/86SLIP
C	CALLED BY SUBROUTINE DAUX TO COMPUTE	DAUX32
C		DAUX32
C		DAUX32
C	-1	DAUX32
C	(C23) = (B22)(PHI) (A23)	DAUX32
C		DAUX32
C	-1	DAUX32
C	(C32) = (B32)(PHI) (A22)	DAUX32
C		DAUX32
	IMPLICIT REAL*8 (A-H,O-Z)	DAUX32
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	DAUX32
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),	SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),	DAUX32
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)	DAUX32
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),	DAUX32
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)	SLIP
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),	DAUX32
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),	DAUX32
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),	DAUX32
*	KQ1(12),KQ2(12),KQTYPE(12)	DAUX32
	LOGICAL*1 FREE	SLIP
	COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S	CHGIII
*	,DN(3,3),DM(3,3),BN(3),IDUM(416),FREE(30)	SLIP
	CALL ELTIME(1,18)	DAUX32
	NQSJNT = NQ2S + NJNT	DAUX32
	DO 60 N=1,NQ	DAUX32
	IF (KQTYPE(N).LT.0) GO TO 60	DAUX32
	K1 = KQ1(N)	DAUX32
	K2 = KQ2(N)	DAUX32
	NNS = NQ2S - NQ + N	DAUX32
	IF (K1.LE.1) GO TO 43	DAUX32
	IF (IABS(JNT(K1-1)).EQ.0) GO TO 43	DAUX32
	IF (FREE(K1-1)) GO TO 43	SLIP
	IF (ISING(K1).NE.0) GO TO 43	DAUX32
		DAUX32
	-1	DAUX32
C	C23(K1-1,N) = B22(K1-1,K1)PHI (K1)A23(K1,N)	DAUX32
C		DAUX32
C	-1	DAUX32
C	C32(N,K1-1) = B32(N,K1)PHI (K1)A22(K1,K1-1)	DAUX32
C		DAUX32
	KJNT = NQSJNT + K1 - 1	DAUX32
	IJ = IJ+1	DAUX32
	IJK(KJNT,NNS) = IJ	DAUX32
	IJK(NNS,KJNT) = IJ+1	DAUX32
	DO 42 I=1,3	DAUX32
	DO 42 J=1,3	DAUX32
	SUM = 0.0	DAUX32





RETURN  
END

DAUX32  
DAUX32

	SUBROUTINE DAUX33		DAUX33
		REV IV	07/24/86SLIP
C	CALL BY SUBROUTINE DAUX TO COMPUTE		DAUX33
C			DAUX33
C			DAUX33
C	(C33) = (B31)(M) <sup>-1</sup> (A13) + (B32)(PHI) <sup>-1</sup> (A23) - (B35)		DAUX33
C			DAUX33
C	(R3) = (B31)(M) <sup>-1</sup> (U1) + (B32)(PHI) <sup>-1</sup> (U2) - (V3)		DAUX33
C			DAUX33
C	IMPLICIT REAL*8 (A-H,O-Z)		DAUX33
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRMD,		DAUX33
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPET(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		DAUX33
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		DAUX33
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		DAUX33
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		DAUX33
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		DAUX33
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		DAUX33
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		DAUX33
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		DAUX33
*	KQ1(12),KQ2(12),KQTYPE(12)		DAUX33
	COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S		CHGIII
	CALL ELTIME(1,19)		DAUX33
	DO 90 N=1,NQ		DAUX33
	IF (KQTYPE(N).LT.0) GO TO 90		DAUX33
	K1 = KQ1(N)		DAUX33
	K2 = KQ2(N)		DAUX33
	NNS = NQ2S - NQ + N		DAUX33
C			DAUX33
C			DAUX33
C	RHS(N) = B31(N,K1)M <sup>-1</sup> (K1)U1(K1) + B32(N,K1)PHI <sup>-1</sup> (K1)U2(K1)		DAUX33
C			DAUX33
C	+ B31(N,K2)M <sup>-1</sup> (K2)U1(K2) + B32(N,K2)PHI <sup>-1</sup> (K2)U2(K2)		DAUX33
C			DAUX33
C	- V3(N)		DAUX33
C			DAUX33
	DO 63 I=1,3		DAUX33
	SUM = 0.0		DAUX33
	DO 62 K=1,3		DAUX33
62	SUM = SUM + B31(I,K,2*N-1)*U1(K,K1) + B32(I,K,2*N-1)*U2(K,K1)		DAUX33
*	+ B31(I,K,2*N)*U1(K,K2) + B32(I,K,2*N)*U2(K,K2)		DAUX33
63	RHS(I,NNS) = SUM - V3(I,N)		DAUX33
C			DAUX33
C			DAUX33
C	C33(N,N) = B31(N,K1)M <sup>-1</sup> (K1)A13(K1,N) + B32(N,K1)PHI <sup>-1</sup> (K1)A23(K1,N)		DAUX33
C			DAUX33
C	+ B31(N,K2)M <sup>-1</sup> (K2)A13(K2,N) + B32(N,K2)PHI <sup>-1</sup> (K2)A23(K2,N)		DAUX33

C		DAUX33
C	- B35(N,N)	DAUX33
C		DAUX33
	IJ = IJ+1	DAUX33
	IJK(MNS,NNS) = IJ	DAUX33
	IF (KQTYPE(N).EQ.2) GO TO 51	DAUX33
	IF (KQTYPE(N).EQ.4) GO TO 51	DAUX33
	DO 65 I=1,3	DAUX33
	DO 65 J=1,3	DAUX33
	SUM = -HHT(I,J,N)	DAUX33
	IF (I.EQ.J) SUM = 1.0+SUM	DAUX33
	DO 64 K=1,3	DAUX33
	64 SUM = SUM + B31(I,K,2*N-1)* RW( K1)*A13(K,J,2*N-1)	DAUX33
	* + B31(I,K,2*N )* RW( K2)*A13(K,J,2*N )	DAUX33
	* + B32(I,K,2*N-1)*RPHI(K,K1)*A23(K,J,2*N-1)	DAUX33
	* + B32(I,K,2*N )*RPHI(K,K2)*A23(K,J,2*N )	DAUX33
	65 C(I,J,IJ) = SUM	DAUX33
	GO TO 59	DAUX33
C		DAUX33
C	FOR KQTYPE = 2 OR 4, SET C33(N,N) = B*I	DAUX33
C	WHERE B = SUM OF DIAGONAL ELEMENTS OF	DAUX33
C	-1 -1	DAUX33
C	(B31)(M) (A13) + (B32)(PHI) (A23)	DAUX33
C		DAUX33
	51 SUM = 0.0	DAUX33
	DO 55 I=1,3	DAUX33
	DO 55 K=1,3	DAUX33
	55 SUM = SUM + B31(I,K,2*N-1)* RW( K1)*A13(K,I,2*N-1)	DAUX33
	* + B31(I,K,2*N )* RW( K2)*A13(K,I,2*N )	DAUX33
	* + B32(I,K,2*N-1)*RPHI(K,K1)*A23(K,I,2*N-1)	DAUX33
	* + B32(I,K,2*N )*RPHI(K,K2)*A23(K,I,2*N )	DAUX33
	DO 57 I=1,3	DAUX33
	DO 56 J=1,3	DAUX33
	56 C(I,J,IJ) = 0.0	DAUX33
	57 C(I,I,IJ) = SUM	DAUX33
	59 IF (N.EQ.NQ) GO TO 90	DAUX33
	N1 = N+1	DAUX33
	DO 85 M=N1,NQ	DAUX33
	IF (KQTYPE(M).LT.0) GO TO 85	DAUX33
	MNS = NQ2S - NQ + M	DAUX33
	IF (ISING(K1).NE.0) GO TO 75	DAUX33
	IF (K1.NE.KQ1(M)) GO TO 70	DAUX33
	IF (IJK(MNS,NNS).NE.0) GO TO 67	DAUX33
C		DAUX33
C	FOR ANY M>N SUCH THAT K1(N) = K1(M)	DAUX33
C		DAUX33
C		DAUX33
C	C33(N,M) = C(N,M) + B31(N,K1) M (K1)A13(K1,M)	DAUX33
C	-1	DAUX33
C	+ B32(N,K1)PHI (K1)A23(K1,M)	DAUX33
C		DAUX33



C			DAUX33
C			DAUX33
C			DAUX33
C			DAUX33
C			DAUX33
C			DAUX33
	IJ = IJ+1		DAUX33
	IJK(MNS,MNS) = IJ		DAUX33
	IJK(MNS,MNS) = IJ+1		DAUX33
	DO 66 J=1,3		DAUX33
	DO 66 I=1,3		DAUX33
	C(I,J,IJ) = 0.0		DAUX33
66	C(I,J,IJ+1) = 0.0		DAUX33
	IJ = IJ+1		DAUX33
67	JJ = IJK(MNS,MNS)		DAUX33
	DO 69 I=1,3		DAUX33
	DO 69 J=1,3		DAUX33
	SUM = C(I,J,JJ)		DAUX33
	TUM = C(I,J,JJ+1)		DAUX33
	DO 68 K=1,3		DAUX33
	SUM = SUM + B31(I,K,2*N-1)* RW( K1)*A13(K,J,2*M-1)		DAUX33
	* + B32(I,K,2*N-1)*RPHI(K,K1)*A23(K,J,2*M-1)		DAUX33
68	TUM = TUM + B31(I,K,2*M-1)* RW( K1)*A13(K,J,2*N-1)		DAUX33
	* + B32(I,K,2*M-1)*RPHI(K,K1)*A23(K,J,2*N-1)		DAUX33
	C(I,J,JJ) = SUM		DAUX33
69	C(I,J,JJ+1) = TUM		DAUX33
70	IF (K1.NE.KQ2(M)) GO TO 75		DAUX33
	IF (IJK(MNS,MNS).NE.0) GO TO 72		DAUX33
C			DAUX33
C			DAUX33
C	FOR ANY M>N SUCH THAT K1(N) = K2(M)		DAUX33
C			DAUX33
C			DAUX33
C			DAUX33
C			DAUX33
C			DAUX33
C			DAUX33
C			DAUX33
C			DAUX33
C			DAUX33
C			DAUX33
C			DAUX33
	IJ = IJ+1		DAUX33
	IJK(MNS,MNS) = IJ		DAUX33
	IJK(MNS,MNS) = IJ+1		DAUX33
	DO 71 J=1,3		DAUX33
	DO 71 I=1,3		DAUX33
	C(I,J,IJ) = 0.0		DAUX33
71	C(I,J,IJ+1) = 0.0		DAUX33
	IJ = IJ+1		DAUX33
72	JJ = IJK(MNS,MNS)		DAUX33

	DO 74 I=1,3	DAUX33
	DO 74 J=1,3	DAUX33
	SUM = C(I,J,JJ)	DAUX33
	TUM = C(I,J,JJ+1)	DAUX33
	DO 73 K=1,3	DAUX33
	SUM = SUM + B31(I,K,2*N-1)* RW( K1)*A13(K,J,2*M )	DAUX33
	* + B32(I,K,2*N-1)*RPHI(K,K1)*A23(K,J,2*M )	DAUX33
73	TUM = TUM + B31(I,K,2*M )* RW( K1)*A13(K,J,2*N-1)	DAUX33
	* + B32(I,K,2*M )*RPHI(K,K1)*A23(K,J,2*N-1)	DAUX33
	C(I,J,JJ ) = SUM	DAUX33
74	C(I,J,JJ+1) = TUM	DAUX33
75	IF (ISING(K2).NE.0) GO TO 85	DAUX33
	IF (K2.NE.KQ1(M)) GO TO 80	DAUX33
	IF (IJK(MNS,NNS).NE.0) GO TO 77	DAUX33
C		DAUX33
C	FOR ANY M>N SUCH THAT K2(N) = K1(M)	DAUX33
C		DAUX33
C		DAUX33
C	C33(N,M) = C(N,M) + B31(N,K2) M <sup>-1</sup> (K2)A13(K1,M)	DAUX33
C		DAUX33
C	+ B32(N,K2)PHI (K2)A23(K1,M)	DAUX33
C		DAUX33
C		DAUX33
C	C33(M,N) = C(M,N) + B31(M,K1) M <sup>-1</sup> (K2)A13(K2,N)	DAUX33
C		DAUX33
C	+ B32(M,K1)PHI (K2)A23(K2,N)	DAUX33
C		DAUX33
	IJ = IJ+1	DAUX33
	IJK(MNS,NNS) = IJ	DAUX33
	IJK(NNS,MNS) = IJ+1	DAUX33
	DO 76 J=1,3	DAUX33
	DO 76 I=1,3	DAUX33
	C(I,J,IJ ) = 0.0	DAUX33
76	C(I,J,IJ+1) = 0.0	DAUX33
	IJ = IJ+1	DAUX33
77	JJ = IJK(MNS,NNS)	DAUX33
	DO 79 I=1,3	DAUX33
	DO 79 J=1,3	DAUX33
	SUM = C(I,J,JJ)	DAUX33
	TUM = C(I,J,JJ+1)	DAUX33
	DO 78 K=1,3	DAUX33
	SUM = SUM + B31(I,K,2*N )* RW( K2)*A13(K,J,2*M-1)	DAUX33
	* + B32(I,K,2*N )*RPHI(K,K2)*A23(K,J,2*M-1)	DAUX33
78	TUM = TUM + B31(I,K,2*M-1)* RW( K2)*A13(K,J,2*N )	DAUX33
	* + B32(I,K,2*M-1)*RPHI(K,K2)*A23(K,J,2*N )	DAUX33
	C(I,J,JJ ) = SUM	DAUX33
79	C(I,J,JJ+1) = TUM	DAUX33
80	IF (K2.NE.KQ2(M)) GO TO 85	DAUX33
	IF (IJK(MNS,NNS).NE.0) GO TO 82	DAUX33
C		DAUX33

C	FOR ANY M>N SUCH THAT K2(N) = K2(M)	DAUX33
C		DAUX33
C		DAUX33
C	$C33(N,M) = C(N,M) + B31(N,K2) M^{-1} (K2) A13(K2,M)$	DAUX33
C		DAUX33
C	$+ B32(N,K2) PHI^{-1} (K2) A23(K2,M)$	DAUX33
C		DAUX33
C		DAUX33
C	$C33(M,N) = C(M,N) + B31(M,K2) M^{-1} (K2) A13(K2,N)$	DAUX33
C		DAUX33
C	$+ B32(M,K2) PHI^{-1} (K2) A23(K2,N)$	DAUX33
C		DAUX33
	IJ = IJ+1	DAUX33
	IJK(MNS,NNS) = IJ	DAUX33
	IJK(NNS,MNS) = IJ+1	DAUX33
	DO 81 J=1,3	DAUX33
	DO 81 I=1,3	DAUX33
	C(I,J,IJ) = 0.0	DAUX33
81	C(I,J,IJ+1) = 0.0	DAUX33
	IJ = IJ+1	DAUX33
82	JJ = IJK(MNS,NNS)	DAUX33
	DO 84 I=1,3	DAUX33
	DO 84 J=1,3	DAUX33
	SUM = C(I,J,JJ)	DAUX33
	TUM = C(I,J,JJ+1)	DAUX33
	DO 83 K=1,3	DAUX33
	SUM = SUM + B31(I,K,2*N) * RW(K2) * A13(K,J,2*M)	DAUX33
	* + B32(I,K,2*N) * RPHI(K,K2) * A23(K,J,2*M)	DAUX33
83	TUM = TUM + B31(I,K,2*M) * RW(K2) * A13(K,J,2*N)	DAUX33
	* + B32(I,K,2*M) * RPHI(K,K2) * A23(K,J,2*N)	DAUX33
	C(I,J,JJ) = SUM	DAUX33
84	C(I,J,JJ+1) = TUM	DAUX33
85	CONTINUE	DAUX33
90	CONTINUE	DAUX33
	CALL ELTIME(2,19)	DAUX33
	RETURN	DAUX33
	END	DAUX33

C

SUBROUTINE DAUX44		DAUX44
	REV IV 07/24/86SLIP	DAUX44
IMPLICIT REAL*8(A-H,O-Z)		DAUX44
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		DAUX44
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		DAUX44
* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		DAUX44
COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		DAUX44
* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		DAUX44
COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		DAUX44
* F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		DAUX44
* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		DAUX44
* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		DAUX44
* KQ1(12),KQ2(12),KQTYPE(12)		DAUX44
COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)		DAUX44
LOGICAL*1 FREE		SLIP
COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S		CHGIII
* ,IDUM(458),FREE(30)		SLIP
IF (NFLX.EQ.0) GO TO 99		DAUX44
CALL ELTIME(1,33)		DAUX44
DO 90 L=1,NFLX		DAUX44
N1 = NFLEX(1,L)		DAUX44
N2 = NFLEX(2,L)		DAUX44
N3 = NFLEX(3,L)		DAUX44
IJ = IJ+1		DAUX44
DO 10 I=1,3		DAUX44
DO 10 J=1,3		DAUX44
C(I,J,IJ) = 0.0		DAUX44
DO 10 K=1,3		DAUX44
10 C(I,J,IJ) = C(I,J,IJ) + B42(I,K,3*L-2)*RPHI(K,N1)*B42(J,K,3*L-2)		DAUX44
* + B42(I,K,3*L-1)*RPHI(K,N2)*B42(J,K,3*L-1)		DAUX44
* + B42(I,K,3*L )*RPHI(K,N3)*B42(J,K,3*L )		DAUX44
NSL = 2*NS+L		DAUX44
IJK(NSL,NSL) = IJ		DAUX44
DO 20 I=1,3		DAUX44
RHS(I,NSL) = -V4(I,L)		DAUX44
DO 20 J=1,3		DAUX44
20 RHS(I,NSL) = RHS(I,NSL) + B42(I,J,3*L-2)*U2(I,N1)		DAUX44
* + B42(I,J,3*L-1)*U2(I,N2)		DAUX44
* + B42(I,J,3*L )*U2(I,N3)		DAUX44
IF (L.EQ.NFLX) GO TO 30		DAUX44
LP1 = L+1		DAUX44
DO 29 M=LP1,NFLX		DAUX44
DO 28 II=1,3,2		DAUX44
IL = NFLEX(II,L)		DAUX44
IF (ISING(IL).NE.0) GO TO 28		DAUX44
DO 27 JJ=1,3,2		DAUX44
IF (NFLEX(II,L).NE.NFLEX(JJ,M)) GO TO 27		DAUX44

NSM = 2*NS+M	DAUX44
JK = IJK(NSL,NSM)	DAUX44
KJ = IJK(NSM,NSL)	DAUX44
IF (JK.GT.0) GO TO 22	DAUX44
IJK(NSL,NSM) = IJ+1	DAUX44
IJK(NSM,NSL) = IJ+2	DAUX44
JK = IJ+1	DAUX44
KJ = IJ+2	DAUX44
IJ = IJ+2	DAUX44
DO 21 I=1,3	DAUX44
DO 21 J=1,3	DAUX44
21 C(I,J,JK) = 0.0	DAUX44
22 LI = 3*L+II-3	DAUX44
MJ = 3*M+JJ-3	DAUX44
DO 24 I=1,3	DAUX44
DO 24 J=1,3	DAUX44
DO 23 K=1,3	DAUX44
23 C(I,J,JK) = C(I,J,JK) + B42(I,K,LI)*RPHI(K,IL)*B42(J,K,MJ)	DAUX44
24 C(J,I,KJ) = C(I,J,JK)	DAUX44
27 CONTINUE	DAUX44
28 CONTINUE	DAUX44
29 CONTINUE	DAUX44
30 IF (NQ.EQ.0) GO TO 40	DAUX44
DO 39 M=1,NQ	DAUX44
IF (KQTYPE(M).LT.0) GO TO 39	DAUX44
DO 38 II=1,3	DAUX44
LM = 0	DAUX44
IF (NFLEX(II,L).EQ.KQ1(M)) LM = 2*M-1	DAUX44
IF (NFLEX(II,L).EQ.KQ2(M)) LM = 2*M	DAUX44
IF (LM.EQ.0) GO TO 38	DAUX44
IL = NFLEX(II,L)	DAUX44
IF (ISING(IL).NE.0) GO TO 38	DAUX44
NSM = 2*NS+NFLX+M	DAUX44
JK = IJK(NSL,NSM)	DAUX44
KJ = IJK(NSM,NSL)	DAUX44
IF (JK.GT.0) GO TO 32	DAUX44
IJK(NSL,NSM) = IJ+1	DAUX44
IJK(NSM,NSL) = IJ+2	DAUX44
JK = IJ+1	DAUX44
KJ = IJ+2	DAUX44
IJ = IJ+2	DAUX44
DO 31 I=1,3	DAUX44
DO 31 J=1,3	DAUX44
C(I,J,JK) = 0.0	DAUX44
31 C(I,J,KJ) = 0.0	DAUX44
32 LI = 3*L+II-3	DAUX44
DO 33 I=1,3	DAUX44
DO 33 J=1,3	DAUX44
DO 33 K=1,3	DAUX44
C(I,J,JK) = C(I,J,JK) + B42(I,K,LI)*RPHI(K,IL)*A23(K,J,LM)	DAUX44

33 C(I,J,KJ) = C(I,J,KJ) + B32(I,K,LM)*RPHI(K,IL)*B42(J,K,LI)	DAUX44
38 CONTINUE	DAUX44
39 CONTINUE	DAUX44
40 IF (NJNT.EQ.0) GO TO 90	DAUX44
DO 59 M=1,NJNT	DAUX44
IF (JNT(M).EQ.0) GO TO 59	DAUX44
DO 58 II=1,3	DAUX44
LM = 0	DAUX44
IF (NFLEX(II,L).EQ.IABS(JNT(M))) LM = 2*M-1	DAUX44
IF (NFLEX(II,L).EQ.M+1) LM = 2*M	DAUX44
IF (LM.EQ.0) GO TO 58	DAUX44
IL = NFLEX(II,L)	DAUX44
IF (ISING(IL).NE.0) GO TO 58	DAUX44
NSM = 2*NS+NFLX+NQ+M	DAUX44
JK = IJK(NSL,NSM)	DAUX44
KJ = IJK(NSM,NSL)	DAUX44
IF (JK.GT.0) GO TO 42	DAUX44
IJK(NSL,NSM) = IJ+1	DAUX44
IJK(NSM,NSL) = IJ+2	DAUX44
JK = IJ+1	DAUX44
KJ = IJ+2	DAUX44
IJ = IJ+2	DAUX44
DO 41 I=1,3	DAUX44
DO 41 J=1,3	DAUX44
41 C(I,J,JK) = 0.0	DAUX44
42 LI = 3*L+II-3	DAUX44
DO 44 I=1,3	DAUX44
DO 44 J=1,3	DAUX44
DO 43 K=1,3	DAUX44
43 C(I,J,JK) = C(I,J,JK) + B42(I,K,LI)*RPHI(K,IL)*B12(J,K,LM)	DAUX44
44 C(J,I,KJ) = C(I,J,JK)	DAUX44
IF (FREE(M)) GO TO 58	SLIP
NSM = 2*NS+NFLX+NQ+NJNT+M	DAUX44
JK = IJK(NSL,NSM)	DAUX44
KJ = IJK(NSM,NSL)	DAUX44
IF (JK.GT.0) GO TO 52	DAUX44
IJK(NSL,NSM) = IJ+1	DAUX44
IJK(NSM,NSL) = IJ+2	DAUX44
JK = IJ+1	DAUX44
KJ = IJ+2	DAUX44
IJ = IJ+2	DAUX44
DO 51 I=1,3	DAUX44
DO 51 J=1,3	DAUX44
51 C(I,J,JK) = 0.0	DAUX44
52 SET = 1.0	DAUX44
IF (IL.EQ.M+1) SET = -1.0	DAUX44
DO 54 I=1,3	DAUX44
DO 54 J=1,3	DAUX44
DO 53 K=1,3	DAUX44
53 C(I,J,JK) = C(I,J,JK) + SET*B42(I,K,LI)*RPHI(K,IL)*A22(K,J,LM)	DAUX44

54 C(J,I,KJ) = C(I,J,JK)  
58 CONTINUE  
59 CONTINUE  
90 CONTINUE  
CALL ELTIME(2,33)  
99 RETURN  
END

DAUX44  
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DAUX44

	SUBROUTINE DAUX55		DAUX55
C		REV IV 07/24/86	SLIP
	IMPLICIT REAL*8(A-H,O-Z)		DAUX55
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		DAUX55
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		DAUX55
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		DAUX55
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		DAUX55
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		DAUX55
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		DAUX55
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		DAUX55
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		DAUX55
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		DAUX55
*	KQ1(12),KQ2(12),KQTYPE(12)		DAUX55
	COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)		DAUX55
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		DAUX55
*	UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	LOGICAL*1 FREE		SLIP
	COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S		CHGIII
*	,IDUM(458),FREE(30)		SLIP
	CALL ELTIME(1,30)		DAUX55
	IS = 0		DAUX55
	DO 99 I=1,NGRND		DAUX55
	IF (ISING(I).LE.0) GO TO 99		DAUX55
	IS = IS+1		DAUX55
	IJ = IJ+1		DAUX55
	IJK(IS,IS) = IJ		DAUX55
	IJK(IS+1,IS+1) = IJ+1		DAUX55
	DO 11 J=1,3		DAUX55
	RHS(J,IS) = U1(J,I) + W(I)*GRAVITY(J)/G		DAUX55
	RHS(J,IS+1) = U2(J,I)		DAUX55
	U1(J,I) = 0.0		DAUX55
	U2(J,I) = 0.0		DAUX55
	DO 10 K=1,3		DAUX55
	C(J,K,IJ) = 0.0		DAUX55
10	C(J,K,IJ+1) = 0.0		DAUX55
	C(J,J,IJ) = W(I)/G		DAUX55
11	C(J,J,IJ+1) = PHI(J,I)		DAUX55
	IJ = IJ+1		DAUX55
	IF (NFLX.EQ.0) GO TO 19		DAUX55
	DO 15 N=1,NFLX		DAUX55
	LN = 0		DAUX55
	IF (NFLEX(1,N).EQ.1) LN = 3*N-2		DAUX55
	IF (NFLEX(2,N).EQ.1) LN = 3*N-1		DAUX55
	IF (NFLEX(3,N).EQ.1) LN = 3*N		DAUX55
	IF (LN.EQ.0) GO TO 15		DAUX55
	DO 14 J=1,3		DAUX55
	DO 14 K=1,3		DAUX55



C(J,K,IJ+1) = B42(K,J,LN)	DAUX55
14 C(J,K,IJ+2) = B42(J,K,LN)	SLIP
NNS = 2*NS+N	DAUX55
IJK(IS+1,NNS) = IJ+1	DAUX55
IJK(NNS,IS+1) = IJ+2	DAUX55
IJ = IJ+2	DAUX55
15 CONTINUE	DAUX55
19 IF (NQ.EQ.0) GO TO 30	DAUX55
DO 25 N=1,NQ	DAUX55
IF (KQTYPE(N).LT.0) GO TO 25	DAUX55
LN = 0	DAUX55
IF (I.EQ.KQ1(N)) LN = 2*N-1	DAUX55
IF (I.EQ.KQ2(N)) LN = 2*N	DAUX55
IF (LN.EQ.0) GO TO 25	DAUX55
DO 20 J=1,3	DAUX55
DO 20 K=1,3	DAUX55
C(J,K,IJ+1) = A13(J,K,LN)	DAUX55
C(J,K,IJ+2) = A23(J,K,LN)	DAUX55
C(J,K,IJ+3) = B31(J,K,LN)	SLIP
20 C(J,K,IJ+4) = B32(J,K,LN)	SLIP
NNS = 2*NS+NFLX+N	DAUX55
IJK(IS ,NNS) = IJ+1	DAUX55
IJK(IS+1,NNS) = IJ+2	DAUX55
IJK(NNS,IS ) = IJ+3	DAUX55
IJK(NNS,IS+1) = IJ+4	DAUX55
IJ = IJ+4	DAUX55
25 CONTINUE	DAUX55
30 IF (NJNT.EQ.0) GO TO 98	DAUX55
DO 65 N=1,NJNT	DAUX55
IF (JNT(N).EQ.0) GO TO 65	DAUX55
LN = 0	DAUX55
IF (I.EQ.IABS(JNT(N))) LN = 2*N-1	DAUX55
IF (I.EQ.N+1) LN = 2*N	DAUX55
IF (LN.EQ.0) GO TO 65	DAUX55
SET = 1.0	DAUX55
IF (I.EQ.N+1) SET = -1.0	DAUX55
DO 40 J=1,3	DAUX55
DO 40 K=1,3	SLIP
C(J,K,IJ+1) = SET*A11(J,K,N)	SLIP
C(J,K,IJ+3) = SET*A11(K,J,N)	SLIP
C(J,K,IJ+2) = B12(K,J,LN)	DAUX55
40 C(J,J,IJ+4) = B12(J,K,LN)	SLIP
NNS = NQ2S + N	DAUX55
IJK(IS ,NNS) = IJ+1	DAUX55
IJK(IS+1,NNS) = IJ+2	DAUX55
IJK(NNS,IS ) = IJ+3	DAUX55
IJK(NNS,IS+1) = IJ+4	DAUX55
IJ = IJ+4	DAUX55
IF (FREE(N)) GO TO 65	SLIP
DO 60 J=1,3	DAUX55

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DO 60 K=1,3
C(J,K,IJ+1) = SET*A22(J,K,LN)
60 C(J,K,IJ+2) = SET*A22(K,J,LN)
NNS = NQ2S + MJNT + N
IJK(IS+1,NNS) = IJ+1
IJK(NNS,IS+1) = IJ+2
IJ = IJ+2
65 CONTINUE
98 IS = IS+1
99 CONTINUE
CALL ELTIME(2,30)
RETURN
END

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DAUX55
DAUX55
SLIP
DAUX55
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DAUX55
DAUX55
DAUX55

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	SUBROUTINE DHPIN(DD,BN,L,M,N)		DHPIN
C		REV IV	07/24/86SLIP
C	SETS DD = D(L) IF JOINT M IS NOT PINNED		DHPIN
C	OR DD = (I-HH.)(D(L)) IF PINNED		DHPIN
C			DHPIN
	IMPLICIT REAL*8 (A-H,O-Z)		DHPIN
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		DHPIN
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		DHPIN
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		DHPIN
	* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		DHPIN
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),		JDRIFT
	* FE(3,30),TQE(3,30),CONST(5,30)		JDRIFT
	DIMENSION DD(3,3),BN(3)		DHPIN
	DO 10 J=1,3		DHPIN
	BN(J) = 0.0		DHPIN
	DO 10 I=1,3		DHPIN
10	DD(I,J) = D(I,J,L)		DHPIN
	LGO = IPIN(M)+8		SLIP
	TSIGN = -1.0		DHPIN
	GO TO (90,90,90,20,90,90,90,90,90,30,90,90,90,90,30,30),LGO		SLIP
20	IF (IEULER(M).GE.7) GO TO 90		DHPIN
	IF (IEULER(M).GE.4) GO TO 30		DHPIN
	TSIGN = 1.0		DHPIN
	DO 21 J=1,3		DHPIN
	DO 21 I=1,3		DHPIN
21	DD(I,J) = 0.0		DHPIN
30	DO 31 J=1,3		DHPIN
	BN(J) = HB(1,N)*D(1,J,L) + HB(2,N)*D(2,J,L) + HB(3,N)*D(3,J,L)		DHPIN
	DO 31 I=1,3		DHPIN
31	DD(I,J) = DD(I,J) + TSIGN*BN(J)*HB(I,N)		DHPIN
90	RETURN		DHPIN
	END		DHPIN

	SUBROUTINE DINT	DINT
C		REV IV 07/23/86TWOPI
	IMPLICIT REAL*8 (A-H,O-Z)	DINT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	DINT
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/INTEST/ SGTEST(3,4,30),XTEST(360 ),SEGT(120),REGT(120)	DINT
C	NOTE: XTEST SINGLY DIMENSIONED HERE.	DINT
	REAL SEGT	DINT
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	DINT
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
	COMMON/CDINT/ UU(4),GH(3,4),	DINT
	* E(3,240), F(5,240),GG(5,240),Y(5,240),U(5,240),	DINT
	* H,HPRINT,HS,TPRINT,TSTART,ICNT,IDBL,IFLAG	DINT
	COMMON/COMAIN/ VAR(240),DER(240),DT,H0,HMAX,HMIN,RSTIME,	DINT
	* ISTEP,NSTEPS,NDINT,NEQ,IRSIN,IRSOUT	DINT
	LOGICAL LNRT	TGMOD1
	CALL ELTIME(1,3)	DINT
	IF (ISTEP.NE.0) GO TO 11	DINT
C		DINT
C	IN=0: INITIAL CALL TO INTEGRATOR - INITIALIZE AND RESET PARAMETERS	DINT
C	NOTE: FOR EARLIER VERSIONS OF CVS, THE VARIABLE 'IN'(ISTEP IN THE	DINT
C	CALLING PROGRAM) RAN FROM 1 TO NSTEPS+1, NOW IT RUNS FROM	DINT
C	0 TO NSTEPS.	DINT
C		DINT
	TPRINT = TIME	DINT
	IDBL = 2	DINT
	K = 0	DINT
	GO TO 13	DINT
C		DINT
C	IN=0: ADVANCE TPRINT - TIME TO RETURN TO CALLING PROGRAM.	DINT
C		DINT
11	TPRINT = TPRINT + DT	DINT
	H = HPRINT	DINT
C		DINT
C	ENTRY TO ADVANCE INTEGRATOR	DINT
C		DINT
12	K = 1	DINT
	CALL UPDATE(K)	DINT
C		DINT
C	NEGATIVE K FROM UPDATE IS INDICATOR TO RESET INTEGRATOR.	DINT
C		DINT
	IF (K.EQ.1) GO TO 15	DINT
C		DINT
C	RESET OR INITIALIZE INTEGRATOR.	DINT
C		DINT
13	H = H0	DINT
	HPRINT = H0	DINT
	HS = 0.0	DINT
	ICNT = -2	DINT
	IF (ISTEP.EQ.0 .OR. NPRT(26).EQ.2) CALL OUTPUT(0)	DINT

	CALL PDAUX (VAR,DER,NEQ,K)	DINT
	IF (ISTEP.NE.0 .AND. NPRT(26).EQ.2) CALL OUTPUT(1)	DINT
	DO 14 I=1,NEQ	DINT
	F(1,I) = VAR(I)	DINT
	F(2,I) = DER(I)	DINT
	DO 14 J=3,5	DINT
	F(J,I) = 0.0	DINT
	U(J,I) = 0.0	DINT
14	Y(J,I) = 0.0	DINT
	IF (ISTEP.EQ.0) GO TO 65	DINT
	K = 1	DINT
C		DINT
C	ADJUST H (CURRENT TIME STEP) IF IT WILL ADVANCE T BEYOND TPRINT.	DINT
C		DINT
15	IF (H+EPS(8).GE.TPRINT-TIME) H = TPRINT-TIME	DINT
C		DINT
C	BACKUP ENTRY POINT IF H HAS BEEN HALVED.	DINT
C		DINT
16	D1 = 0.5*H	DINT
	CALL TRIGFS	DINT
	TSTART = TIME	DINT
	DO 20 I=1,NEQ	DINT
	U(3,I) = Y(5,I)	DINT
	U(4,I) = U(5,I)	DINT
	DO 20 J=1,5	DINT
20	GG(J,I) = F(J,I)	DINT
	CALL CMPUTE (K,1,D1)	DINT
	IF (K.LT.0) GO TO 50	DINT
	CALL ADJUST (1,D1)	DINT
	K = 2	DINT
	CALL CMPUTE (K,0,D1)	DINT
	IF (K.LT.0) GO TO 50	DINT
	CALL ADJUST (2,D1)	DINT
	NQUAT = K	DINT
	K = 3	DINT
	CALL CMPUTE (K,1, H)	DINT
	IF (K.LT.0) GO TO 50	DINT
	CALL ADJUST (3,D1)	DINT
	DO 49 L=1,NDINT	DINT
	M = 1	DINT
	IF (L.EQ.1) M = 0	DINT
	IF (NPRT(26).NE.2) CALL OUTPUT(0)	DINT
	CALL CMPUTE (K,M, H)	DINT
	IF (K.LT.0) GO TO 50	DINT
	FAIL = 1.0	DINT
	JJ = 0	DINT
	DO 47 II=1,NEQ,3	DINT
	JJ = JJ+1	DINT
	IF (XTEST(II).LE.0.0) GO TO 47	DINT
	TT = DER(II)**2 + DER(II+1)**2 + DER(II+2)**2	DINT

	TX = VAR(II)**2 + VAR(II+1)**2 + VAR(II+2)**2	DINT
	TE = 0.0	DINT
	TY = 0.0	DINT
	I2 = II+2	DINT
	DO 45 I=II,I2	DINT
	Z = GG(5,I)*(VAR(I)-GG(1,I)) + GG(2,I) + H*(GG(3,I)+H*GG(4,I))	DINT
	TE = TE + (DER(I)-Z)**2	DINT
	TYD = TT + TX*GG(5,I)**2	DINT
	IF (TYD.EQ.0.0) TYD = 1.0	DINT
45	TY = TY + (DER(I)-Z)**2/TYD	DINT
	TM = 1000.0*TIME	DINT
	IF (NPRT(25).NE.0) WRITE (6,46) TM,SEGT(JJ),REGT(JJ),TT,TE,TY,	DINT
	* (XTEST(I),I=II,I2)	DINT
46	FORMAT ('0 DINT CONV. TEST',F10.3,2X,A4,2X,A8,6G12.4)	DINT
	IF (TT.LT.XTEST(II)) GO TO 47	DINT
	IF (XTEST(II+1).GT.0.0 .AND. TE.LT.XTEST(II+1)) GO TO 47	DINT
	IF (TY.GT.XTEST(II+2)) GO TO 48	DINT
47	CONTINUE	DINT
	FAIL = 0.0	DINT
48	CALL ADJUST (4,D1)	DINT
	IF (FAIL.EQ.0.0) GO TO 60	DINT
	IF (L.EQ.NDINT) GO TO 49	DINT
	CALL CMPUTE (K,1,D1)	DINT
	IF (K.LT.0) GO TO 50	DINT
	CALL ADJUST (5,D1)	DINT
49	CONTINUE	DINT
	IF (NPRT(25).EQ.0) WRITE (6,46) TM,SEGT(JJ),REGT(JJ),TT,TE,TY,	DINT
	* (XTEST(I),I=II,I2)	DINT
50	WRITE (6,51) TIME,H	DINT
51	FORMAT('0 TEST FAILED AT TIME = ',F10.6,' FOR H = ',F10.6)	DINT
	ICNT = 0	DINT
	IDBL = IDBL+2	DINT
	IF (IDBL.GT.6) IDBL = 6	DINT
	IF (K.GE.0) GO TO 58	DINT
	IF (H.GT.HMIN+EPS(8)) GO TO 59	DINT
	WRITE (6,52)	DINT
52	FORMAT('0 PROGRAM TERMINATED. PDAUX NEG SQRT. H < HMIN+EPS8.'/'	DINT
	* ' RERUN PROGRAM WITH SMALLER HMIN ON INPUT CARD A.4')	DINT
	STOP 31	DINT
58	IF (H.LE.HMIN+EPS(8)) GO TO 61	DINT
	IF (NPRT(26).EQ.2) CALL OUTPUT(1)	DINT
59	TIME = TSTART	DINT
	H = 0.5*H	DINT
	HPRINT = 0.5*HPRINT	DINT
	K = 2	DINT
	GO TO 16	DINT
60	IF (H.GT.0.74*HPRINT) ICNT = ICNT+1	DINT
61	K = 4	DINT
	M = 0	DINT
	IF (H.GT.HMIN .AND. IDBL.GT.2) IDBL = IDBL-1	DINT

GG4 = 2.0*H	DINT
GG5 = DEXP(-1600.0*H)	DINT
DO 63 I=1,NEQ	DINT
F(3,I) = GG(3,I) + GG4*GG(4,I)	DINT
F(4,I) = GG(4,I)	DINT
F(5,I) = GG(5,I)	DINT
Y(3,I) = Y(1,I)	DINT
Y(4,I) = Y(2,I)	DINT
Y(5,I) = GG5*U(3,I)	DINT
63 U(5,I) = GG5*U(4,I)	DINT
CALL QSET(F,Y,VAR,DER,NQUAT)	DINT
CALL PDAUX (VAR,DER,M,K)	DINT
DO 64 I=1,NEQ	DINT
F(1,I) = VAR(I)	DINT
64 F(2,I) = DER(I)	DINT
HS = H	DINT
IF (ICNT.LT.IDBL) GO TO 65	DINT
ICNT = 0	DINT
H = DMIN1(2.0*H,HMAX)	DINT
HPRINT = DMIN1(2.0*HPRINT,HMAX)	DINT
65 CALL UPDATE(2)	DINT
XPRINT = TPRINT - TIME	TGMOD1
IF(XPRINT.GE.EPS(8).AND.NPRT(26).NE.3.AND.NPRT(26).GE.0)	TGMOD1
* CALL OUTPUT(1)	TGMOD1
IF(XPRINT.GE.EPS(8)) GO TO 12	TGMOD1
LNRT = .FALSE.	TGMOD1
IF(NPRT(26).GE.0) LNRT = .TRUE.	TGMOD1
IF(NPRT(26).LT.0) INRT = IABS(NPRT(26))	TGMOD1
IF(NPRT(26).LT.0) LNRT = (MOD(ISTEP,INRT).EQ.0)	TGMOD1
IF(LNRT) CALL OUTPUT(1)	TGMOD1
CALL ELTIME(2,3)	DINT
RETURN	DINT
END	DINT

	SUBROUTINE DOTT31 (A,B,C)		DOTT31
C		REV 17	12/20/76DOTT31
C	PERFORMS MATRIX MULTIPLICATION $C = AB'$		DOTT31
C	WHERE C IS A 3X3 MATRIX, AND A AND B ARE VECTORS OF LENGTH 3.		DOTT31
C			DOTT31
	IMPLICIT REAL*8 (A-H,O-Z)		DOTT31
	DIMENSION A(3) , B(3) , C(3,3)		DOTT31
	DO 10 I=1,3		DOTT31
	DO 10 J=1,3		DOTT31
10	C(I,J) = A(I)*B(J)		DOTT31
	RETURN		DOTT31
	END		DOTT31



	SUBROUTINE DOTT33 (A,B,C)		DOTT33
C		REV 17	01/03/77DOTT33
C	PERFORMS MATRIX MULTIPLICATION C = AB'		DOTT33
C	WHERE A, B AND C ARE ALL 3X3 MATRICES.		DOTT33
C			DOTT33
	IMPLICIT REAL*8 (A-H,O-Z)		DOTT33
	DIMENSION A(3,3) , B(3,3) , C(3,3)		DOTT33
	DO 10 I=1,3		DOTT33
	DO 10 J=1,3		DOTT33
10	C(I,J) = A(I,1)*B(J,1) + A(I,2)*B(J,2) + A(I,3)*B(J,3)		DOTT33
	RETURN		DOTT33
	END		DOTT33

	SUBROUTINE DOT31 (A,B,C)		DOT31
		REV 17    01/03/77	DOT31
C	PERFORMS MATRIX MULTIPLICATION $C = A'B$		DOT31
C	WHERE A IS A 3X3 MATRIX, AND B AND C ARE VECTORS OF LENGTH 3.		DOT31
C			DOT31
C	IMPLICIT REAL*8 (A-H,O-Z)		DOT31
	DIMENSION A(3,3) , B(3) , C(3)		DOT31
	$C(1) = A(1,1)*B(1) + A(2,1)*B(2) + A(3,1)*B(3)$		DOT31
	$C(2) = A(1,2)*B(1) + A(2,2)*B(2) + A(3,2)*B(3)$		DOT31
	$C(3) = A(1,3)*B(1) + A(2,3)*B(2) + A(3,3)*B(3)$		DOT31
	RETURN		DOT31
	END		DOT31

	SUBROUTINE DOT33 (A,B,C)		DOT33
C		REV 17	01/03/77DOT33
C	PERFORMS MATRIX MULTIPLICATION C = A'B		DOT33
C	WHERE A, B AND C ARE ALL 3X3 MATRICES.		DOT33
C			DOT33
	IMPLICIT REAL*8 (A-H,O-Z)		DOT33
	DIMENSION A(3,3) , B(3,3) , C(3,3)		DOT33
	DO 10 I=1,3		DOT33
	DO 10 J=1,3		DOT33
10	C(I,J) = A(1,I)*B(1,J) + A(2,I)*B(2,J) + A(3,I)*B(3,J)		DOT33
	RETURN		DOT33
	END		DOT33

	SUBROUTINE DRCIJK (D,ANG,ID,HT,J)		DRCIJK
C		REV 18	02/24/78DRCIJK
	IMPLICIT REAL*8 (A-H,O-Z)		DRCIJK
	DIMENSION D(9,22),HT(9,42),ANG(3,22),ID(4,22),T1(9),T2(9)		DRCIJK
	M = ID(4,J)		DRCIJK
	IF (M.NE.0) GO TO 10		DRCIJK
	CALL DRCYPR (D(1,J),ANG(1,J),ID(1,J))		DRCIJK
	GO TO 99		DRCIJK
10	CALL DRCYPR (T1,ANG(1,J),ID(1,J))		DRCIJK
	IF (M.LT.0) GO TO 20		DRCIJK
	CALL MAT33 (T1,D(1,M),D(1,J))		DRCIJK
	GO TO 99		DRCIJK
20	M = -M		DRCIJK
	CALL DOT33 (HT(1,2*J-3),D(1,M),D(1,J))		DRCIJK
	CALL MAT33 (T1,D(1,J),T2)		DRCIJK
	CALL MAT33 (HT(1,2*J-2),T2,D(1,J))		DRCIJK
99	RETURN		DRCIJK
	END		DRCIJK

	SUBROUTINE DRCQUA(DC,Q)	DRCQUA
		REV III.5 07/31/85JTF785
C	COMPUTES DIRECTION COSINE MATRIX FROM QUATERNIONS	DRCQUA
C	IMPLICIT REAL*8(A-H,O-Z)	DRCQUA
	DIMENSION DC(3,3),Q(4)	DRCQUA
	C = Q(1)**2 - Q(2)**2 - Q(3)**2 - Q(4)**2	JTF785
	DO 12 I = 1,3	DRCQUA
	DO 10 J = 1,3	DRCQUA
10	DC(I,J) = 2.0*Q(I+1)*Q(J+1)	DRCQUA
12	DC(I,I) = DC(I,I) + C	DRCQUA
	E = Q(1) + Q(1)	DRCQUA
	DO 14 I = 1,3	DRCQUA
	J = 1 + MOD(I,3)	DRCQUA
	K = 1 + MOD(I+1,3)	DRCQUA
	D = E*Q(I+1)	DRCQUA
	DC(K,J) = DC(K,J) - D	DRCQUA
14	DC(J,K) = DC(J,K) + D	DRCQUA
	DO 18 I = 1,3	DRCQUA
	DO 18 J = 1,3	DRCQUA
18	IF(DABS(DC(I,J)).GT.1.0D0)DC(I,J) = DSIGN(1.0D0,DC(I,J))	DRCQUA
	RETURN	DRCQUA
	END	DRCQUA

	SUBROUTINE DRCYPR (D,A,ID)		DRCYPR
		REV IV 07/23/86	TWOPI
C	SETS UP 3X3 DIRECTION COSINE MATRIX FOR GIVEN YAW,PITCH AND ROLL.		DRCYPR
C			DRCYPR
C	ARGUMENTS:		DRCYPR
C	D: 3X3 DIRECTION COSINE MATRIX TO BE COMPUTED.		DRCYPR
C	A: ARRAY OF LENGTH 3 CONTAINING ROTATION ANGLES (DEGREES).		DRCYPR
C	I1: AXIS OF ROTATION FOR 1ST ANGLE (1,2,3 = X,Y,Z)		DRCYPR
C	I2: AXIS OF ROTATION FOR 2ND ANGLE (1,2,3 = X,Y,Z)		DRCYPR
C	I3: AXIS OF ROTATION FOR 3RD ANGLE (1,2,3 = X,Y,Z)		DRCYPR
C			DRCYPR
	IMPLICIT REAL*8 (A-H,O-Z)		DRCYPR
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		DRCYPR
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	DIMENSION D(3,3),A(3),ID(3),T(3,3),B(3),S(3)		DRCYPR
	IDSUM = ID(1) + ID(2) + ID(3)		DRCYPR
	DO 12 I=1,3		DRCYPR
	B(I) = A(I)*RADIAN		DRCYPR
	DO 11 J=1,3		DRCYPR
11	D(I,J) = 0.0		DRCYPR
12	D(I,I) = 1.0		DRCYPR
	DO 30 N=1,3		DRCYPR
	IDN = IABS(ID(N))		DRCYPR
	M = 4 - IDN		DRCYPR
	IF (ID(N).LT.0) M = IDSUM - ID(N) - 2		DRCYPR
	IF (B(M).EQ.0.0) GO TO 30		DRCYPR
	CALL ROT (T,IDN,B(M))		DRCYPR
	DO 23 J=1,3		DRCYPR
	DO 21 K=1,3		DRCYPR
	S(K) = D(K,J)		DRCYPR
21	D(K,J) = 0.0		DRCYPR
	DO 22 I=1,3		DRCYPR
	DO 22 K=1,3		DRCYPR
22	D(I,J) = D(I,J) + T(I,K)*S(K)		DRCYPR
23	CONTINUE		DRCYPR
30	CONTINUE		DRCYPR
	RETURN		DRCYPR
	END		DRCYPR

	SUBROUTINE DRIFT		DRIFT
C		REV IV	07/24/86SLIP
C	CORRECTS FOR DRIFT IN CONSTRAINED JOINTS		DRIFT
C			DRIFT
C			DRIFT
	IMPLICIT REAL*8(A-H,O-Z)		DRIFT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		DRIFT
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		DRIFT
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		DRIFT
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		DRIFT
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		DRIFT
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		DRIFT
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),		DRIFT
*	FE(3,30),TQE(3,30),CONST(5,30)		DRIFT
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		DRIFT
*	UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	COMMON/TEMPVS/ T1(3),T2(3),T3(3),T4(3),TP(3,3),H1(3),H2(3)		DRIFT
	IF (NJNT.EQ.0) GO TO 51		DRIFT
	DO 50 J=1,NJNT		DRIFT
	K = IABS(JNT(J))		DRIFT
	IF (K.EQ.0) GO TO 50		DRIFT
	IF (ISING(J+1).LT.0) GO TO 50		DRIFT
C			DRIFT
	M = 0		DRIFT
	IF (IPIN(J).EQ.1) M = 4		DRIFT
	IF (IPIN(J).EQ.6) M = 4		SLIP
	IF (IPIN(J).EQ.7) M = 4		SLIP
	IF (IABS(IPIN(J)).NE.4) GO TO 15		DRIFT
	IF (IEULER(J).EQ.1) M = 2		DRIFT
	IF (IEULER(J).EQ.2) M = 3		DRIFT
	IF (IEULER(J).EQ.3) M = 1		DRIFT
	IF (IEULER(J).EQ.4) M = 4		DRIFT
	IF (IEULER(J).EQ.5) M = 4		DRIFT
	IF (IEULER(J).EQ.6) M = 4		DRIFT
15	IF (M.EQ.0) GO TO 50		DRIFT
	IF (M.EQ.4) GO TO 23		DRIFT
	IF (M.NE.3) GO TO 21		DRIFT
	CALL EJOINT(-1,J)		DRIFT
	CALL CROSS(HIR(1,2,2*J+29),HIR(1,1,2*J+29),T1)		DRIFT
	DO 17 I = 1,3		DRIFT
	H1(I) = CONST(4,J)*HIR(I,1,2*J+29) + CONST(5,J)*T1(I)		DRIFT
17	H2(I) = HIR(I,3,2*J+30)		DRIFT
	GO TO 25		DRIFT
21	DO 22 I = 1,3		DRIFT
	H1(I) = HIR(I,M,2*J+29)		DRIFT
22	H2(I) = HIR(I,M+1,2*J+30)		DRIFT
	GO TO 25		DRIFT
23	DO 24 I = 1,3		DRIFT
	H1(I) = HB(I,2*J-1)		DRIFT

	24 H2(I) = HB(I,2*J)	DRIFT
C		DRIFT
C	** ADJUST DC MATRIX FOR CONSTRAINED JOINTS **	DRIFT
C		DRIFT
	25 CALL DOT31(D(1,1,K),H1,T1)	DRIFT
	CALL MAT31 (D(1,1,J+1),T1,T2)	DRIFT
	CT = T2(1)*H2(1) + T2(2)*H2(2) + T2(3)*H2(3)	DRIFT
	IF(M.GE.3)GO TO 28	DRIFT
	ST = 1.0/DSQRT((1.0 - CT)*(1.0 + CT))	DRIFT
	DO 27 I = 1,3	DRIFT
	27 T2(I) = (H2(I) - CT*T2(I))*ST	DRIFT
	CT = 1.0/ST	DRIFT
	28 CALL CROSS(H2,T2,T3)	DRIFT
	DO 30 L=1,3	DRIFT
	CALL CROSS (T3,D(1,L,J+1),T4)	DRIFT
	ST = T3(1)*D(1,L,J+1) + T3(2)*D(2,L,J+1) + T3(3)*D(3,L,J+1)	DRIFT
	ST = ST/(1.0 + CT)	DRIFT
	DO 30 I=1,3	DRIFT
	30 D(I,L,J+1) = CT*D(I,L,J+1) - T4(I) + ST*T3(I)	DRIFT
C		DRIFT
C	** RENORMALIZATION OF DIRECTION COSINE MATRIX BY **	DRIFT
C	** AVERAGING MATRIX AND TRANSPOSE OF ITS INVERSE **	DRIFT
C		DRIFT
	DO 33 ITER= 1,10	DRIFT
	CALL CFACTT (D(1,1,J+1),TP,DET)	DRIFT
	DO 32 L = 1,3	DRIFT
	DO 32 I = 1,3	DRIFT
	D(I,L,J+1) = 0.5*(D(I,L,J+1)+TP(L,I)/DET)	DRIFT
	32 IF (DABS(D(I,L,J+1)).LT.EPS(15)) D(I,L,J+1) = 0.0	DRIFT
	IF (DABS(DET-1.0).LT.EPS(6)) GO TO 41	DRIFT
	33 CONTINUE	DRIFT
	WRITE (6,34) J,TIME,DET	DRIFT
	34 FORMAT (44H0 DRIFT RENORMALIZATION DID NOT CONVERGE FOR,	DRIFT
	* 10H JOINT NO.,I3,7H TIME =,F10.6,6H DET =,F10.6)	DRIFT
C		DRIFT
C	** ADJUST WMEG FOR CONSTRAINED JOINTS **	DRIFT
C		DRIFT
	41 IF(M.NE.4)GO TO 43	DRIFT
	HW = H2(1)*WMEG(1,J+1) - H1(1)*WMEG(1,K)	DRIFT
	* + H2(2)*WMEG(2,J+1) - H1(2)*WMEG(2,K)	DRIFT
	* + H2(3)*WMEG(3,J+1) - H1(3)*WMEG(3,K)	DRIFT
	CALL DOT31 (D(1,1,K),WMEG(1,K),T1)	DRIFT
	CALL MAT31 (D(1,1,J+1),T1,WMEG(1,J+1))	DRIFT
	DO 42 I=1,3	DRIFT
	42 WMEG(I,J+1) = WMEG(I,J+1) + HW*H2(I)	DRIFT
	GO TO 50	DRIFT
	43 IF(M.NE.3)GO TO 47	DRIFT
	CALL DOT31(D(1,1,K),HIR(1,2,2*J+29),T1)	DRIFT
	CALL MAT31(D(1,1,J+1),T1,H1)	DRIFT
	GO TO 48	DRIFT



47 CALL MAT31(D(1,1,J+1),T1,T2)	DRIFT
CALL CROSS(T2,H2,H1)	DRIFT
48 CALL DOT31(D(1,1,K),WMEG(1,K),T1)	DRIFT
CALL MAT31(D(1,1,J+1),T1,T2)	DRIFT
HW = H1(1)*(T2(1) - WMEG(1,J+1))	DRIFT
* + H1(2)*(T2(2) - WMEG(2,J+1))	DRIFT
* + H1(3)*(T2(3) - WMEG(3,J+1))	DRIFT
DO 49 I = 1,3	DRIFT
49 WMEG(I,J+1) = WMEG(I,J+1) + HW*H1(I)	DRIFT
50 CONTINUE	DRIFT
51 RETURN	DRIFT
END	DRIFT

	SUBROUTINE DSETD(D,TH,T)		DSETD
		REV IV	07/23/86TWOPI
C	UPDATES A DIRECTION COSINE MATRIX (D)		DSETD
C	USING AN INCREMENTAL ANGULAR MOTION (TH).		DSETD
C	ARGUMENTS D: 3X3 DIRECTION COSINE MATRIX TO BE UPDATED.		DSETD
C	TH: 3 COMPONENTS OF INCREMENTAL ANGULAR MOTION		DSETD
C	ABOUT LOCAL X,Y AND Z AXIS RESPECTIVELY.		DSETD
C	T: MAGNITUDE OF VECTOR TH COMPUTED BY ROUTINE.		DSETD
C			DSETD
	IMPLICIT REAL*8(A-H,O-Z)		DSETD
	DIMENSION D(3,3),TH(3),S(3),TEMP(3,3)		DSETD
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		DSETD
	*            UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	T=DSQRT(TH(1)**2+TH(2)**2+TH(3)**2)		DSETD
	IF(T.EQ.0.)RETURN		DSETD
	ST=DSIN(T)		DSETD
	CT=DCOS(T)		DSETD
	STT=ST/T		DSETD
	CTT=STT**2/(1.+CT)		DSETD
	DO 10 J=1,3		DSETD
	S(1)=-TH(3)*D(2,J)+TH(2)*D(3,J)		DSETD
	S(2)= TH(3)*D(1,J)-TH(1)*D(3,J)		DSETD
	S(3)=-TH(2)*D(1,J)+TH(1)*D(2,J)		DSETD
	DTT=(TH(1)*D(1,J)+TH(2)*D(2,J)+TH(3)*D(3,J))*CTT		DSETD
	DO 5 K=1,3		DSETD
	5      D(K,J)=D(K,J)*CT-STT*S(K)+TH(K)*DTT		DSETD
10	CONTINUE		DSETD
C			DSETD
C	RENORMALIZATION OF DIRECTION COSINE MATRIX		DSETD
C	BY AVERAGING MATRIX AND TRANSPOSE OF ITS INVERSE.		DSETD
C			DSETD
	DO 23 ITER=1,10		DSETD
	CALL CFACTT(D,TEMP,DET)		DSETD
	DO 22 I=1,3		DSETD
	DO 22 J=1,3		DSETD
	D(I,J) = 0.5*(D(I,J)+TEMP(J,I)/DET)		DSETD
22	IF (DABS(D(I,J)).LT.EPS(15)) D(I,J)=0.0		DSETD
	IF (DABS(DET-1.0).LT.EPS(6)) GO TO 24		DSETD
23	CONTINUE		DSETD
	WRITE (6,27) DET		DSETD
27	FORMAT('0 DSETD RENORMALIZATION DID NOT CONVERGE, DET =',1PD25.15)		DSETD
24	RETURN		DSETD
	END		DSETD

	SUBROUTINE DSETQ(E,TH,ES,EC,D)		DSETQ
C		REV IV 07/23/86	TWOPI
C	COMPUTES NEW DIRECTION MATRIX (D), GIVEN ORIGINAL MATRIX (E)		DSETQ
C	AND INCREMENTAL MOTION EXPRESSED IN QUATERNION FORM.		DSETQ
C			DSETQ
C	ARGUMENTS:		DSETQ
C			DSETQ
C	E : ORIGINAL DIRECTION COSINE MATRIX.		DSETQ
C	TH : COMPONENTS OF Q ( UX SIN A/2, UY SIN A/2, UZ SIN A/2)		DSETQ
C	ES : SIN**2(A/2)		DSETQ
C	EC : COS (A/2)		DSETQ
C	D : NEW DIRECTION COSINE MATRIX.		DSETQ
C			DSETQ
	IMPLICIT REAL*8(A-H,O-Z)		DSETQ
	DIMENSION D(3,3),TH(3),S(3),TEMP(3,3),E(3,3)		DSETQ
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		DSETQ
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	CT = 1.0 - 2.0*ES		DSETQ
	DO 10 J=1,3		DSETQ
	S(1) = TH(2)*E(3,J) - TH(3)*E(2,J)		DSETQ
	S(2) = TH(3)*E(1,J) - TH(1)*E(3,J)		DSETQ
	S(3) = TH(1)*E(2,J) - TH(2)*E(1,J)		DSETQ
	DTT = TH(1)*E(1,J) + TH(2)*E(2,J) + TH(3)*E(3,J)		DSETQ
	DO 5 K=1,3		DSETQ
	5 D(K,J) = E(K,J)*CT + 2.0*(TH(K)*DTT - EC*S(K))		DSETQ
	10 CONTINUE		DSETQ
C			DSETQ
C	RENORMALIZATION OF DIRECTION COSINE MATRIX		DSETQ
C	BY AVERAGING MATRIX AND TRANSPOSE OF ITS INVERSE.		DSETQ
C			DSETQ
	DO 23 ITER=1,10		DSETQ
	CALL CFACTT(D,TEMP,DET)		DSETQ
	DO 22 I=1,3		DSETQ
	DO 22 J=1,3		DSETQ
	D(I,J) = 0.5*(D(I,J)+TEMP(J,I)/DET)		DSETQ
	22 IF (DABS(D(I,J)).LT.EPS(15)) D(I,J)=0.0		DSETQ
	IF (DABS(DET-1.0).LT.EPS(6)) GO TO 24		DSETQ
	23 CONTINUE		DSETQ
	WRITE (6,27) DET		DSETQ
	27 FORMAT('0 DSETQ RENORMALIZATION DID NOT CONVERGE, DET =',1PD25.15)		DSETQ
	24 RETURN		DSETQ
	END		DSETQ

	SUBROUTINE DSMSOL (A, KK, LL)	REV 03	07/08/74	DSMSOL
C				DSMSOL
C	SOLVES A SET OF SIMULTANEOUS LINEAR EQUATIONS AX=B.			DSMSOL
C				DSMSOL
C	ARGUMENTS:			DSMSOL
C	A: 2-DIMENSIONAL(KK, KK+1) MATRIX OF COEFFICIENTS.			DSMSOL
C	KK: NUMBER OF EQUATIONS AND UNKNOWN.			DSMSOL
C	LL: 1ST DIMENSION OF A IN CALLING PROGRAM.			DSMSOL
C				DSMSOL
C	CALLING PROGRAM SETUP:			DSMSOL
C	A(I, J) FOR I, J=1, KK			DSMSOL
C	A(I, KK+1) = B(I) FOR I=1, KK			DSMSOL
C	THE SOLUTION X IS RETURNED IN COLUMN KK+1 OF A.			DSMSOL
C	MATRIX A IS DESTROYED BY SUBROUTINE.			DSMSOL
C				DSMSOL
	IMPLICIT REAL*8(A-H, O-Z)			DSMSOL
	DIMENSION A(LL, 1)			DSMSOL
	N = KK			DSMSOL
	N1 = N+1			DSMSOL
	DO 50 L=1, N			DSMSOL
	L1 = L+1			DSMSOL
	BIG = 0.0			DSMSOL
	DO 25 I=L, N			DSMSOL
	IF (DABS(A(I, L)).LE.DABS(BIG)) GO TO 25			DSMSOL
	K = I			DSMSOL
	BIG = A(I, L)			DSMSOL
	25 CONTINUE			DSMSOL
	IF (BIG.NE.0.0) GO TO 30			DSMSOL
	WRITE (6, 26)			DSMSOL
	26 FORMAT('0 DSMSOL MATRIX SINGULAR, PROGRAM TERMINATED.')			DSMSOL
	STOP 41			DSMSOL
	30 BIG = 1.0/BIG			DSMSOL
	DO 40 J=L, N1			DSMSOL
	B = A(K, J)			DSMSOL
	A(K, J) = A(L, J)			DSMSOL
	40 A(L, J) = B*BIG			DSMSOL
	IF (L.EQ.N) GO TO 50			DSMSOL
	DO 48 I=L1, N			DSMSOL
	IF (A(I, L).EQ.0.0) GO TO 48			DSMSOL
	DO 45 J=L1, N1			DSMSOL
	45 A(I, J) = A(I, J)-A(I, L)*A(L, J)			DSMSOL
	48 CONTINUE			DSMSOL
	50 CONTINUE			DSMSOL
	IF (N.EQ.1) GO TO 71			DSMSOL
	N2 = N-1			DSMSOL
	DO 60 L=1, N2			DSMSOL
	I = N-L			DSMSOL
	L1 = I+1			DSMSOL
	DO 60 J=L1, N			DSMSOL
	60 A(I, N1) = A(I, N1)-A(I, J)*A(J, N1)			DSMSOL

71 CONTINUE  
RETURN  
END

DSMSOL  
DSMSOL  
DSMSOL

	SUBROUTINE DZP(N,X,GG,E,R,M)		DZP
		REV IV 07/23/86	TWOPI
C	COMPUTES THE STATE VARIABLES (X) FROM THE PARAMETRIC FORM ASSUMED		DZP
C	IN THE INTEGRATION ROUTINE DINT. ALSO EVALUATES THE EXPONENTIAL		DZP
C	WEIGHTS (E) IF M IS NOT ZERO.		DZP
C			DZP
	IMPLICIT REAL*8 (A-H,O-Z)		DZP
	DIMENSION X(1),GG(5,1),E(3,1)		DZP
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		DZP
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
C			DZP
	CALL ELTIME(1,5)		DZP
	IF(M.NE.0) GO TO 10		DZP
C			DZP
C	COMPUTE STATE VARIABLES ONLY.		DZP
C			DZP
	DO 5 I=1,N		DZP
5	X(I) = GG(1,I) + R*(GG(2,I)*E(1,I)		DZP
*	+ R*(GG(3,I)*E(2,I)		DZP
*	+ R*(GG(4,I)*E(3,I) ) )		DZP
	GO TO 90		DZP
C			DZP
C	COMPUTE EXPONENTIAL WEIGHTS AND STATE VARIABLES.		DZP
C			DZP
10	DO 50 I=1,N		DZP
	E(1,I) = 1.0		DZP
	E(2,I) = 0.5		DZP
	E(3,I) = THIRD		DZP
	IF (GG(5,I).EQ.0.0) GO TO 50		DZP
	Z = R*GG(5,I)		DZP
	W = 0.		DZP
	IF (DABS(Z).GT.0.004) GO TO 20		DZP
	W = 4.		DZP
	A = E(3,I)		DZP
	E(3,I) = 0.		DZP
15	E(3,I) = E(3,I)+A		DZP
	A = A*Z/W		DZP
	W = W+1.0		DZP
	IF(E(3,I)+A.NE.E(3,I)) GO TO 15		DZP
	E(2,I) = 0.5+0.5*Z*E(3,I)		DZP
	E(1,I) = 1.+Z*E(2,I)		DZP
	GO TO 50		DZP
20	IF(Z.GT.-40.) W = DEXP(Z)		DZP
	E(1,I) = (W-1.)/Z		DZP
	E(2,I) = (E(1,I)-1.)/Z		DZP
	E(3,I) = (2.*E(2,I)-1.)/Z		DZP
50	X(I) = GG(1,I) + R*(GG(2,I)*E(1,I)		DZP
*	+ R*(GG(3,I)*E(2,I)		DZP
*	+ R*(GG(4,I)*E(3,I) ) )		DZP
C			DZP

90 CALL ELTIME(2,5)  
RETURN  
END

DZP  
DZP  
DZP

	SUBROUTINE EDEPTH (A,B,XM,T,Y,XA,XB,XL,XU)	REV IV 07/23/86	TWOPI
C			EDEPTH
C	DETERMINES XA AND XB, THE POINTS OF MAXIMUM PENETRATION OF TWO		EDEPTH
C	INTERSECTING ELLIPSOIDS A AND B.		EDEPTH
C	ARGUMENTS A,B,XM,T AND X SAME AS FOR SUBROUTINE INTERS.		EDEPTH
C	ARGUMENTS XL AND XU, IF NONZERO, ARE FINAL RESULTS OF LAST CALL.		EDEPTH
C			EDEPTH
	IMPLICIT REAL*8 (A-H,O-Z)		EDEPTH
	DIMENSION A(3,3),B(3,3),XM(3),Y(3),XA(3),XB(3)		EDEPTH
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		EDEPTH
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		EDEPTH
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	DIMENSION C1(3,4),C2(3,4),C3(3,4),XBM(3),PXBL(3),PXAU(3),AB(3,3)		EDEPTH
	DIMENSION AXA(3),BXBM(3),PXAL(3),PXB(3)		EDEPTH
	EQUIVALENCE (XBM(1),C1(1,4)), (PXBL(1),C2(1,4)), (PXAU(1),C3(1,4))		EDEPTH
			EDEPTH
	INITIAL GUESSES		EDEPTH
	XA = Y/T		EDEPTH
	XB = M+(Y-M)/T		EDEPTH
	L = - XB-XA / AXA		EDEPTH
	U = - XB-XA / B(XB-M)		EDEPTH
			EDEPTH
	D1 = 0.0		EDEPTH
	D2 = 0.0		EDEPTH
	DO 9 I=1,3		EDEPTH
	XA(I) = Y(I)/T		EDEPTH
	XBM(I) = (Y(I)-XM(I))/T		EDEPTH
	XB(I) = XBM(I)+XM(I)		EDEPTH
9	D1 = D1+(XB(I)-XA(I))**2		EDEPTH
	IF (DABS(T-1.0).LE.EPS(6)) GO TO 31		EDEPTH
	ITER = 0		EDEPTH
	CALL MAT33 (A,B,AB)		EDEPTH
	IF (XL.NE.0.0) GO TO 11		EDEPTH
	IF (XU.NE.0.0) GO TO 11		EDEPTH
	D3 = 0.0		EDEPTH
	DO 10 I=1,3		EDEPTH
	AXA(I) = A(I,1)*XA(1)		EDEPTH
	* + A(I,2)*XA(2)		EDEPTH
	* + A(I,3)*XA(3)		EDEPTH
	D2 = D2 + AXA(I)**2		EDEPTH
	BXBM(I) = B(I,1)*XBM(1)		EDEPTH
	* + B(I,2)*XBM(2)		EDEPTH
	* + B(I,3)*XBM(3)		EDEPTH
10	D3 = D3+BXBM(I)**2		EDEPTH
	XL = -DSQRT(D1/D2)		EDEPTH
	XU = -DSQRT(D1/D3)		EDEPTH
			EDEPTH
	START OF ITERATION		EDEPTH
			EDEPTH







C  
C  
C  
C

```

*          DXA
C12 = XA'A---
*          DU

*          DXB
C22 = (XB-M)'B---
*          DU

C12 = 0.0
C22 = 0.0
DO 26 I=1,3
PXBU(I) = PXAU(I) + XL*(A(I,1)*PXAU(1)
*        + A(I,2)*PXAU(2) + A(I,3)*PXAU(3) )
C12 = C12 + AXA(I)*PXAU(I)
26 C22 = C22 + BXB(I)*PXBU(I)

SOLVE FOR DL AND DU
C11*DL + C12*DU = C13
C21*DL + C22*DU = C23

DET = C11*C22-C12*C21
DL = (C13*C22-C12*C23)/DET
DU = (C11*C23-C13*C21)/DET

INCREMENT L AND U
TEST FOR CONVERGENCE

XL = XL + DL
XU = XU + DU
IF (DABS(DL/XL).GT.EPS(12)) GO TO 11
IF (DABS(DU/XU).GT.EPS(12)) GO TO 11
31 CONTINUE
RETURN
END

```

[illegible]

C	DOUBLE PRECISION FUNCTION EFUNCT (TH,THD,SPR,JSTOP)	EFUNCT
C	REV 20 04/29/80	EFUNCT
C	COMPUTES NONLINEAR SRRING TORQUE FOR EULER JOINTS.	EFUNCT
C	ARGUMENTS:	EFUNCT
C	TH - THETA IS THE ANGLE OF THE EULER AXIS	EFUNCT
C	THD - THETA DOT	EFUNCT
C	SPR - ARRAY OF 5 VALUES DESCRIBING FUNCTION EVALUATION	EFUNCT
C	JSTOP - INDICATOR TO BE SET TO ONE IF IN STOP	EFUNCT
C		EFUNCT
	IMPLICIT REAL*8(A-H,O-Z)	EFUNCT
	DIMENSION SPR(5)	EFUNCT
	JSTOP = 0	EFUNCT
	EFUNCT = TH*SPR(1)	EFUNCT
	TEN = 10.0	EFUNCT
	Q = DSIGN(TEN*THD,TH*THD)	EFUNCT
	IF (Q.GT.1.0) Q = 1.0	EFUNCT
	IF (Q.LT.-1.0) Q = -1.0	EFUNCT
	X = 0.5*(1.0+SPR(4)+Q*(1.0-SPR(4)))	EFUNCT
	IF (SPR(5).GT.0.0) GO TO 10	EFUNCT
	EFUNCT = X*EFUNCT	EFUNCT
	GO TO 99	EFUNCT
10	IF (DABS(TH).LT.SPR(5)) GO TO 99	EFUNCT
	JSTOP = 1	EFUNCT
	Z = DABS(TH) - SPR(5)	EFUNCT
	EFUNCT = EFUNCT + DSIGN(X*(SPR(2)+Z*SPR(3))*Z**2,TH)	EFUNCT
99	RETURN	EFUNCT
	END	EFUNCT

	SUBROUTINE EJOINT(IJ,NK)		JDRIFT
C		REV IV	07/24/86SLIP
C	COMPUTES THE TORQUES ACTING ON AN EULER JOINT		EJOINT
C	AND ADDS THEM TO THE U2 ARRAY.		EJOINT
C			EJOINT
C	ARGUMENTS:		EJOINT
C	NK = 0 - REGULAR COMPUTATION FOR ALL EULER JOINTS		JDRIFT
C	* 0 - COMPUTE ONLY FOR JOINT NJ IMPULSE		EJOINT
C			EJOINT
C	IJ = 1 IMPULSE ON PRECESSION AXIS ONLY		EJOINT
C	= 2 IMPULSE ON NUTATION AXIS ONLY		EJOINT
C	= 3 IMPULSE ON SPIN AXIS ONLY		EJOINT
C	= 4 IMPULSE ON GLOBALGRAPHIC AXIS		EJOINT
C	NK = 0, IJ * 0, SPECIAL COMPUTATIONS OF HIR AND HB ONLY		JDRIFT
C			EJOINT
	IMPLICIT REAL*8(A-H,O-Z)		EJOINT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		EJOINT
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		EJOINT
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		EJOINT
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		EJOINT
	* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		EJOINT
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		EJOINT
	* F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),		JDRIFT
	* FE(3,30),TQE(3,30),CONST(5,30)		JDRIFT
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),		NCFORC
	* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF		EJOINT
	COMMON/TEMPVI/ CREST,TTI(3),R1I(3),R2I(3),JSTOP(4,2,30)		EJOINT
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		EJOINT
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	COMMON/TEMPVS/ DH1(3,3),DH4(3,3),TH(3,3),HIM(3,3),HIJ(3,3),		EJOINT
	* HDT(3,3),H2(3,3),SH(3),TM(3),TJ(3),WMJ(3),AD(3),		EJOINT
	* CV(3),CS(3),ANGL(3),HD3(3),CC(3),T9(3),LSKIP(3)		EJOINT
	LOGICAL LSKIP		EJOINT
	IF (NJNT.LE.0) GO TO 99		EJOINT
	CALL ELTIME(1,31)		EJOINT
	J1 = 1		EJOINT
	J2 = NJNT		EJOINT
	NJ = NK		JDRIFT
	IF (NJ.EQ.0) GO TO 11		EJOINT
	J1 = NJ		EJOINT
	J2 = NJ		EJOINT
	IF(IJ.LT.0) NJ = 0		JDRIFT
11	DO 98 J=J1,J2		EJOINT
	IF (IABS(IPIN(J)).NE.4) GO TO 98		EJOINT
	M = IABS(JNT(J))		EJOINT
	CALL DOT33(D(1,1,M),HT(1,1,2*J-1),DH1)		EJOINT
	CALL DOT33(D(1,1,J+1),HT(1,1,2*J),DH4)		EJOINT

CALL DOT33(DH4,DH1,TH)	EJOINT
DO 12 I=1,3	EJOINT
12 ANG(I,J) = ANG(I,J) + CONST(I,J)	EJOINT
IC = IEULER(J)	EJOINT
CALL EULRAD (TH,ANG(1,J),IC)	EJOINT
CALL ROT(H2,3,-ANG(1,J))	EJOINT
DO 13 I=1,3	EJOINT
ANG(I,J) = ANG(I,J) - CONST(I,J)	EJOINT
HIR(I,1,J) = DH1(I,3)	EJOINT
HIR(I,3,J) = DH4(I,3)	EJOINT
HIM(I,1) = HT(I,3,2*J-1)	EJOINT
HIJ(I,3) = HT(I,3,2*J)	EJOINT
LSKIP(I) = .FALSE.	EJOINT
FE(I,J) = 0.0	EJOINT
CV(I) = 0.0	EJOINT
CS(I) = 0.0	EJOINT
V2(I,J) = 0.0	EJOINT
TQE(I,J) = 0.0	EJOINT
13 TQ(I,J) = 0.0	EJOINT
WJ(J) = 0.0	EJOINT
TQC = 0.0	EJOINT
IF (IJ.EQ.4) GO TO 55	EJOINT
CALL MAT31 (HT(1,1,2*J-1),H2(1,1),HIM(1,2))	EJOINT
CALL MAT31 (HT(1,1,2*J-1),H2(1,2),HIM(1,3))	EJOINT
CALL DOT31 (D(1,1,M),HIM(1,2),H2(1,2))	EJOINT
CALL DOT31 (D(1,1,M),HIM(1,3),H2(1,3))	EJOINT
CALL CROSS (H2(1,2),HIR(1,3,J),H2(1,1))	EJOINT
CALL DOT31 (D(1,1,M ),WMEG(1,M ),TM)	EJOINT
CALL DOT31 (D(1,1,J+1),WMEG(1,J+1),TJ)	EJOINT
SWJ = 0.0	EJOINT
DO 14 I=1,3	EJOINT
HIR(I,2,J) = H2(I,2)	EJOINT
WMJ(I) = TJ(I) - TM(I)	EJOINT
14 SWJ = SWJ + WMJ(I)**2	EJOINT
WJ(J) = DSQRT(SWJ)	EJOINT
CALL DOT31 (HIR(1,1,J),WMJ,AD)	EJOINT
CALL CROSS (TM,HIR(1,1,J),HDT(1,1))	EJOINT
CALL CROSS (TM,HIR(1,2,J),HDT(1,2))	EJOINT
CALL CROSS (TJ,HIR(1,3,J),HDT(1,3))	EJOINT
CALL MAT31 (D(1,1,J+1),HIR(1,1,J),HIJ(1,1))	EJOINT
CALL MAT31 (D(1,1,J+1),HIR(1,2,J),HIJ(1,2))	EJOINT
CALL MAT31 (D(1,1,M ),HIR(1,3,J),HIM(1,3))	EJOINT
N = IEULER(J)	EJOINT
DO 15 I=1,3	EJOINT
SH(I) = AD(I)	JDRIFT
DO 15 K=1,3	JDRIFT
HIR(I,K,2*J+29) = HIM(I,K)	JDRIFT
15 HIR(I,K,2*J+30) = HIJ(I,K)	JDRIFT
IF (N.EQ.8) GO TO 19	EJOINT
IF (N.GT.3) GO TO 16	EJOINT

SH(N) = 0.0	EJOINT
GO TO 18	EJOINT
16 DO 17 I=1,3	EJOINT
17 IF (I.NE.N-3) SH(I) = 0.0	EJOINT
18 IF (N.NE.2) GO TO 21	EJOINT
19 HX = H2(1,1)*HIR(1,1,J) + H2(2,1)*HIR(2,1,J) + H2(3,1)*HIR(3,1,J)	EJOINT
IF (DABS(HX).GE.EPS(6)) GO TO 20	EJOINT
SH(1) = ANGDI(1,J)	EJOINT
SH(3) = ANGDI(3,J)	EJOINT
GO TO 21	EJOINT
20 CALL DOT31 (H2,WMJ,SH)	EJOINT
SH(1) = SH(1)/HX	EJOINT
IF (N.EQ.2) SH(2) = 0.0	EJOINT
SH(3) = SH(3)/HX	EJOINT
21 DO 22 I=1,3	EJOINT
ANGDI(I,J) = SH(I)	EJOINT
22 HDT(I,2) = HDT(I,2) + SH(1)*H2(I,3)	EJOINT
IF (NJ.NE.0) N = IJ+3	EJOINT
IF (N.GT.3) GO TO 30	EJOINT
N4 = 4-N	EJOINT
IF (N.EQ.2) AHDT = HDT(1,2)*WMJ(1)+HDT(2,2)*WMJ(2)+HDT(3,2)*WMJ(3)	EJOINT
IF (N.NE.2) AHDT = -(SH(2)*HDT(1,2)+SH(N4)*HDT(1,N4))*H2(1,N)	EJOINT
* -(SH(2)*HDT(2,2)+SH(N4)*HDT(2,N4))*H2(2,N)	EJOINT
* -(SH(2)*HDT(3,2)+SH(N4)*HDT(3,N4))*H2(3,N)	EJOINT
CALL MAT31 (D(1,1,M ),H2(1,N),HB(1,2*J-1))	EJOINT
CALL MAT31 (D(1,1,J+1),H2(1,N),HB(1,2*J ))	EJOINT
DO 25 I=1,3	EJOINT
V2(I,J) = AHDT*H2(I,N)	EJOINT
25 IF (N.EQ.1) LSKIP(I) = .TRUE.	EJOINT
GO TO 42	EJOINT
30 IF (N.GT.6) GO TO 40	EJOINT
K3J = 3*J-2	EJOINT
DO 32 I=1,3	EJOINT
IF (NJ.EQ.0) GO TO 31	EJOINT
IF (I.EQ.N-3) CREST = VISC(7,K3J)	EJOINT
TQE(I,J) = H2(I,N-3)	EJOINT
GO TO 32	EJOINT
31 V2(I,J) = -HDT(I,N-3)*AD(N-3)	EJOINT
HB(I,2*J-1) = HIM(I,N-3)	EJOINT
HB(I,2*J ) = HIJ(I,N-3)	EJOINT
IF (I.NE.N-3) LSKIP(I) = .TRUE.	EJOINT
32 K3J = K3J + 1	EJOINT
IF (NJ) 35,42,35	EJOINT
40 IF (N.EQ.7) GO TO 97	EJOINT
42 IF(IJ.NE.0) GOTO 98	JDRIFT
DO 41 I=1,3	JDRIFT
IF (LSKIP(I)) GO TO 41	EJOINT
K3J = 3*J-3+1	EJOINT
CV(I) = ANGDI(I,J)*VISCOS(DABS(ANGDI(I,J)),VISC(1,K3J),HA(I,2*J))	EJOINT
CS(I) = EFUNCT(ANG(I,J),ANGDI(I,J),SPRING(1,K3J),JSTOP(I,1,J))	EJOINT

	FE(I,J) = CS(I) + CV(I) + HA(I,2*J)*HA(I,2*J-1)	EJOINT
41	CONTINUE	EJOINT
	CALL MAT31(HIR(1,1,J),FE(1,J),TQE(1,J))	EJOINT
	IF(NJ.GT.0) GO TO 34	EJOINT
55	IF (IGLOB(J).EQ.0) GO TO 34	EJOINT
	HD3(1) = TH(3,1)	EJOINT
	HD3(2) = TH(3,2)	EJOINT
	HD3(3) = TH(3,3)	EJOINT
	CALL GLOBAL (J,HD3,DH1,TQC,T9,ANGL)	EJOINT
34	CONTINUE	EJOINT
C		EJOINT
C	ADD TORQUE CONVERTED TO LOCAL REFERENCE TO U2 ARRAY BY	EJOINT
C	U2(M ) = U2(M ) + D(M )*TQ	EJOINT
C	U2(J+1) = U2(J+1) - D(J+1)*TQ	EJOINT
C		EJOINT
35	DO 51 I=1,3	EJOINT
	TQ(I,J) = TQE(I,J)+TQC*T9(I)	EJOINT
	TTI(I) = TQ(I,J)	EJOINT
	DO 51 K=1,3	EJOINT
	U2(K,M ) = U2(K,M ) + D(K,I,M )*TQ(I,J)	EJOINT
51	U2(K,J+1) = U2(K,J+1) - D(K,I,J+1)*TQ(I,J)	EJOINT
C		EJOINT
C	STORE DATA INTO PRJNT ARRAY FOR OUTPUT ROUTINE	EJOINT
C		EJOINT
97	PRJNT(1,J) = IEULER(J)	EJOINT
	PRJNT(2,J) = ANG(1,J)	EJOINT
	PRJNT(3,J) = ANG(2,J)	EJOINT
	PRJNT(4,J) = ANG(3,J)	EJOINT
	PRJNT(5,J)=CS(1)**2+CS(3)**2+2.0*CS(1)*CS(3)*TH(3,3)+CS(2)**2	JTF785
	PRJNT(6,J)=CV(1)**2+CV(3)**2+2.0*CV(1)*CV(3)*TH(3,3)+CV(2)**2	JTF785
	PRJNT(7,J) = TQ(1,J)**2 + TQ(2,J)**2 + TQ(3,J)**2	EJOINT
98	CONTINUE	EJOINT
	CALL ELTIME(2,31)	EJOINT
99	RETURN	EJOINT
	END	EJOINT



	DOUBLE PRECISION FUNCTION ELONG(A,B,C,D,E)		ELONG
C		REV 01	10/05/72ELONG
C	COMPUTES ARC LENGTH OF ELLIPSE	$AX^2 + 2BXY + CY^2 = 1$	ELONG
C	FROM THETA=0 (POSITIVE X AXIS) TO THETA=E (RADIAN)		ELONG
C	WHERE D IS NOMINAL INCREMENT OF INTEGRATION.		ELONG
C			ELONG
	IMPLICIT REAL*8(A-H,O-Z)		ELONG
	N=DABS(E/D)		ELONG
	N=N+N		ELONG
	IF(N.EQ.0)N=2		ELONG
	Z=N		ELONG
	T=E/Z		ELONG
	F = DSQRT ((1.+(B/A)**2)/A)		ELONG
	CS=1.		ELONG
	SN=0.		ELONG
	DCS=DCOS(T)		ELONG
	DSN=DSIN(T)		ELONG
	S=F/2.		ELONG
	AC = A+C		ELONG
	BAC = B*B-A*C		ELONG
	DO 10 I=1,N,2		ELONG
	CSS=CS*DCS-SN*DSN		ELONG
	SN=SN*DCS+CS*DSN		ELONG
	CS=CSS		ELONG
	G=(A*CS+B*SN)*CS+(B*CS+C*SN)*SN		ELONG
	G = G**2/(AC + BAC/G)		ELONG
	F=(F+1./(F*G))/2.		ELONG
	S=S+F		ELONG
	CSS=CS*DCS-SN*DSN		ELONG
	SN=SN*DCS+CS*DSN		ELONG
	CS=CSS		ELONG
	G=(A*CS+B*SN)*CS+(B*CS+C*SN)*SN		ELONG
	G = G**2/(AC + BAC/G)		ELONG
	F=(F+1./(F*G))/2.		ELONG
	S=S+F		ELONG
10	CONTINUE		ELONG
	ELONG=(S+S-F)*T/3.		ELONG
	RETURN		ELONG
	END		ELONG

	SUBROUTINE ELTIME(L,N)	ELTIME
		REV III.2 08/08/84REVI
C		ELTIME
C	COUNTS THE NUMBER OF TIMES CERTAIN BASIC SUBROUTINES ARE CALLED	ELTIME
C	AND ACCOUNTS FOR ALL COMPUTER CPU TIME USED BY THESE ROUTINES.	ELTIME
C		ELTIME
C	ARGUMENTS L: 1 INDICATES CALL IS AT START OF ROUTINE	ELTIME
C	2 INDICATES CALL IS AT END OF ROUTINE.	ELTIME
C	>2 PAGE NUMBER FOR CALL AT END OF RUN	PAGE
C	N: THE SUBROUTINE IDENTIFICATION NUMBER.	ELTIME
C		ELTIME
C	ASSUMES FUNCTION LTIME(1) IS GIVING ELAPSED CPU TIME IN INTEGER	ELTIME
C	UNITS OF 0.01 SECONDS SINCE FUNCTION LTIME(0) WAS CALLED.	ELTIME
C		ELTIME
	DIMENSION NT(40),MTIN(40),NC(40),IND(40)	ELTIME
	REAL*8 SUB(40)	ELTIME
	DATA SUB/	ELTIME
	* 8H MAIN3D ,8H INPUT ,8H DINT ,8H PRIPLT ,8H DZP ,	ELTIME
	* 8H PDAUX ,8H UPDATE ,8H OUTPUT ,8H DAUX ,8H SETUP1 ,	ELTIME
	* 8H CHAIN ,8H CONTCT ,8H VISPR ,8H DAUX11 ,8H DAUX12 ,	ELTIME
	* 8H DAUX22 ,8H DAUX31 ,8H DAUX32 ,8H DAUX33 ,8H FSMSOL ,	ELTIME
	* 8H PLELP ,8H BELTRT ,8H SEGSEG ,8H AIRBAG ,8H RSTART ,	ELTIME
	* 8H SETUP2 ,8H IMPULS ,8H IMPLS2 ,8H AIRBG3 ,8H DAUX55 ,	ELTIME
	* 8H EJOINT ,8H SPDAMP ,8H DAUX44 ,8H FLXSEG ,8H EQUILB ,	ELTIME
	* 8H POSTPR ,8H WINDY ,8H HBELT ,8H HPTURB ,8H /	ELTIME
	IF (N.GT.1) GO TO 20	ELTIME
	IF (L.GT.1) GO TO 40	ELTIME
C		ELTIME
C	INITIAL CALL AT BEGINNING OF MAIN PROGRAM.	ELTIME
C		ELTIME
	MTIN(1) = LTIME(0)	ELTIME
	DO 11 I=1,40	ELTIME
	IND(I) = 0	ELTIME
	NC(I) = 0	ELTIME
	MTIN(I) = -1	ELTIME
	11 NT(I) = 0	ELTIME
	NSUB = 1	ELTIME
	IND(1) = 1	ELTIME
	NC(1) = 1	ELTIME
	MTIN(1) = 0	ELTIME
	GO TO 99	ELTIME
C		ELTIME
C	CALL AT BEGINNING OF NTH SUBROUTINE.	ELTIME
C		ELTIME
	20 IF (L.GT.1) GO TO 30	ELTIME
	MTIN(N) = LTIME(1)	ELTIME
	IF (NC(N).NE.0) GO TO 21	ELTIME
	NSUB = NSUB+1	ELTIME
	IND(NSUB) = N	ELTIME
	21 NC(N) = NC(N)+1	ELTIME
	GO TO 99	ELTIME

C		ELTIME
C	CALL AT END OF NTH SUBROUTINE.	ELTIME
C		ELTIME
	30 MTOUT = LTIME(1)	ELTIME
	NDIFF = MTOUT-MTIN(N)	ELTIME
	MTIN(N) = -1	ELTIME
	IF (NDIFF.EQ.0) GO TO 32	ELTIME
	NT(N) = NT(N) + NDIFF	ELTIME
	DO 31 I=1,40	ELTIME
	IF (MTIN(I).NE.-1) MTIN(I) = MTIN(I) + NDIFF	ELTIME
	31 CONTINUE	ELTIME
	32 GO TO 99	ELTIME
C		ELTIME
C	SUBSEQUENT CALLS FROM MAIN PROGRAM, PRINT SUMMARY TABLE.	ELTIME
C		ELTIME
	40 NTSUM = LTIME(1)	ELTIME
	NT(1) = NTSUM - MTIN(1)	ELTIME
	TIME = FLOAT(NTSUM)/100.0	ELTIME
	WRITE (6,41) TIME,L	PAGE
	41 FORMAT('1 ELAPSED CPU TIME =',F10.2,' SECONDS',85X,'PAGE',15//	PAGE
	* ' SUB CALLS TIME % '//)	ELTIME
	PCSUM = 0.0	ELTIME
	NTSUM = 0	ELTIME
	DO 42 I=1,NSUB	ELTIME
	J = IND(I)	ELTIME
	PC = FLOAT(NT(J))/TIME	ELTIME
	PCSUM = PCSUM + PC	ELTIME
	NTSUM = NTSUM + NT(J)	ELTIME
	42 WRITE (6,43) SUB(J),NC(J),NT(J),PC	ELTIME
	43 FORMAT(A10,2I10,F10.2)	ELTIME
	WRITE (6,44) NTSUM,PCSUM	ELTIME
	44 FORMAT('0TOTAL',14X,I10,F10.2)	ELTIME
	99 RETURN	ELTIME
	END	ELTIME

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SUBROUTINE EQUILB (YPR,IYPR)

REV IV

02/01/88MISDOT

ADJUSTS INITIAL INPUT POSITION PARAMETERS SUPPLIED ON CARDS G.2  
AND G.3 SUCH THAT INITIAL NORMAL CONTACT FORCES ARE EQUAL TO  
EITHER SUPPLIED VALUES OR THOSE COMPUTED BY CONSTRAINT FORCES.

IMPLICIT REAL\*8(A-H,O-Z)

DIMENSION YPR(3,30) , IYPR(4,30)

COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,

\* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG

COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),

\* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)

COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),

\* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),

\* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)

COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),

\* F(3,30),TQ(3,30),WJ(30),A11(3,3,30)

COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),

\* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),

\* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),

\* KQ1(12),KQ2(12),KQTYPE(12)

COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)

COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),

\* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),

\* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)

COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)

COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),

\* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI

COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),

\* BLTTTL(5,8),PLTTTL(5,30),BAGTTL(5,6),SEG(30),

\* JOINT(30),CGS(30),JS(30)

COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),

\* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBSGF

REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTTL,BAGTTL,SEG,JOINT

LOGICAL\*1 CGS,JS

COMMON/TEMPVS/ DMNT(3,3),XMN(3),XMM(3),TM(3),RM(3)

DIMENSION TEMP(3),T(5),FX(10),FX1(10)

DIMENSION X(10),GX(10),DX(10),DXP(10),DPN(5,10)

DIMENSION JPL(10),JSG(10),JX(10),M1(10),M2(10),M3(10),MT(10)

DIMENSION NTV(10),N11(10),NSG(10),NAV(10),KSG(5,10)

DIMENSION ISG(5),IPL(5),LTYPE(5),INDGX(5),MTNQ(5)

DIMENSION SX(10),SGX(10),XDEV(10),WORD(2)

DATA BLANK/' / , WORD/' SEGLP' , ' YPR' /

CALL ELTIME (1,35)

INPUT CARDS G.4, G.5.A-G.5.N, AND G.6.A-G.6.M

READ (5,60) NVAR,NCON

WRITE (6,51) NVAR,NCON,NPG

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	NPG=NPG+1	PAGE
51	FORMAT('1',5X,'NVAR =',I3,3X,'NCON =',I3,96X,	PAGE
	* 'PAGE',I5/I20X,'CARD G.4'/)	PAGE
	ICARD = 4	EQUILB
	JCARD = 0	EQUILB
	IF (NVAR.LT.1 .OR. NVAR.GT.10) GO TO 65	EQUILB
	IF (NCON.LT.0 .OR. NCON.GT.5 ) GO TO 65	EQUILB
	WRITE (6,52)	EQUILB
52	FORMAT('0',4X,'J',4X,'NTV',3X,'N11',3X,'NSG',8X,'GX',12X,'XDEV',	EQUILB
	*7X,'JPL',3X,'JSG',3X,'NAV',3X,'KSG(I,J),I=1,NAV',29X,'CARDS G.5'/)	EQUILB
	ICARD = 5	EQUILB
	DO 58 J=1,NVAR	EQUILB
	JCARD = J	EQUILB
	READ (5,53) NTV(J),N11(J),NSG(J),GX(J),XDEV(J),	EQUILB
	* JPL(J),JSG(J),IAV,(KSG(I,J),I=1,IAV)	EQUILB
53	FORMAT(3I4,2F8.0,8I4)	EQUILB
	NAV(J) = IAV	EQUILB
	WRITE (6,54) J,NTV(J),N11(J),NSG(J),GX(J),XDEV(J),	EQUILB
	* JPL(J),JSG(J),IAV,(KSG(I,J),I=1,IAV)	EQUILB
54	FORMAT(4I6,2F15.6,8I6)	EQUILB
	IF (NTV(J).LT.1 .OR. NTV(J).GT.2 ) GO TO 65	EQUILB
	IF (N11(J).LT.1 .OR. N11(J).GT.3 ) GO TO 65	EQUILB
	IF (NSG(J).LT.1 .OR. NSG(J).GT.NSEG) GO TO 65	EQUILB
	IF (NAV(J).LT.0 .OR. NAV(J).GT.5 ) GO TO 65	EQUILB
	IF (JPL(J).LT.1 .OR. JPL(J).GT.NPL ) GO TO 65	EQUILB
	IF (JSG(J).LT.1 .OR. JSG(J).GT.NSEG) GO TO 65	EQUILB
	K = JPL(J)	EQUILB
	NNPL = MNPL(K)	EQUILB
	IF (NNPL.LT.1 .OR. NNPL.GT.5) GO TO 65	EQUILB
	DO 55 I=1,NNPL	EQUILB
	IF (JSG(J).NE.MPL(2,I,K)) GO TO 55	EQUILB
	JSG(J) = I	EQUILB
	GO TO 56	EQUILB
55	CONTINUE	EQUILB
	GO TO 65	EQUILB
56	IF (NAV(J).LE.0) GO TO 58	EQUILB
	DO 57 I=1,IAV	EQUILB
	IF (KSG(I,J).LT.1 .OR. KSG(I,J).GT.NSEG) GO TO 65	EQUILB
57	CONTINUE	EQUILB
58	CONTINUE	EQUILB
	IF (NCON.LE.0) GO TO 17	EQUILB
	WRITE (6,59)	EQUILB
59	FORMAT('0',4X,'I',4X,'IPL',3X,'ISG',2X,'LTYPE',2X,'INDGX',	EQUILB
	* 87X,'CARDS G.6'/)	EQUILB
	ICARD = 6	EQUILB
	DO 64 I=1,NCON	EQUILB
	JCARD = I	EQUILB
	READ (5,60) IPL(I),ISG(I),LTYPE(I),INDGX(I)	EQUILB
	WRITE (6,61) I,IPL(I),ISG(I),LTYPE(I),INDGX(I)	EQUILB
60	FORMAT(4I4)	EQUILB

61	FORMAT(5I6)	EQUILB
	IF ( IPL(I).LT.1 .OR. IPL(I).GT.NPL ) GO TO 65	EQUILB
	IF ( ISG(I).LT.1 .OR. ISG(I).GT.NSEG) GO TO 65	EQUILB
	IF (LTYPE(I).LT.3 .OR. LTYPE(I).GT.4 ) GO TO 65	EQUILB
	IF (INDGX(I).LT.0 .OR. INDGX(I).GT.NVAR) GO TO 65	EQUILB
	J = IPL(I)	EQUILB
	NNPL = MNPL(J)	EQUILB
	IF (NNPL.LT.1 .OR. NNPL.GT.5) GO TO 65	EQUILB
	DO 62 K=1,NNPL	EQUILB
	IF (ISG(I).NE.MPL(2,K,J)) GO TO 62	EQUILB
	ISG(I) = K	EQUILB
	GO TO 63	EQUILB
62	CONTINUE	EQUILB
	GO TO 65	EQUILB
63	IF (INDGX(I).LE.0) GO TO 64	EQUILB
	K = INDGX(I)	EQUILB
	IF (IPL(I).NE.JPL(K) .OR. ISG(I).NE.JSG(K)) GO TO 65	EQUILB
64	CONTINUE	EQUILB
	GO TO 17	EQUILB
C		EQUILB
C	INPUT ERROR - PRINT MESSAGE AND TERMINATE PROGRAM.	EQUILB
C		EQUILB
65	WRITE (6,66) ICARD,JCARD	EQUILB
66	FORMAT('0 INPUT ERROR ON CARD G.',I2,'.',I2,	EQUILB
	* '. PROGRAM TERMINATED.')	EQUILB
	STOP 26	EQUILB
C		EQUILB
C	DATA INITIALIZATION.	EQUILB
C		EQUILB
17	NQORG = NQ	EQUILB
	DO 19 K=1,NVAR	EQUILB
	J = JPL(K)	EQUILB
	I = JSG(K)	EQUILB
	M1(K) = MPL(1,I,J)	EQUILB
	M2(K) = MPL(2,I,J)	EQUILB
	M3(K) = MPL(3,I,J)	EQUILB
	MT(K) = NTPL (I,J)	EQUILB
	JX(K) = 1	EQUILB
	DXP(K) = 0.0	EQUILB
	I1 = NI1(K)	EQUILB
	I2 = NSG(K)	EQUILB
	IF (NTV(K).EQ.1) X(K) = SEGLP(I1,I2)	EQUILB
	IF (NTV(K).EQ.2) X(K) = YPR(I1,I2)	EQUILB
	SX(K) = X(K)	EQUILB
	SGX(K) = GX(K)	EQUILB
	IF (NAV(K).LE.0) GO TO 19	EQUILB
	IAV = NAV(K)	EQUILB
	DO 18 L=1,IAV	EQUILB
	J2 = KSG(L,K)	EQUILB
	IF (NTV(K).EQ.1) DPN(L,K) = SEGLP(I1,I2) - SEGLP(I1,J2)	EQUILB

18	IF (NTV(K).EQ.2) DPN(L,K) = YPR(I1,I2) - YPR(I1,J2)	EQUILB
19	CONTINUE	EQUILB
	IF (NPRT(27).EQ.0) GO TO 20	EQUILB
C		EQUILB
C	LET'S SEE WHAT USER INPUT LOOKS LIKE.	EQUILB
C		EQUILB
	CALL OUTPUT(0)	EQUILB
	CALL DAUX(0)	EQUILB
	CALL PRINT(6H USER )	EQUILB
	CALL OUTPUT(1)	EQUILB
C		EQUILB
C	START FDF FORCE -> CONSTRAINT FORCE ITERATION	EQUILB
C		EQUILB
20	PENDOT = 0.0	EQUILB
	DO 50 JITTER=1,10	EQUILB
C		EQUILB
C	ITERATE INPUT (X) SUCH THAT F(X) = G(X)	EQUILB
C		EQUILB
	MVAR = 2	EQUILB
	IF (NVAR.EQ.1) MVAR = 1	EQUILB
	DO 32 M=1,2	EQUILB
	DO 32 I=MVAR,NVAR	EQUILB
	DO 32 J=1,I	EQUILB
	NITER = 10	EQUILB
	IF (DXP(J).EQ.0.0) NITER = 50	EQUILB
	DX(J) = 0.25	EQUILB
	N1 = M1(J)	EQUILB
	N2 = M2(J)	EQUILB
	N3 = M3(J)	EQUILB
	NP = JPL(J)	EQUILB
	NT = MT(J)	EQUILB
	I1 = NI1(J)	EQUILB
	I2 = MSG(J)	EQUILB
	IAV = NAV(J)	EQUILB
	IF (NTV(J).NE.2) GO TO 15	EQUILB
	CALL DRCIJK (D,YPR,IYPR,HT,I2)	EQUILB
	IF (NAV(J).LE.0) GO TO 15	EQUILB
	DO 14 K=1,IAV	EQUILB
	J2 = KSG(K,J)	EQUILB
14	CALL DRCIJK (D,YPR,IYPR,HT,J2)	EQUILB
15	DO 29 ITER=1,NITER	EQUILB
	CALL CHAIN(0)	JDRIFT
	PEN1 = PEN	EQUILB
	NPSF = 1	EDGE
	CALL PLELP(N2,N3,N1,NP,NT)	MISDOT
	PEN = PSF(1,1)	EDGE
	FX1(J) = FX(J)	EQUILB
	FXJ = 0.0	EQUILB
	IF (PEN.GT.0.0) FXJ = PSF(2,1)	EDGE
	IF (PEN.GT.0.0) CALL FRCDFL (PEN,PENDOT,NT,1,FXJ,ELOSS)	EQUILB

	FX(J) = FXJ	EQUILB
	IF (JX(J)-2) 23,21,25	EQUILB
21	IF (FX(J)*FX1(J).GT.0.0) GO TO 22	EQUILB
	IF (FX1(J).EQ.0.0) JX(J) = 1	EQUILB
	FX(J) = FX1(J)	EQUILB
	PEN = PEN1	EQUILB
	DX(J) = 0.5*DX(J)	EQUILB
	X(J) = X(J) - DX(J)	EQUILB
	GO TO 27	EQUILB
22	F2 = FX(J) - GX(J)	EQUILB
	F1 = FX1(J) - GX(J)	EQUILB
	IF (F1*F2.LE.0.0) GO TO 24	EQUILB
	IF (DABS(F2).LT.DABS(F1)) GO TO 23	EQUILB
26	FX(J) = FX1(J)	EQUILB
	DX(J) = -DX(J)	EQUILB
	PEN = PEN1	EQUILB
	X(J) = X(J) + 2.0*DX(J)	EQUILB
	GO TO 27	EQUILB
23	JX(J) = 1	EQUILB
	IF (PEN.GT.0.0) JX(J) = 2	EQUILB
	IF (ITER.GT.1 .AND. PEN.LT.0.0 .AND. PEN.LT.PEN1) GO TO 26	EQUILB
	X(J) = X(J) + DX(J)	EQUILB
	GO TO 27	EQUILB
24	DXP(J) = DX(J)/(FX(J)-FX1(J))	EQUILB
	JX(J) = 3	EQUILB
25	IF (DABS(FX(J)-GX(J)).LT.EPS(6)) GO TO 30	EQUILB
	IF (PEN.LT.0.0) CALL FRCDFL (-PEN,PENDOT,NT,1,FXJ,ELOSS)	EQUILB
	IF (PEN.LT.0.0) FX(J) = -FXJ	EQUILB
	X(J) = X(J) - DXP(J)*(FX(J)-GX(J))	EQUILB
27	IF (XDEV(J).LE.0.0) GO TO 42	EQUILB
	IF (DABS(X(J)-SX(J)).LE.XDEV(J)) GO TO 42	EQUILB
	WRITE (6,41) J,X(J),SX(J),XDEV(J)	EQUILB
41	FORMAT('0 PROGRAM IS BEING TERMINATED IN SUBROUTINE EQUILB.'//	EQUILB
	* ' ITERATION FOR VARIABLE NO.',I3,' IS NOT CONVERGING.'//	EQUILB
	* ' VALUE OF X IS OUT OF RANGE. VALUES OF X,SX,XDEV ARE'//	EQUILB
	* 3G20.8)	EQUILB
	STOP 27	EQUILB
42	IF (NTV(J).EQ.1) SEGLP(I1,I2) = X(J)	EQUILB
	IF (NTV(J).EQ.2) YPR(I1,I2) = X(J)	EQUILB
	IF (NTV(J).EQ.2) CALL DRCIJK (D,YPR,IYPR,HT,I2)	EQUILB
	IF (NAV(J).LE.0) GO TO 29	EQUILB
	DO 28 K=1,IAV	EQUILB
	J2 = KSG(K,J)	EQUILB
	IF (NTV(J).EQ.1) SEGLP(I1,J2) = X(J) - DPN(K,J)	EQUILB
	IF (NTV(J).EQ.2) YPR(I1,J2) = X(J) - DPN(K,J)	EQUILB
28	IF (NTV(J).EQ.2) CALL DRCIJK (D,YPR,IYPR,HT,J2)	EQUILB
29	CONTINUE	EQUILB
30	IF (NPRT(27).NE.0) WRITE (6,31) M,I,J,ITER,X(J),FX(J)	EQUILB
31	FORMAT(4I3,4X,2F12.6)	EQUILB
32	CONTINUE	EQUILB



	IF (NQ.LE.0) GO TO 40	EQUILB
C		EQUILB
C	COMPUTE VEHICLE COORDINATES FOR FIXED POINT CONSTRAINTS.	EQUILB
C		EQUILB
	DO 35 K=1,NQ	EQUILB
	IF (KQTYPE(K).NE.1) GO TO 35	EQUILB
	IF (KQ2(K).NE.NVEH) GO TO 35	EQUILB
	L = KQ1(K)	EQUILB
	CALL DOT31(D(1,1,L),RK1(1,K),T)	EQUILB
	DO 34 I=1,3	EQUILB
34	T(I) = T(I) + SEGLP(I,L) - SEGLP(I,NVEH)	EQUILB
	CALL MAT31(D(1,1,NVEH),T,RK2(1,K))	EQUILB
35	CONTINUE	EQUILB
40	IF (NPRT(27).EQ.0) GO TO 36	EQUILB
C		EQUILB
C	SOLVE SYSTEM EQUATIONS WITH CONSTRAINTS OFF.	EQUILB
C		EQUILB
	CALL OUTPUT(0)	EQUILB
	CALL DAUX(0)	EQUILB
	CALL PRINT(6HEQUIL2)	EQUILB
	CALL OUTPUT(1)	EQUILB
C		EQUILB
C	SET UP CONSTRAINTS TO PRODUCE ZERO ACCELERATIONS.	EQUILB
C		EQUILB
36	NQ = NQORG	EQUILB
	IF (NCON.LE.0) GO TO 81	EQUILB
	DO 37 I=1,NCON	EQUILB
	NQ = NQ+1	EQUILB
	J = IPL(I)	EQUILB
	K = ISG(I)	EQUILB
	NT = NTPL(K,J)	EQUILB
	NTNQ(I) = NTAB(NT+1)	EQUILB
	NTAB(NT+1) = -NQ	EQUILB
	KQ1(NQ) = MPL(2,K,J)	EQUILB
	KQ2(NQ) = MPL(1,K,J)	EQUILB
37	KQTYPE(NQ) = LTYPE(I)	EQUILB
C		EQUILB
C	SOLVE SYSTEM EQUATIONS WITH CONSTRAINTS ON.	EQUILB
C		EQUILB
	CALL OUTPUT(0)	EQUILB
	CALL DAUX(0)	EQUILB
	IF (NPRT(27).NE.0.AND.JITTER.EQ.1) CALL PRINT(6HEQUIL1)	EQUILB
C		EQUILB
C	FETCH CONSTRAINTS FORCES NORMAL TO PLANE SURFACES.	EQUILB
C	STORE FRICTION FORCE AND TURN OFF CONSTRAINTS.	EQUILB
C		EQUILB
	CONV = 1.0	EQUILB
	DO 39 I=1,NCON	EQUILB
	MQ = NQORG+I	EQUILB
	J = IPL(I)	EQUILB

	K = ISG(I)	EQUILB
	NT = NTPL(K,J)	EQUILB
	NTAB(NT+1) = NTNQ(I)	EQUILB
	M = MPL(2,K,J)	EQUILB
	N = MPL(1,K,J)	EQUILB
	CALL DOT31(D(1,1,N),PL(1,J),TEMP)	EQUILB
	T(I) = TEMP(1)*QQ(1,MQ) + TEMP(2)*QQ(2,MQ) + TEMP(3)*QQ(3,MQ)	EQUILB
	I1 = INDGX(I)	EQUILB
	IF (I1.GT.0 .AND. DABS(GX(I1)+T(I)).GT.EPS(2)) CONV = 0.0	EQUILB
	IF (I1.GT.0) GX(I1) = 0.5*(GX(I1)-T(I))	EQUILB
	DO 38 L=1,3	EQUILB
38	TEMP(L) = QQ(L,MQ) - T(I)*TEMP(L)	EQUILB
	LT = NTAB(NT)	EQUILB
39	CALL MAT31(D(1,1,M),TEMP,TAB(LT+19))	EQUILB
	NQ = NQORG	EQUILB
	IF (CONV.EQ.1.0) GO TO 81	EQUILB
50	CONTINUE	EQUILB
C		EQUILB
C	PRINT INPUT AND CHANGES MADE.	EQUILB
C		EQUILB
81	IF (NJNT.LE.0) GO TO 86	EQUILB
	CALL OUTPUT(0)	EQUILB
	CALL DAUX(0)	EQUILB
	IPRINT = 0	EQUILB
	DO 84 J=1,NJNT	EQUILB
	IF (IPIN(J).GE.0) GO TO 84	EQUILB
	IF (VISC(4,3*J-2).GT.0.0) GO TO 84	EQUILB
	IF (IPIN(J).EQ.-1) T1 = DABS(XDY(HB(1,2*J),D(1,1,J+1),TQ(1,J)))	EQUILB
	IF (IPIN(J).LE.-2) T1 = DSQRT(TQ(1,J)**2+TQ(2,J)**2+TQ(3,J)**2)	EQUILB
	VISC(4,3*J-2) = 1.5*T1	EQUILB
	IF (IPRINT.EQ.0) WRITE (6,82)	EQUILB
82	FORMAT('0 THE FOLLOWING VALUES FOR THE MAX TORQUE FOR A LOCKED JOEQUILB	
	*INT ON CARDS B.5 HAVE BEEN SET UP BY SUBROUTINE EQUILB: '//	EQUILB
	* ' J SYM IPIN T1=VISC(4) ' //	EQUILB
	IPRINT = 1	EQUILB
	WRITE (6,83) J,JOINT(J),IPIN(J),VISC(4,3*J-2)	EQUILB
83	FORMAT(I6,1X,A4,I6,F15.6)	EQUILB
84	CONTINUE	EQUILB
86	IF (NQ.LE.0) GO TO 91	EQUILB
	IPRINT = 0	EQUILB
	DO 89 K=1,NQ	EQUILB
	IF (KQTYPE(K).NE.1) GO TO 89	EQUILB
	IF (KQ2(K).NE.NVEH) GO TO 89	EQUILB
	IF (IPRINT.EQ.0) WRITE (6,87)	EQUILB
87	FORMAT('0 THE FOLLOWING VALUES FOR RK2 ON CARDS D.6 FOR FIXED POIEQUILB	
	*NT CONSTRAINTS HAVE BEEN CHANGED BY SUBROUTINE EQUILB: '//	EQUILB
	* 5X,'K',3X,'KQTYPE',4X,'KQ1',5X,'KQ2',8X,'RK2(X)',	EQUILB
	* 9X,'RK2(Y)',9X,'RK2(Z) '//	EQUILB
	IPRINT = 1	EQUILB
	WRITE (6,88) K,KQTYPE(K),KQ1(K),KQ2(K),(RK2(I,K),I=1,3)	EQUILB

88	FORMAT(16,318,3F15.6)	EQUILB
89	CONTINUE	EQUILB
91	WRITE (6,92)	EQUILB
92	FORMAT('0 THE FOLLOWING VARIABLES ON CARDS G.2 AND G.3 ',	EQUILB
	* 'HAVE BEEN CHANGED BY SUBROUTINE EQUILB:'//)	EQUILB
	DO 95 J=1,NVAR	EQUILB
	I0 = NTV(J)	EQUILB
	I1 = NI1(J)	EQUILB
	I2 = NSG(J)	EQUILB
	WRITE (6,93) WORD(I0),I1,I2,SX(J),X(J),BLANK,J,SGX(J),GX(J)	EQUILB
93	FORMAT(4X,A6,'(',I2,',',I2,') FROM',F12.6,' TO',F12.6,	EQUILB
	* A4,'AND GX(',I2,') FROM',F12.6,' TO',F12.6)	EQUILB
	IF (NAV(J).LE.0) GO TO 95	EQUILB
	IAV = NAV(J)	EQUILB
	DO 94 I=1,IAV	EQUILB
	J2 = KSG(I,J)	EQUILB
	ZSX = SX(J) - DPN(I,J)	EQUILB
	ZXX = X(J) - DPN(I,J)	EQUILB
94	WRITE (6,93) WORD(I0),I1,J2,ZSX,ZXX	EQUILB
95	CONTINUE	EQUILB
	CALL ELTIME (2,35)	EQUILB
	RETURN	EQUILB
	END	EQUILB

```

SUBROUTINE EULRAD(D,A,IC)                                REV IV    07/23/86TWOPI
COMPUTES EULER ANGLES PRECESSION, NUTATION, AND SPIN IN RADIANS
AND PLACES THEM INTO THE A ARRAY FOR GIVEN DIRECTION COSINE MATRIX
ASSUMES  $D = D(S)D(N)D(P)$ , WHERE

$$D(S) = \begin{pmatrix} CS & SS & 0 \\ -SS & CS & 0 \\ 0 & 0 & 1 \end{pmatrix}, D(N) = \begin{pmatrix} 1 & 0 & 0 \\ CN & SN & 0 \\ 0 & -SN & CN \end{pmatrix}, D(P) = \begin{pmatrix} CP & SP & 0 \\ -SP & CP & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

AND P=A(1), N=A(2), S=A(3)
ROUTINE WILL ALWAYS WORK IN THE MEMORY MODE, I.E., WILL PRODUCE A NEW SET OF A'S THAT DIFFER THE LEAST FROM THE INPUTTED A ARRAY. TO USE IN NON-MEMORY MODE,SET ALL A'S TO ZERO, CALL WITH IC = 8.
NEW N IS ALWAYS COMPUTED.
IF N OR PI-N < 10**-6, IC IS USED TO RESOLVE AMBIGUITIES ON P & S, EXCEPT FOR IC = 2 OR 8 WHERE THEY ARE NOT CHANGED.
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION A(3),D(3,3),T(6)
COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),
* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI
IF (D(3,3).GT. 1.0) D(3,3) = 1.0
IF (D(3,3).LT.-1.0) D(3,3) = -1.0
B = DACOS(D(3,3))
T(2) = B-A(2)
T(5) = -B-A(2)
Z = 0.0
IF (B.LT.EPS(6)) Z = 1.0
IF (PI-B.LT.EPS(6)) Z = -1.0
IF (Z.NE.0.0) GO TO 11
T(1) = DATAN2(D(3,1),-D(3,2)) - A(1)
T(4) = T(1) + PI
T(3) = DATAN2(D(1,3), D(2,3)) - A(3)
T(6) = T(3) + PI
GO TO 26
11 T(1) = DATAN2(D(1,2)-Z*D(2,1), D(1,1)+Z*D(2,2)) - A(1) - Z*A(3)
T(3) = T(1)
GO TO (21,22,23,23,22,21,22,22), IC
SET T(1) = 0 EXCEPT FOR IC=3,4
SET T(3) = 0 EXCEPT FOR IC=1,6
21 T(1) = 0.0
GO TO 25
22 T(1) = 0.0
23 T(3) = 0.0

```

25	T(4) = T(1)	EULRAD
	T(6) = T(3)	EULRAD
26	TMAX = 0.0	EULRAD
	J = 3	EULRAD
	DO 30 I=1,6	EULRAD
	T(I) = DMOD(T(I),TWOPI)	EULRAD
	IF (DABS(T(I)).GT.PI ) T(I) = T(I) - DSIGN(TWOPI,T(I))	EULRAD
	IF (DABS(T(I)).LT.TMAX) GO TO 30	EULRAD
	TMAX = DABS(T(I))	EULRAD
	IF (I.GT.3) J = 0	EULRAD
30	CONTINUE	EULRAD
	IF (Z.LT.0.0) T(J+3) = -T(J+3)	EULRAD
	DO 40 I=1,3	EULRAD
	IJ = I+J	EULRAD
40	A(I) = A(I) + T(IJ)	EULRAD
	RETURN	EULRAD
	END	EULRAD

```

C      DOUBLE PRECISION FUNCTION EVALFD (D,N,L)                                EVALFD
C      REV IV      07/23/86JTF786
C      EVALUATE FUNCTION THAT IS DEFINED AT LOCATION N OF TAB ARRAY          EVALFD
C      FOR ABSCISSA VALUE D. EVALUATES DERIVATIVE, FUNCTION OR INTEGRAL      EVALFD
C      AS L EQUALS 0, 1, OR 2. TAB ARRAY IS DEFINED AS FOLLOWS:              EVALFD
C      TAB(N)      - D0 (NO RESTRICTIONS ON D0)                             JTF786
C      TAB(N+1)    - D1 (F1 DEFINED FOR D0 < D < !D1!)                     JTF786
C      TAB(N+2)    - D2 (F2 DEFINED FOR !D1! < D < !D2!)                   JTF786
C      TAB(N+3)    - (NOT CURRENTLY USED)                                    EVALFD
C      TAB(N+4)    - (NOT CURRENTLY USED)                                    EVALFD
C      TAB(N+5)    - START OF DEFINITION OF 1ST PART OF FUNCTION (F1)       EVALFD
C      WHICH IS FOLLOWED BY DEFINITION OF 2ND PART OF FUNCTION (F2),         EVALFD
C      IF ANY.                                                         EVALFD
C      2ND PART OF FUNCTION EXISTS IF D2 IS NON-ZERO.                   EVALFD
C      SIGN OF D1 DETERMINES FORM OF DEFINITION FOR 1ST PART OF           EVALFD
C      THE FUNCTION.                                                    EVALFD
C
C      D1 ZERO INDICATES THAT FUNCTION IS CONSTANT D2 FOR ALL D.          EVALFD
C
C      D1 POSITIVE INDICATES THAT TAB(N+5)-TAB(N+10) CONTAINS              EVALFD
C      A0,A1,...A5. THE COEFFICIENTS OF A 5TH ORDER POLYNOMIAL.            EVALFD
C
C      D1 NEGATIVE INDICATES THAT TAB(N+5) CONTAINS NP (REAL)              EVALFD
C      FOLLOWED BY D(1), F(1), D(2), F(2) ..., D(NP), F(NP)                EVALFD
C
C      WARNING- TABULAR FUNCTION MUST BE DEFINED FOR WHOLE RANGE,          EVALFD
C      THAT IS, FROM D0 TO D1 INCLUSIVE, OR D1 TO D2 INCLUSIVE.           EVALFD
C
C      SIMILARLY, THE SIGN OF D2 (IF NON-ZERO) DETERMINES FORM OF         EVALFD
C      DEFINITION OF 2ND PART OF FUNCTION, IF ANY.                       EVALFD
C
C      IF D < D0      AND D1# 0, DERIVATIVE = 0 OR FUNCTION = F1(D0)       JTF786
C      IF D > !D1!    AND D2=0, DERIVATIVE = 0 OR FUNCTION = F1(!D1!)      JTF786
C      IF D > !D2!    AND D2#0, DERIVATIVE = 0 OR FUNCTION = F2(!D2!)      JTF786
C
C      NOTE: PREVIOUS VERSIONS ASSUMED THAT D0 WAS NON-NEGATIVE AND        EVALFD
C      THAT F = 0 FOR D < D0.                                             JTF786
C
C      IMPLICIT REAL*8(A-H,O-Z)                                           EVALFD
C      COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500) EVALFD
C      F = 0.0                                                             EVALFD
C      IOUTR = 0                                                            EVALFD
C      D0 = TAB(N)                                                           EVALFD
C      D1 = TAB(N+1)                                                         EVALFD
C      D2 = TAB(N+2)                                                         EVALFD
C      IF (D1.NE.0.0) GO TO 26                                              EVALFD
C      IF (L-1) 40,24,25                                                    JTF786
C      24 F = D2                                                            EVALFD

```

	GO TO 40	EVALFD
25	F= (D-D0)*D2	EVALFD
	GO TO 40	EVALFD
C		EVALFD
C	COMPUTE INDEX OF F1 DEFINITION	EVALFD
C		EVALFD
26	NP = N+5	EVALFD
	IF (L.EQ.2) GO TO 41	EVALFD
C		EVALFD
C	DERIVATIVES AND FUNCTIONS HERE, INTEGRALS HAVE OTHER LOGIC	EVALFD
C		EVALFD
	IF (D.GE.D0) GOTO 22	JTF786
C		JTF786
C	D < D0, RETURN F=0 FOR L=0, OR F=F1(D0) FOR L=1.	JTF786
C		JTF786
	IF (L.EQ.0) GOTO 40	JTF786
	X = D0	JTF786
	IF (D1.GT.0.0) GOTO 37	JTF786
	F = TAB(NP+2)	JTF786
	GOTO 40	JTF786
22	IF (D.LT.DABS(D1)) GOTO 31	EVALFD
	IF (D2.NE.0.0) GO TO 32	EVALFD
C		EVALFD
C	D .GE. !D1! , D2 = 0	EVALFD
C		EVALFD
	IF (D1.LE.0.0) GO TO 33	EVALFD
C		EVALFD
C	IOUTR.EQ.1 INDICATES D BEYOND RANGE. DERIVATIVE = 0.	EVALFD
C	IOUTR.EQ.0 INDICATES D.LE. !D1!. COMPUTE POLY DERIVATIVE	EVALFD
C		EVALFD
	IF (D.GT.DABS(D1)) IOUTR = 1	EVALFD
	X = D1	EVALFD
	GO TO 37	EVALFD
C		EVALFD
C	D0 < D < !D1!	EVALFD
C		EVALFD
31	IF (D1.LT.0.0) GO TO 35	EVALFD
	X = D	EVALFD
	GO TO 37	EVALFD
C		EVALFD
C	D .GE. !D1! , D2 NON-ZERO, USE F2	EVALFD
C		EVALFD
32	MP = 6	EVALFD
C		EVALFD
C	COMPUTE INDEX OF F2 DEFINITION	EVALFD
C		EVALFD
	IF (D1.LT.0.0) MP = 2.0 * TAB(NP)+1.0	EVALFD
	NP = NP+MP	EVALFD
	IF (D.LT.DABS(D2)) GO TO 34	EVALFD
	IF (D2.LT.0.0) GO TO 33	EVALFD

C		EVALFD
C	IOUTR.EQ.1 INDICATES D BEYOND RANGE. DERIVATIVE = 0.	EVALFD
C	IOUTR.EQ.0 INDICATES D.LE. !D2!. COMPUTE POLY DERIVATIVE	EVALFD
C		EVALFD
	IF (D.GT.DABS(D2)) IOUTR = 1	EVALFD
C		EVALFD
C	D .GE. D2 (POSITIVE). EVALUATE F2 FOR D2	EVALFD
C		EVALFD
	X = D2	EVALFD
	GO TO 37	EVALFD
C		EVALFD
C	D EXCEEDS TABULAR DEFINITION, SET F = F(NP)	EVALFD
C	IF TABLE DEFINITION EXTENDS BEYOND RANGE, USE TABLE VALUES	EVALFD
C		EVALFD
33	MB = TAB(NP)	EVALFD
	NB = NP+MB+MB	EVALFD
	IF (D .LE. TAB(NB-1)) GO TO 35	EVALFD
	IF (L.EQ.1) F=TAB(NB)	EVALFD
	GO TO 40	EVALFD
C		EVALFD
C	!D1! .LE. D < !D2!	EVALFD
C		EVALFD
34	IF (D2.LT.0.0) GO TO 35	EVALFD
	X = D	EVALFD
	GO TO 37	EVALFD
C		EVALFD
C	EVALUATE F FROM TABULAR DEFINITION	EVALFD
C		EVALFD
35	MB = TAB(NP)	EVALFD
	K1 = NP+3	EVALFD
	K2 = NP+MB+MB	EVALFD
	DO 36 K=K1,K2,2	EVALFD
	IF (D.GT.TAB(K)) GO TO 36	EVALFD
	IF (L-1) 28,27,40	EVALFD
C		EVALFD
C	EVALUATE DERIVATIVE FROM TABLE	EVALFD
C		EVALFD
28	F = (TAB(K+1)-TAB(K-1))/(TAB(K)-TAB(K-2))	EVALFD
	GO TO 40	EVALFD
C		EVALFD
C	EVALUATE FUNCTION FROM TABLE	EVALFD
C		EVALFD
27	R2 = TAB(K)-TAB(K-2)	EVALFD
	R1 = (D-TAB(K-2))/R2	EVALFD
	R2 = (TAB(K)-D )/R2	EVALFD
	F = R1*TAB(K+1)+R2*TAB(K-1)	EVALFD
	GO TO 40	EVALFD
36	CONTINUE	EVALFD
	IF (L.EQ.1) F = TAB(K2)	EVALFD
	GO TO 40	EVALFD



37	IF (IOUTR.EQ.1 .AND. L.EQ.0 ) GO TO 40	EVALFD
	IF (L-1) 38,39,40	EVALFD
C		EVALFD
C	EVALUATE DERIVATIVE OF 5TH DEGREE POLYNOMIAL	EVALFD
C		EVALFD
38	F = TAB(NP+1)+X*(2.0*TAB(NP+2)+X*(3.0*TAB(NP+3)+X*(4.0*TAB(NP+4)+	EVALFD
	* X*5.0*TAB(NP+5))))	EVALFD
	GO TO 40	EVALFD
C		EVALFD
C	EVALUATE 5TH DEGREE POLYNOMIAL	EVALFD
C		EVALFD
39	F = TAB(NP) + X*(TAB(NP+1)+X*(TAB(NP+2)	EVALFD
	* +X*(TAB(NP+3)+X*(TAB(NP+4)+X*TAB(NP+5))))	EVALFD
	GO TO 40	EVALFD
C		EVALFD
C	L=2: COMPUTE INTEGRAL OF FUNCTION FROM D0 TO D.	EVALFD
C		EVALFD
41	IF (D.EQ.D0) GO TO 40	EVALFD
	X0 = D0	EVALFD
	X1 = D1	EVALFD
	DO 50 I=1,2	EVALFD
	IF (X1) 43,49,42	EVALFD
42	A0 = TAB(NP )	EVALFD
	A1 = TAB(NP+1)/2.0	EVALFD
	A2 = TAB(NP+2)/3.0	EVALFD
	A3 = TAB(NP+3)/4.0	EVALFD
	A4 = TAB(NP+4)/5.0	EVALFD
	A5 = TAB(NP+5)/6.0	EVALFD
	NP = NP+6	EVALFD
	X = X0	EVALFD
	IF (X.NE.0.0) F=F-X*(A0+X*(A1+X*(A2+X*(A3+X*(A4+X*A5))))	EVALFD
	X = DMIN1(D,X1)	EVALFD
	IF (X.NE.0.0) F=F+X*(A0+X*(A1+X*(A2+X*(A3+X*(A4+X*A5))))	EVALFD
	IF(D.LE.X1) GO TO 40	EVALFD
	IF(I.EQ.1.AND.D2.NE.0.0) GO TO 49	EVALFD
C		EVALFD
C	NOTE - NP WAS UPDATED NP=NP+6 BEFORE THIS, READY FOR SECOND PASS	EVALFD
C		EVALFD
	F = F + (D-X1)*(TAB(NP-6)+X1*(TAB(NP-5)+X1*(TAB(NP-4)	EVALFD
	* +X1*(TAB(NP-3)+X1*(TAB(NP-2)+X1*TAB(NP-1))))	EVALFD
	GO TO 40	EVALFD
43	MB = TAB(NP)	EVALFD
	K1 = NP+3	EVALFD
	K2 = NP+MB+MB	EVALFD
	NP = K2+1	EVALFD
	DL = DMIN1(D,DABS(X1))	EVALFD
	DO 44 K=K1,K2,2	EVALFD
	IF (X0.GE.TAB(K)) GO TO 44	EVALFD
	Z1 = DMAX1(X0,TAB(K-2))	EVALFD
	Z2 = DMIN1(DL,TAB(K))	EVALFD

FYX = TAB(K-1)*TAB(K) - TAB(K+1)*TAB(K-2)	EVALFD
FY = TAB(K+1) - TAB(K-1)	EVALFD
F = F + (FYX + 0.5*FY*(Z1+Z2)) * (Z2-Z1) / (TAB(K)-TAB(K-2))	EVALFD
IF (Z2.NE.DL) GO TO 44	EVALFD
IF (I.EQ.1.AND.D2.NE.0.0) GO TO 49	EVALFD
IF (Z2. EQ. D) GO TO 40	EVALFD
F = F + (D-Z2)*(FYX+Z2*FY) / (TAB(K)-TAB(K-2))	EVALFD
GO TO 40	EVALFD
44 CONTINUE	EVALFD
49 X0 = DABS(D1)	EVALFD
50 X1 = D2	EVALFD
40 EVALFD = F	EVALFD
RETURN	EVALFD
END	EVALFD

	SUBROUTINE FDINIT	FDINIT
		REV III.2 08/08/84REVIII
C	REPLACES CODE PREVIOUSLY IN SUBROUTINES FINPUT AND HINPUT.	FDINIT
C	FROM FIVE FUNCTION NUMBERS IN NF ARRAY	FDINIT
C	1. SET UP KTITLE	FDINIT
C	2. SET UP NTAB AND TAB ARRAYS	FDINIT
C	3. INCREMENT COUNTERS MXNTB AND MXTB2	FDINIT
C		FDINIT
	IMPLICIT REAL*8 (A-H,O-Z)	FDINIT
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	DIMENB
	COMMON/TEMPVS/ JTITLE(5,51),NF(5),MS(3),KTITLE(31)	FDINIT
C	NOTE: THIS IS SHARED BY SUBS CINPUT, FINPUT, HINPUT AND FDINIT.	FDINIT
	REAL JTITLE,KTITLE	FDINIT
	J1 = MXTB2 + 1	FDINIT
	NT = MXNTB + 1	FDINIT
	NTAB(NT) = J1	FDINIT
	NT = NT+1	FDINIT
	DO 56 L=1,5	FDINIT
	NX = IABS(NF(L))	FDINIT
	NTAB(NT) = 0	FDINIT
	IF (NX.EQ.0) GO TO 56	FDINIT
	NTAB(NT) = ISIGN(NTI(NX),NF(L))	FDINIT
	DO 51 KK = 1,5	FDINIT
	KJ = 5*L+KK+1	FDINIT
51	KTITLE(KJ) = JTITLE(KK,NX)	FDINIT
	IF (NTI(NX).NE.0) GO TO 56	FDINIT
	WRITE(6,54) NX	FDINIT
54	FORMAT ('LO FUNCTION NO.',I4,' HAS NOT BEEN DEFINED. ',	FDINIT
	* ' PROGRAM TERMINATED.')	FDINIT
	STOP 15	FDINIT
56	NT = NT+1	FDINIT
C		FDINIT
C	INITIALIZE TAB ARRAY TO ZERO EXCEPT FOR DMAX, DINER, FDMAX.	FDINIT
C		FDINIT
	J2 = J1+29	FDINIT
	DO 57 JJ=J1,J2	FDINIT
57	TAB(JJ) = 0.0	FDINIT
	NX = NTAB(NT-5)	FDINIT
	IF (NX.LE.0) GO TO 58	BUTLER1
	TAB(J1+8) = DABS(TAB(NX+1))	FDINIT
	IF (TAB(NX+2).NE.0.0) TAB(J1+8) = DABS(TAB(NX+2))	FDINIT
	DX = TAB(J1+8)	FDINIT
	TAB(J1+10) = EVALFD(DX,NX,1)	FDINIT
	NX = NTAB(NT-4)	FDINIT
	IF (NX.LE.0) GO TO 58	FDINIT
	TAB(J1+9) = DABS(TAB(NX+1))	FDINIT
	IF (TAB(NX+2).NE.0.0) TAB(J1+9) = DABS(TAB(NX+2))	FDINIT
58	J1 = J2+1	FDINIT
	MXNTB = NT-1	FDINIT
	MXTB2 = J1-1	FDINIT

```

      IF (MXTB2.GT.4500) WRITE (6,62) MXTB2
62  FORMAT ('0 ERROR IN SUBROUTINE FDINIT, SIZE OF TAB ARRAY =',I8//
*      ' PROGRAM TERMINATED.')
      IF (MXNTB.GT.1250) WRITE (6,63) MXNTB
63  FORMAT ('0 ERROR IN SUBROUTINE FDINIT, SIZE OF NTAB ARRAY =',I8//
*      ' PROGRAM TERMINATED.')
      IF (MXTB2.GT.4500.OR.MXNTB.GT.1250) STOP 16
      RETURN
      END

```

DIMENB  
FDINIT  
FDINIT  
DIMENB  
FDINIT  
FDINIT  
DIMENB  
FDINIT  
FDINIT

```

SUBROUTINE FINPUT                                FINPUT
C                                                    REV IV    02/01/88MISDOT
C INPUT CARDS F.1-F.5 SPECIFYING THE ALLOWED CONTACTS OF THE CRASH FINPUT
C VICTIM BODY SEGMENTS WITH VEHICLE PANELS, BELTS, AIRBAGS AND OTHERFINPUT
C BODY SEGMENTS ALONG WITH THE ASSOCIATED FUNCTIONS TO BE USED FOR FINPUT
C EACH CONTACT. FINPUT
C ALSO SETS UP TABLES TO CONTROL TIME HISTORY INFORMATION FOR FINPUT
C EACH FUNCTION FOR EACH ALLOWED CONTACT. FINPUT
C FINPUT
C IMPLICIT REAL*8(A-H,O-Z) FINPUT
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, FINPUT
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG PAGE
COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60), SLIP
* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90), FINPUT
* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30) FINPUT
COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6), FINPUT
* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6), FINPUT
* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30) FINPUT
COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)DIMENB
COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5), FINPUT
* BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30), FINPUT
* JOINT(30),CGS(30),JS(30) FINPUT
REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT FINPUT
LOGICAL*1 CGS,JS FINPUT
COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24), FINPUT
* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12), FINPUT
* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12), FINPUT
* KQ1(12),KQ2(12),KQTYPE(12) FINPUT
COMMON/WINDFR/ WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30), WINDOP
* MWSEG(7,30),NFWSEG(6),NFWNT(5),MOWSEG(30,30) WINDOP
COMMON/TEMPVS/JTITLE(5,51),NF(5),MS(3),KTITLE(31) FINPUT
C FINPUT
REAL JTITLE,KTITLE,BLANK,SURFCE(2,3) FINPUT
DATA BLANK/4H / FINPUT
DATA SURFCE/4H PL,4HANE ,4H BE,4HLT ,4H SEG,4HMENT/ FINPUT
C FINPUT
MXNTI = 50 FINPUT
MXNTB = 0 FINPUT
MXTB2 = MXTB1 FINPUT
C FINPUT
C INPUT ALLOWED CONTACTS AND FUNCTIONS BY REF. NO. FINPUT
C FINPUT
WRITE (6,31) NPG PAGE
NPG=NPG+1 PAGE
31 FORMAT('1 ALLOWED CONTACTS AND ASSOCIATED FUNCTIONS',80X, PAGE
* 'PAGE',15) PAGE
DO 61 I=1,4 FINPUT
IJK = 0 FINPUT
GO TO (32,34,35,36),I FINPUT
32 IF (NPL.LE.0) GO TO 61 FINPUT

```

C		FINPUT
C	INPUT NO. OF SEGMENTS TO CONTACT EACH PLANE.	FINPUT
C	INPUT CARD F.1.A	FINPUT
C		FINPUT
	READ (5,33) (MNPL(J),J=1,NPL)	FINPUT
33	FORMAT(18I4)	FINPUT
	NJJ = NPL	FINPUT
	GO TO 37	FINPUT
34	IF (NBLT.LE.0) GO TO 61	FINPUT
C		FINPUT
C	INPUT NO. OF SEGMENTS TO CONTACT EACH BELT.	FINPUT
C	INPUT CARD F.2.A	FINPUT
C		FINPUT
	READ (5,33) (MNBLT(J),J=1,NBLT)	FINPUT
	NJJ = NBLT	FINPUT
	GO TO 37	FINPUT
35	IF (NSEG.LE.0) GO TO 61	FINPUT
C		FINPUT
C	INPUT NO. OF SEGMENTS TO CONTACT EACH SEGMENT.	FINPUT
C	INPUT CARD F.3.A	FINPUT
C		FINPUT
	READ (5,33) (MNSEG(J),J=1,NSEG)	FINPUT
	NJJ = NSEG	FINPUT
	NSEG1 = NSEG+1	FINPUT
	DO 26 J=NSEG1,NGRND	FINPUT
26	MNSEG(J) = 0	FINPUT
	GO TO 37	FINPUT
36	IF (NJNT.LE.0) GO TO 61	FINPUT
C		FINPUT
C	INPUT CARD F.4.A	FINPUT
C	SUPPLY IGLOB(J)=1 FOR EACH GLOBALGRAPHIC JOINT J=1,NJNT	FINPUT
C		FINPUT
	READ (5,33) (IGLOB(J),J=1,NJNT)	FINPUT
	NJJ = NJNT	FINPUT
C		FINPUT
C	START OF LOOP TO READ CONTACTS FOR PLANES (I=1), BELTS (I=2),	FINPUT
C	SEGMENTS (I=3) AND FUNCTIONS FOR GLOBALGRAPHIC JOINTS (I=4).	FINPUT
C		FINPUT
37	DO 60 J=1,NJJ	FINPUT
	IF (I.EQ.1) NK = MNPL(J)	FINPUT
	IF (I.EQ.2) NK = MNBLT(J)	FINPUT
	IF (I.EQ.3) NK = MNSEG(J)	FINPUT
	IF (I.EQ.4) NK = IGLOB(J)	FINPUT
	IF (NK.LE.0) GO TO 60	FINPUT
	DO 59 K=1,NK	FINPUT
	IF (IJK.EQ.0) WRITE (6,38) I	FINPUT
38	FORMAT('0',119X,'CARDS F.',I1)	FINPUT
	IF (IJK.EQ.0 .AND. I.NE.4) WRITE (6,39) SURFCE(1,I),SURFCE(2,I)	FINPUT
39	FORMAT('0',3X,2A4,8X,'SEGMENT',2X,'FORCE DEFLECTION',6X,'INERTIAL	FINPUT
	*SPIKE',10X,'R FACTOR',13X,'G FACTOR',10X,'FRICTION COEF. OPT')	EDGE

	IF (IJK.EQ.0 .AND. I.EQ.4) WRITE (6,40)	FINPUT
40	FORMAT('0',5X,'JOINT (GLOBALGRAPHIC)',2X,'TORQUE DEFLECTION',6X,'HFINPUT	FINPUT
	*ERRON FORMULA',10X,'R FACTOR',13X,'G FACTOR',10X,'FRICTION COEF.')	FINPUT
	IJK = 1	FINPUT
C		FINPUT
C	INPUT CONTACT SURFACE NO., SEGMENT NO., AND FUNCTION NOS.	FINPUT
C	INPUT CARD F.(I).(K)	FINPUT
C		FINPUT
	READ (5,33) NJ,MS,NF,NX	EDGE
	WRITE (6,41) NJ,MS,NF,NX	EDGE
41	FORMAT('0',I7,'-',I3,I11,'-',I3,I8,4I21,I12)	EDGE
	IF (NJ.NE.J) WRITE (6,42)	FINPUT
42	FORMAT(' CONTACT INPUT ERROR. PROGRAM TERMINATED.')	FINPUT
	IF (NJ.NE.J) STOP 14	FINPUT
	IF (I.NE.2.AND.NF(5).EQ.0) WRITE(6,20)	MISDOT
20	FORMAT(' FRICTION FUNCTION NUMBER CAN NOT BE ZERO FOR THIS TYPE OF	MISDOT
	* CONTACT')	MISDOT
	IF (I.NE.2.AND.NF(5).EQ.0) STOP 105	MISDOT
	NLT = 1	FINPUT
	DO 43 JJ = 1,31	FINPUT
43	KTITLE(JJ) = BLANK	FINPUT
	GO TO (44,46,48,49),I	FINPUT
C		FINPUT
C	PLACE SEGMENT NO. AND INDEX TO NTAB ARRAY INTO M- AND NT- ARRAYS.	FINPUT
C		FINPUT
44	MPL(1,K,J) = MS(1)	FINPUT
	MPL(2,K,J) = MS(2)	FINPUT
	MPL(3,K,J) = MS(3)	FINPUT
	NTPL(K,J) = MXNTB+1	FINPUT
	DO 45 JJ = 1,5	FINPUT
45	KTITLE(JJ) = PLTTL (JJ,J)	FINPUT
	GO TO 50	FINPUT
46	MBLT(1,K,J) = MS(1)	FINPUT
	MBLT(2,K,J) = MS(2)	FINPUT
	MBLT(3,K,J) = MS(3)	FINPUT
	NTBLT(K,J) = MXNTB+1	FINPUT
	DO 47 JJ = 1,5	FINPUT
47	KTITLE(JJ) = BLTTTL (JJ,J)	FINPUT
C		FINPUT
C	SET UP TWO TABLES FOR FULL BELT FRICTION	FINPUT
C		FINPUT
	IF (NF(5).NE.0) NLT = 2	FINPUT
	GO TO 50	FINPUT
48	MSEG(1,K,J) = MS(1)	FINPUT
	MSEG(2,K,J) = MS(2)	FINPUT
	MSEG(3,K,J) = MS(3)	FINPUT
	NTSEG(K,J) = MXNTB+1	FINPUT
	KTITLE (3) = SEG(J)	FINPUT
	GO TO 50	FINPUT
C		FINPUT

C	NOTE: GLOBALGRAPHIC JOINT WILL SAVE NT IN IGLOB ARRAY	FINPUT
C		FINPUT
	49 IGLOB(J) = MXNTB+1	FINPUT
	KTITLE(2) = JOINT(J)	FINPUT
C		FINPUT
C	SET UP POINTERS TO TAB ARRAY IN NTAB ARRAY.	FINPUT
C		FINPUT
	50 NFJ = MS(2)	FINPUT
	IF (NFJ.GT.0) KTITLE(6) = SEG(NFJ)	FINPUT
	DO 51 JJ=1,MLT	FINPUT
	51 CALL FDINIT	FINPUT
	WRITE (6,53) KTITLE	FINPUT
	53 FORMAT(1X,5A4,1X,A4,5(1X,5A4))	FINPUT
	LT = NTAB(MXNTB-5)	EDGE
	IF (I.EQ.1) TAB(LT+22) = NX	EDGE
	IF (NF(1).NE.0) GO TO 59	EDGE
C		FINPUT
C	IF FORCE DEFLECTION FUNCTION NO. IS ZERO,	FINPUT
C	SET UP FOR ROLLING CONSTRAINT	FINPUT
C		FINPUT
	NQ = NQ+1	FINPUT
	NTAB(MXNTB-4) = -NQ	FINPUT
	KQTYPE(NQ) = -4	FINPUT
	KQ1(NQ) = MS(2)	FINPUT
	KQ2(NQ) = MS(1)	FINPUT
	IF (I.NE.3) GO TO 59	EDGE
	KQ1(NQ) = J	FINPUT
	KQ2(NQ) = MS(2)	FINPUT
	59 CONTINUE	FINPUT
	60 CONTINUE	FINPUT
	61 CONTINUE	FINPUT
C		FINPUT
C	INPUT CARD F.5 - JOINT FUNCTIONS TO BE USED.	FINPUT
C		FINPUT
	IF (NJNT.LE.0) GO TO 81	FINPUT
	IF (NJNTF.NE.0) GO TO 76	FINPUT
	DO 75 J=1,NJNT	FINPUT
	75 JOINTF(J) = 0	FINPUT
	GO TO 81	FINPUT
	76 READ (5,33) (JOINTF(J),J=1,NJNT)	FINPUT
	IJK = 0	FINPUT
	DO 80 J=1,NJNT	FINPUT
	IF (JOINTF(J).EQ.0) GO TO 80	FINPUT
	IF (IJK.EQ.0) WRITE (6,77) NPG	PAGE
	IF (IJK.EQ.0) NPG=NPG+1	PAGE
	77 FORMAT('1',122X,'PAGE',15/120X,'CARD F.5'/	PAGE
	* THE FOLLOWING JOINT RESTORING FORCE FUNCTIONS AS DEFINED	FINPUT
	*ON CARDS E.7 WILL BE USED.'//4X,'JOINT',10X,'FUNCTION'//)	FINPUT
	JF = JOINTF(J)	FINPUT
	IJK = 1	FINPUT



	WRITE (6,78) J,JOINT(J),JF,(JTITLE(I,JF),I=1,5)	FINPUT
78	FORMAT(I6,'-',A4,I10,'-',5A4)	FINPUT
	IF (NTI(JF).EQ.0) WRITE (6,42)	FINPUT
	IF (NTI(JF).EQ.0) STOP 17	FINPUT
80	CONTINUE	FINPUT
C		FINPUT
C	INPUT CONTACT SEGMENTS FOR AIRBAG, IF ANY.	FINPUT
C		FINPUT
81	IF (NBAG.LE.0) GO TO 69	FINPUT
	IJK = 0	FINPUT
	DO 68 J=1,NBAG	FINPUT
C		FINPUT
C	INPUT CARD F.6.(J)	FINPUT
C		FINPUT
	READ (5,63) K,NK,(MBAG(2,I,J),MBAG(3,I,J),I=1,NK)	FINPUT
63	FORMAT(2I4,20I2)	FINPUT
	MNBAG(J) = NK	FINPUT
	IF (NK.EQ.0) GO TO 68	FINPUT
	IF (IJK.EQ.0) WRITE (6,64)	FINPUT
64	FORMAT(////5X,'AIRBAG',4X,'VS.',4X,'SEGMENTS',90X,'CARDS F.6')	FINPUT
	IF (K.NE.J) WRITE (6,42)	FINPUT
	IF (K.NE.J) STOP 20	FINPUT
	WRITE (6,65) J,(MBAG(2,I,J),MBAG(3,I,J),I=1,NK)	FINPUT
65	FORMAT('0 NO.',I2,12X,10(I3,'-',I3))	FINPUT
	DO 66 I=1,NK	FINPUT
	K = MBAG(2,I,J)	FINPUT
66	KTITLE(I) = SEG(K)	FINPUT
	WRITE (6,67) (BAGTTL(I,J),I=1,5),(KTITLE(I),I=1,NK)	FINPUT
67	FORMAT(1X,5A4,10(3X,A4))	FINPUT
68	CONTINUE	FINPUT
C		FINPUT
C	INPUT CARDS F.7.A-F.7.B FOR SUBROUTINE WINDY.	FINPUT
C		FINPUT
69	DO 85 J=1,NGRND	FINPUT
85	MWSEG(1,J) = 0	FINPUT
	IF (NWINDF.EQ.0) GO TO 99	FINPUT
	READ (5,33) (MWSEG(1,J),J=1,NSEG)	FINPUT
	IPAGE = 0	FINPUT
	DO 73 J=1,NSEG	FINPUT
	IWIND(J) = 0	FINPUT
	WTIME(J) = 0.0	FINPUT
	IF (MWSEG(1,J).EQ.0) GO TO 73	FINPUT
	IF (IPAGE.EQ.0) WRITE (6,70) NPG	PAGE
	IF (IPAGE.EQ.0) NPG=NPG+1	PAGE
70	FORMAT('1 SEGMENT WIND FORCES',102X,'PAGE',I5/120X,'CARDS F.7'/	PAGE
*	75X,'DRAG COEFFICIENT BLOCKING'/	WINDOP
*	' SEGMENT-ELLIPSOID SEGMENT-PLANE',	WINDOP
*	16X,'WIND FORCE FUNCTION',10X,'FUNCTION',9X,	WINDOP
*	'SEGMENTS-ELLIPSOID')	WINDOP
	IPAGE = 1	FINPUT

READ(5,86) (MWSEG(I,J),I=1,7), (MOWSEG(J,K),K=1,2*MWSEG(7,J))	WINDOP
86 FORMAT (7I4,22I2/(I30,7I2))	WINDOP
WRITE(6,71) (MWSEG(I,J),I=1,6)	OUT385
71 FORMAT(1H0,I6,2H -,I3,I13,2H -,I3,I31,I23)	OUT385
IF (IABS(MWSEG(1,J)).NE.J) WRITE (6,42)	WINDOP
IF (IABS(MWSEG(1,J)).NE.J) STOP 21	WINDOP
M3 = MWSEG(3,J)	FINPUT
M4 = MWSEG(4,J)	FINPUT
M5 = MWSEG(5,J)	FINPUT
M6 = MWSEG(6,J)	WINDOP
M7 = MWSEG(7,J)	OUT385
DO 172 II=1,5	FIXWBS
KTITLE(II)=BLANK	FIXWBS
172 IF (M6.NE.0) KTITLE(II)=JTITLE(II,M6)	FIXWBS
WRITE (6,72) SEG(J),SEG(M3), (PLTTL(I,M4),I=1,5)	FINPUT
* , (JTITLE(I,M5),I=1,5), (KTITLE(I),I=1,5)	FIXWBS
* , (MOWSEG(J,K),K=1,2*M7)	OUT385
72 FORMAT(3X,A4,14X,A4,1H-,5A4,3X,5A4,3X,5A4,2X,3(5(I3,1H-,I3)/94X))	OUT385
73 CONTINUE	FINPUT
99 RETURN	FINPUT
END	FINPUT

	SUBROUTINE FLXSEG		FLXSEG
C		REV IV	07/23/86TWOPI
	IMPLICIT REAL*8(A-H,O-Z)		FLXSEG
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		FLXSEG
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		FLXSEG
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		FLXSEG
	COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)		FLXSEG
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		FLXSEG
	* UNITL,UNITM,UNITT,GRAVTY(3),TWOPI		TWOPI
	COMMON/TEMPVS/ TT(3,3), THN(4), CN1(3,3), CN(3,3), WNM1(3),		FLXSEG
	* THND(4), PTD(3), WCSN(3), RHSN(3), RHS1(3),		FLXSEG
	* RHS2(3), GF(3,4), GC(3,3), CGC(3,3), THA(3),		FLXSEG
	* THAD(3), THADEG(3), DN2N1(3,3), RMG(3)		FLXSEG
	DIMENSION IDYPR(3)		FLXSEG
	DATA IDYPR/3,2,1/		FLXSEG
	IF (NFLX.EQ.0) GO TO 99		FLXSEG
	CALL ELTIME(1,34)		FLXSEG
	IFX = 1		FLXSEG
11	N1 = NFLEX(1,IFX)		FLXSEG
	N3 = NFLEX(3,IFX)		FLXSEG
	CALL DOT33(D(1,1,N3),D(1,1,N1),TT)		FLXSEG
	THN(1) = DATAN2(TT(1,2),TT(1,1))		FLXSEG
	THN(2) = -DASIN(TT(1,3))		FLXSEG
	THN(3) = DATAN2(TT(2,3),TT(3,3))		FLXSEG
	THN(4) = 1.0		FLXSEG
	CT22 = 1.0-TT(1,3)**2		FLXSEG
	CT2 = DSQRT(CT22)		FLXSEG
	ST2 = -TT(1,3)		FLXSEG
	CT1 = TT(1,1)/CT2		FLXSEG
	ST1 = TT(1,2)/CT2		FLXSEG
	CN1(1,1) = -TT(1,1)*TT(1,3)/CT22		FLXSEG
	CN1(1,2) = -TT(1,2)*TT(1,3)/CT22		FLXSEG
	CN1(1,3) = 1.0		FLXSEG
	CN1(2,1) = -ST1		FLXSEG
	CN1(2,2) = CT1		FLXSEG
	CN1(2,3) = 0.0		FLXSEG
	CN1(3,1) = TT(1,1)/CT22		FLXSEG
	CN1(3,2) = TT(1,2)/CT22		FLXSEG
	CN1(3,3) = 0.0		FLXSEG
	CALL DOT31(TT,WMEG(1,N3),WNM1)		FLXSEG
	DO 12 I=1,3		FLXSEG
12	WNM1(I) = WNM1(I) - WMEG(I,N1)		FLXSEG
	CALL MAT31(CN1,WNM1,THND)		FLXSEG
	THND(4) = 0.0		FLXSEG
	CALL CROSS(WMEG(1,N1),WNM1,WCSN)		FLXSEG
	RHSN(1) = ( (-THND(1)*ST1*ST2 + THND(2)*CT1/CT2)*WNM1(1)		FLXSEG
	* + ( THND(1)*CT1*ST2 + THND(2)*ST1/CT2)*WNM1(2) )/CT2		FLXSEG
	RHSN(2) = -THND(1)*(CT1*WNM1(1) + ST1*WNM1(2))		FLXSEG
	RHSN(3) = ( (-THND(1)*ST1 + THND(2)*CT1*ST2/CT2)*WNM1(1)		FLXSEG



25	RHS1(I) = RHS2(I) - RHS1(I)	FLXSEG
	CALL MAT31(GC, WNM1, RHS2)	FLXSEG
	RHS1(1) = RHS1(1) - THAD(1)*(CN(2,2)*RHS2(2)-CN(1,2)*CSC*RHS2(3))	FLXSEG
*	- THAD(2)*CN(2,2)*CSS*RHS2(3)	FLXSEG
	RHS1(2) = RHS1(2) + THAD(1)*(CN(1,2)*RHS2(2)+CN(2,2)*CSC*RHS2(3))	FLXSEG
*	+ THAD(2)*CN(1,2)*CSS*RHS2(3)	FLXSEG
	RHS1(3) = RHS1(3) - THAD(2)*CSC*RHS2(3)	FLXSEG
	CALL MAT31(GF, RHSN, RHS2)	FLXSEG
	M = 1	FLXSEG
	DO 30 I=1,3	FLXSEG
	DO 26 J=1,3	FLXSEG
	PTD(J) = 0.0	FLXSEG
	DO 26 K=1,3	FLXSEG
	KK = K+M-1	FLXSEG
26	PTD(J) = PTD(J) + HF(J, KK, IFX)*THND(K)	FLXSEG
	RHS2(I) = RHS2(I) + XDY(PTD, CN1, WNM1)	FLXSEG
30	M = M+4	FLXSEG
	CALL MAT31(CN, RHS2, PTD)	FLXSEG
	DO 35 I=1,3	FLXSEG
35	RHS1(I) = RHS1(I) + PTD(I)	FLXSEG
	CALL DOT31(D(1,1,N1), RHS1, V4(1, IFX))	FLXSEG
	IF (IFX.EQ.NFLX) GO TO 98	FLXSEG
	IFX = IFX+1	FLXSEG
	IF (NFLEX(1, IFX).EQ.N1 .AND. NFLEX(3, IFX).EQ.N3) GO TO 13	FLXSEG
	GO TO 11	FLXSEG
98	CALL ELTIME(2, 34)	FLXSEG
99	RETURN	FLXSEG
	END	FLXSEG

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C      DOUBLE PRECISION FUNCTION FINTERP(THETA,PHI,NT)
C
C      REV IV      04/10/87FNFIX
C      COMPUTES THE RESTORING TORQUE OF A JOINT AS A FUNCTION OF THE
C      FLEXURE ANGLE (THETA) AND THE AZIMUTH ANGLE (PHI) AS DEFINED BY
C      FUNCTION NO. NT
C
C      ASSUMES  0 < THETA < PI
C               -PI < PHI < PI
C               DATA IN TAB ARRAY CONTAINS NTHETA,NPHI FOLLOWED BY
C               TWO DIMENSIONAL ARRAY OF FUNCTIONAL VALUES (NTHETA > 0)
C               OR POLYNOMIAL COEFFICIENTS (NTHETA < 0) FOR EQUALLY
C               SPACED VALUES OF PHI.
C
C               THETA(I) = (I-1)*PI/(NTHETA-1) FOR I=1,NTHETA
C               PHI(J) = -PI + (J-1)*2*PI/NPHI FOR J=1,NPHI
C               F(THETA,PI) = F(THETA,-PI)
C
C      SUBROUTINE EVALUATES G1(THETA) = F(THETA,PHI(J) )
C               G2(THETA) = F(THETA,PHI(J+1))
C               FOR PHI(J) < PHI < PHI(J+1)
C      B/ LINEAR INTERPOLATION OR POLYNOMIAL EVALUATION AND THEN LINEAR
C      INTERPOLATES BETWEEN G1 AND G2 TO OBTAIN F(THETA,PHI).
C      IF F < 0, F IS SET TO ZERO, THEREFORE A DEAD BAND IS OBTAINED
C      BY NEGATIVE VALUES IN THE TABLE.
C
C      IMPLICIT REAL*8 (A-H,O-Z)
C      COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),
C      *          UNITL,UNITM,UNITT,GRAVITY(3),TWOPI
C      COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)
C      IERROR = 0
C      IF (PHI.LT.-PI) IERROR = 1
C      IF (PHI.GT.PI) IERROR = 2
C      IF (THETA.LT.0.0) IERROR = 3
C      IF (THETA.GT.PI) IERROR = 4
C      IF (IERROR.NE.0) WRITE (6,11) IERROR,THETA,PHI,NT
C      11 FORMAT('0 IMPROPER ARGUMENTS TO FUNCTION FINTERP. ERROR CODE =',I4)
C      *          '0 THETA =',G25.15, ' PHI =',G25.15, ' NT =',I6)
C      IF (IERROR.NE.0) STOP 36
C      NF = NTI(NT) + 5
C      NTHETA = TAB(NF)
C      NPHI = TAB(NF+1)
C
C      DETERMINE INDEX AND INTERPOLATION PARAMETERS FOR PHI.
C
C      IF (PHI.GE.PI-EPS(15)) PHI=0.0-PI
C      XNP = (PHI+PI)/TWOPI*TAB(NF+1)
C      NP1 = XNP
C      NP2 = NP1+1
C      IF (NP2.GE.NPHI) NP2 = 0
C      RP2 = XNP - DFLOAT(NP1)

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	RP1 = 1.0 - RP2	FNTERP
	NTH = IABS(NTHETA)	FNTERP
	IP1 = NF+1+NP1*NTH	FNTERP
	IP2 = NF+1+NP2*NTH	FNTERP
C		FNTERP
C	DETERMINE INDEX AND INTERPOLATION PARAMETERS FOR THETA.	FNTERP
C		FNTERP
	IF (NTHETA.LT.0) GO TO 20	FNTERP
	XNT = THETA/PI*(TAB(NF)-1.0)	FNTERP
	NT1 = XNT	FNTERP
	RT2 = XNT - DFLOAT(NT1)	FNTERP
	RT1 = 1.0 - RT2	FNTERP
	IT1 = IP1 + NT1	FNTERP
	IT2 = IP2 + NT1	FNTERP
	G1 = RT1*TAB(IT1+1) + RT2*TAB(IT1+2)	FNTERP
	G2 = RT1*TAB(IT2+1) + RT2*TAB(IT2+2)	FNTERP
	GO TO 23	FNTERP
C		FNTERP
C	COMPUTE FOR POLYNOMIALS IN THETA FOR FIXED PHI.	FNTERP
C		FNTERP
20	NPOLY = -NTHETA-1	FNTERP
	IT1 = IP1 + NPOLY + 2	FNTERP
	IT2 = IP2 + NPOLY + 2	FNTERP
	THETA1 = THETA - TAB(IP1+1)	FNTERP
	THETA2 = THETA - TAB(IP2+1)	FNTERP
	G1 = 0.0	FNTERP
	G2 = 0.0	FNTERP
	DO 21 I=1,NPOLY	FNTERP
	IT1 = IT1-1	FNTERP
	IT2 = IT2-1	FNTERP
	G1 = THETA1*(TAB(IT1)+G1)	FNTERP
21	G2 = THETA2*(TAB(IT2)+G2)	FNTERP
	IF (THETA1.LT.0.0) G1=0.0	FNFIX
	IF (THETA2.LT.0.0) G2=0.0	FNFIX
23	FNTERP = RP1*G1 + RP2*G2	FNTERP
	IF (FNTERP.LT.0.0) FNTERP = 0.0	FNTERP
	RETURN	FNTERP
	END	FNTERP

	SUBROUTINE FRCDFL (D,RATE,M,N,FRCDF,ELOSS)	FRCDFL
		REV III.2 08/08/84REVIII
C	EVALUATE FORCE DEFLECTION FUNCTION AT POINT D, WHERE DEFINITION	FRCDFL
C	OF FUNCTION IS CONTROLLED BY M INDEX OF NTAB ARRAY.	FRCDFL
C	DERIVATIVE, FUNCTION OR INTEGRAL IS EVALUATED AS N = 0,1 OR 2.	FRCDFL
C	NTAB(M) - INDEX TO TAB ARRAY FOR REAL DATA	FRCDFL
C	NTAB(M+1) - INDEX TO TAB ARRAY FOR BASE FUNCTION	FRCDFL
C	NTAB(M+2) - INDEX TO TAB ARRAY FOR INERTIAL FUNCTION, IF ANY	FRCDFL
C		FRCDFL
C	ASSUMES 0 < DG < DCUBIC < DREF < DMAX	FRCDFL
C	BUT ANY < MAY BE LESS THAN OR EQUAL TO	FRCDFL
C		FRCDFL
	IMPLICIT REAL*8(A-H,O-Z)	FRCDFL
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	DIMENB
	F = 0.0	FRCDFL
	ELOSS = 0.0	FRCDFL
	L = NTAB(M)	FRCDFL
	TAB(L) = D	FRCDFL
	IF (D.LT.0.0) GO TO 99	FRCDFL
	DMAX = TAB(L+8)	FRCDFL
	IF (D.LT.DMAX) GO TO 10	FRCDFL
C		FRCDFL
C	DMAX < D , USE MAX VALUE	FRCDFL
C		FRCDFL
	IF (N-1) 99,9,99	FRCDFL
	9 FDMAX = TAB(L+10)	FRCDFL
	F = FDMAX	FRCDFL
	GO TO 40	FRCDFL
	10 DREF = TAB(L+7)	FRCDFL
	IF (D.GE.DREF) GO TO 30	FRCDFL
	DCUBIC = TAB(L+6)	FRCDFL
	IF (DCUBIC.GE.DREF) GO TO 20	FRCDFL
	IF (D.LE.DCUBIC) GO TO 20	FRCDFL
C		FRCDFL
C	DCUBIC < D < DREF , USE CUBIC	FRCDFL
C		FRCDFL
	LC = L+14	FRCDFL
	DC0 = TAB(L+18)	FRCDFL
	X = D-DC0	FRCDFL
	IF (N-1) 12,11,99	FRCDFL
C		FRCDFL
C	USE CUBIC DEFINITION	FRCDFL
C		FRCDFL
	11 F = TAB(LC) + X *(TAB(LC+1)+X*(TAB(LC+2)+X*TAB(LC+3)))	FRCDFL
	GO TO 40	FRCDFL
C		FRCDFL
C	USE DERIVATIVE OF CUBIC	FRCDFL
C		FRCDFL
	12 F = TAB(LC+1)+X*(2.0*TAB(LC+2)+X*3.0*TAB(LC+3))	FRCDFL
	GO TO 99	FRCDFL



20	DG = TAB(L+5)	FRCDFL
	IF (D.LE.DG) GO TO 40	FRCDFL
C		FRCDFL
C	DG < D < DCUBIC , USE QUADRATIC	FRCDFL
C		FRCDFL
	LQ = L+11	FRCDFL
	X = D-DG	FRCDFL
	IF (N-1) 22,21,99	FRCDFL
C		FRCDFL
C	USE QUADRATIC DEFINITION	FRCDFL
C		FRCDFL
21	F = TAB(LQ)+X*(TAB(LQ+1)+X*TAB(LQ+2))	FRCDFL
	GO TO 40	FRCDFL
C		FRCDFL
C	USE DERIVATIVE OF QUADRATIC.	FRCDFL
C		FRCDFL
22	F = TAB(LQ+1)+X*2.0*TAB(LQ+2)	FRCDFL
	GO TO 99	FRCDFL
C		FRCDFL
C	DREF < D < DMAX, USE BASE FUNCTION	FRCDFL
C		FRCDFL
30	IF (N-1) 31,31,99	FRCDFL
31	NB = NTAB(M+1)	FRCDFL
C		FRCDFL
C	EVALUATE BASE FUNCTION	FRCDFL
C		FRCDFL
	IF (NB.GT.0) F = EVALFD(D,NB,N)	FRCDFL
	NI = NTAB(M+2)	FRCDFL
C		FRCDFL
C	ADD INERTIAL FUNCTION , IF ANY	FRCDFL
C		FRCDFL
	IF (NI.GT.0) F = F+EVALFD(D,NI,N)	FRCDFL
40	IF (N.NE.1) GO TO 99	FRCDFL
C		FRCDFL
C	COMPUTE AND ADD RATE DEPENDENT FUNCTIONS, IF ANY.	FRCDFL
C		FRCDFL
C	CURRENT RESTRICTIONS:	FRCDFL
C		FRCDFL
C	1) COMPUTED FOR N=1 (FUNCTION) ONLY.	FRCDFL
C		FRCDFL
C	2) FUNCTION NOS. M+2,M+3 AND M+4 (USED FOR INERTIAL SPIKE,	FRCDFL
C	R FACTOR AND G FACTOR FUNCTIONS) MUST BE NEGATIVE OR ZERO,	FRCDFL
C	I.E., THESE FUNCTIONS CANNOT BE USED IN CONJUNCTION WITH	FRCDFL
C	THE RATE DEPENDENT FUNCTIONS.	FRCDFL
C		FRCDFL
C	3) ASSUMES THE FUNCTIONAL FORM	FRCDFL
C		FRCDFL
C	$F(D,D') = F1(D) + F2(D)*F3(D') + F4(D')$	FRCDFL
C		FRCDFL
C	WHERE F1(D) IS DEFINED BY FUNCTION NTAB(M+1)>0,	FRCDFL

C	I.E., NORMAL FORCE DEFLECTION FUNCTION WITH NO	FRCDFL
C	INERTIAL SPIKE FUNCTION AND DEFAULT VALUES	FRCDFL
C	R=1 AND G=0 (UNLOADING AND RELOADING SAME AS	FRCDFL
C	ORIGINAL LOADING);	FRCDFL
C		FRCDFL
C	F2(D ) IS DEFINED BY FUNCTION NTAB(M+2)<0,	FRCDFL
C	IF NTAB(M+2)=0, F2(D )=0;	FRCDFL
C		FRCDFL
C	F3(D') IS DEFINED BY FUNCTION NTAB(M+3)<0,	FRCDFL
C	IF NTAB(M+3)=0, F3(D')=0;	FRCDFL
C		FRCDFL
C	AND F4(D') IS DEFINED BY FUNCTION NTAB(M+4)<0,	FRCDFL
C	IF NTAB(M+4)=0, F4(D')=0.	FRCDFL
C		FRCDFL
C	NOTE: FUNCTIONAL FORM CAN BE CHANGED BY REVISING PROGRAM	FRCDFL
C	BETWEEN STATEMENTS 40 AND 99.	FRCDFL
C		FRCDFL
	F2 = 0.0	FRCDFL
	F3 = 0.0	FRCDFL
	F4 = 0.0	FRCDFL
	N2 = -NTAB(M+2)	FRCDFL
	N3 = -NTAB(M+3)	FRCDFL
	N4 = -NTAB(M+4)	FRCDFL
	IF (N2.GT.0) F2 = EVALFD (D, N2,N)	FRCDFL
	IF (N3.GT.0) F3 = EVALFD (RATE,N3,N)	FRCDFL
	IF (N4.GT.0) F4 = EVALFD (RATE,N4,N)	FRCDFL
	F = F + F2*F3 + F4	FRCDFL
	ELOSS = RATE*(F2*F3+F4)	FRCDFL
99	FRCDF = F	FRCDFL
	RETURN	FRCDFL
	END	FRCDFL

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SUBROUTINE FSMSOL (C,R,NN,MX,MAXN,JN,MAXDIM)
      REV III.2 08/08/84REVIII
      SOLVES A SET OF SIMULTANEOUS EQUATIONS OF SIZE 3*MM
      WHERE THE MATRIX CONSISTS OF A SET OF 3*3 SUBMATRICES
      STORED IN C(3,3,IJ). THE LOCATION OF THE I,J ELEMENT
      IS STORED IN NN(I,J). I.E. IJ= NN(I,J)

      A NEGATIVE IJ IMPLIES THAT C( , ,IJ!) IS AN
      IDENTITY AND THE RIGHT SIDE IS ZERO. A NEGATIVE
      IJ WILL ONLY OCCUR ON A DIAGONAL ENTRY OF NN.

      THE BASIC EQUATION IS CX=R

      DURING THE SOLUTION THE C MATRIX IS DESTROYED ,IT MAY
      BE NECESSARY TO ADD TO THE C ARRAY.
      THE SOLUTION IS STORED IN R.

      INPUT

      C(3,3,K) GIVEN ARRAY
      R(3,MM) GIVEN RIGHT HAND SIDE
      NN(JJ,JJ) GIVEN ARRAY CONTAINING LOCATIONS OF I,J,ELEMENT
      MX SIZE OF SYSTEM OF SUBMATRICES (POSITIVE INDICATES
          THAT C MATRIX IS SYMMETRIC, NEGATIVE IT IS NOT.)
      MAXN LARGEST VALUE IN NN ARRAY
      JN DIMENSION OF NN
      MAXDIM THIRD DIMENSION OF C IN CALLING ROUTINE

      IMPLICIT REAL*8 (A-H,O-Z)
      COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,
      * NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG
      DIMENSION C(3,3,1),R(3,1),NN(JN,1)
      CALL ELTIME(1,20)
      MM = IABS(MX)
      IF (MM.LE.0) GO TO 99
      MM1 = MM-1
      MP1 = MM+1
      DO 50 II=1,MM
      I = MP1-II

      START PIVOT AT BOTTOM - FIND PIVOT - INVERT.

      L = NN(I,I)
      IF (L.LE.0) GO TO 50
      DO 14 M=1,3
      B = 1.0/C(M,M,L)
      C(M,M,L) = 1.0
      C(M,1,L) = B*C(M,1,L)
      C(M,2,L) = B*C(M,2,L)
      C(M,3,L) = B*C(M,3,L)

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IF (KI.EQ.0 .AND. IK.EQ.0) GO TO 40	FSMSOL
DO 30 J=K,IM1	FSMSOL
IJ = NN(I,J)	FSMSOL
JI = NN(J,I)	FSMSOL
IF (KI.EQ.0 .OR. IJ.EQ.0) GO TO 24	FSMSOL
KJ = NN(K,J)	FSMSOL
IF (KJ.NE.0) GO TO 22	FSMSOL
MAXN = MAXN+1	FSMSOL
IF (MAXN.GT.MAXDIM) GO TO 41	FSMSOL
KJ = MAXN	FSMSOL
NN(K,J) = KJ	FSMSOL
DO 21 M=1,3	FSMSOL
DO 21 N=1,3	FSMSOL
21 C(N,M,KJ) = 0.0	FSMSOL
22 DO 23 M=1,3	FSMSOL
DO 23 N=1,3	FSMSOL
23 C(N,M,KJ) = C(N,M,KJ) - C(N,1,KI)*C(1,M,IJ)	FSMSOL
* - C(N,2,KI)*C(2,M,IJ)	FSMSOL
* - C(N,3,KI)*C(3,M,IJ)	FSMSOL
24 IF (J.EQ.K) GO TO 30	FSMSOL
IF (JI.EQ.0 .OR. IK.EQ.0) GO TO 30	FSMSOL
JK = NN(J,K)	FSMSOL
IF (JK.NE.0) GO TO 26	FSMSOL
MAXN = MAXN+1	FSMSOL
IF (MAXN.GT.MAXDIM) GO TO 41	FSMSOL
JK = MAXN	FSMSOL
NN(J,K) = JK	FSMSOL
DO 25 M=1,3	FSMSOL
DO 25 N=1,3	FSMSOL
25 C(N,M,JK) = 0.0	FSMSOL
26 IF (MX.LT.0) GO TO 28	FSMSOL
DO 27 M=1,3	FSMSOL
DO 27 N=1,3	FSMSOL
27 C(N,M,JK) = C(M,N,KJ)	FSMSOL
GO TO 30	FSMSOL
28 DO 29 M=1,3	FSMSOL
DO 29 N=1,3	FSMSOL
29 C(N,M,JK) = C(N,M,JK) - C(N,1,JI)*C(1,M,IK)	FSMSOL
* - C(N,2,JI)*C(2,M,IK)	FSMSOL
* - C(N,3,JI)*C(3,M,IK)	FSMSOL
30 CONTINUE	FSMSOL
IF (KI.EQ.0) GO TO 40	FSMSOL
DO 35 N=1,3	FSMSOL
35 R(N,K) = R(N,K) - C(N,1,KI)*R(1,I)	FSMSOL
* - C(N,2,KI)*R(2,I)	FSMSOL
* - C(N,3,KI)*R(3,I)	FSMSOL
40 CONTINUE	FSMSOL
50 CONTINUE	FSMSOL
GO TO 51	FSMSOL
41 WRITE (6,49) MAXDIM,NPG,(L,L=1,MM)	FSMSOL
	PAGE

	NPG=NPG+1	PAGE
	DO 42 I=1,MM	FSMSOL
42	WRITE (6,43) I,(NN(I,L),L=1,MM)	FSMSOL
43	FORMAT(I3,3X,40I3,3X/6X,40I3)	FSMSOL
	WRITE (6,44) NPG	PAGE
	NPG=NPG+1	PAGE
44	FORMAT('1 FSMSOL PRINT OF RHS ARRAY',96X,'PAGE',I5//)	PAGE
	DO 45 K=1,MM	FSMSOL
45	WRITE (6,46) K,(R(I,K),I=1,3)	FSMSOL
46	FORMAT(I6,9G14.7)	FSMSOL
	WRITE (6,47) NPG	PAGE
	NPG=NPG+1	PAGE
47	FORMAT('1 FSMSOL PRINT OF C ARRAY ELEMENTS',89X,'PAGE',I5//)	PAGE
	DO 48 K=1,MAXN	FSMSOL
48	WRITE (6,46) K,((C(I,L,K),L=1,3),I=1,3)	FSMSOL
49	FORMAT('1 MAXIMUM DIMENSION OF',I4,' ON C ARRAY HAS BEEN EXCEEDED	FSMSOL
	*IN SUBROUTINE FSMSOL.',46X,'PAGE',I5// IF 600, CALL IS FROM SUBRO	PAGE
	*UTINE DAUX. IF 200'	PAGE
	* , ' CALL IS FROM SUBROUTINE HPTURB.'/' PROGRAM IS BEING TERMINATE	PAGE
	*D. COMPLETE PRINT-OUT OF IJK, RHS AND C ARRAYS FOLLOW.'//	FSMSOL
	*' FSMSOL PRINT OF IJK MATRIX'//(6X,40I3))	FSMSOL
	STOP 35	FSMSOL
C		FSMSOL
C	BACKDOWN SOLUTION	FSMSOL
C		FSMSOL
51	IF (MM.EQ.1) GO TO 99	FSMSOL
	DO 90 J=1,MM1	FSMSOL
	IP = J+1	FSMSOL
	DO 80 I=IP,MM	FSMSOL
	IF (NN(I,J).EQ.0) GO TO 80	FSMSOL
	IJ = NN(I,J)	FSMSOL
	DO 75 N=1,3	FSMSOL
75	R(N,I) = R(N,I) - C(N,1,IJ)*R(1,J)	FSMSOL
	* - C(N,2,IJ)*R(2,J)	FSMSOL
	* - C(N,3,IJ)*R(3,J)	FSMSOL
80	CONTINUE	FSMSOL
90	CONTINUE	FSMSOL
99	CALL ELTIME(2,20)	FSMSOL
	RETURN	FSMSOL
	END	FSMSOL

C

SUBROUTINE GLOBAL (J,HD3,DH1,TQC,T9,ANGL)	GLOBAL
IMPLICIT REAL*8 (A-H,O-Z)	GLOBAL
DIMENSION HD3(3),DH1(3,3),T9(3),ANGL(3),CC(3)	GLOBAL
COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),	SLIP
* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),	GLOBAL
* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)	GLOBAL
COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	DIMENB
COMMON/TEMPVI/ CREST,TTI(3),RII(3),R2I(3),JSTOP(4,2,30)	GLOBAL
COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	GLOBAL
* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
IF (DABS(HD3(3)).GT.1.0-EPS(6)) GO TO 34	GLOBAL
ANGL(1) = DACOS(HD3(3))	GLOBAL
NT = IGLOB(J)	GLOBAL
NT1 = NTAP(NT+2)	GLOBAL
CALL HERRON(HD3,NT1,THETO,THETOP)	GLOBAL
JSTOP(4,1,J) = 0	GLOBAL
IF (ANGL(1).LE.THETO) GO TO 34	GLOBAL
JSTOP(4,1,J) = 1	GLOBAL
MT = NTAB(NT+5)	GLOBAL
CREST = TAB(MT+3)	GLOBAL
STH2 = 1.0-HD3(3)**2	GLOBAL
STH = DSQRT(STH2)	GLOBAL
CTH = HD3(3)/STH	GLOBAL
CST = DSQRT(STH2+THETOP**2)	GLOBAL
DR = (ANGL(1)-THETO)*STH/CST	GLOBAL
LT = NTAB(NT)	GLOBAL
TAB(LT) = DR	GLOBAL
NTAB(NT+2) = 0	GLOBAL
DRDOT = 0.0	GLOBAL
CALL FRCDFL (DR,DRDOT,NT,1,TQF,ELOSS)	GLOBAL
NTAB(NT+2) = NT1	GLOBAL
TQC = TQF/CST	GLOBAL
CC(1) = -HD3(2)+HD3(1)*CTH*THETOP	GLOBAL
CC(2) = HD3(1)+HD3(2)*CTH*THETOP	GLOBAL
CC(3) = -STH*THETOP	GLOBAL
DO 28 L=1,3	GLOBAL
28 T9(L) = CC(1)*DH1(L,1) + CC(2)*DH1(L,2) + CC(3)*DH1(L,3)	GLOBAL
34 RETURN	GLOBAL
END	GLOBAL

REV IV 07/24/86

	SUBROUTINE HBELT (J1,J2,KNL0,IND)		HBELT
C		REV IV	02/01/88MISDOT
C	ARGUMENTS:		HBELT
C	J1,J2 - FIRST AND LAST INDEX FOR BELTS.		HBELT
C	KNL0 - ZERO VALUE FOR KNL INDEX.		HBELT
C	IND - 0: CALL IS FROM SUBROUTINE CONTCT		HBELT
C	1: CALL IS FROM SUBROUTINE UPDATE		HBELT
C			HBELT
	IMPLICIT REAL*8 (A-H,O-Z)		HBELT
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)		EDGE
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		MISDOT
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		MISDOT
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		HBELT
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		HBELT
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)		DIMENB
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),		NCFORC
	* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF		HBELT
	COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),		HBELT
	* XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),		HBELT
	* NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)		HBELT
C	THIS COMMON/TEMPVS/ IS SHARED BY HPTURB, HBPLAY, HBELT AND HSETC.		HBELT
	COMMON/TEMPVS/ B(3,3,3),S(3,3),T(3),R(3),V(3),T1(3),T2(3),		HBELT
	* E(3,3,50),EDOT(3,50),FCE(3,50),FR(3,50),ZR(3,50),		HBELT
	* TR(3,50),U(3,50),PTLOSS(2,50),BL(50),FB(50),FP(50),		HBELT
	* OLDBB(100),RHS(3,54),C(3,3,200),IJK(54,54)		HBELT
	CALL ELTIME (1,38)		HBELT
	NTP = 0		HBELT
	K2 = 0		HBELT
	DO 31 JB=J1,J2		HBELT
	IF (IND.EQ.0) NBSF = NBSF + 1		HBELT
	IF (NPTPLY(JB).LE.0) GO TO 31		HBELT
C			HBELT
C	FIRST LOOP ON K		HBELT
C	COMPUTE Z(K),ZR(K),E3(K),U(K-1),BL(K-1),FB(K-1)		HBELT
C	NEED NL(K),BB(K-1)		HBELT
C	NOTE: AN INDEX K-1 REFERS TO BELT SEGMENT BETWEEN K-1 AND K.		HBELT
C			HBELT
	K1 = K2 + 1		HBELT
	K2 = K2 + NPTPLY(JB)		HBELT
	DO 20 K=K1,K2		HBELT
	KNL = KNL0 + K		HBELT
	KI = NL(1,KNL)		HBELT
C			HBELT
C	HERE K IS INDEX OF POINTS IN PLAY ON EACH HARNESS		HBELT
C	KNL IS INDEX OF ALL POINTS IN PLAY		HBELT
C	KI IS INDEX OF ALL POINTS		HBELT
C			HBELT
	KS = IABS(IBAR(1,KI))		HBELT
	IF (KS.GT.100) NTP = 1		HBELT
	IF (KS.GT.100) KS = MOD(KS,100)		HBELT



KE = IBAR(2,KI)	HBELT
CALL DOT31 (D(1,1,KS),BAR(4,KI),T1)	HBELT
CALL DOT31 (D(1,1,KS),BAR(7,KI),T2)	HBELT
DO 11 J=1,3	HBELT
R(J) = V(J)	HBELT
V(J) = BAR(J+3,KI) + BAR(J+6,KI)	HBELT
TR(J,K) = T1(J)	HBELT
ZR(J,K) = T1(J) + T2(J)	HBELT
S(J,2) = S(J,1)	HBELT
11 S(J,1) = SEGLP(J,KS) + ZR(J,K)	HBELT
CALL CROSS (WMEG(1,KS),V,T)	HBELT
IF (KE.EQ.0) GO TO 12	HBELT
CALL MAT31 (BD(7,KE),BAR(4,KI),T2)	HBELT
CALL DOT31 (D(1,1,KS),T2,T1)	HBELT
12 DO 13 J=1,3	HBELT
T(J) = T(J) + BAR(J+12,KI)	HBELT
13 E(J,3,K) = T1(J)	HBELT
CALL DOT31 (D(1,1,KS),T,V)	HBELT
DO 14 J=1,3	HBELT
14 V(J) = V(J) + SEGLV(J,KS)	HBELT
FB(K) = 0.0	HBELT
FP(K) = 0.0	HBELT
IF (K.EQ.K1) GO TO 20	HBELT
DO 15 J=1,3	HBELT
15 U(J,K-1) = S(J,1) - S(J,2)	HBELT
BL(K-1) = DSQRT(U(1,K-1)**2 + U(2,K-1)**2 + U(3,K-1)**2)	HBELT
DO 16 J=1,3	HBELT
16 U(J,K-1) = U(J,K-1)/BL(K-1)	HBELT
STRAIN = (BL(K-1)/BB(KNL-1)) - 1.0	HBELT
IF (STRAIN.LT.EPS(12)) STRAIN = 0.0	MISDOT
NT = NL(2,KNL)	HBELT
BLDOT = U(1,K-1)*(V(1)-R(1))	HBELT
* + U(2,K-1)*(V(2)-R(2))	HBELT
* + U(3,K-1)*(V(3)-R(3))	HBELT
STRDOT = (BB(KNL-1)*BLDOT-BL(K-1)*BBDOT(KNL-1))/BB(KNL-1)**2	HBELT
CALL FRCDL (STRAIN,STRDOT,NT,0,FPK,ELOSS)	HBELT
CALL FRCDL (STRAIN,STRDOT,NT,1,FBK,ELOSS)	HBELT
PTLOSS(1,K-1) = BB(KNL-1)*ELOSS	HBELT
FP(K-1) = FPK	HBELT
FB(K-1) = FBK	HBELT
IF (IND.NE.0) GO TO 20	ENDPFX
IF (K.NE.K1+1) GO TO 19	ENDPFX
BSF(1,NBSF) = STRAIN	ENDPFX
BSF(2,NBSF) = FBK	ENDPFX
19 IF (K.NE.K2) GO TO 20	ENDPFX
BSF(3,NBSF) = STRAIN	ENDPFX
BSF(4,NBSF) = FBK	ENDPFX
20 CONTINUE	HBELT
C	HBELT
C SECOND LOOP ON K	HBELT

C	COMPUTE FCE(K),E1(K),E2(K),EDOT(K),FR(K),U1(KS),U2(KS)	HBELT
C	NEED FB(K&K-1),U(K&K-1),ZR(K),E3(K)	HBELT
C		HBELT
	DO 30 K=K1,K2	HBELT
	KNL = KNLO + K	HBELT
	KI = NL(1,KNL)	HBELT
	KS = IABS(IBAR(1,KI))	HBELT
	IF (KS.GT.100) KS = MOD(KS,100)	HBELT
	DO 21 J=1,3	HBELT
	FCE(J,K) = 0.0	BUTLER1
	IF (K.NE.K2) FCE(J,K) = FB(K)*U(J,K)	BUTLER1
21	IF (K.NE.K1) FCE(J,K) = FCE(J,K) - FB(K-1)*U(J,K-1)	HBELT
	NT = IBAR(3,KI)	HBELT
	NF = NTAB(NT+5)	HBELT
	IF (NF.EQ.0 .AND. IND.EQ.0) GO TO 30	HBELT
	IF (IBAR(4,KI).EQ.0) GO TO 22	HBELT
	CALL DOT31 (D(1,1,KS),BAR(10,KI),T1)	HBELT
	GO TO 24	HBELT
22	DO 23 J=1,3	HBELT
	T1(J) = 0.0	HBELT
	IF (K.NE.K2) T1(J) = U(J,K)	HBELT
23	IF (K.NE.K1) T1(J) = T1(J) + U(J,K-1)	HBELT
24	CALL CROSS (T1,E(1,3,K),E(1,1,K))	HBELT
	CALL CROSS (E(1,3,K),E(1,1,K),E(1,2,K))	HBELT
	DO 25 J=1,3	HBELT
	EDOT(J,K) = DSQRT(E(1,J,K)**2 + E(2,J,K)**2 + E(3,J,K)**2)	HBELT
	DO 25 I=1,3	HBELT
25	E(I,J,K) = E(I,J,K)/EDOT(J,K)	HBELT
	CALL DOT31 (E(1,1,K),FCE(1,K),FR(1,K))	HBELT
30	CONTINUE	HBELT
31	CONTINUE	HBELT
	IF (MTP.LE.0) GO TO 41	HBELT
C		HBELT
C	SUM FCE,FR FOR TIE-POINTS	HBELT
C		HBELT
	KNL1 = KNLO + 2	HBELT
	KNL2 = KNLO + K2	HBELT
	DO 40 KNL=KNL1,KNL2	HBELT
	KI = NL(1,KNL)	HBELT
	KS = IABS(IBAR(1,KI))	HBELT
	IF (KS.LT.100) GO TO 40	HBELT
	KS1 = KS/100	HBELT
	KH = KNL - KNLO	HBELT
	MH = 0	HBELT
	DO 38 JNL=KNL1,KNL	HBELT
	KI = NL(1,JNL-1)	HBELT
	KS = IABS(IBAR(1,KI))	HBELT
	IF (KS.LT.100) GO TO 38	HBELT
	KS2 = KS/100	HBELT
	IF (KS2.NE.KS1) GO TO 38	HBELT

JH = JNL-1 - KNLO	HBELT
IF (MH.EQ.0) MH = JH	HBELT
DO 37 J=1,3	HBELT
IF (MH.EQ.JH) FCE(J,MH) = FCE(J,MH) + FCE(J,KH)	HBELT
37 FCE(J,JH) = FCE(J,MH)	HBELT
CALL DOT31 (E(1,1,JH),FCE(1,JH),FR(1,JH))	HBELT
38 CONTINUE	HBELT
IF (MH.EQ.0) GO TO 40	HBELT
KI = NL(1,KNL)	HBELT
IBAR(1,KI) = -IABS(IBAR(1,KI))	HBELT
DO 39 J=1,3	HBELT
39 FCE(J,KH) = FCE(J,MH)	HBELT
CALL DOT31 (E(1,1,KH),FCE(1,KH),FR(1,KH))	HBELT
40 CONTINUE	HBELT
C	HBELT
C IF CALL IS FROM SUBROUTINE CONTCT,	HBELT
C ADD FORCES (FCE) MODIFIED BY FRICTION TO U1,U2 ARRAYS.	HBELT
C	HBELT
41 IF (IND.NE.0) GO TO 52	HBELT
K2 = 0	HBELT
DO 51 JB=J1,J2	HBELT
IF (NPTPLY(JB).LE.0) GO TO 51	HBELT
K1 = K2 + 1	HBELT
K2 = K2 + NPTPLY(JB)	HBELT
DO 50 K=K1,K2	HBELT
KNL = KNLO + K	HBELT
KI = NL(1,KNL)	HBELT
IF (IBAR(1,KI).LT.0) GO TO 50	HBELT
KS = IBAR(1,KI)	HBELT
IF (KS.GT.100) KS = MOD(KS,100)	HBELT
NT = IBAR(3,KI)	HBELT
NF = NTAB(NT+5)	HBELT
IF (NF.EQ.0) GO TO 43	HBELT
DO 42 J=1,3	HBELT
42 T1(J) = FR(J,K)	HBELT
FR1 = TAB(NF+2)*DABS(T1(3))	HBELT
FR2 = TAB(NF+4)*DABS(T1(3))	HBELT
IF (DABS(T1(1)).GT.FR1) T1(1) = DSIGN(FR1,T1(1))	HBELT
IF (DABS(T1(2)).GT.FR2) T1(2) = DSIGN(FR2,T1(2))	HBELT
CALL MAT31 (E(1,1,K),T1,FCE(1,K))	HBELT
43 CALL CROSS (ZR(1,K),FCE(1,K),T2)	HBELT
CALL MAT31 (D(1,1,KS),T2,T1)	HBELT
DO 44 J=1,3	HBELT
U1(J,KS) = U1(J,KS) + FCE(J,K)	HBELT
44 U2(J,KS) = U2(J,KS) + T1(J)	HBELT
50 CONTINUE	HBELT
51 CONTINUE	HBELT
52 KNLO = KNLO + K2	HBELT
CALL ELTIME (2,38)	HBELT
RETURN	HBELT
END	HBELT

	SUBROUTINE HBPLAY	HBPLAY
		REV III.5 10/17/85EDGE
C	IMPLICIT REAL*8 (A-H,O-Z)	HBPLAY
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	HBPLAY
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)	EDGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	HBPLAY
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	HBPLAY
	COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),	HBPLAY
	* XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),	HBPLAY
	* NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)	HBPLAY
C	THIS COMMON/TEMPVS/ IS SHARED BY HPTURB, HBPLAY, HBELT AND HSETC.	HBPLAY
	COMMON/TEMPVS/ B(3,3,3),S(3,3),T(3),R(3),V(3),T1(3),T2(3),	HBPLAY
	* E(3,3,50),EDOT(3,50),FCE(3,50),FR(3,50),ZR(3,50),	HBPLAY
	* TR(3,50),U(3,50),PTLOSS(2,50),BL(50),FB(50),FP(50),	HBPLAY
	* OLDBB(100),RHS(3,54),C(3,3,200),IJK(54,54)	HBPLAY
	IF (NHRNSS.LE.0) GO TO 99	HBPLAY
C		HBPLAY
C	SAVE PREVIOUS NL,BB AND PLOSS ARRAYS.	HBPLAY
C	USE IJK,OLDBB AND PTLOSS AS TEMP STORAGE.	HBPLAY
C		HBPLAY
	DO 10 I=1,100	HBPLAY
	IJK(I,1) = NL(1,I)	HBPLAY
	PTLOSS(I,1) = PLOSS(1,I)	HBPLAY
10	OLDBB(I) = BB(I)	HBPLAY
	JNL = 1	HBPLAY
	J1 = 1	HBPLAY
	K1 = 1	HBPLAY
	LL = 0	HBPLAY
	DO 90 NH=1,NHRNSS	HBPLAY
	IF (NBLTPH(NH).LE.0) GO TO 90	HBPLAY
	J2 = J1 + NBLTPH(NH) - 1	HBPLAY
	DO 80 NB=J1,J2	HBPLAY
	L1 = LL	HBPLAY
	IF (NPTSPB(NB).LE.0) GO TO 80	HBPLAY
	K2 = K1 + NPTSPB(NB) - 1	HBPLAY
	KB = 0	HBPLAY
	DO 30 K=K1,K2	HBPLAY
	KB = KB + 1	HBPLAY
C		HBPLAY
C	HERE K IS INDEX OF ALL POINTS	HBPLAY
C	KB IS INDEX OF POINTS ON A SINGLE BELT	HBPLAY
C	LL IS INDEX OF ALL POINTS IN PLAY	HBPLAY
C	JB IS INDEX OF PREVIOUS POINT ON BELT IN PLAY	HBPLAY
C		HBPLAY
	KS = IABS(IBAR(1,K))	HBPLAY
	IF (KS.GT.100) KS = MOD(KS,100)	HBPLAY
	CALL DOT31 (D(1,1,KS),BAR(4,K),T1)	HBPLAY
	CALL DOT31 (D(1,1,KS),BAR(7,K),T2)	HBPLAY
	DO 11 J=1,3	HBPLAY

11	U(J,KB) = SEGLP(J,KS) + T1(J) + T2(J)	HBPLAY
	IF (K.EQ.K1) GO TO 30	HBPLAY
	LL = LL + 1	HBPLAY
12	JJ = NL(1,LL)	HBPLAY
	JB = JJ - K1 + 1	HBPLAY
	DSS = 0.0	HBPLAY
	DO 13 J=1,3	HBPLAY
	ZR(J,KB) = U(J,KB) - U(J,JB)	HBPLAY
13	DSS = DSS + ZR(J,KB)**2	HBPLAY
	BL(LL) = DSQRT(DSS)	HBPLAY
	IF (JJ.EQ.K1 .OR. IABS(IBAR(1,JJ)).GT.100) GO TO 30	HBPLAY
	JS = IBAR(1,JJ)	HBPLAY
	JE = IBAR(2,JJ)	HBPLAY
	IF (JE.LE.0) GO TO 30	HBPLAY
	CALL MAT31 (BD(7,JE),BAR(4,JJ),T2)	HBPLAY
	CALL DOT31 (D(1,1,JS),T2,R)	HBPLAY
	DPR = 0.0	HBPLAY
	DO 17 J=1,3	HBPLAY
17	DPR = DPR + R(J)*(ZR(J,KB)/BL(LL) - ZR(J,JB)/BL(LL-1))	HBPLAY
	IF (DPR.LT.0.0) GO TO 30	HBPLAY
	LL = LL - 1	HBPLAY
	GO TO 12	HBPLAY
30	NL(1,LL+1) = K	HBPLAY
	L2 = L1 + 1	HBPLAY
	LL = LL + 1	HBPLAY
	L3 = LL-1	HBPLAY
	DO 31 J=L2,LL	HBPLAY
31	NL(2,J) = NTHRNS(NB)	HBPLAY
	IF (XLONG(NB).EQ.0.0) GO TO 35	HBPLAY
C		HBPLAY
C	FIRST TIME IN ROUTINE, SET INITIAL BB ARRAY.	HBPLAY
C	INPUT XLONG MUST BE NON-ZERO TO TRIGGER THIS TEST.	HBPLAY
C		HBPLAY
	XLG = 0.0	HBPLAY
	DO 32 J=L2,L3	HBPLAY
32	XLG = XLG + BL(J)	HBPLAY
	XLG = 1.0 + XLONG(NB)/XLG	HBPLAY
	DO 33 J=L2,L3	HBPLAY
33	BB(J) = XLG*BL(J)	HBPLAY
	XLONG(NB) = 0.0	HBPLAY
	GO TO 52	HBPLAY
C		HBPLAY
C	DETERMINE IF NEW NL ARRAY IS DIFFERENT FROM PREVIOUS NL ARRAY.	HBPLAY
C	IF SO, RECOMPUTE BB ELEMENTS FOR POINTS THAT ARE DIFFERENT.	HBPLAY
C		HBPLAY
35	IF (NL(1,L2).EQ.IJK(JWL,1)) GO TO 61	HBPLAY
	WRITE (6,62)	HBPLAY
62	FORMAT ('O LOGIC ERROR IN SUB HBPLAY. PROGRAM TERMINATED.')	HBPLAY
	STOP 42	HBPLAY
61	LTEST = 0	HBPLAY

	M = L2	HBPLAY
	N = JNL	HBPLAY
36	IF (NL(1,M+1)-IJK(N+1,1)) 39,37,41	HBPLAY
37	BB(M) = OLDBB(N)	HBPLAY
	PLOSS(1,M) = PTLOSS(N,1)	HBPLAY
38	M = M+1	HBPLAY
	N = N+1	HBPLAY
	IF (M-LL) 36,51,51	HBPLAY
C		HBPLAY
C	POINT M+1 IS NEW.	HBPLAY
C		HBPLAY
39	MO = M	HBPLAY
	NO = N	HBPLAY
	LTEST = 1	HBPLAY
40	M = M+1	HBPLAY
C		CHGIII
C	MODIFY NEW POINT TO LIE IN BELT PLANE	CHGIII
C		CHGIII
	IP1 = N - 1	CHGIII
	IF (N.GT.JNL) GO TO 63	CHGIII
	IP1 = N	CHGIII
C	(IS THIRD POINT AVAILABLE FROM OLD POINTS IN PLAY?)	CHGIII
	IF (IJK(N+1,1).EQ.NL(1,LL)) GO TO 43	CHGIII
63	DO 64 I=1,3	CHGIII
	IP = IP1 + I - 1	CHGIII
C	(USE OLD POINTS IP = N-1,N,N+1 IF N > JNL	CHGIII
C	OR IP = N,N+1,N+2 IF N = JNL AND N+2 EXISTS)	CHGIII
	NI = IJK(IP,1)	CHGIII
	NSI= IABS(IBAR(1,NI))	NSFIX
	IF (NSI.GT.100) NSI = MOD(NSI,100)	NSFIX
	CALL DOT31 (D(1,1,NSI),BAR(4,NI),T1)	NSFIX
	CALL DOT31 (D(1,1,NSI),BAR(7,NI),T2)	NSFIX
	DO 64 J=1,3	CHGIII
64	S(J,1) = SEGLP(J,NSI)+ T1(J) + T2(J)	NSFIX
	DO 65 J=1,3	CHGIII
	S(J,3) = S(J,3) - S(J,2)	CHGIII
65	S(J,2) = S(J,2) - S(J,1)	CHGIII
C	(S(*,1) IS POINT P1 IN INERTIAL REFERENCE)	CHGIII
C	(S(*,2) IS VECTOR (P2-P1) IN INERTIAL REFERENCE)	CHGIII
C	(S(*,3) IS VECTOR (P3-P2) IN INERTIAL REFERENCE)	CHGIII
	CALL CROSS (S(1,3),S(1,2),T2)	CHGIII
	ABST = DSQRT(T2(1)**2 + T2(2)**2 + T2(3)**2)	CHGIII
	DO 66 J=1,3	CHGIII
66	T2(J) = T2(J)/ABST	CHGIII
C	(T2 IS T, THE NORMALIZED PLANE VECTOR IN INERTIAL REFERENCE)	CHGIII
	MI = NL(1,M)	CHGIII
	MS = IABS(IBAR(1,MI))	CHGIII
	IF (MS.GT.100) MS = MOD(MS,100)	CHGIII
	ME = IBAR(2,MI)	CHGIII
	CALL MAT31 (D(1,1,MS),T2,T1)	CHGIII

C	(T1 IS T IN ELLIPSOID REFERENCE OF NEW POINT M)	CHGIII
	D1 = T2(1)*S(1,1) + T2(2)*S(2,1) + T2(3)*S(3,1)	CHGIII
	D2 = T1(1)*BAR(7,MI) + T1(2)*BAR(8,MI) + T1(3)*BAR(9,MI)	CHGIII
	D3 = T2(1)*SEGLP(1,MS) + T2(2)*SEGLP(2,MS) + T2(3)*SEGLP(3,MS)	CHGIII
	DD = D1 - D2 - D3	CHGIII
C	(DD IS D, THE DISTANCE OF ELLIPSOID CENTER TO PLANE)	CHGIII
	CALL MAT31 (BD(16,ME),T1,R)	CHGIII
	BX = DD/(T1(1)*R(1) + T1(2)*R(2) + T1(3)*R(3))	CHGIII
	D4 = T1(1)*BAR(4,MI) + T1(2)*BAR(5,MI) + T1(3)*BAR(6,MI)	CHGIII
	DO 67 J=1,3	CHGIII
	R(J) = BX*R(J)	CHGIII
C	(R IS S, THE CENTER OF THE ELLIPSE)	CHGIII
67	V(J) = BAR(J+3,MI) + (DD-D4)*T1(J)	CHGIII
C	(BAR(J+3,MI) IS P, THE NEW POINT TO BE ADDED)	CHGIII
C	(V IS Q, THE PROJECTION OF POINT P ONTO THE PLANE)	CHGIII
	AX = DSQRT( (BX*DD-1.0) / (BX*DD-XDY(V,BD(7,ME),V)) )	CHGIII
	DO 68 J=1,3	CHGIII
68	BAR(J+3,MI) = R(J) + AX*(V(J)-R(J))	CHGIII
C	(BAR(J+3,MI) IS R = S + A(Q - S), Q EXTENDED TO ELLIPSOID)	CHGIII
	GO TO 43	HBPLAY
C		HBPLAY
C	POINT N+1 IS DROPPED.	HBPLAY
C		HBPLAY
41	MO = M	HBPLAY
	NO = N	HBPLAY
	LTEST = 1	HBPLAY
42	N = N+1	HBPLAY
43	IF (NL(1,M+1)-IJK(N+1,1)) 40,44,42	HBPLAY
C		HBPLAY
C	POINTS NO TO N+1 ARE BEING REPLACED WITH POINTS MO TO M+1.	HBPLAY
C		HBPLAY
44	SUMBL = 0.0	HBPLAY
	DO 45 J=MO,M	HBPLAY
45	SUMBL = SUMBL + BL(J)	HBPLAY
	SUMPL = 0.0	HBPLAY
	SUMBB = 0.0	HBPLAY
	DO 46 J=NO,N	HBPLAY
	SUMPL = SUMPL + PTLOSS(J,1)	HBPLAY
46	SUMBB = SUMBB + OLDBB(J)	HBPLAY
	RATPL = SUMPL/SUMBL	HBPLAY
	RATIO = SUMBB/SUMBL	HBPLAY
	DO 47 J=MO,M	HBPLAY
	PLOSS(1,J) = RATPL*BL(J)	HBPLAY
47	BB(J) = RATIO*BL(J)	HBPLAY
	GO TO 38	HBPLAY
51	JNL = N+1	HBPLAY
	IF (LTEST.EQ.0) GO TO 79	HBPLAY
C		HBPLAY
C	PRINT NEW POINT ARRAY IF DIFFERENT.	HBPLAY
C		HBPLAY

52	NPTS = LL - L1	HBPLAY
	USEC = 1000.0*TIME	HBPLAY
	WRITE (6,53) USEC,NH,NB,NPTS,NTHRNS(NB)	HBPLAY
53	FORMAT ('0 HBPLAY TIME =',F10.3,' MSEC. NH,NB,NPTS NT=',4I6)	HBPLAY
	WRITE (6,54) (NL(1,J),J=L2,LL)	HBPLAY
54	FORMAT (' NL(1)=' ,15I8/(8X,15I8))	HBPLAY
	WRITE (6,55) (BB(J),J=L2,L3)	HBPLAY
55	FORMAT (' BB =',6X,14F8.3/(6X,15F8.3))	HBPLAY
79	K1 = K2 + 1	HBPLAY
80	NPTPLY(NB) = LL - L1	HBPLAY
	J1 = J2 + 1	HBPLAY
90	CONTINUE	HBPLAY
99	RETURN	HBPLAY
	END	HBPLAY



	SUBROUTINE HEDING (LINES,LPP)		HEDING
C		REV IV 02/01/88	MISDOT
	IMPLICIT REAL*8 (A-H,O-Z)		HEDING
	COMMON/CONTRL/ TIME,NSEG,NJNT,MPL,NBLT,NBAG,NVEH,NGRND,		HEDING
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),		HEDING
	* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),		HEDING
	* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)		HEDING
	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),		HEDING
	* BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30),		HEDING
	* JOINT(30),CGS(30),JS(30)		HEDING
	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT		HEDING
	LOGICAL*1 CGS,JS		HEDING
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),		NCFORC
	* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF		HEDING
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		HEDING
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),		ATBIII
	* NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)		TTHKREF
	COMMON/DAMPER/ APSDM(3,20),APSDN(3,20),ASD(5,20),MSDM(20),MSDN(20)		HEDING
	COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),		HEDING
	* XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),		HEDING
	* NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)		HEDING
C	NOTE: SUBROUTINES POSTPR & HEDING SHARE THIS COMMON/TEMPVS/.		HEDING
C	SEE COMMENT IN POSTPR ABOUT FIRST DIMENSION OF PLDATA.		HEDING
	REAL HEAD,PHED,BLANK,PLDATA,USEC,ZTTH,AHED,AHEAD,GHED,ZZZ		PLTINC
	COMMON/TEMPVS/ TDATA(14,65),HEAD(20),NOPL(150),MOPL(150),		CHGIII
	* MIPL(150),PLDATA(97,20),USEC(45),ZZZ(1000,25),ZTTH(14,45,65)		MISDOT
	LOGICAL LOLD , LNEW		HEDING
	DIMENSION PHED(5),HEDJ(4,2),HEADJJ(4,2),HEADR(20)		TTHKREF
	DATA HEDJ/SHIPIN FL,SHEXURE A,SHZIMUTH ,SHTORSSION ,		HEDING
	* SHIEULER ,SHPREC. N,SHUTATION ,SH SPIN /		HEDING
	DIMENSION AHED(5,2),AHEAD(5,20),GHED(2)		ACCEL
	DATA AHED/4H IN ,4H ,4H REF,4HEREN,4HCE ,		ACCEL
	* 4H AC,4HCELE,4HROME,4HTER ,4H /		ACCEL
	DATA GHED/4H(OG),4H(IG)/		ACCEL
	DATA BLANK/4H /		HEDING
	DATA PHED/4HSPRF,4HPNL1,4HPNL2,4HPNL3,4HPNL4/		HEDING
	NPRT4 = NPRT(4) + 4		HEDING
	IF (NPRT4.LE.0 .OR. NPRT4.GT.8) STOP 40		HEDING
	GO TO (11,11,82,12,12,11,11,12) , NPRT4		HEDING
11	LOLD = .FALSE.		HEDING
	LNEW = .TRUE.		HEDING
	GO TO 13		HEDING
12	LOLD = .TRUE.		HEDING
	LNEW = .FALSE.		HEDING
13	MT = 20		HEDING
	NLINES = MOD(LINES-1,LPP)+1		HEDING
	XPAGE = 0.01*FLOAT((LINES + LPP-1)/LPP)		HEDING
C			HEDING

C	NOTE: MT WILL BE THE PAGE OR OUTPUT UNIT COUNTER	HEDING
C	NT WILL BE THE ACTUAL OUTPUT UNIT NUMBER	HEDING
C	IT WILL BE THE INDEX TO THE DATA ARRAY	HEDING
C	NLINES WILL BE THE NUMBER OF LINES TO BE PRINTED	HEDING
C		HEDING
C	EVERY LPP LINES PRINT HEADINGS FOR 9 TYPES OF OUTPUT ABOVE.	WINDOP
C		HEDING
	DO 20 K=1,9	WINDOP
	IF (MSG(K).LE.0) GO TO 20	HEDING
	KSG = MSG(K)	HEDING
	IF (K.EQ.9) GO TO 455	WINDOP
	J3 = 3	HEDING
	IF (K.EQ.7) J3 = 2	HEDING
	DO 19 J1=1,KSG,J3	HEDING
	MT = MT + 1	HEDING
	NT = MT	HEDING
	IF (LNEW) NT = 6	HEDING
	IT = MT - 20	HEDING
	PAGE = FLOAT(MT) + XPAGE	HEDING
C	P & E PRINTER CARRIAGE CONTROL	PECONV
	CALL CARCON(NT,1)	PECONV
	IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE
	IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
	IF (NT.EQ.6) NPG=NPG+1	PAGE
	WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL	PAGE
	IF (K.EQ.1) WRITE (NT,22)	TTHKREF
	IF (K.EQ.2) WRITE (NT,23) UNITL,UNITT	TTHKREF
	IF (K.EQ.3) WRITE (NT,24) UNITL	TTHKREF
	IF (K.EQ.4) WRITE (NT,25) UNITT	TTHKREF
	IF (K.EQ.5) WRITE (NT,26) UNITT	TTHKREF
	IF (K.EQ.6) WRITE (NT,27)	TTHKREF
	IF (K.EQ.7) WRITE (NT,28)	HEDING
	IF (K.EQ.8) WRITE(NT,200) UNITM	TTHKREF
	J2 = MIN0(J1+J3-1,KSG)	HEDING
	DO 14 J=J1,J2	HEDING
	KK = MSG(J,K)	HEDING
	HEAD(J) = SEG(IABS(KK))	ACCEL
	IF ((K.LT.7).OR.(K.EQ.8)) GO TO 214	TTHKREF
	KK = IABS(KK)	HEDING
	HEAD(J) = JOINT(KK)	HEDING
	JJ2 = J-J1+1	HEDING
	K2 = 1	HEDING
	IF (MSG(J,K).LT.0) K2 = 2	HEDING
	DO 35 K1=1,4	HEDING
	35 HEADJJ(K1,JJ2) = HEDJ(K1,K2)	HEDING
	GO TO 14	TTHKREF
214	IF (MSG(J,K).LT.0) GOTO 302	ACCEL
	IF (KREF(J,K).EQ.0) HEADR(J)=SEG(NVEH)	ACCEL
	IF (K.EQ.8) HEADR(J)=SEG(NGRND)	TTHKREF

IF (K.EQ.1 .OR. K.EQ.4) HEADR(J)=SEG(KK)	TTHKREF
IF (KREF(J,K).NE.0) HEADR(J)=SEG(KREF(J,K))	TTHKREF
DO 301 II=1,5	ACCEL
301 AHEAD(II,J)=AHED(II,1)	ACCEL
AHEAD(2,J)=HEADR(J)	ACCEL
GOTO 14	ACCEL
302 HEADR(J)=SEG(IABS(KK))	ACCEL
DO 303 II=1,4	ACCEL
303 AHEAD(II,J)=AHED(II,2)	ACCEL
AHEAD(5,J)=GHED(KREF(J,K)+1)	ACCEL
14 CONTINUE	HEDING
IF (K.LE.3) WRITE (NT,29) (BLANK,(XSG(I,J,K),I=1,3),J=J1,J2)	HEDING
IF (K.LE.6) WRITE (NT,30) (BLANK,MSG(J,K),HEAD(J),J=J1,J2)	HEDING
IF (K.EQ.8) WRITE (NT,30) (BLANK,MSG(J,K),HEAD(J),J=J1,J2)	WINDOP
IF (K.LE.6 .OR. K.EQ.8) WRITE (NT,230)	ACCEL
* (BLANK,(AHEAD(II,J),II=1,5),J=J1,J2)	ACCEL
IF ((K.LE.5).OR.(K.EQ.8)) WRITE (NT,31) (BLANK,J=J1,J2)	WINDOP
IF (K.EQ.6) WRITE (NT,32) (BLANK,J=J1,J2)	HEDING
IF ((K.LT.7).OR.(K.EQ.8)) GOTO 15	WINDOP
WRITE (NT,33) (BLANK,MSG(J,K),HEAD(J),J=J1,J2)	HEDING
WRITE (NT,36) (BLANK,UNITL,UNITM,J=J1,J2)	HEDING
WRITE (NT,37) (BLANK,(HEADJJ(K1,J),K1=1,4),J=1,JJ2)	HEDING
15 WRITE (NT,38)	HEDING
IF (.NOT.LNEW) GO TO 19	HEDING
IF (K.EQ.7) GO TO 17	HEDING
JJ = 4*(J2-J1+1)	HEDING
DO 16 I=1,NLINES	HEDING
16 WRITE (NT,39) USEC(I),(ZTTH(J,I,IT),J=1,JJ)	HEDING
GO TO 19	HEDING
17 JJ = 7*(J2-J1+1)	HEDING
DO 18 I=1,NLINES	HEDING
18 WRITE (NT,40) USEC(I),(ZTTH(J,I,IT),J=1,JJ)	HEDING
19 CONTINUE	HEDING
GO TO 20	CHGIII
C	CHGIII
C PRINT HEADING FOR JOINT FORCES & TORQUES	CHGIII
C	CHGIII
455 CONTINUE	CHGIII
DO 860 II=1,KSG	CHGIII
IF(KREF(II,K).EQ.0) KRF = NVEH	TTHKREF
IF(KREF(II,K).NE.0) KRF = KREF(II,K)	TTHKREF
JRF = MSG(II,9)	WINDOP
MT = MT + 1	CHGIII
NT = MT	CHGIII
IF (LNEW) NT = 6	CHGIII
C P & E CARRIAGE CONTROL	PECONV
CALL CARCON(NT,1)	PECONV
IT = MT - 20	CHGIII
PAGE = FLOAT (MT) + XPAGE	CHGIII
IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE

IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
IF (NT.EQ.6) NPG=NPG+1	PAGE
WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL	PAGE
WRITE (NT,850) JOINT(JRF),SEG(JRF+1),SEG(KRF)	OUT385
WRITE (NT,38)	CHGIII
WRITE (NT,851) UNITM,UNITL,UNITM	CHGIII
WRITE (NT,852)	CHGIII
WRITE (NT,38)	CHGIII
IF (.NOT.LNEW) GO TO 857	CHGIII
DO 858 JK=1,NLINES	CHGIII
WRITE (NT,856) USEC(JK),(ZTTH(J,JK,IT),J=1,6)	CHGIII
858 CONTINUE	CHGIII
857 CONTINUE	CHGIII
850 FORMAT(' '/47X,	TTHKREF
* A4,' JOINT FORCES & TORQUES ON ',A4,' IN ',A4,' REFERENCE')	OUT385
851 FORMAT(4X,4HTIME,7X,13HJOINT FORCE (,A4,7H 10**2),10X,	CHGIII
*14HJOINT TORQUE (,A4,1H-,A4,7H 10**2))	CHGIII
852 FORMAT(3X,6H(MSEC),8X,1HX,8X,1HY,8X,1HZ,14X,1HX,11X,1HY,11X,1HZ)	CHGIII
856 FORMAT(F9.3,3X,3F9.3,3X,3(2X,D10.3))	CHGIII
860 CONTINUE	CHGIII
20 CONTINUE	HEDING
121 FORMAT('1',18X,'DATE:',3X,4A4,80X,'PAGE',I5)	PAGE
21 FORMAT(8X,'RUN DESCRIPTION:',3X,20A4/27X,20A4,'PAGE:',F6.2/	PAGE
* 3X,'VEHICLE DECELERATION:',3X,20A4/	HEDING
* 11X,'CRASH VICTIM:',3X,5A4 )	HEDING
22 FORMAT(' '/47X,	TTHKREF
* 'POINT TOTAL ACCELERATION (G'S)'/)	TTHKREF
23 FORMAT(' '/47X,	TTHKREF
* 'POINT REL. VELOCITY (',A4,'/',A4,')'/)	TTHKREF
24 FORMAT(' '/47X,	TTHKREF
* 'POINT REL. LINEAR DISPLACEMENT (',A4,')'/)	TTHKREF
25 FORMAT(' '/47X,	TTHKREF
* 'SEGMENT ANGULAR ACCELERATION (REV/',A4,'**2)'/)	TTHKREF
26 FORMAT(' '/47X,	TTHKREF
* 'SEGMENT REL. ANGULAR VELOCITY (REV/',A4,')'/)	TTHKREF
27 FORMAT(' '/47X,	TTHKREF
* 'SEGMENT REL. ANGULAR DISPLACEMENT (DEG)'/)	TTHKREF
28 FORMAT(' '/47X,'JOINT PARAMETERS'/)	TTHKREF
200 FORMAT(' '/47X,'SEGMENT WIND FORCE (',A4,')'/)	TTHKREF
29 FORMAT(9X,3(A4,3X,'POINT (',F6.2,',',F6.2,',',F6.2,') ON '))	HEDING
30 FORMAT('       ',3(A4,9X,'SEGMENT NO.',I3,' - ',A4,5X) )	TTHKREF
230 FORMAT('       TIME ',3(A4,9X,5A4,6X))	ACCEL
31 FORMAT('       (MSEC)',3(A4,5X,'X',8X,'Y',8X,'Z',7X,'RES',1X) )	HEDING
32 FORMAT('       (MSEC)',3(A4,4X,'YAW',5X,'PITCH',5X,'ROLL',5X,'RES '))	HEDING
33 FORMAT(9X,2(A1,21X,'JOINT NO.',I3,' - ',A4,20X) )	HEDING
36 FORMAT('       TIME ',2(A1,'STATE',5X,'JOINT ANGLES (DEG)',8X,	HEDING
*       'TOTAL TORQUE (',2A4,') '))	HEDING
37 FORMAT('       (MSEC)',2(A1,4A8,4X,'SPRING VISCOUS   RES. '))	HEDING
38 FORMAT(1X)	HEDING
39 FORMAT(F9.3,3(3X,4F9.3) )	HEDING

	40 FORMAT(F9.3,2(F5.0,3F9.3,2X,3F9.3))	HEDING
C		ATBIII
C	PRINT BODY PROPERTIES CONTROLLED BY H.10 CARDS	WINDOP
C		ATBIII
	IF (MCG.EQ.0) GO TO 131	ATBIII
	DO 130 NCG=1,MCG	ATBIII
	MT = MT +1	ATBIII
	NT = MT	ATBIII
	IF (LNEW) NT = 6	ATBIII
C	P & E CARRIAGE CONTROL	PECONV
	CALL CARCON(NT,1)	PECONV
	IT = MT - 20	ATBIII
	PAGE = FLOAT(MT) + XPAGE	ATBIII
	IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE
	IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
	IF (NT.EQ.6) NPG=NPG+1	PAGE
	WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL	PAGE
	M = MCGIN(1,MCG)	ATBIII
	WRITE (NT,132) M,SEG(M)	ATBIII
	N = MCGIN(2,MCG)	ATBIII
	WRITE (NT,133) (MCGIN(I+2,MCG),I=1,N)	ATBIII
	WRITE (NT,38)	ATBIII
	WRITE (NT,134) UNITL,UNITM,UNITT,UNITL,UNITM,UNITT,UNITM,UNITL	KINETIC
	WRITE (NT,38)	ATBIII
	IF (.NOT.LNEW) GO TO 130	ATBIII
	DO 129 I=1,NLINES	ATBIII
129	WRITE (NT,135) USEC(I),(ZTTH(J,I,IT),J=1,12)	KINETIC
130	CONTINUE	ATBIII
131	CONTINUE	ATBIII
132	FORMAT(' ',47X,39HBODY PROPERTIES - REFERENCE SEGMENT NO.,	TTHKREF
	* 13,2H (,A4,1H) )	ATBIII
133	FORMAT(15X,21HINCLUDED SEGMENT NOS:,20I3)	ATBIII
134	FORMAT(14X,17HCENTER OF GRAVITY,13X,15HLINEAR MOMENTUM,17X,	KINETIC
	* 16HANGULAR MOMENTUM,18X,14HKINETIC ENERGY/	KINETIC
	* 4X,4HTIME,11X,1H(,A4,1H),21X,1H(,A4,1H-,A4,1H),19X,	KINETIC
	* 1H(,A4,1H-,A4,1H-,A4,1H),20X,1H(,A4,1H-,A4,1H)/	MISC
	* 3X,6H(MSEC),5X,1HX,7X,1HY,7X,1HZ,	KINETIC
	* 2(10X,1HX,10X,1HY,10X,1HZ),6X,6HLINEAR,5X,	KINETIC
	* 7HANGULAR,5X,5HTOTAL)	KINETIC
135	FORMAT(F9.3,3F8.3,9(1X,D10.3))	KINETIC
C		HEDING
C	PLANE FORCES HEADINGS	HEDING
C		HEDING
	MPSF = 0	HEDING
	IF (NPL.EQ.0) GO TO 52	HEDING
	IF (NPRT(18).EQ.1.OR.NPRT(18).EQ.7) GO TO 52	VARTTH
	IF (NPRT(18).EQ.10.OR.NPRT(18).EQ.11) GO TO 52	VARTTH
	IF (NPRT(18).GE.14) GO TO 52	VARTTH
	DO 42 J=1,NPL	HEDING
	IF (MNPL(J).EQ.0) GO TO 42	HEDING

KPL = MNPL(J)	HEDING
DO 41 I=1,KPL	HEDING
MPSF = MPSF+1	HEDING
NOPL(MPSF) = J	HEDING
IF (MPL(3,I,J).LT.0) MIPL(MPSF) = MPL(2,I,J)	CHGIII
IF (MPL(3,I,J).GE.0) MIPL(MPSF) = MPL(1,I,J)	CHGIII
41 MOPL(MPSF) = MPL(2,I,J)	HEDING
42 CONTINUE	HEDING
IF (MPSF.EQ.0) GO TO 52	HEDING
DO 44 J1=1,MPSF,2	HEDING
J2 = MINO(J1+1,MPSF)	HEDING
MT = MT + 1	HEDING
NT = MT	HEDING
IF (LNEW) NT = 6	HEDING
C P & E CARTRIDGE CONTROL	PECONV
CALL CARCON(NT,1)	PECONV
IT = MT - 20	HEDING
PAGE = FLOAT(MT) + XPAGE	HEDING
IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE
IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
IF (NT.EQ.6) NPG=NPG+1	PAGE
WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL	PAGE
WRITE (NT,45)	HEDING
N1 = NOPL(J1)	HEDING
N2 = NOPL(J2)	HEDING
M1 = MOPL(J1)	HEDING
M2 = MOPL(J2)	HEDING
MM1 = MIPL(J1)	CHGIII
MM2 = MIPL(J2)	CHGIII
IF (J1.EQ.J2) WRITE (NT,46)	HEDING
* BLANK,N1,( PLTTL(I,N1),I=1,5),M1,SEG(M1)	HEDING
IF (J1.NE.J2) WRITE (NT,46)	HEDING
* BLANK,N1,( PLTTL(I,N1),I=1,5),M1,SEG(M1),	HEDING
* BLANK,N2,( PLTTL(I,N2),I=1,5),M2,SEG(M2)	HEDING
WRITE (NT,47) (BLANK,UNITL,J=J1,J2)	HEDING
IF (J1.EQ.J2) WRITE (NT,48) BLANK,SEG(MM1)	CHGIII
IF (J1.NE.J2) WRITE (NT,448) BLANK,SEG(MM1),BLANK,SEG(MM2)	CHGIII
WRITE (NT,49) (BLANK,UNITL,UNITM,UNITM,UNITM,J=J1,J2)	HEDING
WRITE (NT,38)	HEDING
IF (.NOT.LNEW) GO TO 44	HEDING
JJ = 7*(J2-J1+1)	HEDING
DO 43 I=1,NLINES	HEDING
43 WRITE (NT,50) USEC(I),(ZTTH(J,I,IT),J=1,JJ)	HEDING
44 CONTINUE	HEDING
45 FORMAT(27X,'CONTACT FORCES - SEGMENT PANELS VS. SEGMENTS' )	CHGIII
46 FORMAT(' '/8X,2(A4,' PANEL',I3,' (' ,5A4,' ) VS. SEGMENT',I3,	HEDING
* ' (' ,A4,' ) ' )	HEDING
47 FORMAT(' '/8X,A4,'DEFL- NORMAL FRICTION RESULTANT CONTACT LOCATHEDING	
*ION (' ,A4,' )',A2,'DEFL- NORMAL FRICTION RESULTANT CONTACT LOCATHEDING	
*ION (' ,A4,' )')	HEDING

48	FORMAT(' TIME',A4,'ECTION	FORCE	FORCE	FORCE	(' ,A4	CHGIII
	*, 'REFERENCE')' )					CHGIII
448	FORMAT(' TIME',A4,'ECTION	FORCE	FORCE	FORCE	(' ,A4	CHGIII
	*, 'REFERENCE)',2X,A4,'ECTION	FORCE	FORCE	FORCE	(' ,A4	CHGIII
	*, 'REFERENCE')' )					CHGIII
49	FORMAT(' (MSEC)',2(A3, '(' ,A4,')',2X, '(' ,A4,')',4X, '(' ,A4,')',3X,					HEDING
	* '(' ,A4,')' X Y Z ') )					HEDING
50	FORMAT(F9.3,2(F9.3,3F9.2,3F8.3) )					HEDING
51	FORMAT(3X, ' (MSEC)',4(A1,9X, 'X',8X, 'Y',8X, 'Z',1X))					HEDING
C						HEDING
C	BELT FORCES HEADINGS					HEDING
C						HEDING
52	MBSF = 0					HEDING
	IF (NPRT(18).EQ.2.OR.NPRT(18).GE.13) GO TO 83					VARTTH
	IF (NPRT(18).GE.7.AND.NPRT(18).LE.9) GO TO 83					VARTTH
	IF (NBLT.EQ.0) GO TO 83					HEDING
	DO 54 J=1,NBLT					HEDING
	IF (MNBLT(J).EQ.0) GO TO 54					HEDING
	MBSF = MBSF+1					HEDING
	NOPL(MBSF) = J					HEDING
	MOPL(MBSF) = MBLT(2,1,J)					HEDING
54	CONTINUE					HEDING
	IF (MBSF.EQ.0) GO TO 83					HEDING
	DO 56 J1=1,MBSF,2					HEDING
	J2 = MINO(J1+1,MBSF)					HEDING
	MT = MT + 1					HEDING
	NT = MT					HEDING
	IF (LNEW) NT = 6					HEDING
C	P & E CARRIAGE CONTROL					PECONV
	CALL CARCON(NT,1)					PECONV
	IT = MT - 20					HEDING
	PAGE = FLOAT(MT) + XPAGE					HEDING
	IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG					PAGE
	IF (NT.NE.6) WRITE(NT,121) DATE					PAGE
	IF (NT.EQ.6) NPG=NPG+1					PAGE
	WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL					PAGE
	WRITE (NT,57)					HEDING
	N1 = NOPL(J1)					HEDING
	N2 = NOPL(J2)					HEDING
	M1 = MOPL(J1)					HEDING
	M2 = MOPL(J2)					HEDING
	IF (J1.EQ.J2) WRITE (NT,58)					HEDING
	* BLANK,N1,(BLTTTL(I,N1),I=1,5),M1,SEG(M1)					HEDING
	IF (J1.NE.J2) WRITE (NT,58)					HEDING
	* BLANK,N1,(BLTTTL(I,N1),I=1,5),M1,SEG(M1),					HEDING
	* BLANK,N2,(BLTTTL(I,N2),I=1,5),M2,SEG(M2)					HEDING
	WRITE (NT,59) (BLANK,J=J1,J2)					HEDING
	WRITE (NT,60) (BLANK,J=J1,J2)					HEDING
	WRITE (NT,61) (BLANK,UNITL,UNITL,UNITM,UNITL,UNITL,UNITM,J=J1,J2)					HEDING
	WRITE (NT,38)					HEDING

	IF (.NOT.LNEW) GO TO 56	HEDING
	JJ = 4*(J2-J1+1)	HEDING
	DO 55 I=1,NLINES	HEDING
	55 WRITE (NT,62) USEC(I),(ZTTH(J,I,IT),J=1,JJ)	HEDING
	56 CONTINUE	HEDING
	57 FORMAT('0',26X,'CONTACT FORCES - BELTS VS. SEGMENTS')	HEDING
	58 FORMAT(' ',7X,2(A4,' BELT',I3,' (' ,5A4,' ) VS. SEGMENT',I3,	HEDING
	* (' ,A4,' ) ' ) )	HEDING
	59 FORMAT(' ',2X,2(A4,11X,'ANCHOR POINT A',14X,'ANCHOR POINT B'))	HEDING
	60 FORMAT(4X,'TIME',2(A4,5X,'STRAIN',7X,'FORCE',12X,	HEDING
	* 'STRAIN',7X,'FORCE',3X) )	HEDING
	61 FORMAT(3X,'(MSEC)',2(A4,2X,' (' ,A4,' / ' ,A4,' )',4X,' (' ,A4,' )',9X,	HEDING
	* ' (' ,A4,' / ' ,A4,' )',4X,' (' ,A4,' )',3X) )	HEDING
	62 FORMAT(F9.3,4(F15.6,F12.2,3X) )	HEDING
C		HEDING
C	HARNESSE BELT ENDPOINTS FORCES HEADINGS	HEDING
C		HEDING
	83 IF (NHRNSS.LE.0) GO TO 91	HEDING
	MBSF = 0	HEDING
	IF (NPRT(18).EQ.3.OR.NPRT(18).EQ.11) GO TO 91	VARTTH
	IF (NPRT(18).EQ.9.OR.NPRT(18).EQ.8) GO TO 91	VARTTH
	IF (NPRT(18).EQ.13.OR.NPRT(18).EQ.14) GO TO 91	VARTTH
	IF (NPRT(18).GE.16) GO TO 91	VARTTH
	J1 = 1	HEDING
	K1 = 1	HEDING
	DO 85 I=1,NHRNSS	HEDING
	IF (NBLTPH(I).LE.0) GO TO 85	HEDING
	J2 = J1 + NBLTPH(I) - 1	HEDING
	DO 84 J=J1,J2	HEDING
	MBSF = MBSF + 1	HEDING
	IF (NPTSPB(J).LE.0) GO TO 84	HEDING
	K2 = K1 + NPTSPB(J) - 1	HEDING
	NOPL(2*MBSF-1) = J	HEDING
	NOPL(2*MBSF ) = I	HEDING
	MOPL(2*MBSF-1) = K1	HEDING
	MOPL(2*MBSF ) = K2	HEDING
	K1 = K2 + 1	HEDING
	84 CONTINUE	HEDING
	J1 = J2 + 1	HEDING
	85 CONTINUE	HEDING
	DO 87 J1=1,MBSF,2	HEDING
	J2 = MINO(J1+1,MBSF)	HEDING
	MT = MT + 1	HEDING
	NT = MT	HEDING
	IF (LNEW) NT = 6	HEDING
C	P & E CARRIAGE CONTROL	PECONV
	CALL CARCON(NT,1)	PECONV
	IT = MT - 20	HEDING
	PAGE = FLOAT(MT) + XPAGE	HEDING
	IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE



IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
IF (NT.EQ.6) NPG=NPG+1	PAGE
WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL	PAGE
WRITE (NT,88)	HEDING
WRITE (NT,89) (BLANK,NOPL(2*J-1),NOPL(2*J),J=J1,J2)	HEDING
WRITE (NT,90) (BLANK,MOPL(2*J-1),MOPL(2*J),J=J1,J2)	HEDING
WRITE (NT,60) (BLANK,J=J1,J2)	HEDING
WRITE (NT,61) (BLANK,UNITL,UNITL,UNITM,UNITL,UNITL,UNITM,J=J1,J2)	HEDING
WRITE (NT,38)	HEDING
IF (.NOT.LNEW) GO TO 87	HEDING
JJ = 4*(J2-J1+1)	HEDING
DO 86 I=1,NLINES	HEDING
86 WRITE (NT,62) USEC(I),(ZTTH(J,I,IT),J=1,JJ)	HEDING
87 CONTINUE	HEDING
88 FORMAT('0',26X,'HARNES SYSTEM BELT ENDPOINT FORCES')	HEDING
89 FORMAT(9X,2(A4,11X,'BELT NO.',14,' OF HARNES NO.',13,15X))	HEDING
90 FORMAT(9X,2(A4,6X,'POINT NO.',15,16X,'POINT NO.',15,6X))	HEDING
C	HEDING
C SPRING DAMPER FORCES HEADINGS	HEDING
C	HEDING
91 IF (NSD.LE.0) GO TO 63	HEDING
IF (NPRT(18).EQ.4.OR.NPRT(18).EQ.9) GO TO 63	VARTTH
IF (NPRT(18).GE.12) GO TO 63	VARTTH
DO 94 J1=1,NSD,4	HEDING
J2 = MIN0(J1+3,NSD)	HEDING
MT = MT + 1	HEDING
NT = MT	HEDING
IF (LNEW) NT = 6	HEDING
C P & E CARRIAGE CONTROL	PECONV
CALL CARCON(NT,1)	PECONV
IT = MT - 20	HEDING
PAGE = FLOAT(MT) + XPAGE	HEDING
IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE
IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
IF (NT.EQ.6) NPG=NPG+1	PAGE
WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL	PAGE
WRITE (NT,95) (BLANK,J,J=J1,J2)	HEDING
DO 92 J=J1,J2	HEDING
M1 = MSDM(J)	HEDING
N1 = MSDN(J)	HEDING
C POSSIBLE OVERFLOW INTO NOPL ARRAY IS INTENTIONAL.	HEDING
HEAD(2*J-1) = SEG(M1)	HEDING
92 HEAD(2*J ) = SEG(N1)	HEDING
WRITE (NT,96) (BLANK,MSDM(J),HEAD(2*J-1),MSDN(J),HEAD(2*J),J=J1,J2)	HEDING
WRITE (NT,97) (BLANK,J=J1,J2)	HEDING
WRITE (NT,98) (BLANK,UNITL,UNITM,J=J1,J2)	HEDING
WRITE (NT,38)	HEDING
IF (.NOT.LNEW) GO TO 94	HEDING
JJ = 2*(J2-J1+1)	HEDING
DO 93 I=1,NLINES	HEDING

93	WRITE (NT,99) USEC(I), (ZTTH(J,I,IT), J=1, JJ)	HEDING
94	CONTINUE	HEDING
95	FORMAT('0', 26X, 'SPRING DAMPER FORCES' /	HEDING
*	9X, 4(A3, 3X, 'SPRING DAMPER NO.', I3, 4X))	HEDING
96	FORMAT(9X, 4(A3, 'SEG', I3, '(', A4, ') - SEG', I3, '(', A4, ')'))	HEDING
97	FORMAT(4X, 'TIME', 1X, 4(A3, 5X, 'LENGTH', 7X, 'FORCE', 4X))	HEDING
98	FORMAT(3X, ' (MSEC)', 4(A3, 5X, '(', A4, ')', 6X, '(', A4, ')', 4X))	HEDING
99	FORMAT (F9.3, 4(F14.3, F12.2, 4X))	HEDING
C		HEDING
C	SEGMENT FORCES HEADINGS	HEDING
C		HEDING
63	MSSF = 0	HEDING
	IF (NPRT(18).EQ.5.OR.NPRT(18).EQ.13) GO TO 161	VARTTH
	IF (NPRT(18).EQ.10.OR.NPRT(18).EQ.11) GO TO 161	VARTTH
	IF (NPRT(18).GE.15) GO TO 161	VARTTH
	DO 65 J=1, MSEG	HEDING
	IF (MNSEG(J).EQ.0) GO TO 65	HEDING
	LSEG = MNSEG(J)	HEDING
	DO 64 I=1, LSEG	HEDING
	MSSF = MSSF+1	HEDING
	NOPL(MSSF) = J	HEDING
64	MOPL(MSSF) = MSEG(2, I, J)	HEDING
65	CONTINUE	HEDING
	IF (MSSF.EQ.0) GO TO 70	HEDING
	DO 67 J=1, MSSF	HEDING
	MT = MT + 1	HEDING
	NT = MT	HEDING
	IF (LNEW) NT = 6	HEDING
C	P & E CARRIAGE CONTROL	PECONV
	CALL CARCON(NT, 1)	PECONV
	IT = MT - 20	HEDING
	PAGE = FLOAT(MT) + XPAGE	HEDING
	IF (NT.EQ.6) WRITE(NT, 121) DATE, BLANK, NPG	PAGE
	IF (NT.NE.6) WRITE(NT, 121) DATE	PAGE
	IF (NT.EQ.6) NPG=NPG+1	PAGE
	WRITE (NT, 21) COMENT, PAGE, VPSTTL, BDYTTL	PAGE
	N1 = NOPL(J)	HEDING
	M1 = MOPL(J)	HEDING
	WRITE (NT, 68) N1, SEG(N1), M1, SEG(M1), UNITL, N1, M1	HEDING
*	, UNITL, UNITM, UNITM, UNITM	HEDING
	IF (.NOT.LNEW) GO TO 67	HEDING
	DO 66 I=1, N1LINES	HEDING
66	WRITE (NT, 69) USEC(I), (ZTTH(JJ, I, IT), JJ=1, 10)	HEDING
67	CONTINUE	HEDING
68	FORMAT('0', 26X, 'CONTACT FORCES - SEGMENT NO.', I3, '(', A4,	HEDING
*	) VS. SEGMENT NO.', I3, '(', A4, ')') //	HEDING
*	13X, 'DEFL- NORMAL FRICTION RESULTANT',	HEDING
*	14X, 'CONTACT LOCATION (' , A4, ')') /	HEDING
*	4X, 'TIME ECTION', 3(3X, 'FORCE', 1X),	HEDING
*	2(' SEG.', I3, ' LOCAL REFERENCE ')/	HEDING

	* 3X,'(MSEC)',3X,'('',A4,'')', 3(3X,'('',A4,'')')	HEDING
	* 2(5X,'X',7X,'Y',7X,'Z',4X)/1X)	HEDING
	69 FORMAT(2F9.3,3F9.2,3F8.3,2X,3F8.3)	HEDING
	161 CONTINUE	VARTTH
C		HEDING
C	AIRBAG FORCES HEADINGS	HEDING
C		HEDING
	70 IF (NBAG.EQ.0) GO TO 82	HEDING
	IF (NPRT(18).EQ.6.OR.NPRT(18).EQ.9) GO TO 82	VARTTH
	IF (NPRT(18).GE.12) GO TO 82	VARTTH
	DO 77 J=1,NBAG	HEDING
	IF (MNBAG(J).EQ.0) GO TO 77	HEDING
	MT = MT + 1	HEDING
	NT = MT	HEDING
	IF (LNEW) NT = 6	HEDING
C	P & E CARRIAGE CONTROL	PECONV
	CALL CARCON(NT,1)	PECONV
	IT = MT - 20	HEDING
	PAGE = FLOAT(MT) + XPAGE	HEDING
	IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE
	IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
	IF (NT.EQ.6) NPG=NPG+1	PAGE
	WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL	PAGE
	WRITE (NT,78) J,(BAGTTL(I,J),I=1,5)	HEDING
	IF (.NOT.LNEW) GO TO 72	HEDING
	DO 71 I=1,NLINES	HEDING
	71 WRITE (NT, 79) USEC(I),(ZTTH(JJ,I,IT),JJ=1,12)	HEDING
	72 KBAG = 0	HEDING
	KP = NPANEL(J)+1	HEDING
	DO 73 K=1,KP	HEDING
	KBAG = KBAG+1	HEDING
	73 HEAD(KBAG) = PHED(K)	HEDING
	KP = MNBAG(J)	HEDING
	DO 74 K=1,KP	HEDING
	KBAG = KBAG+1	HEDING
	M = MBAG(2,K,J)	HEDING
	74 HEAD(KBAG) = SEG(M)	HEDING
	DO 76 J1=1,KBAG,4	HEDING
	J2 = MIN0(J1+3,KBAG)	HEDING
	MT = MT + 1	HEDING
	NT = MT	HEDING
	IF (LNEW) NT = 6	HEDING
C	P & E CARRIAGE CONTROL	PECONV
	CALL CARCON(NT,1)	PECONV
	IT = MT - 20	HEDING
	PAGE = FLOAT(MT) + XPAGE	HEDING
	IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE
	IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
	IF (NT.EQ.6) NPG=NPG+1	PAGE
	WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL	PAGE

WRITE (NT,80)UNITM,J,(BAGTTL(I,J),I=1,5),(BLANK,J,HEAD(K),K=J1,J2)	HEDING
WRITE (NT,51) (BLANK,K=J1,J2)	HEDING
WRITE (NT,38)	HEDING
IF (.NOT.LNEW) GO TO 76	HEDING
JJ = 3*(J2-J1+1)	HEDING
DO 75 I=1,NLINES	HEDING
75 WRITE (NT, 81) USEC(I),(ZTTH(K,I,IT),K=1,JJ)	HEDING
76 CONTINUE	HEDING
77 CONTINUE	HEDING
78 FORMAT('0',26X,'PARAMETERS FOR AIRBAG NO.',I2,4X,5A4//	HEDING
* 16X,'SUPPLY CYLINDER STATIC'/	HEDING
* 4X,'TIME',8X,'PRES.',4X,'TEMP.',4X,'PRES.',12X,'AIRBAG',	HEDING
* 3X,'CENTER',14X,'AIRBAG SEMIAXES',12X,'ORIENTATION (DEG.)'/	HEDING
* 3X,'(MSEC)',7X,'(PSIG) (DEG.R) (PSIG)',8X,'X',8X,'Y',8X,'Z',	HEDING
* 11X,'A',8X,'B',8X,'C',10X,'YAW'.4X,'PITCH',5X,'ROLL'/ )	HEDING
79 FORMAT (F9.3,3X,3F9.2,2(3X,3F9.3),3X,3F9.2)	HEDING
80 FORMAT('0',26X,'CONTACT FORCES (' ,A4,') ON AIRBAG NO.',I2,4X,5A4//	HEDING
* /4X,'TIME',4(A1,11X,'AIRBAG',I2,' VS. ' ,A4,1X))	HEDING
81 FORMAT (F9.3,4(3X,3F9.2))	HEDING
82 RETURN	HEDING
END	HEDING

	SUBROUTINE HERRON(HD3,NT1,THETO,THETOP)	HERRON
C		REV IV 07/23/86TWOPI
C	COMPUTES THETO - ANGLE OF JOINT STOP	HERRON
C	THETOP- DERIVATIVE OF THETO WITH RESPECT TO PHI	HERRON
C		HERRON
C	FROM HD3 - COMPONENTS OF VECTOR DEFINING PHI	HERRON
C	NT1 - INDEX TO TAB ARRAY DEFINING FUNCTION	HERRON
C		HERRON
	IMPLICIT REAL*8(A-H,O-Z)	HERRON
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	DIMENB
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	HERRON
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
	DIMENSION HD3(3)	HERRON
	IF (TAB(NT1+1).LE.0.0) GO TO 30	HERRON
	IF (TAB(NT1+2).LE.0.0) GO TO 30	HERRON
C		HERRON
C	THETO = P1(CP) + SP*P2(CP)	HERRON
C		HERRON
C	THETOP = -SP*P1'(CP) + CP*P2(CP) - SP**2*P2'(CP)	HERRON
C		HERRON
C	WHERE P1(X),P2(X) ARE THE TWO 5TH ORDER POLYNOMIALS DEFINED	HERRON
C	IN TAB(NT1+5) AND TAB(NT1+11)	HERRON
C	P1'(X),P2'(X) ARE THEIR DERIVATIVES WITH RESPECT TO PHI	HERRON
C	AND SP,CP ARE SIN(PHI) AND COS(PHI)	HERRON
C		HERRON
	STH2 = 1.0-HD3(3)**2	HERRON
	STH = DSQRT(STH2)	HERRON
	CP = HD3(1)/STH	HERRON
	SP = HD3(2)/STH	HERRON
	P1 = TAB(NT1+5 )+ CP*(TAB(NT1+6 )	HERRON
	* + CP*(TAB(NT1+7 )	HERRON
	* + CP*(TAB(NT1+8 )	HERRON
	* + CP*(TAB(NT1+9 )	HERRON
	* + CP*(TAB(NT1+10) ) ) ) ) )	HERRON
	P2 = TAB(NT1+11)+ CP*(TAB(NT1+12)	HERRON
	* + CP*(TAB(NT1+13)	HERRON
	* + CP*(TAB(NT1+14)	HERRON
	* + CP*(TAB(NT1+15)	HERRON
	* + CP*(TAB(NT1+16) ) ) ) ) )	HERRON
	P1P = TAB(NT1+6 )+ CP*(2.0*TAB(NT1+7 )	HERRON
	* + CP*(3.0*TAB(NT1+8 )	HERRON
	* + CP*(4.0*TAB(NT1+9 )	HERRON
	* + CP*(5.0*TAB(NT1+10) ) ) ) )	HERRON
	P2P = TAB(NT1+12)+ CP*(2.0*TAB(NT1+13)	HERRON
	* + CP*(3.0*TAB(NT1+14)	HERRON
	* + CP*(4.0*TAB(NT1+15)	HERRON
	* + CP*(5.0*TAB(NT1+16) ) ) ) )	HERRON
	THETO = P1 + SP*P2	HERRON
	THETOP = CP*P2 - SP*(P1P + SP*P2P)	HERRON
	GO TO 99	HERRON

C		HERRON
C	EVALUATE THETO AND THETOP FROM REGULAR FUNCTION DEFINITION WHERE	HERRON
C	THETO (ORDINATE) IS A FUNCTION OF PHI (ABSCISSA) (0 < PHI < 2*PI)	HERRON
C		HERRON
	30 PHI = DATAN2(HD3(2),HD3(1))	HERRON
	IF (PHI.LT.0.0) PHI = PHI + TWOPI	TWOPI
	THETO = EVALFD(PHI,NT1,1)	HERRON
	THETOP = EVALFD(PHI,NT1,0)	HERRON
	99 RETURN	HERRON
	END	HERRON

C	SUBROUTINE HICCSI(NPTS)	HICCSI
C		REV IV 10/08/87PLTINC
C		HICCSI
C	COMPUTES HIC, HSI AND CSI FOR CVS PROGRAM.	HICCSI
C		HICCSI
C	ASSUMES Z ARRAY CONTAINS	HICCSI
C	Z(I,1),I=1,NPTS : TIME POINTS (SECONDS)	HICCSI
C	Z(I,JH),I=1,NPTS : HEAD RESULTANT ACCELERATIONS (G'S)	HICCSI
C	Z(I,JC),I=1,NPTS : CHEST RESULTANT ACCELERATIONS (G'S)	HICCSI
C		HICCSI
C	NOTE:	HICCSI
C	IF JDTPTS(1)=0, HEAD RESULTANT IS NOT AVAILABLE (JH=NULL,JC=2).	HICCSI
C	IF JDTPTS(2)=0, CHEST RESULTANT IS NOT AVAILABLE (JH=2,JC=NULL).	HICCSI
C	OTHERWISE, JH=2 AND JC=3.	HICCSI
C		HICCSI
	COMMON/CDINT/ JDTPTS(18),Z(1000,3)	PLTINC
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	PAGE
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	REAL*8 TIME	PAGE
	DIMENSION AREA(1000)	PLTINC
	IF (NPTS.LT.25) GO TO 25	HICCSI
	WRITE (6,14) NPG	PAGE
	NPG=NPG+1	PAGE
14	FORMAT (1H1, ' HIC, HSI AND CSI RESULTS',96X,'PAGE',15)	PAGE
	JH = 2	HICCSI
	JC = 3	HICCSI
	IF (JDTPTS(1).EQ.0) JC = 2	HICCSI
	CSI = 0.0	HICCSI
	HSI = 0.0	HICCSI
	HIC = 0.0	HICCSI
	CMX = Z(1,JC)	HICCSI
	HMX = Z(1,JH)	HICCSI
	IF (JDTPTS(2).EQ.0) GO TO 16	HICCSI
C		HICCSI
C	COMPUTE CSI - CHEST SEVERITY INDEX	HICCSI
C		HICCSI
	H1 = SQRT(Z(1,JC)) * Z(1,JC)**2	HICCSI
	DO 15 I=2,NPTS	HICCSI
	H2 = SQRT(Z(I,JC)) * Z(I,JC)**2	HICCSI
	DT = Z(I,1) - Z(I-1,1)	HICCSI
	CSI = CSI + 0.5*DT*(H1+H2)	HICCSI
	IF (CMX.GT.Z(I,JC)) GO TO 15	HICCSI
	CMX = Z(I,JC)	HICCSI
	CMT = Z(I,1)	HICCSI
15	H1 = H2	HICCSI
	CSI = 0.001*CSI	HICCSI
16	IF (JDTPTS(1).EQ.0) GO TO 23	HICCSI
C		HICCSI
C	COMPUTE HSI - HEAD SEVERITY INDEX - AND AREA TABLE	HICCSI
C		HICCSI

	AREA(1) = 0.0	HICCSI
	H1 = SQRT(Z(1,JH)) * Z(1,JH)**2	HICCSI
	DO 17 I=2,NPTS	HICCSI
	H2 = SQRT(Z(I,JH)) * Z(I,JH)**2	HICCSI
	DT = 0.5*(Z(I,1) - Z(I-1,1))	HICCSI
	AREA(I) = AREA(I-1) + DT*(Z(I-1,JH)+Z(I,JH))	HICCSI
	HSI = HSI + DT*(H1+H2)	HICCSI
	IF (HMX.GT.Z(I,JH)) GO TO 17	HICCSI
	HMX = Z(I,JH)	HICCSI
	HMT = Z(I,1)	HICCSI
17	H1 = H2	HICCSI
	HSI = 0.001*HSI	HICCSI
C		HICCSI
C	COMPUTE HIC - HEAD INJURY CRITERION - AND TIME DURATION HT1,HT2	HICCSI
C		HICCSI
	DO 19 K=2,NPTS	HICCSI
	DO 18 L=K,NPTS	HICCSI
	DT = Z(L,1) - Z(K-1,1)	HICCSI
	DH = AREA(L) - AREA(K-1)	HICCSI
	HT = DH/DT	HICCSI
	HM = DT*SQRT(HT)*HT**2	HICCSI
	IF (HM.LE.HIC) GO TO 18	HICCSI
	HIC = HM	HICCSI
	HT1 = Z(K-1,1)	HICCSI
	HT2 = Z(L,1)	HICCSI
	HA2 = Z(L,JH)	HICCSI
	HA1 = Z(K-1,JH)	HICCSI
	AVE = HT	HICCSI
18	CONTINUE	HICCSI
19	CONTINUE	HICCSI
	HIC = 0.001*HIC	HICCSI
	WRITE (6,21) HIC,HT1,HT2,HA1,HA2,AVE	HICCSI
21	FORMAT (1H0, ' HEAD INJURY CRITERION'//	HICCSI
	* ' HIC = ', F8.2,	HICCSI
	* 9X, 'TIME DURATION = ', F9.3, ' TO ', F9.3, ' MSEC'//	HICCSI
	* 20X, 'WITH HEAD RESULTANTS = ', F9.3, ' AND ', F9.3, ' G'S'//	HICCSI
	*14X, 'AVERAGE HEAD RESULTANT FOR TIME DURATION = ', F9.3, ' G'S') HICCSI	HICCSI
	WRITE (6,22) HSI,HMX,HMT	HICCSI
22	FORMAT (1H0, ' HEAD SEVERITY INDEX'//	HICCSI
	* ' HSI = ', F8.2//	HICCSI
	* ' MAX HEAD RESULTANT = ', F9.3, ' G'S AT ', F9.3, ' MSEC') HICCSI	HICCSI
23	IF (JDTPTS(2).EQ.0) GO TO 25	HICCSI
	WRITE (6,24) CSI,CMX,CMT	HICCSI
24	FORMAT (1H0, ' CHEST SEVERITY INDEX'//	HICCSI
	* ' CSI = ', F8.2//	HICCSI
	* ' MAX CHEST RESULTANT = ', F9.3, ' G'S AT ', F9.3, ' MSEC') HICCSI	HICCSI
25	CONTINUE	TGMOD1
	IF(NPTS.LT.25) WRITE(6,101) NPTS	TGMOD1
101	FORMAT(1X,/,2X,'HIC, HSI AND CSI NOT COMPUTED BECAUSE THE NUMBER	TGMOD1
	*OF POINTS TO BE USED IN THE COMPUTATION =',12,',',/,2X	TGMOD1



\* 'WHICH IS LESS THAN THE MINIMUM REQUIREMENT OF 25 POINTS.',/)  
RETURN  
END

TGMOD1  
TGMOD1  
HICCSI

	SUBROUTINE HINPUT	HINPUT
		REV IV 07/23/86TWOPI
C	CONTROLS THE INPUT OF CARDS F.8.A - F.8.D CONTAINING THE SETUP AND	HINPUT
C	CONTROL OF THE HARNESS BELT SYSTEM.	HINPUT
C		HINPUT
C		HINPUT
	IMPLICIT REAL*8(A-H,O-Z)	HINPUT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	HINPUT
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	HINPUT
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
	COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),	HINPUT
	* XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),	HINPUT
	* NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)	HINPUT
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	DIMENB
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)	EDGE
	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),	HINPUT
	* BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30),	HINPUT
	* JOINT(30),CGS(30),JS(30)	HINPUT
	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT	HINPUT
	LOGICAL*1 CGS,JS	HINPUT
C	THIS COMMON/TEMVVS/ IS SHARED BY CINPUT, FINPUT, HINPUT AND FDINIT	HINPUT
	COMMON/TEMPVS/ JTITLE(5,51),NF(5),MS(3),KTITLE(31)	HINPUT
	REAL JTITLE,KTITLE	HINPUT
	IF (NHRNSS.EQ.0) GO TO 99	HINPUT
C		HINPUT
C	INPUT CARD F.8.A	HINPUT
C	(NOTE: NHRNSS NOW SUPPLIED ON INPUT CARD D.1)	HINPUT
C	NBLTPH - NO. OF BELTS PER HARNESS	HINPUT
C		HINPUT
	READ (5,11) (NBLTPH(I),I=1,NHRNSS)	HINPUT
11	FORMAT(18I4)	HINPUT
	WRITE (6,12) NPG,NHRNSS,(NBLTPH(I),I=1,NHRNSS)	PAGE
	NPG=NPG+1	PAGE
12	FORMAT('1 HARNESS-BELT SYSTEM INPUT',96X,'PAGE',15/120X,	PAGE
	* 'CARDS F.8'/' NO. OF HARNESSES =' ,I4//	PAGE
	* ' NO. OF BELTS PER HARNESS =' ,5I6)	HINPUT
	J1 = 1	HINPUT
	K1 = 1	HINPUT
	DO 90 I=1,NHRNSS	HINPUT
	IF (NBLTPH(I).LE.0) GO TO 90	HINPUT
	J2 = J1 + NBLTPH(I) -1	HINPUT
C		HINPUT
C	INPUT CARD F.8.B - NPTSPB - NO. OF POINTS PER BELT.	HINPUT
C		HINPUT
	READ (5,11) (NPTSPB(J),J=J1,J2)	HINPUT
	WRITE (6,13) I,(NPTSPB(J),J=J1,J2)	HINPUT
13	FORMAT('0 FOR HARNESS NO.',13,' NO. OF POINTS PER BELT =' ,20I4)	HINPUT
	DO 80 J=J1,J2	HINPUT
	IF (NPTSPB(J).EQ.0) GO TO 80	HINPUT

C		HINPUT
C	INPUT CARD F.8.C - 5 FUNCTION NOS AND LENGTE OF EACH BELT.	HINPUT
C		HINPUT
	READ (5,14) NF,XLONG(J)	HINPUT
14	FORMAT(5I4,F12.6)	HINPUT
	WRITE (6,15) I,J,NF,XLONG(J),UNITL	HINPUT
15	FORMAT('0 HARNESS NO.',I3,' BELT NO.',I3,' FUNCTION NOS.',5I6,	HINPUT
*	' REFERENCE SLACK = ',F9.3,1X,A4/)	HINPUT
	IF (XLONG(J).EQ.0.0) XLONG(J) = EPS(24)	HINPUT
	WRITE (6,16)	HINPUT
16	FORMAT ('0 K KS KE NT NPD NDR FUNCTION NOS.',	HINPUT
*	66X,'CARDS F.8.D'/)	CHGIII
C		HINPUT
C	SET UP POINTERS IN NTAB AND INITIAL VALUES OF TAB FOR BELT J	HINPUT
C	AS WAS DONE FOR OTHER CONTACTS IN SUBROUTINE FINPUT.	HINPUT
C		HINPUT
	NTHRNS(J) = MXNTB+1	HINPUT
	CALL FDINIT	HINPUT
	K2 = K1 + NPTSPB(J) - 1	HINPUT
	DO 70 K=K1,K2	HINPUT
C		HINPUT
C	INPUT CARD F.8.D	HINPUT
C		HINPUT
	READ (5,21) KS,KE,NPD,NDR,NF, (BAR(L,K),L=1,3)	HINPUT
21	FORMAT (9I4,3F12.0)	HINPUT
	READ (5,22) (BAR(L,K),L=7,12)	HINPUT
22	FORMAT (6F12.0)	HINPUT
	ICHEC = 0	CHGIII
	IF (K.EQ.K1.OR.K.EQ.K2) ICHEC = 1	CHGIII
	IF (ICHEC.EQ.1.AND.NPD.EQ.0) STOP 60	CHGIII
	IF (ICHEC.EQ.1.AND.NDR.EQ.0) STOP 61	CHGIII
	IF (NDR.EQ.0.AND.NPD.NE.0) STOP 62	CHGIII
	IBAR(1,K) = KS	HINPUT
	IBAR(2,K) = KE	HINPUT
	IBAR(4,K) = NPD	HINPUT
	IBAR(5,K) = NDR	HINPUT
	IBAR(3,K) = MXNTB+1	HINPUT
	CALL FDINIT	HINPUT
	SQRER = 1.0	HINPUT
	IF (KE.NE.0) SQRER = DSQRT(XDY(BAR(1,K),BD(7,KE),BAR(1,K)))	HINPUT
	DO 26 L=1,3	HINPUT
	IF (KE.NE.0) BAR(L+6,K) = BD(L+3,KE)	HINPUT
26	BAR(L+3,K) = BAR(L,K)/SQRER	HINPUT
	WRITE (6,31) K,(IBAR(L,K),L=1 ),NF	HINPUT
31	FORMAT (11I6)	HINPUT
70	CONTINUE	HINPUT
	WRITE (6,71) UNITL,UNITL,UNITL,UNITL	HINPUT
71	FORMAT ('0',12X,'BASE REFERENCE (' , A4,')',	HINPUT
*	7X,'ADJUSTED REFERENCE (' , A4,')',	HINPUT
*	11X,'OFFSET (' , A4,')',	HINPUT

[illegible]

	SUBROUTINE HPTURB		HPTURB
C		REV IV	07/23/86TWOPI
	IMPLICIT REAL*8 (A-H,O-Z)		HPTURB
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		HPTURB
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		HPTURB
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)		EDGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		HPTURB
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		HPTURB
	COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),		ATBIII
	* NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)		TTHKREF
	COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),		HPTURB
	* XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),		HPTURB
	* NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)		HPTURB
C	THIS COMMON/TEMPVS/ IS SHARED BY HPTURB, HBPLAY, HBELT AND HSETC.		HPTURB
	COMMON/TEMPVS/ B(3,3,3),S(3,3),T(3),R(3),V(3),T1(3),T2(3),		HPTURB
	* E(3,3,50),EDOT(3,50),FCE(3,50),FR(3,50),ZR(3,50),		HPTURB
	* TR(3,50),U(3,50),PTLOSS(2,50),BL(50),FB(50),FP(50),		HPTURB
	* OLDBB(100),RHS(3,54),C(3,3,200),IJK(54,54)		HPTURB
	DIMENSION BLOSS(2,20),HLOSS(2,5)		HPTURB
	EQUIVALENCE (BLOSS(1,1),C(1,1,1)) , (HLOSS(1,1),C(1,1,10))		HPTURB
	LOGICAL LAST		HPTURB
	DATA MAXITR/10/		HPTURB
	CALL ELTIME (1,39)		HPTURB
	CALL HBPLAY		HPTURB
	DHT = 0.0		HPTURB
	IF (TIME.NE.0.0) DHT = TIME - HTIME(1)		HPTURB
	HTIME(1) = TIME		HPTURB
	DO 11 J=1,100		HPTURB
	PTLOSS(J,1) = 0.0		HPTURB
	OLDBB(J) = BB(J)		HPTURB
	DO 11 I=1,3		HPTURB
11	BAR(I,J) = BAR(I+3,J)		HPTURB
	TSEC = 1000.0*TIME		HPTURB
	IF (NPRT(28).NE.0) WRITE (6,12) TSEC,NPG,UNITL,UNITM,UNITL,		PAGE
	* UNITL,UNITM,UNITL,UNITM		HPTURB
	IF (NPRT(28).NE.0) NPG=NPG+1		PAGE
12	FORMAT('1 HARNESS BELT RESULTS FOR TIME =',F9.3,' MSEC.',73X,		PAGE
	* 'PAGE',15///		PAGE
	* 36X,'BELT STRAIN',6X,'(LOCAL OR ELLIPSOID)',18X,		CHGIII
	* '(INERTIAL)',14X,'PENETRATION'/		CHGIII
	* ' POINT POINT SEGMENT LENGTH ENERGY LOSS',5X,		HPTURB
	* 'REFERENCE POINT (' ,A4,')',13X,'BELT FORCES (' ,A4,')',		AFREVS
	* 9X,'ENERGY LOSS'/		HPTURB
	* ' NO. INDEX NO. (' ,A4,') (' ,2A4,')',7X,		HPTURB
	* 'X',8X,'Y',8X,'Z',13X,'X',10X,'Y',10X,'Z',8X,'(' ,2A4,')'//)		HPTURB
	J1 = 1		HPTURB
	K0 = 1		HPTURB
	KNLO = 0		HPTURB

	DO 61 NH=1,NHRNSS	HPTURB
	IF (NBLTPH(NH).LE.0) GO TO 61	HPTURB
	ITER = 1	HPTURB
	KNL1 = KNLO	HPTURB
	KNLN = 0	CHGIII
C		HPTURB
C	START OF DO 59 ITER=1,MAXITR LOOP	HPTURB
C		HPTURB
	13 NJ2 = 54	HPTURB
	DO 14 I=1,NJ2	HPTURB
	DO 14 J=1,NJ2	HPTURB
	14 IJK(I,J) = 0	HPTURB
	KNLO = KNL1	HPTURB
	J2 = J1 + NBLTPH(NH) - 1	HPTURB
	NTP = 0	HPTURB
	IJ = 0	HPTURB
	CALL HBELT (J1,J2,KNLO,1)	HPTURB
	KHO = 0	HPTURB
	KNLO = KNL1	HPTURB
	DO 15 NB=J1,J2	HPTURB
	IF (NPTPLY(NB).LE.0) GO TO 15	HPTURB
	NPTS = NPTPLY(NB)	HPTURB
	CALL HSETC (NPTS,KHO,KNLO,NTP,IJ)	HPTURB
	KHO = KHO + NPTS	HPTURB
	KNLO = KNLO + NPTS	HPTURB
	15 CONTINUE	HPTURB
	KNLN = KNLO	CHGIII
C		HPTURB
C	SET UP C AND IJK ELEMENTS FOR TIE-POINTS.	HPTURB
C		HPTURB
	KNLO = KNL1	HPTURB
	KNLK = KNLO + 1	HPTURB
	K1 = KNLK	HPTURB
	DO 22 NB=J1,J2	HPTURB
	IF (NPTPLY(NB).LE.0) GO TO 22	HPTURB
	K2 = K1 + NPTPLY(NB) - 1	HPTURB
	DO 21 KNL=K1,K2	HPTURB
	KI = NL(1,KNL)	HPTURB
	KS = IABS(IBAR(1,KI))	HPTURB
	IF (KS.LT.100) GO TO 21	HPTURB
	KS1 = KS/100	HPTURB
	DO 16 K=KNLK,KNL	HPTURB
	KK = K	HPTURB
	KI = NL(1,K)	HPTURB
	KS = IABS(IBAR(1,KI))	HPTURB
	IF (KS.LT.100) GO TO 16	HPTURB
	KS2 = KS/100	HPTURB
	IF (KS2.EQ.KS1) GO TO 17	HPTURB
	16 CONTINUE	HPTURB
	17 IF (KK.EQ.KNL) GO TO 21	HPTURB

KK1 = KK - KNLO	HPTURB
KK2 = KNL - KNLO	HPTURB
IQ1 = MAX0(1, KK2-1)	HPTURB
IQ2 = MIN0(KK2+1, KH0)	HPTURB
DO 18 IQ=IQ1, IQ2	HPTURB
IF (IJK(KK2, IQ).EQ.0) GO TO 18	HPTURB
IJK(KK1, IQ) = IJK(KK2, IQ)	HPTURB
IJK(KK2, IQ) = 0	HPTURB
18 CONTINUE	HPTURB
IJK(KK2, KK2) = IJ+1	HPTURB
IJK(KK2, KK1) = IJ+2	HPTURB
DO 20 J=1, 3	HPTURB
DO 19 I=1, 3	HPTURB
C(I, J, IJ+1) = 0.0	HPTURB
19 C(I, J, IJ+2) = 0.0	HPTURB
C(J, J, IJ+1) = 1.0	HPTURB
20 C(J, J, IJ+2) = -1.0	HPTURB
IJ = IJ + 2	HPTURB
21 CONTINUE	HPTURB
K1 = K2 + 1	HPTURB
22 CONTINUE	HPTURB
MJ2 = -(KH0+NTP)	HPTURB
IF (NPRT(28).LT.3) GO TO 29	HPTURB
NJ2 = -MJ2	HPTURB
DO 25 J=1, NJ2	HPTURB
25 WRITE (6, 26) J, (RHS(I, J), I=1, 3), (IJK(J, I), I=1, NJ2)	HPTURB
26 FORMAT (I6, 3F12.6, 20I4/(42X, 20I4))	HPTURB
DO 27 KLM=1, IJ	HPTURB
27 WRITE (6, 28) KLM, ((C(J, I, KLM), I=1, 3), J=1, 3)	HPTURB
28 FORMAT (I6, 9F12.6)	HPTURB
29 CALL FSMSOL (C, RHS, IJK, MJ2, IJ, 54, 200)	HPTURB
IF (NPRT(28).LT.3) GO TO 31	HPTURB
DO 30 J=1, NJ2	HPTURB
30 WRITE (6, 26) J, (RHS(I, J), I=1, 3), (IJK(J, I), I=1, NJ2)	HPTURB
31 ONE = 1.0	HPTURB
DELMAX = 0.0	HPTURB
SCALE = 1.0	HPTURB
DO 44 IT=1, 2	HPTURB
K1 = K0	HPTURB
KH = 0	HPTURB
KR = NTP	HPTURB
DO 43 NB=J1, J2	HPTURB
IF (NPPLY(NB).LE.0) GO TO 43	HPTURB
K2 = K1 + NPPLY(NB) - 1	HPTURB
DO 42 K=K1, K2	HPTURB
KH = KH + 1	HPTURB
KR = KR + 1	HPTURB
C	HPTURB
C	HPTURB
C	HPTURB
HERE K IS INDEX OF ALL POINTS IN PLAY	HPTURB
KH IS INDEX OF ALL POINTS IN PLAY ON A SINGLE HARNESS	HPTURB

C	KR IS INDEX OF RHS ARRAY ELEMENTS	HPTURB
C		HPTURB
	KI = NL(1,K)	HPTURB
	KS = IABS(IBAR(1,KI))	HPTURB
	IF (KS.GT.100) KS = MOD(KS,100)	HPTURB
	IF (IBAR(5,KI).EQ.0) GO TO 32	HPTURB
	CALL MAT31 (D(1,1,KS),RHS(1,KR),R)	HPTURB
	GO TO 37	HPTURB
C		HPTURB
C	NOTE: ENDPOINTS (K = K1 & K2) MUST BE TYPE 5.	HPTURB
C		HPTURB
	32 CALL DOT31 (E(1,1,KH),RHS(1,KR),T1)	HPTURB
	IF (IT.EQ.2) GO TO 33	HPTURB
	DELMAX = DMAX1(DELMAX,DABS(T1(2)/DMIN1(BB(K),BB(K-1))))	HPTURB
	GO TO 34	HPTURB
	33 BB(K) = BB(K) + SCALE*T1(2)	HPTURB
	BB(K-1) = BB(K-1) - SCALE*T1(2)	HPTURB
	34 DO 35 J=1,3	HPTURB
	35 T2(J) = T1(1)*E(J,1,KH) + T1(3)*E(J,3,KH)	HPTURB
	CALL MAT31 (D(1,1,KS),T2,R)	HPTURB
	IF (NPRT(28).GE.3) WRITE (6,36) K,T1,T2,R	HPTURB
	36 FORMAT ('0',I6,3(3X,3F12.6))	HPTURB
	37 IF (IT.EQ.2) GO TO 39	HPTURB
	DO 38 J=1,3	HPTURB
	38 DELMAX = DMAX1(DELMAX,DABS(R(J)/DMAX1(EPS(1),DABS(BAR(J+3,KI)))))	HPTURB
	GO TO 42	HPTURB
	39 DO 40 J=1,3	HPTURB
	40 BAR(J+3,KI) = BAR(J+3,KI) + SCALE*R(J)	HPTURB
	KE = IBAR(2,KI)	HPTURB
	IF (KE.EQ.0) GO TO 42	HPTURB
	RER = XDY(BAR(4,KI),BD(7,KE),BAR(4,KI))	HPTURB
	IF (RER.LE.1.0) GO TO 42	HPTURB
	SQRER = 1.0/DSQRT(RER)	HPTURB
	DO 41 J=1,3	HPTURB
	41 BAR(J+3,KI) = SQRER*BAR(J+3,KI)	HPTURB
	42 CONTINUE	HPTURB
	K1 = K2 + 1	HPTURB
	43 CONTINUE	HPTURB
	IF (IT.EQ.2) GO TO 44	HPTURB
	IF (DELMAX.NE.0.0) SCALE = DMIN1(ONE,EPS(1)/DELMAX)	HPTURB
	44 CONTINUE	HPTURB
	IF (NPRT(28).GE.2) WRITE (6,45) ITER,DELMAX,SCALE	HPTURB
	45 FORMAT ('0 ITER =',I6,' DELMAX =',F15.6,' SCALE =',F15.6)	HPTURB
	LAST = DELMAX.LE.EPS(2) .OR. ITER.EQ.MAXITR	HPTURB
	IF (.NOT.LAST) GO TO 52	HPTURB
	KH = 0	HPTURB
	K1 = K0	HPTURB
	HLOSS(1,NH) = 0.0	HPTURB
	HLOSS(2,NH) = 0.0	HPTURB
	DO 51 NB=J1,J2	HPTURB



BLOSS(1,NB) = 0.0	HPTURB
BLOSS(2,NB) = 0.0	HPTURB
IF (NPTPLY(NB).LE.0) GO TO 51	HPTURB
K2 = K1 + NPTPLY(NB) - 1	HPTURB
KK1 = NL(1,K1)	HPTURB
KK2 = NL(1,K2)	HPTURB
DO 46 K=KK1,KK2	HPTURB
DO 46 J=1,3	HPTURB
46 BAR(J+12,K) = 0.0	HPTURB
IF (DHT.EQ.0.0) GO TO 49	HPTURB
DO 48 K=K1,K2	HPTURB
KH = KH + 1	HPTURB
KI = NL(1,K)	HPTURB
PLOSS(2,KI) = PLOSS(2,KI) + DHT*PTLOSS(2,KH)	HPTURB
IF (K.EQ.K1) GO TO 47	HPTURB
BBDOT(K-1) = (BB(K-1)-OLDBB(K-1))/DHT	HPTURB
PLOSS(1,K-1) = PLOSS(1,K-1) + DHT*PTLOSS(1,KH-1)	HPTURB
BLOSS(1,NB) = BLOSS(1,NB) + PLOSS(1,K-1)	HPTURB
47 DO 48 J=1,3	HPTURB
48 BAR(J+12,KI) = (BAR(J+3,KI)-BAR(J,KI))/DHT	HPTURB
BBDOT(K2) = 0.0	HPTURB
PLOSS(1,K2) = 0.0	HPTURB
49 K1 = K2+1	HPTURB
DO 50 K=KK1,KK2	HPTURB
50 BLOSS(2,NB) = BLOSS(2,NB) + PLOSS(2,K)	HPTURB
HLOSS(1,NH) = HLOSS(1,NH) + BLOSS(1,NB)	HPTURB
HLOSS(2,NH) = HLOSS(2,NH) + BLOSS(2,NB)	HPTURB
51 CONTINUE	HPTURB
52 IF (NPRT(28).EQ.0) GO TO 59	HPTURB
IF (.NOT.LAST .AND. IABS(NPRT(28)).EQ.1) GO TO 59	HPTURB
K1 = K0	HPTURB
KH = 0	HPTURB
DO 57 NB=J1,J2	HPTURB
IF (NPTPLY(NB).LE.0) GO TO 57	HPTURB
WRITE (6,53) NB,NH	HPTURB
53 FORMAT ('0 BELT NO.',I4,' OF HARNESS NO.',I4)	HPTURB
K2 = K1 + NPTPLY(NB) - 1	HPTURB
DO 54 K=K1,K2	HPTURB
KH = KH + 1	HPTURB
KI = NL(1,K)	HPTURB
KS = IBAR(1,KI)	HPTURB
BK = 0.0	HPTURB
IF (K.NE.K1) BK = BB(K-1)	HPTURB
PLS = 0.0	HPTURB
IF (K.NE.K1) PLS = PLOSS(1,K-1)	HPTURB
T(1) = BAR(4,KI)	HPTURB
T(2) = BAR(5,KI)	HPTURB
T(3) = BAR(6,KI)	HPTURB
KJ = MOD(IABS(KS),100)	HPTURB
IF (LPMI(KJ).NE.0) CALL DOT31 (DPMI(1,1,KJ),BAR(4,KI),T)	HPTURB

54	WRITE (6,55) K,KI,KS,BK,PLS,(T(J),J=1,3),	HPTURB
	* (FCE(J,KH),J=1,3),PLOSS(2,KI)	HPTURB
55	FORMAT (3I8,F10.3,F12.3,2X,3F9.3,3X,3F11.3,3X,F12.3)	HPTURB
	IF (LAST) WRITE (6,56) BLOSS(1,NB),BLOSS(2,NB)	HPTURB
56	FORMAT ('0 TOTAL BELT ENERGY LOSS',7X,F12.3,68X,F12.3)	HPTURB
	K1 = K2 + 1	HPTURB
57	CONTINUE	HPTURB
	IF (LAST) WRITE (6,58) HLOSS(1,NH),HLOSS(2,NH)	HPTURB
58	FORMAT ('0 TOTAL HARNESS ENERGY LOSS',7X,F12.3,68X,F12.3)	HPTURB
59	ITER = ITER + 1	HPTURB
C		HPTURB
C	END OF DO 59 ITER=1,MAXITR LOOP	HPTURB
C		HPTURB
	IF (.NOT.LAST) GO TO 13	HPTURB
	IF (ITER.GT.MAXITR) WRITE (6,60) MAXITR,TSEC,DELMAX,SCALE	HPTURB
60	FORMAT ('0 HPTURB ITER =',I4,' AT TIME =',F8.3,	HPTURB
	* ' MSEC. DELMAX =',F10.6,' SCALE =',F10.6)	HPTURB
	J1 = J2 + 1	HPTURB
	K0 = K1	HPTURB
	KNLO = KNLN	CHGIII
61	CONTINUE	HPTURB
	IF (NPRT(28).LT.0) NPRT(28) = 0	HPTURB
	CALL ELTIME (2,39)	HPTURB
	RETURN	HPTURB
	END	HPTURB



C	CNORM = 0.0	HSETC
	IF (K.NE.K2) CNORM = FB(KH)/BL(KH)	HSETC
	IF (K.NE.K1) CNORM = CNORM + FB(KH-1)/BL(KH-1)	HSETC
	KI = NL(1,KNL)	HSETC
	IF (IABS(IBAR(1,KI)).GT.100) GO TO 14	HSETC
C	IF (CNORM.NE.0.0) GO TO 14	BUTLER1
	KK = IJK(K,K)	HSETC
	DO 13 I=1,3	HSETC
13	C(I,I,KK) = ONE	HSETC
	IF (CNORM.EQ.0.0) GO TO 60	BUTLER1
14	KK = IBAR(3,KI)	HSETC
	NFD = NTAB(KK+1)	HSETC
	NFR = NTAB(KK+5)	HSETC
C		HSETC
C	SET UP B(3,3,3) AND S(3,3)	HSETC
C		HSETC
	MK(1) = KH	HSETC
	MK(2) = KH-1	HSETC
	IF (K.EQ.K2) MK(1) = 0	HSETC
	IF (K.EQ.K1) MK(2) = 0	HSETC
	DO 18 M=1,2	HSETC
	KK = MK(M)	HSETC
	IF (KK.NE.0 .AND. CNORM.NE.0.0) GO TO 16	HSETC
	DO 15 I=1,3	HSETC
	S(I,M) = 0.0	HSETC
	DO 15 J=1,3	HSETC
15	B(I,J,M) = 0.0	HSETC
	GO TO 18	HSETC
16	CALL DOT31 (E(1,1,KH),U(1,KK),T)	HSETC
	KIM = KNL + 1 - M	HSETC
	FB1 = FB(KK)/BL(KK)	HSETC
	FB2 = FP(KK)/BB(KIM) - FB1	HSETC
	FB3 = FP(KK)*BL(KK)/BB(KIM)**2	HSETC
	DO 17 I=1,3	HSETC
	SGN = ONE	HSETC
	IF (FR(I,KH).LT.0.0) SGN = -ONE	HSETC
	S(I,M) = SGN*(FB3*T(I))	HSETC
	DO 17 J=1,3	HSETC
17	B(I,J,M) = SGN*(FB1*E(J,I,KH) + FB2*T(I)*U(J,KK))	HSETC
18	CONTINUE	HSETC
	DO 19 I=1,3	HSETC
	S(I,3) = -(S(I,1) + S(I,2))	HSETC
	DO 19 J=1,3	HSETC
19	B(I,J,3) = -(B(I,J,1) + B(I,J,2))	HSETC
	IF (NFR.EQ.0) GO TO 20	HSETC
	R(1) = TAB(NFR+2)	HSETC
	R(2) = TAB(NFR+4)	HSETC
20	R(3) = 0.0	HSETC
	DO 50 M=1,3	HSETC

	RH = 0.0	HSETC
	IF (M.EQ.3) GO TO 31	HSETC
	IF (NFR.EQ.0) GO TO 48	HSETC
C		HSETC
C	CONSTRAINTS 1 AND 2	HSETC
C		HSETC
	SGN = -ONE	HSETC
	FR3 = DABS(FR(M,KH)) - R(M)*DABS(FR(3,KH))	HSETC
	IF (IBAR(1,KI).GT.0) RH = FR3	HSETC
	IF (FR3.LE.0.0) GO TO 48	HSETC
	GO TO 40	HSETC
C		HSETC
C	CONSTRAINT NO. 3	HSETC
C		HSETC
31	IF (NFD.EQ.0) GO TO 48	HSETC
	IF (IBAR(1,KI).LT.0) GO TO 40	HSETC
	SGN = ONE	HSETC
	RMAG2 = TR(1,KH)**2 + TR(2,KH)**2 + TR(3,KH)**2	HSETC
	RMAG = DSQRT(RMAG2)	HSETC
	RER2 = TR(1,KH)*E(1,3,KH) + TR(2,KH)*E(2,3,KH) + TR(3,KH)*E(3,3,KH)	HSETC
	RER2 = EDOT(3,KH)*RER2	HSETC
	RER = DSQRT(RER2)	HSETC
	PEN = RMAG/RER - RMAG	HSETC
	RRDOT = BAR(4,KI)*BAR(13,KI)	HSETC
	* + BAR(5,KI)*BAR(14,KI)	HSETC
	* + BAR(6,KI)*BAR(15,KI)	HSETC
	KS = IABS(IBAR(1,KI))	HSETC
	IF (KS.GT.100) KS = MOD(KS,100)	HSETC
	CALL DOT31 (D(1,1,KS),BAR(13,KI),T)	HSETC
	ERDOT = E(1,3,KH)*T(1) + E(2,3,KH)*T(2) + E(3,3,KH)*T(3)	HSETC
	C1 = PEN/RMAG2	HSETC
	C2 = RMAG*EDOT(3,KH)/(RER*RER2)	HSETC
	PDOT = C1*RRDOT - C2*ERDOT	HSETC
	NFDZ = IBAR(3,KI)	CHGIII
	CALL FRCDFL (PEN,PDOT,NFDZ,0,FDP,ELOSS)	CHGIII
	CALL FRCDFL (PEN,PDOT,NFDZ,1,FD,ELOSS)	CHGIII
	RH = FD + FR(3,KH)	HSETC
	PTLOSS(2,KH) = ELOSS	HSETC
	C1 = FDP*C1	HSETC
	C2 = FDP*C2	HSETC
	SGNB3 = -DSIGN(ONE,FR(3,KH))	HSETC
	DO 32 J=1,3	HSETC
32	B(3,J,3) = SGNB3*B(3,J,3) - C1*TR(J,KH) + C2*E(J,3,KH)	HSETC
40	DO 47 LL=1,3	HSETC
	L = 4 - LL	HSETC
	IF (KM(L).EQ.0) GO TO 47	HSETC
	DO 42 J=1,3	HSETC
42	V(J) = R(M)*B(3,J,L) + SGN*B(M,J,L)	HSETC
	KL = KM(L)	HSETC
	KML = KNL + KL - K	HSETC

KIL = NL(1,KML)	HSETC
IF (IBAR(5,KIL).NE.0) GO TO 43	HSETC
KHL = KH + KL - K	HSETC
CALL DOT31 (E(1,1,KHL),V,T)	HSETC
T(2) = R(M)*S(3,L) + SGN*S(M,L)	HSETC
CALL MAT31 (E(1,1,KHL),T,V)	HSETC
43 IF (LL.NE.1) GO TO 44	HSETC
VE = V(1)*E(1,M,KH) + V(2)*E(2,M,KH) + V(3)*E(3,M,KH)	HSETC
EV = 1.0	HSETC
IF (IABS(IBAR(1,KI)).LT.100)	HSETC
* EV = DSIGN(ONE,VE)/DSQRT(V(1)**2+V(2)**2+V(3)**2)	HSETC
RH = EV*RH	HSETC
44 IF (IJK(K,KL).NE.0) GO TO 45	HSETC
IJ = IJ+1	HSETC
IJK(K,KL) = IJ	HSETC
45 KK = IJK(K,KL)	HSETC
DO 46 J=1,3	HSETC
VEV = EV*V(J)	HSETC
DO 46 I=1,3	HSETC
46 C(I,J,KK) = C(I,J,KK) + E(I,M,KH)*VEV	HSETC
47 CONTINUE	HSETC
DO 41 I=1,3	HSETC
41 RHS(I,K) = RHS(I,K) + RH*E(I,M,KH)	HSETC
GO TO 50	HSETC
48 IF (IBAR(1,KI).LE.0) GO TO 50	HSETC
KK = IJK(K,K)	HSETC
DO 49 I=1,3	HSETC
DO 49 J=1,3	HSETC
49 C(I,J,KK) = C(I,J,KK) + E(I,M,KH)*E(J,M,KH)	HSETC
50 CONTINUE	HSETC
60 CONTINUE	HSETC
RETURN	HSETC
END	HSETC

	SUBROUTINE HYABF(B,Z,A,F)		HYABF
C		REV IV	02/07/87HYABF
	IMPLICIT REAL*8(A-H,O-Z)		HYABF
C			HYABF
C	CALCULATES A, AZ, Z.AZ: OLD FORM MUST BE DIAGONAL		HYABF
C			HYABF
	DIMENSION B(24),Z(1),A(3,3)		HYABF
	P2 = 0.0		HYABF
	IF(B(1).LT.0.0)P2 = -B(1) - 2.0		HYABF
	F = 0.0		HYABF
	DO 30 I = 1,3		HYABF
	J = I		HYABF
	IF(B(1).LT.0.0)GO TO 10		HYABF
	A(I,1) = 1.0/B(I)**2		HYABF
	GO TO 15		HYABF
10	A(I,1) = B(I+16)		HYABF
	J = J + 1		HYABF
	A(I,1) = HYFCN(A(I,1),Z(I),B(J),P2)		HYABF
C	IF(P2.GT.0.0)A(I,1) = A(I,1)*DABS(Z(I)/B(J))**P2		HYABF
15	DO 20 J = 2,3		HYABF
20	A(I,J) = A(I,J-1)*Z(I)		HYABF
30	F = F + A(I,3)		HYABF
	RETURN		HYABF
	END		HYABF

	SUBROUTINE HYBND(M,Z,IV,U,C,X)		HYBND
C		REV IV	02/07/87HYBND
	IMPLICIT REAL*8(A-H,O-Z)		HYBND
C			HYBND
C	SEARCHES FOR POINT NEAREST CORNER - DIRECTION C*U		HYBND
C			HYBND
	DIMENSION Z(3,12),IV(12),U(3),X(3)		HYBND
	DO 20 I = 1,M,2		HYBND
	J = IV(I)		HYBND
	ATST = C*(U(1)*Z(1,J) + U(2)*Z(2,J) + U(3)*Z(3,J))		HYBND
	IF(I.EQ.1)GO TO 10		HYBND
	TEST = AMAX - ATST		HYBND
	COMP = DMAX1(DABS(AMAX),DABS(ATST))		HYBND
C	PRECISION TEST - TRY >1000??		HYBND
	IF(1000.*DABS(TEST).LT.COMP)TEST = 0.0		HYBND
	IF(TEST)10,15,20		HYBND
C	IF(AMAX-ATST)10,15,20		HYBND
	10 AMAX = ATST		HYBND
	J1 = J		HYBND
	15 J2 = J		HYBND
	20 CONTINUE		HYBND
	DO 25 I = 1,3		HYBND
	25 X(I) = 0.5*(Z(I,J1) + Z(I,J2))		HYBND
	RETURN		HYBND
	END		HYBND



	SUBROUTINE HYBOX(E,T,P,N,Z,IV)		HYBOX
C		REV IV 02/07/87	HYBOX
	IMPLICIT REAL*8(A-H,O-Z)		HYBOX
C			HYBOX
C	COMPUTES THE INTERSECTION OF A PLANE WITH THE EDGES OF A BOX		HYBOX
C			HYBOX
	DIMENSION T(3),E(3),TU(3),T2(3),P(3)		HYBOX
C	TO BE SAFE IV AND Z SHOULD BE DIMENSION 14 IN CALLING PROGRAM		HYBOX
	DIMENSION IV(12)		HYBOX
	DIMENSION Z(3,12)		HYBOX
	DATA ONE/1.0D0/		HYBOX
C	T - PLANE VECTOR, P POINT IN PLANE		HYBOX
	TUV = 0.0		HYBOX
	DO 10 I = 1,3		HYBOX
	TU(I) = T(I)*E(I)		HYBOX
	T2(I) = 2.0*TU(I)		HYBOX
10	TUV = TUV + T(I)*(E(I) + P(I))		HYBOX
	N = 0		HYBOX
	J = 2		HYBOX
	K = 3		HYBOX
	DO 45 I = 1,3		HYBOX
	CK = -E(K)		HYBOX
	P1 = TUV		HYBOX
	DO 40 LL = 1,2		HYBOX
	P2 = P1 - T2(I)		HYBOX
	P3 = P2 - T2(J)		HYBOX
	P4 = P1 - T2(J)		HYBOX
	M = N		HYBOX
	IF(DSIGN(ONE,P2).EQ.DSIGN(ONE,P1))GO TO 15		HYBOX
	M = M + 1		HYBOX
	Z(I,M) = (P1/TU(I) - 1.0)*E(I)		HYBOX
	Z(J,M) = -E(J)		HYBOX
	Z(K,M) = CK		HYBOX
15	IF(DSIGN(ONE,P3).EQ.DSIGN(ONE,P2))GO TO 20		HYBOX
	M = M + 1		HYBOX
	Z(I,M) = E(I)		HYBOX
	Z(J,M) = (P2/TU(J) - 1.0)*E(J)		HYBOX
	Z(K,M) = CK		HYBOX
20	IF(DSIGN(ONE,P3).EQ.DSIGN(ONE,P4))GO TO 25		HYBOX
	M = M + 1		HYBOX
	Z(I,M) = (P4/TU(I) - 1.0)*E(I)		HYBOX
	Z(J,M) = E(J)		HYBOX
	Z(K,M) = CK		HYBOX
25	IF(DSIGN(ONE,P4).EQ.DSIGN(ONE,P1))GO TO 30		HYBOX
	M = M + 1		HYBOX
	Z(I,M) = -E(I)		HYBOX
	Z(J,M) = (P1/TU(J) - 1.0)*E(J)		HYBOX
	Z(K,M) = CK		HYBOX
30	IF(M.EQ.N)GO TO 35		HYBOX
	CHECK FOR PRECISION (+--+ .OR -+--)		HYBOX



```

      SUBROUTINE HYDAD(D,A,DAD)
C
      IMPLICIT REAL*8(A-H,O-Z)
      COMPUTES D'A(*,1)D
      DIMENSION D(3,3),A(3),DAD(3,3)
      DO 10 I = 1,3
      DO 10 J = 1,3
      DAD(I,J) = 0.0
      DO 10 K = 1,3
10 DAD(I,J) = DAD(I,J) + D(K,I)*A(K)*D(K,J)
      RETURN
      END

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      HYDAD
REV IV 02/07/87HYDAD
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SUBROUTINE HYEST(BM,BN,TAB)	HYEST
C	REV IV 07/23/87HYEST
C LINEAR PROGRAM	HYEST
IMPLICIT REAL*8(A-H,O-Z)	HYEST
DIMENSION BM(24),BN(24),TAB(8)	HYEST
COMMON/TEMPVS/D12(3,3),A(3,3),B(3,3),XMN(3),RLN(3),XMM(3),	HYEST
* T(3),R(3),C(3,3),V(7)	HYEST
C R GOES FROM M TO N D12 = DM*DN'	HYEST
C R = 0 CANNOT BE SOLVED WITH THIS METHOD	HYEST
BE = 1.0	HYEST
RR = R(1)**2 + R(2)**2 + R(3)**2	HYEST
IF(RR.EQ.0.0)GO TO 30	HYEST
C R.R = 0 INVALID	HYEST
M = 1	HYEST
N = 1	HYEST
IF(BM(1).LT.0.0)M = 2	HYEST
IF(BN(1).LT.0.0)N = 2	HYEST
PM = 2.	HYEST
PN = 2.	HYEST
IF(M.EQ.2)PM = -BM(1)	HYEST
IF(N.EQ.2)PN = -BN(1)	HYEST
DO 10 I = 1,3	HYEST
T(I) = R(I)	HYEST
DO 10 J = 1,3	HYEST
10 B(I,J) = D12(I,J)	HYEST
IF(N.EQ.2)CALL DOTT33(D12,BN(8),B)	HYEST
DO 15 I = 1,3	HYEST
DO 15 J = 1,3	HYEST
15 C(I,J) = B(I,J)	HYEST
IF(M.EQ.2)CALL MAT33(BM(8),B,C)	HYEST
C C WILL TRANSFORM FROM NN TO MM	HYEST
IF(M.EQ.2)CALL MAT31(BM(8),B,T)	HYEST
CALL HYPX(BM(M),BN(N))	HYEST
BE = V(7)	HYEST
IF(V(7).LE.1.0)GO TO 30	HYEST
CALL HYABF(BM(1),V(1),A,F1)	HYEST
CALL HYABF(BN(1),V(4),B,F2)	HYEST
C ESTIMATE ALPHA	HYEST
AA = A(1,2)**2 + A(2,2)**2 + A(3,2)**2	HYEST
BB = B(1,2)**2 + B(2,2)**2 + B(3,2)**2	HYEST
ALP = DSQRT(AA/BB)	HYEST
RA = F1**(1.0/PM)	HYEST
RB = F2**(1.0/PN)	HYEST
ALP = ALP*RA*F2/(RB*F1)	HYEST
C SCALE POINTS TO ELLIPSOIDS	HYEST
DO 20 I = 1,3	HYEST
V(I) = V(I)/RA	HYEST
20 V(I+3) = V(I+3)/RB	HYEST
C ESTIMATE BETA	HYEST
CALL MAT31(C,V(4),T)	HYEST

```

      BE = (V(1)-T(1))**2 + (V(2)-T(2))**2 + (V(3) - T(3))**2
      BE = DSQRT(BE/RR)
C  STORE VALUES IN TAB ARRAY FOR CONTACT
      TAB(1) = ALP
      DO 25 I = 1,6
25  TAB(I+2) = V(I)
30  TAB(2) = BE
      RETURN
      END

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	DOUBLE PRECISION FUNCTION HYFCN(C,Z,A,P)		HYFCN
C	IMPLICIT REAL*8(A-H,O-Z)	REV IV	02/07/87HYFCN
	HYFCN = C		HYFCN
	IF(P.EQ.0.0)GO TO 10		HYFCN
	HYFCN = 0.0		HYFCN
	IF(Z.EQ.0.0)GO TO 10		HYFCN
	Q = P*(DLOG(DABS(Z)) - DLOG(A))		HYFCN
	IF(Q.GT.-88.5) HYFCN = C*DEXP(Q)		HYFCN
10	RETURN		HYFCN
	END		HYFCN

SUBROUTINE HYLIM(A,U,B,V,C,W,Z,BD)		HYLIM
C	IMPLICIT REAL*8(A-H,O-Z)	HYLIM
C	GIVEN Z, FIND A,B,Z: ZEZ = 1, ZEV = 0, TZ = TP	HYLIM
	DIMENSION BD(24)	HYLIM
	DIMENSION U(3),V(3),W(3),EI(3),EJ(3),T(3),TV(3)	HYLIM
	DIMENSION Z(3),E(3),EV(3),Q(3),S(3),EZ(3)	HYLIM
	DIMENSION SM(3,3)	HYLIM
	LOGICAL PASS,USEV	HYLIM
	PASS = .FALSE.	HYLIM
	ITER = 100	HYLIM
	PP = -1./BD(1)	HYLIM
	POW = -BD(1) - 2.0	HYLIM
	P1 = -BD(1) - 1.0	HYLIM
	P01 = 1.0/P1	HYLIM
	P2 = -BD(1)/P1	HYLIM
	DO 10 I = 1,3	HYLIM
	TV(I) = 0.0	HYLIM
10	IF(V(I).NE.0.0)TV(I) = HYFCN(1.0/V(I),V(I),BD(I+1),P2)	HYFIX
C	GET RECIPROCAL SET	HYLIM
	CALL CROSS(V,W,EI)	HYLIM
	CALL CROSS(W,U,EJ)	HYLIM
	CALL CROSS(U,V,T)	HYLIM
	EIU = EI(1)*U(1) + EI(2)*U(2) + EI(3)*U(3)	HYLIM
	G = C*EIU	HYLIM
C		HYLIM
	DO 55 IT = 1,ITER	HYLIM
	EVM = 0.0	HYLIM
	EVZ = 0.0	HYLIM
	ZEZ = 0.0	HYLIM
	USEV = .FALSE.	HYLIM
	DO 15 I = 1,3	HYLIM
	E(I) = HYFCN(BD(I+16),Z(I),BD(I+1),POW)	HYLIM
	EV(I) = E(I)*V(I)	HYLIM
	IF(EV(I).EQ.0.0)USEV = .TRUE.	HYLIM
	IF(DABS(EV(I)).GT.EVM)EVM = DABS(EV(I))	HYLIM
	EZ(I) = E(I)*Z(I)	HYLIM
	IF(DABS(EZ(I)).GT.EVZ)EVZ = DABS(EZ(I))	HYLIM
15	ZEZ = ZEZ + Z(I)*EZ(I)	HYLIM
	RHO = ZEZ*PP	HYLIM
	DO 20 I = 1,3	HYLIM
20	Z(I) = Z(I)/RHO	HYLIM
	IF(PASS)GO TO 60	HYLIM
	RHOZ = ZEZ/RHO	HYLIM
	RHOV = EVM*RHOZ/RHO	HYLIM
	RHOZ = EVZ*RHOZ	HYLIM
	IF(.NOT.USEV)GO TO 30	HYLIM
	RHOV = 1.0	HYLIM
	DO 25 I = 1,3	HYLIM
25	EV(I) = TV(I)	HYLIM

C WHAT IF NO TV IS 0 AND EV ARE ALL 0 ?

30 DO 35 I = 1,3

EV(I) = EV(I)/RHOV

35 EZ(I) = EZ(I)/RHOZ

C SET UP MATRIX

CALL CROSS(EV, T, SM(1,1))

CALL CROSS(T, EZ, SM(1,2))

CALL CROSS(EZ, EV, SM(1,3))

TZV = T(1)\*SM(1,3) + T(2)\*SM(2,3) + T(3)\*SM(3,3)

TZ = T(1)\*Z(1) + T(2)\*Z(2) + T(3)\*Z(3)

ZEV = Z(1)\*EV(1) + Z(2)\*EV(2) + Z(3)\*EV(3)

IF(TZV.EQ.0.0)STOP 39

ZEV = ZEV/TZV

Q(1) = 0.0

Q(2) = -ZEV

IF(.NOT.USEV)Q(2) = Q(2)/P1

Q(3) = (G - TZ)/TZV

CALL MAT31(SM,Q,S)

SS = 0.0

ZZ = 0.0

DO 50 I = 1,3

SS = SS + DABS(S(I))

IF(DABS(Z(I)).LT.0.1\*BD(I+1))GO TO 45

IF(DABS(S(I)).GT.DABS(Z(I)))S(I) = DSIGN(0.5\*Z(I),S(I))

45 Z(I) = Z(I) + S(I)

IF(DABS(Z(I)).GT.BD(I+1))Z(I) = DSIGN(BD(I+1),Z(I))

50 ZZ = ZZ + DABS(Z(I))

IF(SS.LT.1.0E-10\*ZZ)PASS = .TRUE.

55 CONTINUE

C

60 A = (EI(1)\*Z(1) + EI(2)\*Z(2) + EI(3)\*Z(3))/EIU

B = (EJ(1)\*Z(1) + EJ(2)\*Z(2) + EJ(3)\*Z(3))/EIU

RETURN

END

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[illegible]

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IF(E(I).EQ.0.0)GO TO 60
DO 55 M = 1,8
55 S(I,M) = S(I,M) - E(I)*S(K,M)
60 CONTINUE
GO TO 10
65 RETURN
END
```

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SUBROUTINE HYL PX(BM,BN)		HYLPX
C		REV IV 02/07/87HYLPX
C	LINEAR PROGRAM EXEC	HYLPX
	IMPLICIT REAL*8(A-H,O-Z)	HYLPX
	DIMENSION BM(23),BN(23)	HYLPX
	COMMON/TEMPVS/D12(3,3),P(3,3),Q(3,3),XMN(3),RLN(3),XMM(3),	HYLPX
	* R(3),H(3),D(3,3),V(7),S(9,8),C(16),A(7),B(3),	HYLPX
	* E(9),T(7),ID(16),IP(2)	HYLPX
	CALL MAT31(D,BN,B)	HYLPX
	DO 10 I = 1,3	HYLPX
	B(I) = BM(I) - B(I) + R(I)	HYLPX
	A(I) = BM(I)	HYLPX
10	A(I+3) = BN(I)	HYLPX
	A(7) = -1.0	HYLPX
	DO 15 I = 1,16	HYLPX
	C(I) = 0.0	HYLPX
15	ID(I) = I	HYLPX
	C(7) = -1.0	HYLPX
	DO 20 I = 1,9	HYLPX
	DO 20 J = 1,8	HYLPX
20	S(I,J) = 0.0	HYLPX
C		HYLPX
COSTS	0 0 -1	HYLPX
C	I -D -R A - DB + R (>0) INF COST	HYLPX
C	I 0 0 2A	HYLPX
C	0 1 0 2B	HYLPX
C		HYLPX
	DO 25 I = 1,6	HYLPX
25	S(I+3,I) = 1.0	HYLPX
	DO 30 I = 1,3	HYLPX
	C(I+7) = 10.	HYLPX
	S(I,7) = -R(I)	HYLPX
	S(I,I) = 1.0	HYLPX
	S(I,8) = B(I)	HYLPX
	S(I+3,8) = 2.0*A(I)	HYLPX
	S(I+6,8) = 2.0*A(I+3)	HYLPX
	DO 30 J = 1,3	HYLPX
30	S(I,J+3) = -D(I,J)	HYLPX
CHECK	SIGN OF RHS	HYLPX
	DO 40 I = 1,3	HYLPX
	IF(B(I).GE.0.0)GO TO 40	HYLPX
	DO 35 J = 1,8	HYLPX
35	S(I,J) = -S(I,J)	HYLPX
40	CONTINUE	HYLPX
	J1 = 1	HYLPX
	J2 = 7	HYLPX
C		HYLPX
	CALL HYLPR(J1,J2,ID,C,S,E,T)	HYLPX
	NK = 0	HYLPX
	NZ = 0	HYLPX

[illegible]

	SUBROUTINE HYNTR(BM,BN,TAB)		HYNTR
C		REV IV 02/07/87	HYNTR
	IMPLICIT REAL*8(A-H,O-Z)		HYNTR
	CALCULATIONS IN SEGMENT M'S REFERENCE		HYNTR
	DIMENSION BM(24),BN(24),TAB(8)		HYNTR
	COMMON/TEMPVS/D12(3,3),A(3,3),B(3,3),XMN(3),RLN(3),XMM(3),		HYNTR
	* AZ(3),R(3),Z(3),DNM(3,3),DAD(3,3),DBD(3,3),		HYNTR
	* BMD(3,3),TMP(3,3),S(5,6),ZVR(3),BZV(3),V(3),		HYNTR
	* ZM(3),VN(3),F(2),BV(3)		HYNTR
	P1 = 2.0		HYNTR
	P2 = 2.0		HYNTR
	IF(BM(1).LT.-2.0)P1 = -BM(1)		HYNTR
	IF(BN(1).LT.-2.0)P2 = -BN(1)		HYNTR
	C1 = P1 - 1.0		HYNTR
	CN = P2 - 1.0		HYNTR
C	DNM TRANSFORMS FROM M TO NN		HYNTR
	K = 8		HYNTR
	DO 15 J = 1,3		HYNTR
	DO 10 I = 1,3		HYNTR
	BMD(I,J) = 0.0		HYNTR
	IF(BM(1).LT.0.0)BMD(I,J) = BM(K)		HYNTR
	DNM(I,J) = D12(I,J)		HYNTR
10	K = K + 1		HYNTR
15	IF(BM(1).GT.0.0)BMD(J,J) = 1.0		HYNTR
	IF(BN(1).LT.0.0)CALL DOTT33(BN(8),D12,DNM)		HYNTR
	ALP = TAB(1)		HYNTR
	BET = TAB(2)		HYNTR
	DO 20 I = 1,3		HYNTR
	ZM(I) = TAB(I+2)		HYNTR
20	VN(I) = TAB(I+5)		HYNTR
C	PUT VECTORS INTO M'S REFERENCE		HYNTR
	CALL DOT31(BMD,ZM,Z)		HYNTR
	CALL DOT31(DNM,VN,V)		HYNTR
	DO 25 I = 1,3		HYNTR
25	ZVR(I) = Z(I) - V(I) - BET*R(I)		HYNTR
C			HYNTR
	DO 40 ITER = 1,100		HYNTR
	CALL HYABF(BM,ZM,A,F(1))		HYNTR
	CALL HYABF(BN,VN,B,F(2))		HYNTR
	CALL DOT31(BMD,A(1,2),AZ)		HYNTR
	CALL DOT31(DNM,B(1,2),BV)		HYNTR
	CALL HYDAD(BMD,A,DAD)		HYNTR
	CALL HYDAD(DNM,B,DBD)		HYNTR
	CALL MAT31(DBD,R,S(1,5))		HYNTR
	CALL MAT31(DBD,ZVR,BZV)		HYNTR
	C2 = CN*ALP		HYNTR
C	SET UP S MATRIX		HYNTR
	S(4,4) = 0.0		HYNTR
	S(5,5) = 0.0		HYNTR
	S(4,6) = (1.0 - F(2))/P2 -V(1)*BZV(1) -V(2)*BZV(2) -V(3)*BZV(3)		HYNTR

S(5,6) = (1.0 - F(1))/P1	HYNTR
S(4,5) = -BV(1)*R(1) - BV(2)*R(2) - BV(3)*R(3)	HYNTR
S(5,4) = 0.0	HYNTR
DO 30 I = 1,3	HYNTR
S(I,4) = BV(I)	HYNTR
S(4,I) = BV(I)	HYNTR
S(I,5) = -C2*S(I,5)	HYNTR
S(5,I) = AZ(I)	HYNTR
S(I,6) = -AZ(I) - ALP*BV(I) - C2*BZV(I)	HYNTR
DO 30 J = 1,3	HYNTR
30 S(I,J) = C1*DAD(I,J) + C2*DBD(I,J)	HYNTR
CALL HYSOL(S,5,5)	HYNTR
TALP = ALP + S(4,6)	HYNTR
IF(TALP.LE.0.0)TALP = ALP/2.0	HYNTR
ALP = TALP	HYNTR
TBET = BET + S(5,6)	HYNTR
IF(TBET.LE.0.0)TBET = BET/2.0	HYNTR
BET = TBET	HYNTR
SS = 0.0	HYNTR
ZZ = 0.0	HYNTR
DO 35 I = 1,3	HYNTR
SS = SS + DABS(S(I,6))	HYNTR
Z(I) = Z(I) + S(I,6)	HYNTR
ZZ = ZZ + DABS(Z(I))	HYNTR
V(I) = Z(I) - BET*R(I)	HYNTR
35 ZVR(I) = 0.0	HYNTR
CALL MAT31(BMD,Z,ZM)	HYNTR
CALL MAT31(DNM,V,VN)	HYNTR
CONVERGENCE TEST DEPENDS ON REAL*4 (1.0E-5) OR REAL*8 (??)	HYNTR
IF(SS.LT.1.0E-10*ZZ)GO TO 50	HYNTR
K = 1	HYNTR
L = 1	HYNTR
IF(BM(1).LT.0.0)K = 2	HYNTR
IF(BN(1).LT.0.0)L = 2	HYNTR
DO 37 I = 1,3	HYNTR
IF(DABS(ZM(I)).GT.BM(K)) ZM(I) = DSIGN(BM(K),ZM(I))	HYNTR
IF(DABS(VN(I)).GT.BN(L)) VN(I) = DSIGN(BN(L),VN(I))	HYNTR
K = K + 1	HYNTR
37 L = L + 1	HYNTR
CALL DOT31(BMD,ZM,Z)	HYNTR
CALL DOT31(DNM,VN,V)	HYNTR
DO 38 I = 1,3	HYNTR
38 ZVR(I) = Z(I) - V(I) - BET*R(I)	HYNTR
40 CONTINUE	HYNTR
C WRITE(6,45)	HYNTR
C 45 FORMAT(' HYNTR DID NOT CONVERGE, CONTACT IGNORED.')	HYNTR
BET = 1.0	HYNTR
50 TAB(1) = ALP	HYNTR
TAB(2) = BET	HYNTR
DO 55 I = 1,3	HYNTR

TAB(I+2) = ZM(I)  
55 TAB(I+5) = VN(I)  
RETURN  
END

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	DOUBLE PRECISION FUNCTION HYPEN(BD,E,V)		HYPEN
C		REV IV	02/07/87HYPEN
C	POINT OF MAXIMUM PENETRATION		HYPEN
C	SOLVES FOR VALUE OF ALP USED BY PLELP		HYPEN
C	POWERS OF HYPERELLIPSOID MAY BE DIFFERENT		HYPEN
	IMPLICIT REAL*8(A-H,O-Z)		HYPEN
	DIMENSION BD(24),E(3),V(3)		HYPEN
	FX(A) = A**E(1)*V(1)+A**E(2)*V(2)+A**E(3)*V(3)-1.0		HYPEN
	L = 1		HYPEN
	VM = V(1)		HYPEN
	DO 10 I = 2,3		HYPEN
	IF (V(I).LE.VM) GO TO 10		HYPEN
	L = I		HYPEN
	VM = V(I)		HYPEN
10	CONTINUE		HYPEN
	A = V(1) + V(2) + V(3)		HYPEN
	A = 1.0/A**(1.0/E(L))		HYPEN
	DEL = A/2.0		HYPEN
	AP = 0.0		HYPEN
12	F = FX(A)		HYPEN
	IF (DABS(F).LT.1.D-08) GO TO 40		HYPEN
	IF (F) 16,40,14		HYPEN
14	IF (A-DEL.LE.0.0) DEL = A/2.0		HYPEN
	AP = A		HYPEN
	FP = F		HYPEN
	A = A - DEL		HYPEN
	GO TO 12		HYPEN
16	IF (AP.NE.0.0) GO TO 18		HYPEN
	A = A + DEL		HYPEN
	GO TO 12		HYPEN
18	AM = A		HYPEN
	FM = F		HYPEN
20	IF (FP.EQ.FM) GO TO 40		HYPEN
	DEL = -FM*(AP - AM)/(FP - FM)		HYPEN
	AN = AM + DEL		HYPEN
	IF (AN.EQ.A) GO TO 40		HYPEN
	A = AN		HYPEN
	F = FX(A)		HYPEN
	IF (DABS(F).LT.1.D-08) GO TO 40		HYPEN
	IF (F) 18,40,22		HYPEN
22	FP = F		HYPEN
	AP = A		HYPEN
	GO TO 20		HYPEN
40	HYPEN = A		HYPEN
	RETURN		HYPEN
	END		HYPEN



```

C      SUBROUTINE HYREA (L,H,AREA,AB,BB)
      IMPLICIT REAL*8(A-H,O-Z)
      DIMENSION H(2,2,5)
      AREA = 0.0
      AB = 0.0
      BB = 0.0
      IF (L.LT.2) GO TO 20
      DO 15 I = 1,L
      AR = H(1,1,I)*H(2,2,I) - H(1,2,I)*H(2,1,I)
      IF (AR.EQ.0.0) GO TO 5
      AB = AB + AR*(H(1,1,I) + H(1,2,I))
      BB = BB + AR*(H(2,1,I) + H(2,2,I))
      AREA = AREA + AR
5     AR = H(1,2,I)*H(2,1,I+1) - H(1,1,I+1)*H(2,2,I)
      IF (AR.EQ.0.0) GO TO 15
      AB = AB + AR*(H(1,1,I+1) + H(1,2,I))
      BB = BB + AR*(H(2,1,I+1) + H(2,2,I))
      AREA = AREA + AR
15    CONTINUE
      IF (AREA.LE.0.0) GO TO 20
      AREA = 3.0*AREA
      AB = AB/AREA
      BB = BB/AREA
C     AREA = AREA/6.0
20    RETURN
      END

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REV IV 12/11/87HYFIX
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SUBROUTINE HYVAL(A,U,R,BD,L)		HYVAL
C	IMPLICIT REAL*8(A-H,O-Z)	HYFIX
C	GIVEN A,U,R: COMPUTE A      Z = A*U + R	HYVAL
	DIMENSION BD(24),U(3),R(3),RM(2)	HYFIX
	ONE = 1.0	HYFIX
	POW = -BD(1) - 2.0	HYVAL
C	ARE THESE THE CORRECT TESTS??	HYFIX
	TEST = -BD(1)*0.000001	HYFIX
	TESD = 0.000001	HYFIX
	CALL HYVBX(U,R,BD(2),M,RM)	HYVAL
	A = 0.0	HYFIX
	IF (M.LT.L) GO TO 50	HYFIX
C	THIS SHOULD NEVER HAPPEN - IMPLIES R IS OUTSIDE BOX	HYFIX
	A = RM(L)	HYVAL
	IF (DABS(A).LT.TESD) GO TO 50	HYFIX
	DEL = A/5.0	HYFIX
	NSTEP = 0	HYFIX
C	ITERATION LOOP	HYFIX
10	DEL = DEL/4.0	HYFIX
	NSTEP = NSTEP + 1	HYFIX
	IF (NSTEP.LT.100) GO TO 12	HYFIX
	WRITE(6,11) M,A,DEL,F1,F2,L,RM(1),RM(2),U,R,BD	HYFIX
11	FORMAT(' HYV ',I4,4F11.6,I3,2F11.6/4X,3F11.6,4X,3F11.6/ * 4(2X,7F10.4/))	HYFIX
	STOP 102	HYFIX
12	F2 = HYVFN(A,U,R,BD,POW)	HYFIX
	IF (DABS(F2).LT.TEST) GO TO 50	HYFIX
	IF (F2) 20,50,30	HYFIX
15	F2 = HYVFN(A,U,R,BD,POW)	HYFIX
	NSTEP = NSTEP + 1	HYFIX
	IF (NSTEP.LT.100) GO TO 17	HYFIX
	WRITE(6,11) M,A,DEL,F1,F2,L,RM(1),RM(2),U,R,BD	HYFIX
	STOP 103	HYFIX
17	IF (DABS(F2).LT.TEST) GO TO 50	HYFIX
	IF (F2) 20,50,35	HYFIX
20	IF (DSIGN(ONE,A).EQ.DSIGN(ONE,A+DEL)) GO TO 22	HYFIX
	A = A/2.0	HYFIX
	DL = -A	HYFIX
	GO TO 23	HYFIX
22	DL = DEL	HYFIX
	A = A + DEL	HYFIX
23	F1 = F2	HYFIX
	GO TO 15	HYFIX
25	F2 = HYVFN(A,U,R,BD,POW)	HYFIX
	NSTEP = NSTEP + 1	HYFIX
	IF (NSTEP.LT.100) GO TO 27	HYFIX
	WRITE(6,11) M,A,DEL,F1,F2,L,RM(1),RM(2),U,R,BD	HYFIX
	STOP 104	HYFIX
27	IF (DABS(F2).LT.TEST) GO TO 50	HYFIX

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      IF (F2) 35,50,30
30  IF (DSIGN(ONE,A).EQ.DSIGN(ONE,A-DEL)) GO TO 32
      A = A/2.0
      DL = -A
      GO TO 33
32  DL = -DEL
      A = A - DEL
33  F1 = F2
      GO TO 25
35  IF (F1.EQ.F2) GO TO 50
      A = A + F2*DL/(F1 - F2)
      IF (DABS(DEL).GT.TESD) GO TO 10
C
50  RETURN
    END

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	SUBROUTINE HYVBX(Q,S,B,M,RM)		HYVBX
C	IMPLICIT REAL*8(A-H,O-Z)	REV IV	02/07/87HYVBX
	DIMENSION Q(3),S(3),B(3),RM(2)		HYVBX
C	FINDS LIMITS OF BOX IN DIRECTION Q, Z = R*Q + S		HYVBX
	LOGICAL VAL		HYVBX
	M = 0		HYVBX
	C = -1.0		HYVBX
	DO 30 I = 1,3		HYVBX
	IF(Q(I).EQ.0.0)GO TO 30		HYVBX
	DO 25 K = 1,2		HYVBX
	VAL = .TRUE.		HYVBX
	D = C*B(I) - S(I)		HYVBX
	DO 10 J = 1,3		HYVBX
	IF(J.EQ.I)GO TO 10		HYVBX
	IF(DABS(D*Q(J) + S(J)*Q(I)).GT.DABS(B(J)*Q(I)))VAL = .FALSE.		HYVBX
C	IF(DABS(R*Q(J) + S(J)).GT.B(J))VAL = .FALSE.		HYVBX
10	CONTINUE		HYVBX
	IF(.NOT.VAL)GO TO 25		HYVBX
	R = D/Q(I)		HYVBX
	IF(M.EQ.0)GO TO 20		HYVBX
	DO 15 L = 1,M		HYVBX
	IF(R.EQ.RM(L)) GO TO 25		HYVBX
15	CONTINUE		HYVBX
20	M = M + 1		HYVBX
	RM(M) = R		HYVBX
25	C = -C		HYVBX
30	CONTINUE		HYVBX
	IF(M.EQ.0)GO TO 35		HYVBX
	IF(RM(1).LT.RM(2))GO TO 35		HYVBX
	R = RM(1)		HYVBX
	RM(1) = RM(2)		HYVBX
	RM(2) = R		HYVBX
35	RETURN		HYVBX
	END		HYVBX



	SUBROUTINE IMPLS2(MODE,J,H)	IMPLS2
		REV IV 07/24/86SLIP
C	CALLLED BY SUBROUTINE UPDATE WHEN JOINT J LOCKS TO APPLY IMPULSE	IMPLS2
C	TO SET P.(D(M)'W(M) - D(N)'W(N)) = 0	IMPLS2
C		IMPLS2
C	ARGUMENTS:	IMPLS2
C	MODE - 0: FULL LOCK P = I	IMPLS2
C	1: AXIS (H) FREE P = I-HH'	IMPLS2
C	-1: AXIS (H) LOCKED P = HH'	IMPLS2
C		IMPLS2
C	J - JOINT IDENTIFICATION NUMBER	IMPLS2
C		IMPLS2
C	H - AXIS VECTOR	IMPLS2
C		IMPLS2
C	IMPLICIT REAL*8(A-H,O-Z)	IMPLS2
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	IMPLS2
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	IMPLS2
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	IMPLS2
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),	SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),	IMPLS2
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)	IMPLS2
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),	IMPLS2
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)	SLIP
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),	IMPLS2
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),	IMPLS2
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),	IMPLS2
*	KQ1(12),KQ2(12),KQTYPE(12)	IMPLS2
	COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)	IMPLS2
	COMMON/TEMPVS/ SM(3),SN(3),TM(3,3),TN(3,3),T(3,4),TT(3,4)	IMPLS2
	DIMENSION TWA(3,3,30),TLA(3,3,30),H(3)	IMPLS2
	CALL ELTIME(1,28)	IMPLS2
	M = JNT(J)	IMPLS2
	N = J+1	IMPLS2
	DO 20 L=1,3	IMPLS2
	DO 12 K=1,NGRND	IMPLS2
	DO 12 I=1,3	IMPLS2
	U1(I,K) = 0.0	IMPLS2
12	U2(I,K) = 0.0	IMPLS2
	DO 13 K=1,NJNT	IMPLS2
	DO 13 I=1,3	IMPLS2
	V1(I,K) = 0.0	IMPLS2
13	V2(I,K) = 0.0	IMPLS2
	IF (NQ.LE.0) GO TO 15	IMPLS2
	DO 14 K=1,NQ	IMPLS2
	DO 14 I=1,3	IMPLS2
14	V3(I,K) = 0.0	IMPLS2
15	IF (NFLX.EQ.0) GO TO 18	IMPLS2
	DO 19 K=1,NFLX	IMPLS2

DO 19 I=1,3	IMPLS2
19 V4(I,K) = 0.0	IMPLS2
18 DO 16 I=1,3	IMPLS2
U2(I,M) = RPHI(I,M)*D(I,L,M)	IMPLS2
16 U2(I,N) = -RPHI(I,N)*D(I,L,N)	IMPLS2
CALL DAUX(L)	IMPLS2
DO 17 K=1,NGRND	IMPLS2
DO 17 I=1,3	IMPLS2
TLA(I,L,K) = SEGLA(I,K)	IMPLS2
17 TWA(I,L,K) = WMEGD(I,K)	IMPLS2
20 CONTINUE	IMPLS2
CALL DOT33(D(1,1,M),TWA(1,1,M),TM)	IMPLS2
CALL DOT33(D(1,1,N),TWA(1,1,N),TN)	IMPLS2
CALL DOT31(D(1,1,M),WMEG(1,M),SM)	IMPLS2
CALL DOT31(D(1,1,N),WMEG(1,N),SN)	IMPLS2
DO 22 I=1,3	IMPLS2
DO 21 K=1,3	IMPLS2
T(I,K) = TM(I,K) - TN(I,K)	IMPLS2
21 TT(I,K) = T(I,K)	IMPLS2
T(I,4) = SN(I) - SM(I)	IMPLS2
22 TT(I,4) = H(I)	IMPLS2
IF (MODE.GE.0) CALL DSMSOL(T,3,3)	IMPLS2
IF (MODE.GT.0) CALL DSMSOL(TT,3,3)	IMPLS2
IF (MODE) 24,29,25	IMPLS2
24 ST = 0.0	IMPLS2
STT = XDY(H,T,H)	IMPLS2
GO TO 26	IMPLS2
25 ST = 1.0	IMPLS2
STT = -(H(1)*TT(1,4) + H(2)*TT(2,4) + H(3)*TT(3,4))	IMPLS2
26 STT = (H(1)*T(1,4) + H(2)*T(2,4) + H(3)*T(3,4))/STT	IMPLS2
DO 27 I=1,3	IMPLS2
27 T(I,4) = ST*T(I,4) + STT*TT(I,4)	IMPLS2
29 DO 30 K=1,NGRND	IMPLS2
DO 30 I=1,3	IMPLS2
DO 30 L=1,3	IMPLS2
SEGLV(I,K) = SEGLV(I,K) + T(L,4)*TLA(I,L,K)	IMPLS2
30 WMEG(I,K) = WMEG(I,K) + T(L,4)*TWA(I,L,K)	IMPLS2
IF (NPRT(3).NE.0) CALL PRINT(6HIMPLS2)	IMPLS2
CALL ELTIME(2,28)	IMPLS2
RETURN	IMPLS2
END	IMPLS2



	SUBROUTINE IMPULS(I1,I2,I3)		IMPULS
		REV IV	07/24/86SLIP
C	ARGUMENTS: I1 = 1 - IMPULS FOR PLELP.		IMPULS
C	3 - IMPULS FOR SEGSEG.		IMPULS
C	4 - IMPULS FOR VISPR OR EJOINT		IMPULS
C	I2 = INDEX OF CONTACTING SEGMENT OR JOINT AXIS		IMPULS
C	I3 = INDEX OF PLANE, SEGMENT OR JOINT AXIS		IMPULS
C			IMPULS
C	IMPLICIT REAL*8 (A-H,O-Z)		IMPULS
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		IMPULS
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		IMPULS
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		IMPULS
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		IMPULS
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		IMPULS
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		IMPULS
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),		IMPULS
*	MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),		IMPULS
*	NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)		IMPULS
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		IMPULS
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		IMPULS
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		IMPULS
*	KQ1(12),KQ2(12),KQTYPE(12)		IMPULS
	COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)		IMPULS
	COMMON/TEMPVI/ CREST,TTI(3),RII(3),R2I(3),JSTOP(4,2,30)		IMPULS
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)		DIMENB
	DIMENSION TEMP(3),DWR1(3),DWR2(3),DWR3(3),DWR4(3),VREL(3),DV(3)		IMPULS
	IF (TIME.EQ.0.0) GO TO 99		IMPULS
C			IMPULS
C	SPECIAL SETUP FOR CALL TO SUBROUTINE DAUX		IMPULS
C	REPLACE SETUP WITH U1,U2,V1,V2,V3 = 0.		IMPULS
C	ASSUME OTHER ARRAYS FROM PREVIOUS CALL TO DAUX.		IMPULS
C			IMPULS
	CALL ELTIME(1,27)		IMPULS
	CALL OUTPUT(0)		IMPULS
	KQTEST = 0		IMPULS
	NT = 0		IMPULS
	IF (I1.EQ.1) NT = NTPL (I2,I3)		IMPULS
	IF (I1.EQ.3) NT = NTSEG(I2,I3)		IMPULS
	IF (NT.EQ.0) GO TO 29		IMPULS
	KQ = -NTAB(NT+1)		IMPULS
	IF (KQ.LE.0) GO TO 29		IMPULS
	KQTYPE(KQ) = IABS(KQTYPE(KQ))		IMPULS
	CALL DAUX(0)		IMPULS
29	IF (NQ.LE.0) GO TO 31		IMPULS
	DO 30 J=1,NQ		IMPULS
	DO 30 I=1,3		IMPULS

30	V3(I,J) = 0.0	IMPULS
31	DO 32 J=1,NGRND	IMPULS
	DO 32 I=1,3	IMPULS
	U1(I,J) = 0.0	IMPULS
32	U2(I,J) = 0.0	IMPULS
	IF (NJNT.LE.0) GO TO 21	IMPULS
	DO 33 J=1,NJNT	IMPULS
	DO 33 I=1,3	IMPULS
	V1(I,J) = 0.0	IMPULS
33	V2(I,J) = 0.0	IMPULS
21	IF (NFLX.EQ.0) GO TO 23	IMPULS
	DO 22 J=1,NFLX	IMPULS
	DO 22 I=1,3	IMPULS
22	V4(I,J) = 0.0	IMPULS
C		IMPULS
C	REPLACE CALLS TO CONTACT AND VISPR WITH SINGLE CALL	IMPULS
C	AT FIRST CONTACT IF NOT CONSTRAINT.	IMPULS
C		IMPULS
23	IF (I1.NE.1) GO TO 34	IMPULS
	NT = NTPL(I2,I3)	IMPULS
	M1 = MPL(1,I2,I3)	IMPULS
	M2 = MPL(2,I2,I3)	IMPULS
	M3 = MPL(3,I2,I3)	IMPULS
	CALL PLELP(M2,M3,M1,I3,NT)	IMPULS
	IF (NTAB(NT+1).LT.0) GO TO 37	IMPULS
	K1 = M2	IMPULS
	K2 = M1	IMPULS
	GO TO 39	IMPULS
34	IF (I1.NE.3) GO TO 35	IMPULS
	NT = NTSEG(I2,I3)	IMPULS
	M1 = MSEG(1,I2,I3)	IMPULS
	M2 = MSEG(2,I2,I3)	IMPULS
	M3 = MSEG(3,I2,I3)	IMPULS
	CALL SEGSEG(I3,M1,M2,M3,NT)	IMPULS
	IF (NTAB(NT+1).LT.0) GO TO 37	IMPULS
	K1 = I3	IMPULS
	K2 = M2	IMPULS
	GO TO 39	IMPULS
35	IF (I1.NE.4) WRITE (6,36) I1,I2,I3	IMPULS
36	FORMAT('O IMPROPER ARGUMENTS TO SUBROUTINE IMPULS'/	IMPULS
	* ' ARGUMENTS = ', 3I6 /	IMPULS
	* ' PROGRAM TERMINATED' )	IMPULS
	IF (I1.NE.4) STOP 33	IMPULS
C		IMPULS
C	RECALL VISPR FOR JOINT STOP.	IMPULS
C		IMPULS
	IF (IABS(IPIN(I3)).NE.4) GO TO 25	IMPULS
	CALL EJOINT(I2,I3)	IMPULS
	GO TO 26	IMPULS
25	CALL VISPR(I2,I3)	IMPULS

26	K1 = IABS(JNT(I3))	IMPULS
	K2 = I3+1	IMPULS
	GO TO 39	IMPULS
C		IMPULS
C	SET UP SPECIAL U1,U2 FOR FIRST CONTACT OF CONSTRAINT.	IMPULS
C		IMPULS
37	KQ = -NTAB(NT+1)	IMPULS
	KQTEST = 1	IMPULS
	KQTYPE(KQ) = -IABS(KQTYPE(KQ))	IMPULS
	K1 = KQ1(KQ)	IMPULS
	K2 = KQ2(KQ)	IMPULS
	IF (K1.GT.NSEG) GO TO 38	IMPULS
	CALL MAT31(A13(1,1,2*KQ-1),QQ(1,KQ),U1(1,K1))	IMPULS
	CALL MAT31(A23(1,1,2*KQ-1),QQ(1,KQ),U2(1,K1))	IMPULS
38	IF (K2.GT.NSEG) GO TO 39	IMPULS
	CALL MAT31(A13(1,1,2*KQ),QQ(1,KQ),U1(1,K2))	IMPULS
	CALL MAT31(A23(1,1,2*KQ),QQ(1,KQ),U2(1,K2))	IMPULS
C		IMPULS
C	FINAL SETUP OF U1 AND U2	IMPULS
C		IMPULS
39	DO 40 J=1,NGRND	IMPULS
	DO 40 I=1,3	IMPULS
	U1(I,J) = U1(I,J)*RW(J)	IMPULS
40	U2(I,J) = U2(I,J)*RPHI(I,J)	IMPULS
	CALL DAUX(I1)	IMPULS
	IF (KQTEST.EQ.1) KQTYPE(KQ) = IABS(KQTYPE(KQ))	IMPULS
	IF (NPRT(10).NE.0) CALL PRINT(6HPREIMP)	IMPULS
	IF (I1.GT.3) GO TO 51	IMPULS
	IF (NPRT(10).NE.0) WRITE (6,42) R1I,R2I	IMPULS
42	FORMAT ('0'/(6G20.8))	IMPULS
	CALL CROSS(WMEG (1,K1),R1I(1),TEMP)	IMPULS
	CALL DOT31(D(1,1,K1),TEMP,DWR1(1))	IMPULS
	CALL CROSS(WMEG (1,K2),R2I(1),TEMP)	IMPULS
	CALL DOT31(D(1,1,K2),TEMP,DWR2(1))	IMPULS
	CALL CROSS(WMEGD(1,K1),R1I(1),TEMP)	IMPULS
	CALL DOT31(D(1,1,K1),TEMP,DWR3(1))	IMPULS
	CALL CROSS(WMEGD(1,K2),R2I(1),TEMP)	IMPULS
	CALL DOT31(D(1,1,K2),TEMP,DWR4(1))	IMPULS
	TVREL = 0.0	IMPULS
	TDV = 0.0	IMPULS
	DO 50 I=1,3	IMPULS
	VREL(I) = SEGLV(I,K1)+DWR1(I) - SEGLV(I,K2)-DWR2(I)	IMPULS
	DV (I) = SEGLA(I,K1)+DWR3(I) - SEGLA(I,K2)-DWR4(I)	IMPULS
	TVREL = TVREL + TTI(I)*VREL(I)	IMPULS
50	TDV = TDV + TTI(I)*DV (I)	IMPULS
	GO TO 53	IMPULS
51	CALL DOT31(D(1,1,K1),WMEG (1,K1),DWR1(1))	IMPULS
	CALL DOT31(D(1,1,K2),WMEG (1,K2),DWR2(1))	IMPULS
	CALL DOT31(D(1,1,K1),WMEGD(1,K1),DWR3(1))	IMPULS
	CALL DOT31(D(1,1,K2),WMEGD(1,K2),DWR4(1))	IMPULS

TVREL = 0.0	IMPULS
TDV = 0.0	IMPULS
DO 52 I=1,3	IMPULS
VREL(I) = DWR1(I) - DWR2(I)	IMPULS
DV (I) = DWR3(I) - DWR4(I)	IMPULS
TVREL = TVREL + TTI(I)*VREL(I)	IMPULS
52 TDV = TDV + TTI(I)*DV (I)	IMPULS
53 ALPHA = 0.0	IMPULS
C	IMPULS
C NOTE: CREST IS SUPPLIED AS (1+E)/2 WHERE E IS THE CLASSICAL	IMPULS
C COEFFICIENT OF RESTITUTION BUT WITH A RANGE OF -1 TO +1.	IMPULS
C CREST HAS A RANGE OF 0 TO +1 WHERE 0 (E=-1) REPRESENTS NO IMPULSE.	IMPULS
C	IMPULS
IF (TDV.NE.0.0) ALPHA = -2.0*CREST*TVREL/TDV	IMPULS
IF (NPRT(10).NE.0) WRITE (6,42) DWR1,DWR2,DWR3,DWR4,	IMPULS
* TTI,VREL,DV,	IMPULS
* TVREL,TDV,CREST,ALPHA	IMPULS
DO 60 J=1,NGRND	IMPULS
DO 60 I=1,3	IMPULS
SEGLV(I,J) = SEGLV(I,J) + ALPHA*SEGLA(I,J)	IMPULS
60 WMEG (I,J) = WMEG (I,J) + ALPHA*WMEGD(I,J)	IMPULS
IF (NPRT(10).NE.0) CALL OUTPUT(1)	IMPULS
IF (NPRT( 3).NE.0) CALL PRINT(6HIMPULS)	IMPULS
CALL ELTIME(2,27)	IMPULS
99 RETURN	IMPULS
END	IMPULS

	SUBROUTINE INITIAL	INITAL
C		REV IV 07/24/86SLIP
C	PERFORMS CARD INPUT AND COMPUTATIONS FOR INITIAL	INITAL
C	POSITIONING OF THE CRASH VICTIM'S BODY SEGMENTS.	INITAL
C		INITAL
	IMPLICIT REAL*8(A-H,O-Z)	INITAL
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	INITAL
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	INITAL
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	INITAL
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),	SLIP
	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),	INITAL
	* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)	INITAL
	COMMON/VPOSTN/ ZPLT(3),SPLT(3),AXV(3,6),VATAB(6,501,6),	VEHICL
	* VTO(6),VDT(6),TIMEV(6),OMEGV(6),NVTAB(6),INDXV(6)	INITAL
	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),	INITAL
	* BLTTTL(5,8),PLTTTL(5,30),BAGTTL(5,6),SEG(30),	INITAL
	* JOINT(30),CGS(30),JS(30)	INITAL
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),	JDRIFT
	* FE(3,30),TQE(3,30),CONST(5,30)	JDRIFT
	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTTL,BAGTTL,SEG,JOINT	INITAL
	LOGICAL*1 CGS,JS	INITAL
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	INITAL
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
	COMMON/TEMPVS/ TMP(140),WMGDEG(3,30),T(3),S(3),A(3,2),Z(3,3)	SLIP
C	NOTE : CHAIN ALSO USES TEMPVS.	INITAL
	DIMENSION YPR(3,30) , IYPR(4,30)	INITAL
C		INITAL
C	INPUT CARD G.1.A (PLOT COORDINATES OF VEHICLE REFERENCE ORIGIN)	INITAL
C		INITAL
	READ(5,22) ZPLT,I1,J1,I2,J2,I3	INITAL
22	FORMAT(3F10.0,5I4)	INITAL
	S(1) = 10.0	INITAL
	S(2) = 6.0	INITAL
	S(3) = 1.0	INITAL
C		INITAL
C	IF J1*0, INPUT CARD G.1.B (PLOT SCALING INPUT)	INITAL
C		INITAL
	IF (J1.NE.0) READ (5,22) S	INITAL
	SPLT(1) = 1.0/S(3)	INITAL
	SPLT(2) = 1.0/S(3)	INITAL
	SPLT(3) = -(S(1)/S(2))/S(3)	INITAL
	WRITE (6,23) NPG,ZPLT,I1,J1,I2,J2,I3,S	PAGE
	NPG=NPG+1	PAGE
23	FORMAT('1 SUBROUTINE INITIAL INPUT',98X,'PAGE',I5/120X,'CARD G.1'/	PAGE
	* ' ZPLT(X) ZPLT(Y) ZPLT(Z) I1 J1 I2 J2 I3',	INITAL
	* ' SPLT(1) SPLT(2) SPLT(3)'/3F10.0,5I6,3F10.2)	INITAL
C		INITAL
C	INPUT CARDS G.2.A - G.2.N	INITAL
C		INITAL

C	INITIAL LINEAR POSITION (IN) AND (IF I3=1) VELOCITY (IN/SEC)	INITAL
C	OF EACH BASE BODY SEGMENT. IF I3=0, VELOCITY WILL BE SET TO	INITAL
C	INITIAL VELOCITY OF VEHICLE. INPUTS IN INERTIAL REFERENCE.	INITAL
C		INITAL
	DO 37 J=1,NSEG	INITAL
	IF(J.GT.1.AND.IABS(JNT(J-1)).GT.0) GO TO 37	INITAL
	READ(5,24) (SEGLP(I,J),I=1,3),(SEGLV(I,J),I=1,3)	INITAL
24	FORMAT (6F10.0 , 4I3)	INITAL
	IF(I3.GT.0) GO TO 37	INITAL
	DO 36 I=1,3	INITAL
36	SEGLV(I,J) = SEGLV(I,NVEH)	INITAL
37	CONTINUE	INITAL
C		INITAL
C	INPUT CARDS G.3.A - G.3.N	INITAL
C		INITAL
C	FOR EACH BODY SEGMENT SUPPLY YAW, PITCH AND ROLL (DEGREES)	INITAL
C	AND (IF I3=1) THE ANGULAR VELOCITY IN LOCAL REFERENCE (DEG/SEC).	INITAL
C	IF I3=0, THE ANGULAR VELOCITY (BLANK ON INPUT CARDS) WILL BE SET	INITAL
C	EQUAL TO THE INITIAL ANGULAR VELOCITY OF THE VEHICLE.	INITAL
C		INITAL
	FIRST = 0.0	INITAL
	DO 40 J=1,NSEG	INITAL
	READ (5,24) (YPR(I,J),I=1,3),(WMGDEG(I,J),I=1,3),(IYPR(I,J),I=1,4)	INITAL
	ID1 = IYPR(1,J)	INITAL
	DO 38 I=1,3	INITAL
	IF (ID1.EQ.0) IYPR(I,J) = I	INITAL
38	WMG(I,J) = WMGDEG(I,J)*RADIAN	INITAL
	IF (ID1.GE.0) GO TO 60	INITAL
C		INITAL
C	READ CARD G.3.J2 FOR SEGMENT NO. J WHEN IYPR(1,J) IS NEGATIVE.	INITAL
C		INITAL
	READ (5,24) A,II,IK,JJ,JK	INITAL
	IJ = II	INITAL
	LK = IK	INITAL
	DO 54 K=1,2	INITAL
	IF (IJ.GT.0) GO TO 52	INITAL
	DO 51 I=1,3	INITAL
51	Z(I,LK) = A(I,K)	INITAL
	GO TO 53	INITAL
52	DA1 = A(1,K)*RADIAN	INITAL
	DA2 = A(2,K)*RADIAN	INITAL
	SA1 = DSIN(DA1)	INITAL
	SA2 = DSIN(DA2)	INITAL
	CA1 = DCOS(DA1)	INITAL
	CA2 = DCOS(DA2)	INITAL
	IJ1 = IJ+1	INITAL
	IJ2 = IJ+2	INITAL
	IF (IJ1.GT.3) IJ1= IJ1-3	INITAL
	IF (IJ2.GT.3) IJ2= IJ2-3	INITAL
	SGN = 1.0	INITAL

IF (SA1.LT.0.0 .AND. CA2.LT.0.0) SGN = -1.0	INITAL
Z(IJ ,LK) = SGN*SA1*CA2	INITAL
Z(IJ1,LK) = SGN*SA1*SA2	INITAL
Z(IJ2,LK) = SGN*CA1*CA2	INITAL
53 IJ = JJ	INITAL
54 LK = JK	INITAL
ZDOTIJ = Z(1,IK)*Z(1,JK) + Z(2,IK)*Z(2,JK) + Z(3,IK)*Z(3,JK)	INITAL
ZDOTII = Z(1,IK)*Z(1,IK) + Z(2,IK)*Z(2,IK) + Z(3,IK)*Z(3,IK)	INITAL
RATIO = ZDOTIJ/ZDOTII	INITAL
DO 55 I=1,3	INITAL
55 Z(I,JK) = Z(I,JK) - RATIO*Z(I,IK)	INITAL
LK = 6-1K-JK	INITAL
IT = MOD(JK-1K+3,3)	INITAL
IF (IT.EQ.1) CALL CROSS(Z(1,IK),Z(1,JK),Z(1,LK))	INITAL
IF (IT.EQ.2) CALL CROSS(Z(1,JK),Z(1,IK),Z(1,LK))	INITAL
DO 57 K=1,3	INITAL
IYPR(K,J) = 4-K	INITAL
SUM = 0.0	INITAL
DO 56 I=1,3	INITAL
56 SUM = SUM + Z(I,K)**2	INITAL
SQUM = DSQRT(SUM)	INITAL
DO 57 I=1,3	INITAL
57 D(K,I,J) = Z(I,K)/SQUM	INITAL
CALL YPRDEG (D(1,1,J),YPR(1,J))	INITAL
IF (FIRST.EQ.0.0) WRITE (6,58)	INITAL
58 FORMAT('0 INITIAL ANGULAR ROTATIONS COMPUTED FROM CARDS G.3.J2'//	INITAL
* ' SEGMENT',10X,'SEGMENT PRIMARY AXIS',	INITAL
* 12X,'SEGMENT SECONDARY AXIS',30X,'ANGULAR ROTATIONS (DEG)'	INITAL
* ' NO. SEG',9X,'A1',8X,'A2',8X,'A3',11X,'B1',8X,'B2',8X,	INITAL
* 'B3',7X,'II IK JJ JK',9X,'YAW',6X,'PITCH',5X,'ROLL'//	INITAL
FIRST = 1.0	INITAL
WRITE (6,59) J,SEG(J),A,II,IK,JJ,JK,(YPR(I,J),I=1,3)	INITAL
59 FORMAT (I4,1X,A4,3X,3F10.3,3X,3F10.3,3X,4I4,3X,3F10.3)	INITAL
60 M = IYPR(4,J)	INITAL
IF (M.EQ.0) M=NGRND	INITAL
JF (M.GE.J .AND. M.LE.NSEG) STOP 24	INITAL
IF (J.EQ.1) GO TO 80	VAXCHG
IF (M.LT.0 .AND. -M.NE.IABS(JNT(J-1))) STOP 25	INITAL
80 CALL DRC1JK (D,YPR,IYPR,HT,J)	VAXCHG
IF (I3.GT.0) GO TO 40	INITAL
CALL DOT31(D(1,1,NVEH),WMEG(1,NVEH),T)	INITAL
CALL MAT31(D(1,1,J),T,WMEG(1,J))	INITAL
DO 39 I=1,3	INITAL
39 WMGDEG(I,J) = WMEG(I,J)/RADIAN	INITAL
40 CONTINUE	INITAL
CALL VEHPOS	INITAL
IF(NJNT.EQ.0) GOTO 41	JDRIFT
CALL CHAIN(0)	JDRIFT
CALL EJOINT(1,0)	JDRIFT
DO 62 J=1,NJNT	JDRIFT

	IF(IABS(IPIN(J)).NE.4) GOTO 62	JDRIFT
	IF(IEULER(J).NE.2) GOTO 62	JDRIFT
	DA1 = ANG(2,J) + CONST(2,J)	JDRIFT
	CONST(4,J) = DCOS(DA1)	JDRIFT
	CONST(5,J) = DSIN(DA1)	JDRIFT
62	CONTINUE	JDRIFT
C		INITAL
C	OUTPUT INITIAL BODY SEGMENT POSITIONS.	INITAL
C		INITAL
41	WRITE (6,42) UNITL,UNITL,UNITT	JDRIFT
42	FORMAT('0 INITIAL POSITIONS (INERTIAL REFERENCE)',70X,'CARDS G.2'/INITAL	INITAL
	* /' SEGMENT',11X,'LINEAR POSITION (' ,A4,')',	INITAL
	* 14X,'LINEAR VELOCITY (' ,A4,')/ ,A4,')'/	AFREVS
	* ' NO. SEG',2(9X,'X',11X,'Y',11X,'Z',5X) )	INITAL
	WRITE (6,43) (J,SEG(J), (SEGLP(I,J),I=1,3), (SEGLV(I,J),I=1,3)	INITAL
	* ,J=1,NSEG)	INITAL
43	FORMAT(I4,1X,A4,3X,3F12.5,3X,3F12.5)	INITAL
	WRITE (6,44) UNITT	INITAL
44	FORMAT('0 INITIAL ANGULAR ROTATION AND VELOCITY',71X,'CARDS G.3'//INITAL	INITAL
	* ' SEGMENT',11X,'ANGULAR ROTATION (DEG)',	AFREVS
	* 14X,'ANGULAR VELOCITY (DEG/' ,A4,')'/	INITAL
	* ' NO. SEG',8X,'YAW',8X,'PITCH',7X,'ROLL',	INITAL
	* 13X,'X',11X,'Y',11X,'Z',15X,'IYPR' )	INITAL
	WRITE (6,46) (J,SEG(J), (YPR(I,J),I=1,3), (WMGDEG(I,J),I=1,3),	INITAL
	* (IYPR(I,J),I=1,4),J=1,NSEG)	INITAL
46	FORMAT(I4,1X,A4,3X,3F12.5,3X,3F12.5,3X,4I4)	INITAL
	IF (I3.EQ.0) WRITE (6,45)	INITAL
45	FORMAT('0 LINEAR AND ANGULAR VELOCITIES HAVE BEEN SET EQUAL TO THEINITAL	INITAL
	* INITIAL VEHICLE VELOCITIES.')	INITAL
	IF (NHRNSS.NE.0) CALL HBPLAY	INITAL
	IF (I1.EQ.15) CALL EQUILB (YPR,IYPR)	INITAL
	CALL UNIT1(0)	JDRIFT
	CALL ROTATE	INITAL
	CALL ELTIME(2,2)	INITAL
	RETURN	INITAL
	END	INITAL



	SUBROUTINE INTERS(A,B,XM,T,X,V,AX)		INTER
C		REV IV	07/23/86TWOPI
C	DETERMINES INTERSECTION OF ELLIPSOIDS		INTER
C	$X'AX = 1$		INTER
C	$(X'-M')B(X-M) = 1$		INTER
C	WHERE A AND B ARE ELLIPSOID MATRICES		INTER
C	IF T ENTERS AS +1.0 , A IS EXTERNAL TO B AND		INTER
C	AS -1.0 , A IS INTERNAL TO B.		INTER
C			INTER
C	IF V ENTERS AS NON-ZERO, WILL USE PREVIOUS VALUE FOR START.		INTER
C	(AX) RETURNS AS (A)*(X).		INTER
C			INTER
C	RETURNS T>1 - NO INTERSECTION		INTER
C	T<1 - INTERSECTION IN WHICH CASE X WILL		INTER
C	CONTAIN COORDINATES OF CONTACT OF		INTER
C	CONTRACTED ELLIPSOIDS.		INTER
C			INTER
	IMPLICIT REAL*8 (A-H,O-Z)		INTER
	DIMENSION A(3,3),B(3,3),XM(3),X(3)		INTER
	DIMENSION C(3,4),Z(3),BM(3),AX(3),AM(3)		INTER
	EQUIVALENCE (Z(1),C(1,4))		INTER
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		INTER
	*                  UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
C			INTER
C	INITIALIZATION		INTER
C	EVALUATE BM,M'AM,M'BM		INTER
	SET N=0, V=M'BM/M'AM		INTER
			INTER
	N = 0		INTER
	BMM = 0.0		INTER
	AMM = 0.0		INTER
	DO 11 I=1,3		INTER
	BM(I) = 0.0		INTER
	AM(I) = 0.0		INTER
	DO 10 J=1,3		INTER
	IF (DABS(A(I,J)).LT.EPS(20)) A(I,J) = 0.0		INTER
	AM(I) = AM(I) + A(I,J)*XM(J)		INTER
	IF (DABS(B(I,J)).LT.EPS(20)) B(I,J) = 0.0		INTER
10	BM(I) = BM(I) + B(I,J)*XM(J)		INTER
	BMM = BMM + XM(I)*BM(I)		INTER
11	AMM = AMM + XM(I)*AM(I)		INTER
	IF (V.EQ.0.0) V=T*DSQRT(BMM/AMM)		INTER
	IDONE = 0		INTER
C			INTER
C		NEWTON-RAPHSON ITERATION FOR	INTER
C		G(V) = FA(V)-FB(V) = 0	INTER
		SOLVE (VA+B)X = BM FOR X	INTER
	ITER = 0		INTER
20	ITER = ITER+1		INTER
	DO 22 I=1,3		INTER
	DO 21 J=1,3		INTER
21	C(I,J) = V*A(I,J) + B(I,J)		INTER
22	Z(I) = BM(I)		INTER

C	CALL DSMSOL(C,3,3)	EVALUATE AX	INTERS
C		$FA(V) = X'AX$	INTERS
C		$FB(V) = -V(X'-M')AX$	INTERS
	FA = 0.0		INTERS
	FB = 0.0		INTERS
	CALL MAT31(A,Z,AX)		INTERS
	DO 30 I=1,3		INTERS
	X(I) = Z(I)		INTERS
	FA = FA+X(I)*AX(I)		INTERS
30	FB = FB+(X(I)-XM(I))*AX(I)		INTERS
	FB = -V*FB		INTERS
	IF (T.LT.0.0) FA = 1.0/FA		INTERS
	IF (IDONE.EQ.1) GO TO 60		INTERS
C		TEST FOR INTERSECTION	INTERS
	IF (FA-FB) 32,60,31		INTERS
C		IF FA>FB>1, NO INTERSECTION	INTERS
31	IF (T.GT.0.0.AND.FB.LT.1.0) GO TO 40		INTERS
	IF (T.LT.0.0.AND.FA.GT.1.0) GO TO 40		INTERS
	IF (N.EQ.0) GO TO 60		INTERS
	GO TO 62		INTERS
C		IF FA<FB<1, INTERSECTION	INTERS
32	IF (T.GT.0.0.AND.FB.LE.1.0) N=1		INTERS
	IF (T.LT.0.0.AND.FA.GE.1.0) N=1		INTERS
C		SOLVE (VA+B)Z = AX FOR Z	INTERS
40	DO 42 I=1,3		INTERS
	DO 41 J=1,3		INTERS
41	C(I,J) = V*A(I,J) + B(I,J)		INTERS
42	Z(I) = AX(I)		INTERS
	CALL DSMSOL(C,3,3)		INTERS
C		$F'A(V) = -2X'AZ$	INTERS
	CALL MAT31 (A,Z,AX)		INTERS
	FPA = X(1)*AX(1)		INTERS
	* + X(2)*AX(2)		INTERS
	* + X(3)*AX(3)		INTERS
	FPA = -(FPA+FPA)		INTERS
C		$DV = -G(V)/G'(V)$	INTERS
	DV = 1.0 + V		INTERS
	IF (T.LT.0.0) DV = V-FA**2		INTERS
	DV = (FB-FA)/(DV*FPA)		INTERS
	IF (ITER.GE.50) GO TO 62		INTERS
C		TEST FOR CONVERGENCE	INTERS
	IF (T*(V+DV).LE.0.0) DV = -0.5*V		INTERS
	V = V+DV		INTERS
	DV = DABS(DV/V)		INTERS
	IF (DV.LE.EPS(12)) IDONE=1		INTERS
	GO TO 20		INTERS
C		$FA(V) = FB(B)$ , RETURN	INTERS
60	IF (T.LT.0.0) FA = 1.0/FB		INTERS
	T = DSQRT(FA)		INTERS

```
IF (FA.GT.1.0) GO TO 61
N = 1
GO TO 71
61 IF (N.EQ.0) GO TO 71
62 WRITE (6,63)
63 FORMAT(' INTERS ITERATION DID NOT CONVERGE')
71 CONTINUE
RETURN
END
```

```
INTERs
INTERs
INTERs
INTERs
INTERs
INTERs
INTERs
INTERs
```

	SUBROUTINE KINPUT	KINPUT
		REV IV 07/23/86TWOPI
C	PERFORMS THE FOLLOWING CARD INPUT AFTER CARDS E.1-E.4 (SUBROUTINE KINPUT	KINPUT
C	CINPUT) AND BEFORE CARDS F.1-F.5 (SUBROUTINE FINPUT).	KINPUT
C	CARD E.5 - NO LONGER REQUIRED	WINDOP
C	CARDS E.6 - DEFINITIONS OF WIND FORCE FUNCTIONS AND DRAG	WINDOP
C	COEFFICIENT FUNCTIONS	WINDOP
C	CARDS E.7 - DEFINITIONS OF JOINT RESTORING FORCE FUNCTIONS	KINPUT
C		KINPUT
	IMPLICIT REAL*8(A-H,O-Z)	KINPUT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	KINPUT
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	DIMENB
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	KINPUT
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),	WINDOP
	* BLTTTL(5,8),PLTTTL(5,30),BAGTTL(5,6),SEG(30),	WINDOP
	* JOINT(30),CGS(30),JS(30)	WINDOP
	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTTL,BAGTTL,SEG,JOINT	TGMOD1
	COMMON/TEMPVS/ JTITLE(5,51),NF(5),MS(3),KTITLE(31),TH(50)	KINPUT
C	NOTE: TEMPVS IS SHARED HERE WITH SUBROUTINES CINPUT AND FINPUT.	KINPUT
	REAL BLANK,JTITLE,KTITLE	KINPUT
	DATA BLANK/4H /	KINPUT
11	FORMAT(2I6)	KINPUT
	J1 = MXTB1+1	KINPUT
	IF (NWINDF.LE.0) GO TO 31	KINPUT
	DO 30 K=1,NWINDF	KINPUT
C		KINPUT
C	INPUT CARD E.6.A - FUNCTION NO. AND TITLE	KINPUT
C		KINPUT
	READ (5,12) I,(KTITLE(J),J=1,5)	KINPUT
12	FORMAT(I4,4X,5A4)	KINPUT
	WRITE (6,13) I,(KTITLE(J),J=1,5),I,J1,NPG	PAGE
	NPG=NPG+1	PAGE
13	FORMAT('1 WIND FORCE FUNCTION NO.',I4,4X,5A4,10X,'NTI(',I2,') =',	KINPUT
	* 15,46X,'PAGE',I5/120X,'CARDS E.6'/)	PAGE
	IF (I.LE.0.OR.I.GT.50) WRITE (6,14)	KINPUT
14	FORMAT('0 IMPROPER FUNCTION NO. PROGRAM TERMINATED.')	KINPUT
	IF (I.LE.0.OR.I.GT.50) STOP 11	KINPUT
	IF (NTI(I).NE.0) WRITE (6,15) I	KINPUT
15	FORMAT('0 FUNCTION NO.',I4,') HAS ALREADY BEEN INPUTTED AND WILL BE	KINPUT
	* REPLACED BY THIS FUNCTION.')	KINPUT
	NTI(I) = J1	KINPUT
	DO 16 J=1,5	KINPUT
16	JTITLE(J,I) = KTITLE(J)	KINPUT
	J2 = J1+4	KINPUT
C		KINPUT
C	INPUT CARD E.6.B	WINDOP
C		WINDOP
	READ (5,60) (TAB(J),J=J1,J2-2),NSV,NSR	WINDOP

60	FORMAT(3F12.0,2I12)	WINDOP
	TAB(J2-1) = DFLOAT(NSV)	WINDOP
	TAB(J2) = DFLOAT(NSR)	WINDOP
	IF (TAB(J1).EQ.0.0) GOTO 22	WINDOP
	WRITE(6,23) (TAB(J),J=J1,J2-2),NSV,SEG(NSV),NSR,SEG(NSR)	WINDOP
23	FORMAT(' SPEC. HEAT RATIO      SONIC VEL.      ABS. PRESS.',7X,	WINDOP
	*      'SEGMENT      REF. SEGMENT',/3F15.4,2(I11,A4)//)	WINDOP
	J1=J2+1	WINDOP
	GOTO 30	MISC
22	WRITE (6,18) (TAB(J),J=J1,J2)	KINPUT
17	FORMAT(6F12.0)	KINPUT
18	FORMAT(10X,'D0',13X,'D1',13X,'D2',13X,'D3',8X,'REF. SEGMENT',	WINDOP
	*      /5F15.4//)	WINDOP
	J1 = J2+1	KINPUT
C		KINPUT
C	INPUT CARD E.6.C - NTMPTS	KINPUT
C		KINPUT
	READ (5,11) NTMPTS	KINPUT
	WRITE (6,19) NTMPTS	KINPUT
19	FORMAT('0 WIND FORCE TABLES FOR ',I6,' TIME POINTS.'//	KINPUT
	*      11X,'T',14X,'FX(T)',15X,'FY(T)',15X,'FZ(T)'    /)	KINPUT
	TAB(J1) = NTMPTS	KINPUT
	J1 = J1+1	KINPUT
	J2 = J1+4*NTMPTS-1	KINPUT
C		KINPUT
C	INPUT CARDS E.6.D-E.6.N - NTMPTS CARDS OF T,FX(T),FY(T),FZ(T)	KINPUT
C		KINPUT
	READ (5,20) (TAB(J),J=J1,J2)	KINPUT
	WRITE (6,21) (TAB(J),J=J1,J2)	KINPUT
20	FORMAT(4F12.0)	KINPUT
21	FORMAT(3X,F12.6,3G20.6)	KINPUT
	J1 = J2+1	KINPUT
30	CONTINUE	KINPUT
31	IF (NJNTF.LE.0) GO TO 51	KINPUT
	DO 50 K=1,NJNTF	KINPUT
C		KINPUT
C	INPUT CARD E.7.A - FUNCTION NO. AND TITLE	KINPUT
C		KINPUT
	READ (5,12) I,(KTITLE(J),J=1,5)	KINPUT
	WRITE (6,32) I,(KTITLE(J),J=1,5),I,J1,NPG	PAGE
	NPG=NPG+1	PAGE
32	FORMAT('1 JOINT FORCE FUNCTION NO.',I4,4X,5A4,10X,'NTI(',I2,') ='	KINPUT
	*      I5,45X,'PAGE',I5/120X,'CARDS E.7'//)	PAGE
	IF (I.LE.0.OR.I.GT.50) WRITE (6,14)	KINPUT
	IF (I.LE.0.OR.I.GT.50) STOP 12	KINPUT
	IF (NTI(I).NE.0) WRITE (6,15) I	KINPUT
	NTI(I) = J1	KINPUT
	DO 33 J=1,5	KINPUT
33	JTITL(J,I) = KTITL(J)	KINPUT
C		KINPUT

C	INPUT CARD E.7.B - D0,D1,D2,D3,D4 (FOR NOW A BLANK CARD).	KINPUT
C		KINPUT
	J2 = J1+4	KINPUT
	READ (5,17) (TAB(J),J=J1,J2)	KINPUT
	WRITE (6,18) (TAB(J),J=J1,J2)	KINPUT
	J1 = J2+1	KINPUT
C		KINPUT
C	INPUT CARD E.7.C - NTHETA,NPHI	KINPUT
C		KINPUT
	READ (5,11) NTHETA,NPHI	KINPUT
	TAB(J1) = NTHETA	KINPUT
	TAB(J1+1) = NPHI	KINPUT
	J1 = J1+2	KINPUT
	IF (NTHETA.LT.0) GO TO 38	KINPUT
	DO 35 J=1,NTHETA	KINPUT
35	TH(J) = DFLOAT(J-1)*180.0/DFLOAT(NTHETA-1)	KINPUT
	WRITE (6,36) NTHETA,NPHI,(TH(J),J=2,NTHETA)	KINPUT
36	FORMAT('0 FUNCTION IS TABULAR FOR' ,I3,' X',I3,' VALUES OF THETA AKINPUT	
	*ND PHI'//30X,'THETA'/5X,'PHI',5X,'THETA0',F16.3,4F20.3/	KINPUT
	* (15X,5F20.3))	KINPUT
37	FORMAT(F9.2,F10.3,5G20.7/(19X,5G20.7))	KINPUT
	GO TO 40	KINPUT
38	NPOLY = -NTHETA -1	KINPUT
	WRITE (6,39) NPOLY,NPHI,(BLANK,J,J=1,NPOLY)	KINPUT
39	FORMAT('0 FUNCTION IS COEFFICIENTS OF' ,I3,' ORDER POLYNOMIALS IN KINPUT	
	*(THETA-THETA0) FOR',I3,' VALUES OF PHI.'//	KINPUT
	* 27X,'COEFFICIENTS OF (THETA-THETA0)**N'/	KINPUT
	* 5X,'PHI',5X,'THETA0',7X,5(A4,'N =',I2,11X)/(26X,A4,'N =',I2,11X,KINPUT	
	* A4,'N =',I2,11X,A4,'N =',I2,11X,A4,'N =',I2,11X,A4,'N =',I2) ) KINPUT	
40	WRITE (6,21)	KINPUT
	DO 49 I=1,NPHI	KINPUT
	PHIDEG = DFLOAT(I-1)*360.0/DFLOAT(NPHI) - 180.0	KINPUT
C		KINPUT
C	INPUT CARDS E.7.D - E.7.N NPHI SETS WITH NTHETA ITEMS PER SET.	KINPUT
C	EACH SET I IS FOR PHI(I) = -180 +(I-1)*360/NPHI DEGREES AND	KINPUT
C	ASSUMES DATA FOR PHI(NPHI+1) = 180 IS SAME AS PHI(1) = -180.	KINPUT
C		KINPUT
	J2 = J1 + IABS(NTHETA) -1	KINPUT
	READ (5,17) (TAB(J),J=J1,J2)	KINPUT
	WRITE (6,37) PHIDEG,(TAB(J),J=J1,J2)	KINPUT
	IF (NTHETA.LT.0) TAB(J1) = TAB(J1)*RADIAN	KINPUT
	IF (NTHETA.LT.0) GO TO 49	KINPUT
C		KINPUT
C	FOR TABULAR DATA, FILL IN ZERO VALUES WITH INTERPOLATED NEGATIVE KINPUT	
C	VALUES. OVERWRITE VALUE IN FIRST COLUMN (SUPPLIED AS THETA0) WITH KINPUT	
C	VALUE FOR THETA = 0 AND ALL OTHER ZERO VALUES.	KINPUT
C		KINPUT
	THETA0 = TAB(J1)	KINPUT
	IF (THETA0.EQ.0.0) GO TO 49	KINPUT
	JJ = THETA0*DFLOAT(NTHETA-1)/180.0 + 1.0 + EPS(6)	KINPUT

JJ1 = J1+JJ	KINPUT
IERROR = 0	KINPUT
IF (JJ1.GT.J2) IERROR = 1	KINPUT
IF (TAB(JJ1).LE.0.0) IERROR = 2	KINPUT
IF (IERROR.NE.0) GO TO 46	KINPUT
DO 45 J=1, JJ	KINPUT
J1J = J1+J-1	KINPUT
IF (J.NE.1.AND.TAB(J1J).GT.0.0) IERROR = 3	KINPUT
45 TAB(J1J) = TAB(JJ1)*(TH(J)-THETA0)/(TH(JJ+1)-THETA0)	KINPUT
46 IF (IERROR.NE.0) WRITE (6,47) IERROR	KINPUT
47 FORMAT('0 INPUT ERROR. INCONSISTENT VALUE OF THETA0. IERROR = ',I2,	KINPUT
* ' PROGRAM TERMINATED.')	KINPUT
IF (IERROR.NE.0) STOP 13	KINPUT
49 J1 = J2+1	KINPUT
50 CONTINUE	KINPUT
51 MXTB1 = J1-1	KINPUT
RETURN	KINPUT
END	KINPUT

	SUBROUTINE LINAXS(X0,Y0,THETA,NINTVS,TOTLGT)		LINAXS
		REV 18	02/28/78LINAXS
C	PURPOSE : PREPARE A LINEAR AXIS ON A PLOT.		LINAXS
C			LINAXS
C	DESCRIPTION OF PARAMETERS:		LINAXS
C	X0,Y0 - STARTING POINT (IN INCHES, REL TO PLOTTER ORIGIN).		LINAXS
C			LINAXS
C	THETA - ANGLE OF AXIS, IN DEGREES.		LINAXS
C			LINAXS
C	NINTVS- MAGNITUDE = NO. OF INTERVALS DELINEATED BY TIC MARKS.		LINAXS
C	- SIGN DETERMINES WHETHER TIC MARKS ARE PLACED ON		LINAXS
C	POSITIVE OR NEGATIVE SIDE OF AXIS, RESPECTIVELY		LINAXS
C	(POSITIVE SIDE IS TO LEFT OF DIRECTION OF TRAVEL).		LINAXS
C			LINAXS
C	TOTLGT- TOTAL LENGTH OF AXIS, IN INCHES.		LINAXS
C			LINAXS
C	SUBROUTINES REQUIRED : SIN, COS, PLOT (NOTE: SINGLE PRECISION).		LINAXS
C			LINAXS
C	AUTHOR: W. D. FRYER, CALSPAN (MARCH 1967).		LINAXS
C			LINAXS
C	PLAGIARIZED FROM CALSPAN SUBROUTINE LIBRARY (NO. CU 0035).		LINAXS
C			LINAXS
	THR = 1.7453293E-2 * THETA		LINAXS
	SINT = SIN(THR)		LINAXS
	COST = COS(THR)		LINAXS
C			LINAXS
	DL = ABS(TOTLGT/ FLOAT(NINTVS))		LINAXS
	DX = DL*COST		LINAXS
	DY = DL*SINT		LINAXS
C			LINAXS
	TICK = -0.12* SINT		LINAXS
	TICY = 0.12* COST		LINAXS
	IF(NINTVS.GT.0) GO TO 30		LINAXS
	TICK = -TICK		LINAXS
	TICY = -TICY		LINAXS
C			LINAXS
30	X = X0		LINAXS
	Y = Y0		LINAXS
C			LINAXS
	CALL PLOT (X +TICK,Y+TICY,3)		LINAXS
	CALL PLOT (X,Y,2)		LINAXS
	NINT = IABS(NINTVS)		LINAXS
	DO 40 I=1,NINT		LINAXS
	X = X+DX		LINAXS
	Y = Y+DY		LINAXS
	CALL PLOT(X,Y,2)		LINAXS
	CALL PLOT(X+TICK,Y+TICY,2)		LINAXS
40	CALL PLOT(X,Y,2)		LINAXS
C			LINAXS
	RETURN		LINAXS
	END		LINAXS



SUBROUTINE LOGAXS(XO,YO,THETA,NDEC,EXTENT)

LOGAXS

REV 19 09/18/79LOGAXS

PURPOSE : PREPARE LOGARITHMIC AXIS ON A PLOT.

LOGAXS

DESCRIPTION OF PARAMETERS:

LOGAXS

XO,YO - STARTING POINT (IN INCHES, REL TO PLOTTER ORIGIN).

LOGAXS

THETA - ANGLE OF AXIS (DEGREES).

LOGAXS

NDECS - MAGNITUDE OF NDECS SPECIFIES NO. OF DECADES.

LOGAXS

- SIGN DETERMINES WHETHER TIC MARKS ARE TO BE PLACED  
ON POS. OR NEG. SIDE OF AXIS, RESP. (POS. SIDE IS  
TO LEFT OF PREDOMINANT DIRECTION OF TRAVEL).

LOGAXS

EXTENT- MAGNITUDE OF EXTENT SETS OVER-ALL LENGTH OF AXIS  
IN INCHES. IF EXTENT IS POSITIVE, TIC MARKS ARE  
SPACED NORMALLY (LARGE INTERVALS FIRST). IF EXTENT  
IS NEGATIVE, TIC MARKS ARE SPACED IN REVERSE ORDER  
(SMALL INTERVALS FIRST).

LOGAXS

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LOGAXS

SUBROUTINES REQUIRED : SIN, COS, PLOT (NOTE: SINGLE PRECISION).

LOGAXS

AUTHOR: W. D. FRYER, CALSPAN (MARCH 1967).

LOGAXS

PLAGIARIZED FROM CALSPAN SUBROUTINE LIBRARY (NO. CU 0036).

LOGAXS

LOGAXS

LOGAXS

LOGAXS

LOGAXS

LOGICAL REVERS

LOGAXS

REAL XL(18),XLO(19)

LOGAXS

EQUIVALENCE (XLO(2),XL(1))

LOGAXS

DATA XLO/ 0.0 , 0.17609, 0.30103, 0.39794, 0.47712, 0.54407,

LOGAXS

\* 0.60206, 0.65321, 0.69897, 0.74036, 0.77815, 0.81291, 0.84510,

LOGAXS

\* 0.87506, 0.90309, 0.92942, 0.95424, 0.97772, 1.0 /

LOGAXS

DATA RPD /1.7453293E-2/

LOGAXS

REVERS = .FALSE.

LOGAXS

IF(EXTENT.LT.0.0) REVERS = .TRUE.

LOGAXS

NODEC = IABS(NDEC)

LOGAXS

SPDEC = ABS(EXTENT) / FLOAT(NODEC)

LOGAXS

THR = THETA\*RPD

LOGAXS

COST = COS(THR)

LOGAXS

SINT = SIN(THR)

LOGAXS

TICK1 = -0.05\*SINT

LOGAXS

TICY1 = 0.05\*COST

LOGAXS

TICKA = -0.12\*SINT

LOGAXS

TICKB = -0.20\*SINT

LOGAXS

LOGAXS

LOGAXS

LOGAXS

LOGAXS

LOGAXS

	TICYA = 0.12*COST	LOGAXS
	TICYB = 0.20*COST	LOGAXS
	IF(NDEC.GT.0) GO TO 50	LOGAXS
C		LOGAXS
	TICK1 = -TICK1	LOGAXS
	TICY1 = - TICY1	LOGAXS
	TICK2 = -TICK2	LOGAXS
	TICKA = - TICKA	LOGAXS
	TICYA = -TICYA	LOGAXS
	TICKB = -TICKB	LOGAXS
	TICYB = - TICYB	LOGAXS
C		LOGAXS
50	COST = COST*SPDEC	LOGAXS
	SINT = SINT* SPDEC	LOGAXS
	TICK2 = TICKA	LOGAXS
	TICY2 = TICYA	LOGAXS
C		LOGAXS
	XD = X0	LOGAXS
	YD = Y0	LOGAXS
	ND = 1	LOGAXS
	N = 0	LOGAXS
C		LOGAXS
C	*****GO TO START POS.*****	LOGAXS
	CALL PLOT(X0+TICKB,Y0+TICYB,3)	LOGAXS
	CALL PLOT(X0,Y0,2)	LOGAXS
C		LOGAXS
60	N = N+1	LOGAXS
	Q = XL(N)	LOGAXS
	IF(.NOT. REVERS) GO TO 65	LOGAXS
	M = 18-N	LOGAXS
	Q = 1.0-XL(M)	LOGAXS
65	X = XD + Q*COST	LOGAXS
	Y = YD + Q*SINT	LOGAXS
	CALL PLOT(X,Y,2)	LOGAXS
	CALL PLOT(X+TICK1,Y+TICY1,2)	LOGAXS
	CALL PLOT (X,Y,2 )	LOGAXS
C		LOGAXS
	N = N+1	LOGAXS
	Q = XL(N)	LOGAXS
	IF(.NOT. REVERS) GO TO 75	LOGAXS
	M = 18-N	LOGAXS
	Q = 1.0 - XL(M)	LOGAXS
75	X = XD + Q*COST	LOGAXS
	Y = YD + Q*SINT	LOGAXS
	CALL PLOT(X,Y,2)	LOGAXS
	CALL PLOT (X+TICK2,Y+TICY2,2)	LOGAXS
	CALL PLOT(X,Y,2)	LOGAXS
C		LOGAXS
	IF(N-16) 60,80,100	LOGAXS
C		LOGAXS

80	TICK2 = TICKB	LOGAXS
	TICY2 = TICYB	LOGAXS
	GO TO 60	LOGAXS
C		LOGAXS
100	IF (ND .EQ. NODEC) GO TO 200	LOGAXS
	TICK2 = TICKA	LOGAXS
	TICY2 = TICYA	LOGAXS
	N = 0	LOGAXS
	XD = X	LOGAXS
	YD = Y	LOGAXS
	ND = ND+1	LOGAXS
	GO TO 60	LOGAXS
C		LOGAXS
200	RETURN	LOGAXS
	END	LOGAXS

	FUNCTION LTIME(N)	LTIME
C		REV III.2 08/08/84REVIII
C	TEMPORARY FORTRAN VERSION OF S/370 ASSEMBLER LANGUAGE ROUTINE FROM	LTIME
C	CALSPAN LIBRARY THAT MEASURES ELAPSED CPU TIME IN UNITS OF 0.01	LTIME
C	SECONDS. IT SHOULD BE REPLACED WITH AN EQUIVALENT ROUTINE BY THE	LTIME
C	USER TO ENABLE SUBROUTINE ELTIME TO PERFORM ON HIS COMPUTER.	LTIME
C		LTIME
C	ORIGINAL CALSPAN ROUTINE PERFORMS AS FOLLOWS:	LTIME
C	IT = LTIME(0) GIVES ELAPSED CPU TIME (INTEGER NUMBER OF 0.01	LTIME
C	SECOND UNITS) SINCE SUBROUTINE REFERENCE WAS	LTIME
C	RESET, AND RESETS THIS REFERENCE.	LTIME
C	IT = LTIME(1) SAME, EXCEPT THAT THE REFERENCE IS NOT RESET.	LTIME
C		LTIME
C	THIS SUBROUTINE DOESN'T WORK WITH THE P-E COMPUTER	PECONV
C	BUT THE CODE IS LEFT HERE AS A DUMMY SUBROUTINE.	PECONV
C	HOWEVER, THERE IS A VERSION OF THIS SUBROUTINE THAT	PECONV
C	CAN BE USED, BUT IT CAN ONLY BE COMPILED WITH THE	PECONV
C	P-E FORTRAN 0 COMPILER. THE OBJECT DECK FOR THIS	PECONV
C	SUBROUTINE IS KEPT SEPARATELY AND INCLUDED IN THE	PECONV
C	TASK FILE WHEN THE PROGRAM IS LINKED	PECONV
C		PECONV
	DATA KTIME/0/	LTIME
	KTIME = KTIME+1	LTIME
	LTIME = KTIME	LTIME
	IF (N.EQ.0) KTIME = 0	LTIME
	RETURN	LTIME
	END	LTIME

	SUBROUTINE MAT31 (A,B,C)			MAT31
C		REV 17	01/03/77	MAT31
C	PERFORMS MATRIX MULTIPLICATION C = AB			MAT31
C	WHERE A IS A 3X3 MATRIX, AND B AND C ARE VECTORS OF LENGTH 3.			MAT31
C				MAT31
	IMPLICIT REAL*8 (A-H,O-Z)			MAT31
	DIMENSION A(3,3) , B(3) , C(3)			MAT31
	C(1) = A(1,1)*B(1) + A(1,2)*B(2) + A(1,3)*B(3)			MAT31
	C(2) = A(2,1)*B(1) + A(2,2)*B(2) + A(2,3)*B(3)			MAT31
	C(3) = A(3,1)*B(1) + A(3,2)*B(2) + A(3,3)*B(3)			MAT31
	RETURN			MAT31
	END			MAT31

	SUBROUTINE MAT33 (A,B,C)			MAT33
C		REV 17	01/03/77	MAT33
C	PERFORMS MATRIX MULTIPLICATION C = AB			MAT33
C	WHERE A, B AND C ARE ALL 3X3 MATRICES.			MAT33
C				MAT33
	IMPLICIT REAL*8 (A-H,O-Z)			MAT33
	DIMENSION A(3,3) , B(3,3) , C(3,3)			MAT33
	DO 10 I=1,3			MAT33
	DO 10 J=1,3			MAT33
10	C(I,J) = A(I,1)*B(1,J) + A(I,2)*B(2,J) + A(I,3)*B(3,J)			MAT33
	RETURN			MAT33
	END			MAT33

	SUBROUTINE ORTHO(P,X,L)		ORTHO
		REV 03    05/31/73	ORTHO
C	GENERATES A SET OF RIGHT HANDED ORTHONORMAL VECTORS (P),		ORTHO
C	GIVEN ONE OF THE VECTORS (X), WHERE		ORTHO
C	P - LX3 MATRIX OF 3 ORTHONORMAL VECTORS TO BE GENERATED.		ORTHO
C	X - GIVEN VECTOR.		ORTHO
C	L - 1ST SUBSCRIPT OF P IN CALLING PROGRAM.		ORTHO
C			ORTHO
	IMPLICIT REAL*8(A-H,O-Z)		ORTHO
	DIMENSION P(L,3),X(3)		ORTHO
	M=2		ORTHO
	N=3		ORTHO
	TEST=0.		ORTHO
	DO 5 I=1,3		ORTHO
	P(I,3)=X(I)		ORTHO
	D=1.-X(I)**2		ORTHO
	IF(D.LE.TEST)GO TO 4		ORTHO
	TEST=D		ORTHO
	D=DSQRT(D)		ORTHO
	P(I,1)=D		ORTHO
	P(I,2)=0.		ORTHO
	P(M,2)=X(N)/D		ORTHO
	P(N,2)=-X(M)/D		ORTHO
	P(M,1)=X(I)*P(N,2)		ORTHO
	P(N,1)=-X(I)*P(M,2)		ORTHO
4	M=N		ORTHO
	N=I		ORTHO
5	CONTINUE		ORTHO
	RETURN		ORTHO
	END		ORTHO

	SUBROUTINE OUTPUT(IJK)		REV IV 02/01/88MISDOT	OUTPUT
C				
C	CONTROLS TABULATED OUTPUT ON FORTRAN UNITS (STARTING WITH NO. 21)			OUTPUT
C	OF SELECTED OPTIONAL SEGMENT LINEAR AND ANGULAR ACCELERATIONS,			OUTPUT
C	VELOCITIES AND DISPLACEMENTS, JOINT PARAMETERS AND SELECTED DATA			OUTPUT
C	FROM ALL ALLOWED CONTACT FORCE COMPUTATIONS BETWEEN BODY SEGMENTS			OUTPUT
C	AND VEHICLE COMPONENTS.			OUTPUT
C				OUTPUT
	IMPLICIT REAL*8 (A-H,O-Z)			OUTPUT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,			OUTPUT
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG			PAGE
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),			OUTPUT
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)			SLIP
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),			OUTPUT
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)			OUTPUT
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),			SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),			OUTPUT
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)			OUTPUT
	COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),			OUTPUT
*	MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),			OUTPUT
*	NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)			OUTPUT
	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),			OUTPUT
*	BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30),			OUTPUT
*	JOINT(30),CGS(30),JS(30)			OUTPUT
	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT			OUTPUT
	LOGICAL*1 CGS,JS			OUTPUT
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),			NCFORC
*	PRJNT(7,30),NPANEL(5),NPSF,NBST,NSSF,NBGSF			OUTPUT
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),			OUTPUT
*	UNITL,UNITM,UNITT,GRAVITY(3),TWOPI			TWOPI
	COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),			ATBIII
*	NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)			TTHKREF
	COMMON/COMAIN/VAR(240),DER(240),DT,HO,HMAX,HMIN,RSTIME,			OUTPUT
*	ISTEP,NSTEPS,NDINT,NEQ,IRSIN,IRSOUT			OUTPUT
	COMMON/DAMPER/ APSDM(3,20),APSDN(3,20),ASD(5,20),MSDM(20),MSDN(20)			OUTPUT
	COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),			OUTPUT
*	XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),			OUTPUT
*	NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)			OUTPUT
	COMMON/WINDFR/ WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30),			WINDOP
*	MWSEG(7,30),NFWSEG(6),NFWNT(5),MOWSEG(30,30)			WINDOP
	COMMON/TEMPVS/ TDATA(14,65),ACC(7,20),T1(3),T2(3),T3(3),T4(9)			CHGIII
*	,T5(3,3),T6(3,3),T7(3)			CHGIII
	LOGICAL LTAPES , LTHIST			OUTPUT
	DATA LINES/-1/,LPP/45/,NTMAX/65/			CHGIII
	DATA KMAX/20/,NMAX/22/,MCGMAX/5/			CHGIII
C				OUTPUT
	IF (IJK.NE.0) GO TO 13			OUTPUT
C				OUTPUT
C	SET ALL FORCE ARRAYS TO ZERO.			OUTPUT
C				OUTPUT



	DO 2 I=1,7	MISDOT
	DO 2 J=1,70	MISDOT
2	PSF(I,J) = 0.0	MISDOT
	DO 3 I=1,4	MISDOT
	DO 3 J=1,20	MISDOT
3	BSF(I,J) = 0.0	MISDOT
	DO 4 I=1,10	MISDOT
	DO 4 J=1,40	MISDOT
4	SSF(I,J) = 0.0	MISDOT
	DO 5 I=1,3	MISDOT
	DO 5 J=1,20	MISDOT
5	BAGSF(I,J) = 0.0	MISDOT
	DO 6 I=1,7	MISDOT
	DO 6 J=1,30	MISDOT
6	PRJNT(I,J) = 0.0	MISDOT
	GO TO 66	OUTPUT
C		OUTPUT
C	LTHIST = TRUE MEANS PRINT LINE OF TIME HISTORY DATA FOR THIS	OUTPUT
C	TIME POINT ON EACH OUTPUT UNIT (NT).	OUTPUT
C		OUTPUT
C	LTAPE8 = TRUE MEANS WRITE TIME HISTORY DATA ON TAPE 8.	OUTPUT
C		OUTPUT
	13 NPRT4 = NPRT(4) + 4	OUTPUT
	IF (NPRT4.LE.0 .OR. NPRT4.GT.8) STOP 37	OUTPUT
	IF(NPRT(26).EQ.6) GO TO 66	TGMOD1
	GO TO (66,66,66,15,16,17,17,16) , NPRT4	OUTPUT
	15 LTAPE8 = .FALSE.	OUTSTP
	LTHIST = .TRUE.	TGMOD1
	GO TO 116	TGMOD1
	16 LTHIST = .TRUE.	TGMOD1
	LTAPE8 = .TRUE.	TGMOD1
	GO TO 116	TGMOD1
	17 LTHIST = .FALSE.	TGMOD1
	LTAPE8 = .TRUE.	TGMOD1
	GO TO 217	TGMOD1
	116 TEST = DMOD(TIME,DT)	OUTSTP
	TEST = DMIN1(TEST,DABS(DT-TEST))	OUTSTP
	IF ((NPRT(26).EQ.0.OR.NPRT(26).EQ.3).AND.TEST.GE.EPS(8))	TGMOD1
	* LTHIST=.FALSE.	TGMOD1
	IF(.NOT.LTAPE8.AND..NOT.LTHIST) GO TO 66	FIXTTH
	217 CONTINUE	TGMOD1
	IF(NPRT(26).EQ.4) LTHIST=.FALSE.	TGMOD1
	IF(NPRT(26).EQ.5) LTAPE8=.FALSE.	TGMOD1
	IF(.NOT.LTAPE8.AND..NOT.LTHIST) GO TO 66	TGMOD1
	CALL ELTIME (1,8)	OUTPUT
	IF (LINES.GE.0) GO TO 21	FIXTTH
	PREVT = -999.0	OUTPUT
	LINES = 0	FIXTTH
	IF (IRSIN.NE.0) GO TO 10	OUTPUT
C		OUTPUT

C	1ST TIME IN ROUTINE, READ CARD INPUT FOR OUTPUT CONTROL.	OUTPUT
C		OUTPUT
C	1. NO. OF POINT TOTAL ACCELERATIONS ,POINT NOS. AND LOCATION	CHGIII
C	2. NO. OF POINT REL. VELOCITIES ,POINT NOS. AND LOCATION	CHGIII
C	3. NO. OF POINT REL. LINEAR DISPLACEMENTS ,POINT NOS. AND LOCATION	CHGIII
C	4. NO. OF SEGMENT ANGULAR ACCELERATIONS AND SEGMENT NOS.	CHGIII
C	5. NO. OF SEGMENT REL. ANGULAR VELOCITIES AND SEGMENT NOS.	CHGIII
C	6. NO. OF SEGMENT REL. ANGULAR DISPLACEMENTS AND SEGMENT NOS.	CHGIII
C	7. NO. OF JOINT PARAMETERS AND JOINT NOS.	OUTPUT
C	8. NO. OF SEGMENT WIND FORCES AND SEGMENT NOS.	WINDOP
C	9. NO. OF JOINT FORCES AND TORQUE NOS.	WINDOP
C	10. NO. OF CENTER OF GRAVITY AND RELATED INFORMATION	WINDOP
C		OUTPUT
	WRITE(6,478)	CHGIII
478	FORMAT(1X,/,2X,'TABULAR TIME HISTORY CONTROL PARAMETERS')	CHGIII
	WRITE(6,479)	CHGIII
479	FORMAT(3X,'TYPE KSG SELECTED SEGMENTS OR JOINTS')	TTHKREF
	DO 20 K=1,9	WINDOP
C		OUTPUT
C	INPUT CARDS H.(K).(J) FOR K=1,3	OUTPUT
C		OUTPUT
	IF (K.LE.3) READ (5,18) KSG,KREF(1,K),MSG(1,K),(XSG(I,1,K),I=1,3)	TTHKREF
18	FORMAT (I6,2I3,3F12.6)	TTHKREF
	IF (KSG.GT.KMAX) STOP 84	CHGIII
	IF (K.GT.3) GO TO 201	ATBIII
	IF (KSG.LE.1) READ(5,213) IDUMMY	ATBIII
213	FORMAT(I2)	ATBIII
	IF (KSG.LE.1) GO TO 201	ATBIII
	DO 205 J=2,KSG	ATBIII
	READ (5,210) KREF(J,K),MSG(J,K),(XSG(I,J,K),I=1,3)	TTHKREF
210	FORMAT (I9,I3,3F12.6)	TTHKREF
205	CONTINUE	ATBIII
201	CONTINUE	ATBIII
C		OUTPUT
C	INPUT CARDS H.(K) FOR K=4,9	WINDOP
C		OUTPUT
	IF (K.GT.3) READ (5,19) KSG,(KREF(J,K),MSG(J,K),J=1,KSG)	TTHKREF
19	FORMAT(I6,22I3/(I9,21I3))	TTHKREF
	IF (KSG.GT.KMAX) STOP 85	CHGIII
	WRITE (6,78) K,KSG,(MSG(J,K),J=1,KSG)	TTHKREF
	WRITE (6,81) (KREF(J,K),J=1,KSG)	TTHKREF
78	FORMAT(' H.',I1,1X,I3,3X,20I3)	TTHKREF
81	FORMAT(' REF ',20I3)	TTHKREF
	DO 80 J=1,KSG	TTHKREF
	IF(KREF(J,K).GT.NGRND.OR.KREF(J,K).LT.0) STOP 55	TTHKREF
80	CONTINUE	TTHKREF
	IF (K.NE.7 .OR. KSG.EQ.0) GO TO 20	OUTPUT
	DO 12 J=1,KSG	OUTPUT
	L = MSG(J,K)	OUTPUT
	IF (IABS(IPIN(L)).EQ.4) MSG(J,K) = -L	OUTPUT

12	CONTINUE	OUTPUT
20	MSG(K) = KSG	OUTPUT
C		ATBIII
C	READ INPUT CARDS H.10	WINDOP
C		ATBIII
	READ (5,111) MCG	ATBIII
111	FORMAT(I6)	ATBIII
	IF (MCG.GT.MCGMAX) STOP 86	CHGIII
	IF (MCG.EQ.0) GO TO 114	ATBIII
	DO 113 K=1,MCG	ATBIII
	READ (5,112) M,N,(MCGIN(I+2,K),I=1,N)	ATBIII
112	FORMAT (24I3)	ATBIII
	IF (N.GT.NMAX) STOP 87	CHGIII
	WRITE (6,117) N,(MCGIN(I+2,K),I=1,N)	TTHKREF
117	FORMAT(' H.10',I3,3X,22I3)	TTHKREF
	WRITE (6,81) M	TTHKREF
	MCGIN(1,K) = M	ATBIII
113	MCGIN(2,K) = N	ATBIII
114	CONTINUE	ATBIII
10	IF (.NOT.LTAPES) GO TO 21	OUTPUT
	WRITE (8)	OUTPUT
	* NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,NPANEL,	OUTPUT
	* MNPL,MNBLT,MNSEG,MNBAG,MPL,MBLT,MSEG,MBAG	OUTPUT
	WRITE (8)	OUTPUT
	* DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,	OUTPUT
	* SEG,JOINT,UNITL,UNITM,UNITT,MSG,MSG,XSG,MCG,	ATBIII
	* MCGIN,KREF,NHRNSS,NBLTPH,NPTSPB,NSD,MSDM,MSDN	CHGIII
21	IF(LTHIST) LINES= LINES + 1	FIXTTH
	IF (MOD(LINES,LPP).EQ.1 .AND. LTHIST) CALL HEDING (LINES,LPP)	OUTPUT
	NT = 20	OUTPUT
	USEC = 1000.0*TIME	OUTPUT
C		OUTPUT
C	COMPUTE AND PRINT DATA FOR 9 TYPES OF OUTPUT ABOVE	WINDOP
C		OUTPUT
	DO 44 K=1,9	WINDOP
	IF (MSG(K).LE.0) GO TO 44	OUTPUT
	KSG = MSG(K)	OUTPUT
	IF (K.GT.8) GO TO 440	WINDOP
	J3 = 3	OUTPUT
	IF (K.EQ.7) J3 = 2	OUTPUT
	DO 43 J1=1,KSG,J3	OUTPUT
	J2 = MIN0(J1+J3-1,KSG)	OUTPUT
	NT =NT + 1	OUTPUT
C	SETUP LOGICAL UNIT CONTROL (FOR PRINTER) FOR PERKIN & ELMER	PECONV
	CALL CARCON(NT,1)	PECONV
	DO 38 J=J1,J2	OUTPUT
	L = IABS(MSG(J,K))	OUTPUT
	GO TO (22,24,26,29,31,34,35,601),K	WINDOP
C		OUTPUT
C	1. POINT TOTAL ACCELERATION IN KREF(1) REFERENCE	CHGIII
C		OUTPUT
22	IF(LPMI(L).EQ.0) GO TO 521	CHGIII

CALL MAT31(DPMI(1,1,L),XSG(1,J,K),T7)	CHGIII
GO TO 523	CHGIII
521 DO 522 JL=1,3	CHGIII
522 T7(JL) = XSG(JL,J,K)	CHGIII
523 CALL CROSS (WMEG(1,L),T7,T1)	CHGIII
CALL CROSS (WMEG(1,L),T1,T2)	OUTPUT
CALL CROSS (WMEGD(1,L),T7,T3)	CHGIII
CALL MAT31(D(1,1,L),GRAVITY,T7)	ACCEL
CALL MAT31(D(1,1,L),SEGLA(1,L),T4)	OUTPUT
DO 23 I=1,3	OUTPUT
IF(MSG(J,K).LT.0) T4(I)=T4(I)+T7(I)	ACCEL
ACC(I,J) = (T4(I)+T3(I)+T2(I))/G	OUTPUT
23 T1(I) = ACC(I,J)	OUTPUT
IF(MSG(J,K).GE.0) GO TO 405	ACCEL
KRF=L	ACCEL
IF(LPMI(KRF).NE.0) CALL DOT31(DPMI(1,1,KRF),T1,ACC(1,J))	ACCEL
IF(KREF(J,K).EQ.1) GOTO 33	ACCEL
DO 600 II=1,3	ACCEL
600 ACC(II,J)=ACC(II,J)-GRAVITY(II)/G	ACCEL
GOTO 33	ACCEL
C	OUTPUT
C	CHGIII
C	OUTPUT
2. POINT REL. VELOCITY IN KREF(2) REFERENCE	TTHKREF
24 IF(KREF(J,2).EQ.0) KRF = NVEH	TTHKREF
IF(KREF(J,2).NE.0) KRF = KREF(J,2)	CHGIII
IF(LPMI(L).EQ.0) GO TO 524	CHGIII
CALL MAT31(DPMI(1,1,L),XSG(1,J,K),T7)	CHGIII
GO TO 525	CHGIII
524 DO 526 JL=1,3	CHGIII
526 T7(JL) = XSG(JL,J,K)	CHGIII
525 CALL CROSS (WMEG(1,L),T7,T1)	CHGIII
CALL DOT31(D(1,1,L),T1,T2)	OUTPUT
DO 25 I=1,3	OUTPUT
25 T3(I) = T2(I) + SEGLV(I,L) - SEGLV(I,KRF)	CHGIII
GO TO 28	OUTPUT
C	OUTPUT
C	CHGIII
C	OUTPUT
3. POINT REL. LINEAR DISPLACEMENT IN KREF(3) REFERENCE	TTHKREF
26 IF(KREF(J,3).EQ.0) KRF = NVEH	TTHKREF
IF(KREF(J,3).NE.0) KRF = KREF(J,3)	CHGIII
IF (LPMI(L).EQ.0) GO TO 76	OUTPUT
CALL DOT33 (DPMI(1,1,L),D(1,1,L),T4)	OUTPUT
CALL DOT31 (T4,XSG(1,J,K),T1)	OUTPUT
GO TO 77	OUTPUT
76 CALL DOT31 (D(1,1,L),XSG(1,J,K),T1)	OUTPUT
77 DO 27 I=1,3	OUTPUT
27 T3(I) = T1(I) + SEGLP(I,L) - SEGLP(I,KRF)	CHGIII
28 IF (LPMI(KRF).EQ.0) GO TO 403	CHGIII
CALL DOT33(DPMI(1,1,KRF),D(1,1,KRF),T5)	CHGIII
CALL MAT31(T5,T3,ACC(1,J))	CHGIII

	GO TO 33	OUTPUT
403	CALL MAT31(D(1,1,KRF),T3,ACC(1,J))	CHGIII
33	ACC(4,J) = DSQRT(ACC(1,J)**2+ACC(2,J)**2+ACC(3,J)**2)	CHGIII
	GO TO 38	CHGIII
C		OUTPUT
C	4. SEGMENT ANGULAR ACCELERATION IN KREF(4) REFERENCE	CHGIII
C		OUTPUT
29	DO 30 I=1,3	OUTPUT
	ACC(I,J) = WMEGD(I,L)/(2.0*PI)	OUTPUT
30	T1(I) = ACC(I,J)	OUTPUT
405	CONTINUE	CHGIII
	IF(KREF(J,K).EQ.0) GO TO 401	TTHKREF
	KRF = KREF(J,K)	TTHKREF
	IF(LPMI(KRF).EQ.0) GO TO 402	CHGIII
	CALL DOT33(DPMI(1,1,KRF),D(1,1,KRF),T5)	CHGIII
	CALL DOTT33(T5,D(1,1,L),T6)	CHGIII
	CALL MAT31(T6,T1,ACC(1,J))	CHGIII
	GO TO 33	CHGIII
402	CALL DOTT33(D(1,1,KRF),D(1,1,L),T6)	CHGIII
	CALL MAT31(T6,T1,ACC(1,J))	CHGIII
	GO TO 33	CHGIII
401	KRF = L	CHGIII
	IF(LPMI(KRF).NE.0) CALL DOT31(DPMI(1,1,KRF),T1,ACC(1,J))	CHGIII
	GO TO 33	OUTPUT
C		OUTPUT
C	5. SEGMENT REL. ANGULAR VELOCITY IN KREF(5) REFERENCE	CHGIII
C		OUTPUT
31	IF(KREF(J,5).EQ.0) KRF = NVEH	TTHKREF
	IF(KREF(J,5).NE.0) KRF = KREF(J,5)	TTHKREF
	CALL DOT31(D(1,1,L),WMEG(1,L),T1)	CHGIII
	CALL MAT31(D(1,1,KRF),T1,T2)	CHGIII
	DO 32 I=1,3	OUTPUT
	IF(KRF.NE.L) T2(I)=T2(I)-WMEG(I,KRF)	PLTINC
32	T3(I) = T2(I)/(2.0*PI)	PLTINC
	IF(LPMI(KRF).EQ.0) GO TO 449	CHGIII
	CALL DOT31(DPMI(1,1,KRF),T3,ACC(1,J))	CHGIII
	GO TO 483	CHGIII
449	CONTINUE	CHGIII
	DO 457 KJL=1,3	CHGIII
457	ACC(KJL,J) = T3(KJL)	CHGIII
483	ACC(4,J) = DSQRT(ACC(1,J)**2+ACC(2,J)**2+ACC(3,J)**2)	CHGIII
	GO TO 38	OUTPUT
C		OUTPUT
C	6. SEGMENT REL. ANGULAR DISPLACEMENT IN KREF(6) REFERENCE	CHGIII
C		OUTPUT
34	IF(KREF(J,6).EQ.0) KRF = NVEH	TTHKREF
	IF(KREF(J,6).NE.0) KRF = KREF(J,6)	TTHKREF
	IF(LPMI(KRF).EQ.0.AND.LPMI(L).EQ.0) GO TO 36	CHGIII
	IF(LPMI(L).EQ.0) GO TO 435	CHGIII
	CALL DOT33(DPMI(1,1,L),D(1,1,L),T4)	CHGIII

435	IF (LPMI(KRF).EQ.0) GO TO 436	CHGIII
	CALL DOT33(DPMI(1,1,KRF),D(1,1,KRF),T5)	CHGIII
436	IF (LPMI(L).NE.0) GO TO 438	CHGIII
	CALL DOTT33(D(1,1,L),T5,T1)	CHGIII
	GO TO 37	CHGIII
438	IF (LPMI(KRF).NE.0) GO TO 439	CHGIII
	CALL DOTT33(T4,D(1,1,KRF),T1)	CHGIII
	GO TO 37	CHGIII
439	CALL DOTT33(T4,T5,T1)	CHGIII
	GO TO 37	CHGIII
36	CALL DOTT33(D(1,1,L),D(1,1,KRF),T1)	CHGIII
37	CALL YPRDEG(T1,ACC(1,J))	OUTPUT
	TRACE = 0.5*(T1(1)+T2(2)+T3(3)-1.0)	OUTPUT
	IF (TRACE.GT. 1.0) TRACE = 1.0	OUTPUT
	IF (TRACE.LT.-1.0) TRACE = -1.0	OUTPUT
	ACC(4,J) = DACOS(TRACE)/RADIAN	OUTPUT
	GO TO 38	OUTPUT
C		OUTPUT
C	7. JOINT PARAMETERS	OUTPUT
C		OUTPUT
35	ACC(1,J) = PRJNT(1,L)	OUTPUT
	ACC(2,J) = PRJNT(2,L)/RADIAN	OUTPUT
	ACC(3,J) = PRJNT(3,L)/RADIAN	OUTPUT
	ACC(4,J) = PRJNT(4,L)/RADIAN	OUTPUT
	ACC(5,J) = DSQRT(PRJNT(5,L))	OUTPUT
	ACC(6,J) = DSQRT(PRJNT(6,L))	OUTPUT
	ACC(7,J) = DSQRT(PRJNT(7,L))	OUTPUT
	GOTO 38	WINDOP
C		WINDOP
C	8. SEGMENT WIND FORCE IN KREF(8) REFERENCE	WINDOP
C		WINDOP
601	IF(KREF(J,8).EQ.0) KRF = NGRND	TTHKREF
	IF(KREF(J,8).NE.0) KRF = KREF(J,8)	TTHKREF
	CALL MAT31(D(1,1,KRF),WF(1,L),T2)	WINDOP
	IF(LPMI(KRF).EQ.0) GO TO 602	WINDOP
	CALL DOT31(DPMI(1,1,KRF),T2,ACC(1,J))	WINDOP
	GO TO 604	WINDOP
602	CONTINUE	WINDOP
	DO 603 KJL=1,3	WINDOP
603	ACC(KJL,J) = T2(KJL)	WINDOP
604	ACC(4,J) = DSQRT(ACC(1,J)**2+ACC(2,J)**2+ACC(3,J)**2)	WINDOP
38	CONTINUE	OUTPUT
	IF (.NOT.LTAPE8) GO TO 40	OUTPUT
	KK = 0	OUTPUT
	I2 = 4	OUTPUT
	IF (K.EQ.7) I2 = 7	OUTPUT
	DO 39 J=J1,J2	OUTPUT
	DO 39 I=1,I2	OUTPUT
	KK = KK+1	OUTPUT
39	TDATA(KK,NT-20) = ACC(I,J)	OUTPUT

40	IF (.NOT.LTHIST) GO TO 43	OUTPUT
	IF (K.LE.6) WRITE (NT,41) USEC,((ACC(I,J),I=1,4),J=J1,J2)	OUTPUT
	IF (K.EQ.8) WRITE (NT,41) USEC,((ACC(I,J),I=1,4),J=J1,J2)	WINDOP
41	FORMAT(F9.3,3(3X,4F9.3) )	OUTPUT
	IF (K.EQ.7) WRITE (NT,42) USEC,((ACC(I,J),I=1,7),J=J1,J2)	OUTPUT
42	FORMAT(F9.3,2(F5.0,3F9.3,2X,3F9.3))	OUTPUT
43	CONTINUE	OUTPUT
	GO TO 44	CHGIII
C		ATBIII
C	9. JOINT FORCES & TORQUES IN KREF(9) GEOMETRIC COORDINATE SYSTEM	WINDOP
C		CHGIII
440	DO 860 L=1,KSG	PLTINC
	KRF = NVEH	PLTINC
	IF(KREF(L,9).NE.0) KRF = KREF(L,9)	PLTINC
	LL=MSG(L,K)	CHGIII
	IF (LPMI(KRF).EQ.0) GO TO 851	CHGIII
	CALL DOT33 (DPMI(1,1,KRF),D(1,1,KRF),T5)	CHGIII
	CALL MAT31 (T5,F(1,LL),T1)	CHGIII
	CALL MAT31 (T5,TQ(1,LL),T2)	CHGIII
	DO 852 JJ=1,3	CHGIII
	T1(JJ) = T1(JJ)/100.0	CHGIII
852	T2(JJ) = -T2(JJ)/100.0	OUT385
	GO TO 859	CHGIII
851	CONTINUE	CHGIII
	CALL MAT31 (D(1,1,KRF),F(1,LL),T1)	CHGIII
	CALL MAT31 (D(1,1,KRF),TQ(1,LL),T2)	CHGIII
	DO 853 JJ=1,3	CHGIII
	T1(JJ) = T1(JJ)/100.0	CHGIII
853	T2(JJ) = -T2(JJ)/100.0	OUT385
859	NT = NT + 1	CHGIII
C	P & E CARRIAGE CONTROL	PECONV
	CALL CARCON(NT,1)	PECONV
	IF (.NOT.LTAPE8) GO TO 855	CHGIII
	DO 854 JL=1,3	CHGIII
	TDATA (JL ,NT-20) = T1(JL)	CHGIII
854	TDATA (JL+3,NT-20) = T2(JL)	CHGIII
855	CONTINUE	CHGIII
	IF (LTHIST) WRITE (NT,857) USEC,T1,T2	CHGIII
857	FORMAT(F9.3,3X,3F9.3,3X,3(2X,D10.3))	CHGIII
860	CONTINUE	CHGIII
44	CONTINUE	CHGIII
C		ATBIII
C	10. PRINT BODY PROPERTIES	WINDOP
C		ATBIII
	IF (MCG.EQ.0) GO TO 131	ATBIII
	DO 130 NCG=1,MCG	ATBIII
	M = MCGIN(1,NCG)	ATBIII
	N = MCGIN(2,NCG)	ATBIII
	DO 120 J=1,9	ATBIII
120	T4(J) = 0.0	ATBIII

SUMW = 0.0	ATBIII
T7(1)=0.0	KINETIC
T7(2)=0.0	KINETIC
DO 123 I=1,N	ATBIII
K = MCGIN(I+2, NCG)	ATBIII
WG = W(K)/G	ATBIII
V=(SEGLV(1,K)-SEGLV(1,M))**2	KINETIC
* +(SEGLV(2,K)-SEGLV(2,M))**2	KINETIC
* +(SEGLV(3,K)-SEGLV(3,M))**2	KINETIC
T7(1)=T7(1)+0.5*WG*V	KINETIC
SUMW = SUMW + WG	ATBIII
DO 121 J=1,3	ATBIII
T7(2)=T7(2)+0.5*PHI(J,K)*(WMEG(J,K)-WMEG(J,M))**2	KINETIC
121 T1(J) = PHI(J,K)*WMEG(J,K)	ATBIII
CALL DOT31 (D(1,1,K),T1,T2)	ATBIII
CALL CROSS (SEGLP(1,K),SEGLV(1,K),T1)	ATBIII
DO 122 J=1,3	ATBIII
T4(J ) = T4(J ) + WG*SEGLP(J,K)	ATBIII
T4(J+3) = T4(J+3) + WG*SEGLV(J,K)	ATBIII
122 T4(J+6) = T4(J+6) + WG*T1(J) + T2(J)	ATBIII
123 CONTINUE	ATBIII
T7(3)=T7(1)+T7(2)	KINETIC
DO 124 J=1,3	ATBIII
124 T4(J) = T4(J)/SUMW - SEGLP(J,M)	ATBIII
C	ATBIII
C TRANSFORM FROM PRINCIPAL AXES TO LOCAL AXES	TGMOD1
C	ATBIII
IF (LPMI(M).EQ.0) GO TO 330	ATBIII
CALL DOT33(DPMI(1,1,M),D(1,1,M),T5)	ATBIII
CALL MAT31(T5,T4(1),T1)	ATBIII
CALL MAT31(T5,T4(4),T2)	ATBIII
CALL MAT31(T5,T4(7),T3)	ATBIII
GO TO 333	ATBIII
330 CONTINUE	ATBIII
CALL MAT31 (D(1,1,M),T4(1),T1)	ATBIII
CALL MAT31 (D(1,1,M),T4(4),T2)	ATBIII
CALL MAT31 (D(1,1,M),T4(7),T3)	ATBIII
333 CONTINUE	ATBIII
NT = NT + 1	ATBIII
IF (.NOT.LTAPE8) GO TO 126	ATBIII
DO 125 J=1,3	ATBIII
TDATA (J ,NT-20) = T1(J)	ATBIII
TDATA (J+3,NT-20) = T2(J)	ATBIII
TDATA(J+9,NT-20) = T7(J)	KINETIC
125 TDATA(J+6,NT-20) = T3(J)	ATBIII
126 IF (LTHIST) WRITE (NT,127) USEC,T1,T2,T3,T7	KINETIC
127 FORMAT (F9.3,3F8.3,9(1X,D10.3))	KINETIC
130 CONTINUE	ATBIII
131 CONTINUE	ATBIII
C	OUTPUT



C	PRINT PLANE FORCES	OUTPUT
C		OUTPUT
	MPSF = 0	OUTPUT
	IF (NPL.EQ.0) GO TO 49	OUTPUT
	IF (NPRT(18).EQ.1.OR.NPRT(18).EQ.7) GO TO 49	VARTTH
	IF (NPRT(18).EQ.10.OR.NPRT(18).EQ.11) GO TO 49	VARTTH
	IF (NPRT(18).GE.14) GO TO 49	VARTTH
	DO 45 J=1,NPL	OUTPUT
45	MPSF = MPSF + MNPL(J)	OUTPUT
	IF (MPSF.EQ.0) GO TO 49	OUTPUT
	DO 47 J1=1,MPSF,2	OUTPUT
	J2 = MINO(J1+1,MPSF)	OUTPUT
	NT = NT+1	OUTPUT
C	SETUP LOGICAL UNIT CONTROL (PRINTER CONTROL) FOR P & E	PECONV
	CALL CARCON(NT,1)	PECONV
	IF (.NOT.LTAPES) GO TO 47	OUTPUT
	KK = 0	OUTPUT
	DO 46 J=J1,J2	OUTPUT
	DO 46 I=1,7	OUTPUT
	KK = KK+1	OUTPUT
46	TDATA(KK,NT-20) = PSF(I,J)	OUTPUT
47	IF (LTHIST) WRITE (NT,48) USEC,((PSF(I,J),I=1,7),J=J1,J2)	OUTPUT
48	FORMAT(F9.3,2(F9.3,3F9.2,3F8.3) )	OUTPUT
C		OUTPUT
C	PRINT BELT FORCES	OUTPUT
C		OUTPUT
49	MBSF = 0	OUTPUT
	IF (NBLT.EQ.0) GO TO 67	OUTPUT
	IF (NPRT(18).EQ.2.OR.NPRT(18).GE.13) GO TO 67	VARTTH
	IF (NPRT(18).GE.7.AND.NPRT(18).LE.9) GO TO 67	VARTTH
	DO 50 J=1,NBLT	OUTPUT
50	MBSF = MBSF + MNBLT(J)	OUTPUT
	IF (MBSF.EQ.0) GO TO 67	OUTPUT
	DO 52 J1=1,MBSF,2	OUTPUT
	J2 = MINO(J1+1,MBSF)	OUTPUT
	NT = NT+1	OUTPUT
C	LOGICAL UNIT (PRINTER CONTROL) FOR P & E	PECONV
	CALL CARCON(NT,1)	PECONV
	IF (.NOT.LTAPES) GO TO 52	OUTPUT
	KK = 0	OUTPUT
	DO 51 J=J1,J2	OUTPUT
	DO 51 I=1,4	OUTPUT
	KK = KK+1	OUTPUT
51	TDATA(KK,NT-20) = BSF(I,J)	OUTPUT
52	IF (LTHIST) WRITE (NT,53) USEC,((BSF(I,J),I=1,4),J=J1,J2)	OUTPUT
53	FORMAT(F9.3,4(F15.6,F12.2,3X) )	OUTPUT
C		OUTPUT
C	PRINT HARNESS-BELT ENDPOINT FORCES (STORED IN BSF ARRAY).	OUTPUT
C		OUTPUT
67	IF (NHRNSS.LE.0) GO TO 71	OUTPUT

	IF (NPRT(18).EQ.3.OR.NPRT(18).EQ.11) GO TO 71	VARTTH
	IF (NPRT(18).EQ.9.OR.NPRT(18).EQ.8) GO TO 71	VARTTH
	IF (NPRT(18).EQ.13.OR.NPRT(18).EQ.14) GO TO 71	VARTTH
	IF (NPRT(18).GE.16) GO TO 71	VARTTH
	MBSF1 = MBSF + 1	OUTPUT
	DO 68 I=1,NHRNSS	OUTPUT
68	MBSF = MBSF + NBLTPH(I)	OUTPUT
	DO 70 J1=MBSF1,MBSF,2	OUTPUT
	J2 = MINO(J1+1,MBSF)	OUTPUT
	NT = NT+1	OUTPUT
C	LOGICAL UNIT (PRINTER CONTROL) FOR P & E	PECONV
	CALL CARCON(NT,1)	PECONV
	IF (.NOT.LTAPE8) GO TO 70	OUTPUT
	KK = 0	OUTPUT
	DO 69 J=J1,J2	OUTPUT
	DO 69 I=1,4	OUTPUT
	KK = KK+1	OUTPUT
69	TDATA(KK,NT-20) = BSF(I,J)	OUTPUT
70	IF (LTHIST) WRITE (NT,53) USEC,((BSF(I,J),I=1,4),J=J1,J2)	OUTPUT
C		OUTPUT
C	PRINT SPRING DAMPER FORCES (STORED IN BSF ARRAY).	OUTPUT
C		OUTPUT
71	IF (NSD.LE.0) GO TO 54	OUTPUT
	IF (NPRT(18).EQ.4.OR.NPRT(18).EQ.9) GO TO 54	VARTTH
	IF (NPRT(18).GE.12) GO TO 54	VARTTH
	MBSF1 = MBSF + 1	OUTPUT
	MBSF = MBSF + (NSD+1)/2	OUTPUT
	DO 73 J1=MBSF1,MBSF,2	OUTPUT
	J2 = MINO(J1+1,MBSF)	OUTPUT
	NT = NT+1	OUTPUT
C	LOGICAL UNIT (PRINTER CONTROL) FOR P & E	PECONV
	CALL CARCON(NT,1)	PECONV
	IF (.NOT.LTAPE8) GO TO 73	OUTPUT
	KK = 0	OUTPUT
	DO 72 J=J1,J2	OUTPUT
	DO 72 I=1,4	OUTPUT
	KK = KK+1	OUTPUT
72	TDATA(KK,NT-20) = BSF(I,J)	OUTPUT
73	IF (LTHIST) WRITE (NT,74) USEC,((BSF(I,J),I=1,4),J=J1,J2)	OUTPUT
74	FORMAT (F9.3,4(F14.3,F12.2,4X))	OUTPUT
C		OUTPUT
C	PRINT SEGMENT CONTACT FORCES	OUTPUT
C		OUTPUT
54	MSSF = 0	OUTPUT
	IF (NPRT(18).EQ.5.OR.NPRT(18).EQ.13) GO TO 161	VARTTH
	IF (NPRT(18).EQ.10.OR.NPRT(18).EQ.11) GO TO 161	VARTTH
	IF (NPRT(18).GE.15) GO TO 161	VARTTH
	DO 55 J=1,NSEG	OUTPUT
55	MSSF = MSSF + MNSEG(J)	OUTPUT
	IF (MSSF.EQ.0) GO TO 59	OUTPUT

DO 57 J=1,MSSF	OUTPUT
NT = NT+1	OUTPUT
C LOGICAL UNIT (PRINTER CONTROL) FOR P & E	PECONV
CALL CARCON(NT,1)	PECONV
IF (.NOT.LTAPE8) GO TO 57	OUTPUT
DO 58 I=1,10	OUTPUT
56 TDATA(I,NT-20) = SSF(I,J)	OUTPUT
57 IF (LTHIST) WRITE (NT,58) USEC,(SSF(I,J),I=1,10)	OUTPUT
58 FORMAT(2F9.3,3F9.2,3F8.3,2X,3F8.3)	OUTPUT
161 CONTINUE	VARTTH
C	OUTPUT
C PRINT AIRBAG FORCES	OUTPUT
C	OUTPUT
59 IF (NBAG.EQ.0) GO TO 65	OUTPUT
IF (NPRT(18).EQ.6.OR.NPRT(18).EQ.9) GO TO 65	VARTTH
IF (NPRT(18).GE.12) GO TO 65	VARTTH
K1 = 1	OUTPUT
DO 64 J=1,NBAG	OUTPUT
IF (MNBAG(J).EQ.0) GO TO 64	OUTPUT
KBAG = MNBAG(J)+NPANEL(J)+5	OUTPUT
DO 63 J1=1,KBAG,4	OUTPUT
J2 = MIN0(J1+3,KBAG)	OUTPUT
K2 = K1+J2-J1	OUTPUT
NT = NT+1	OUTPUT
C LOGICAL UNIT (PRINTER CONTROL) FOR P & E	PECONV
CALL CARCON(NT,1)	PECONV
IF (.NOT.LTAPE8) GO TO 61	OUTPUT
KK = 0	OUTPUT
DO 60 K=K1,K2	OUTPUT
DO 60 I=1,3	OUTPUT
KK = KK+1	OUTPUT
60 TDATA(KK,NT-20) = BAGSF(I,K)	OUTPUT
61 IF (.NOT.LTHIST) GO TO 63	OUTPUT
IF (J1.EQ.1) WRITE (NT,75) USEC,((BAGSF(I,K),I=1,3),K=K1,K2)	OUTPUT
IF (J1.NE.1) WRITE (NT,62) USEC,((BAGSF(I,K),I=1,3),K=K1,K2)	OUTPUT
75 FORMAT (F9.3,3X,3F9.2,2(3X,3F9.3),3X,3F9.2)	OUTPUT
62 FORMAT(F9.3,4(3X,3F9.2))	OUTPUT
63 K1 = K2+1	OUTPUT
64 CONTINUE	OUTPUT
65 NT = NT-20	OUTPUT
IF(NT.GT.NTMAX) STOP 56	CHGIII
IF (LTAPE8) WRITE (8) NT,USEC,((TDATA(I,J),I=1,14),J=1,NT)	OUTPUT
PREVT = TIME	OUTPUT
CALL ELTIME(2,8)	OUTPUT
66 RETURN	OUTPUT
END	OUTPUT

C	SUBROUTINE PANEL (DRR,ZR,JB)	PANEL
C		REV III.2 08/08/84REVIII
C	COMPUTES AIRBAG PARAMETERS DURING INFLATION OF BAG.	PANEL
C		PANEL
C	GIVEN: DRR - DC MATRIX RELATIVE TO VEHICLE	PANEL
C	ZR - CG LOCATION IN VEHICLE REFERENCE	PANEL
C		PANEL
C	COMPUTE: SEGLP,SEGLV,SEGLA,D,WMEG & WMEGD FOR SEGMENT JB.	PANEL
		PANEL
	IMPLICIT REAL*8 (A-H,O-Z)	PANEL
	DIMENSION DRR(3,3),ZR(3),T1(3),T2(3)	PANEL
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	PANEL
	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	PANEL
	*          SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	PANEL
	CALL MAT33 (DRR,D(1,1,NVEH),D(1,1,JB))	PANEL
	CALL MAT31 (DRR,WMEG(1,NVEH),WMEG(1,JB))	PANEL
	CALL DOT31 (D(1,1,NVEH),ZR,SEGLP(1,JB))	PANEL
	CALL CROSS (WMEG(1,NVEH),ZR,T1)	PANEL
	CALL DOT31 (D(1,1,NVEH),T1,SEGLV(1,JB))	PANEL
	CALL CROSS (WMEG(1,NVEH),T1,T2)	PANEL
	CALL DOT31 (D(1,1,NVEH),T2,SEGLA(1,JB))	PANEL
	DO 10 I=1,3	PANEL
	SEGLP(I,JB) = SEGLP(I,JB) + SEGLP(I,NVEH)	PANEL
	SEGLV(I,JB) = SEGLV(I,JB) + SEGLV(I,NVEH)	PANEL
	SEGLA(I,JB) = SEGLA(I,JB) + SEGLA(I,NVEH)	PANEL
10	WMEGD(I,JB) = WMEGD(I,NVEH)	PANEL
	RETURN	PANEL
	END	PANEL

	SUBROUTINE PDAUX (VAR,DER,NEQ,KDINT)	PDAUX
	REV IV 07/24/86SLIP	
PURPOSE IS TO ACT AS INTERFACE BETWEEN INTEGRATOR AND DAUX TO		PDAUX
ACCOMODATE VARIABLE NUMBER OF FUNCTIONS TO BE INTEGRATED.		PDAUX
ARGUMENTS:		PDAUX
VAR - ARRAY OF NEQ STATE VARIABLES UPDATED BY DINT.		PDAUX
DER - ARRAY OF NEQ DERIVATIVES TO BE SUPPLIED BY DAUX.		PDAUX
NEQ - NUMBER OF STATE VARIABLES AND DERIVATIVES.		PDAUX
KDINT - INTEGRATION STEP NUMBER IN DINT.		PDAUX
IMPLICIT REAL*8 (A-H,O-Z)		PDAUX
DIMENSION VAR(3,1),DER(3,1)		PDAUX
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		PDAUX
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		PDAUX
* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		PDAUX
COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		PDAUX
* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		PDAUX
COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),		PDAUX
* BLTTTL(5,8),PLTTTL(5,30),BAGTTL(5,6),SEG(30),		PDAUX
* JOINT(30),CGS(30),JS(30)		PDAUX
REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTTL,BAGTTL,SEG,JOINT		PDAUX
LOGICAL*1 CGS,JS		PDAUX
COMMON/INTEST/ SGTEST(3,4,30),XTEST(3,120),SEGT(120),REGT(120)		PDAUX
REAL SEGT		PDAUX
COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)		PDAUX
COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),		SLIP
* FE(3,30),TQE(3,30),CONST(5,30)		SLIP
COMMON/TEMPVS/ T(3,30),VXT(3)		PDAUX
DIMENSION SD(3,3,30),E1(30),NTST(30),LSEG(30),RGTTTL(4)		PDAUX
LOGICAL LSEG		PDAUX
DATA NTST/30*0/		PDAUX
DATA RGTTTL/8HANG VEL,8HLIN VEL,8HANG ACC,8HLIN ACC /		PDAUX
CALL ELTIME(1,6)		PDAUX
MBAG = NGRND		PDAUX
IF (NTST(1).NE.0) GO TO 10		PDAUX
LSEG(1) = .FALSE.		VAXCHG
NTST(1) = 1		ATBIII
DO 5 M=2,MBAG		ATBIII
LSEG(M) = ISING(M).GE.0 .AND. JNT(M-1).NE.0		ATBIII
IF (IABS(IPIN(M-1)).GE.5.AND.IEULER(M-1).GE.0) LSEG(M)=.FALSE.		SLIP
5 NTST(M) = M		PDAUX
NTST(NGRND) = -NGRND		PDAUX
LSEG(NGRND) = .TRUE.		PDAUX
IF (NFLX.EQ.0) GO TO 10		PDAUX
DO 6 J=1,NFLX		PDAUX
M = NFLEX(2,J)		PDAUX
6 NTST(M) = -M		PDAUX

10	IF (KDINT.EQ.4) GO TO 48	PDAUX
	IF (KDINT.GT.0) GO TO 20	PDAUX
C		PDAUX
C	KDINT=0 IMPLIES INITIAL CALL FROM DINT. PDAUX TO SUPPLY INITIAL	PDAUX
C	VALUES TO STATE VARIABLES AND COMPUTE VALUE OF NEQ.	PDAUX
C		PDAUX
C	(A) SET Q TO IDENTITY QUATERNION	PDAUX
C		PDAUX
	N = 0	PDAUX
	DO 12 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 12	PDAUX
	N = N+1	PDAUX
	REGT(N) = RGTTL(1)	PDAUX
	SEGT(N) = SEG(M)	PDAUX
	E1(N) = 1.0	PDAUX
	DO 11 I=1,3	PDAUX
	XTEST(I,N) = SGTEST(I,1,M)**2	PDAUX
11	VAR(I,N) = 0.0	PDAUX
12	CONTINUE	PDAUX
C		PDAUX
C	(B) SEGLP OF REFERENCE SEGMENTS	PDAUX
C		PDAUX
	DO 14 M=1,MBAG	PDAUX
	IF (LSEG(M)) GO TO 14	PDAUX
	N = N+1	PDAUX
	REGT(N) = RGTTL(2)	PDAUX
	SEGT(N) = SEG(M)	PDAUX
	DO 13 I=1,3	PDAUX
	XTEST(I,N) = SGTEST(I,2,M)**2	PDAUX
13	VAR(I,N) = SEGLP(I,M)	PDAUX
14	CONTINUE	PDAUX
C		PDAUX
C	(C) WMEG	PDAUX
C		PDAUX
	DO 16 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 16	PDAUX
	N = N+1	PDAUX
	REGT(N) = RGTTL(3)	PDAUX
	SEGT(N) = SEG(M)	PDAUX
	DO 15 I=1,3	PDAUX
	XTEST(I,N) = SGTEST(I,3,M)**2	PDAUX
15	VAR(I,N) = WMEG(I,M)	PDAUX
16	CONTINUE	PDAUX
C		PDAUX
C	(D) SEGLV OF REFERENCE SEGMENTS	PDAUX
C		PDAUX
	DO 18 M=1,MBAG	PDAUX
	IF (LSEG(M)) GO TO 18	PDAUX
	N = N+1	PDAUX

	REGT(N) = RGTTL(4)	PDAUX
	SEGT(N) = SEG(M)	PDAUX
	DO 17 I=1,3	PDAUX
	XTEST(I,N) = SGTEST(I,4,M)**2	PDAUX
17	VAR(I,N) = SEGLV(I,M)	PDAUX
18	CONTINUE	PDAUX
	NEQ = 3*N	PDAUX
	GO TO 40	PDAUX
20	IF (KDINT.NE.1) GO TO 30	PDAUX
C		PDAUX
C	KDINT = 1, 1ST STEP IN ADVANCING INTEGRATING INTERVAL,	PDAUX
C	SAVE DC MATRICES IF TIME HAS ADVANCED.	PDAUX
C		PDAUX
	N = 0	PDAUX
	DO 22 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 22	PDAUX
	N = N+1	PDAUX
	DO 21 J=1,3	PDAUX
	DO 21 I=1,3	PDAUX
21	SD(I,J,N) = D(I,J,M)	PDAUX
22	CONTINUE	PDAUX
C		PDAUX
C	KDINT > 0,1 - FETCH SAVED DC MATRICES AND UPDATE BY CURRENT THETA.	PDAUX
C		PDAUX
C	(A) UPDATE D BY Q	PDAUX
C		PDAUX
30	N = 0	PDAUX
	DO 32 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 32	PDAUX
	N = N+1	PDAUX
	EDOTE = VAR(1,N)**2 + VAR(2,N)**2 + VAR(3,N)**2	PDAUX
	IF (EDOTE.GE.1.0) KDINT = -KDINT	PDAUX
	IF (KDINT.LE.0) GO TO 99	PDAUX
	E1(N) = DSQRT(1.0-EDOTE)	PDAUX
	CALL DSETQ(SD(1,1,N),VAR(1,N),EDOTE,E1(N),D(1,1,M))	PDAUX
32	CONTINUE	PDAUX
C		PDAUX
C	KDINT > 0 - STORE STATE VARIABLES INTO PROGRAM ARRAYS.	PDAUX
C		PDAUX
C	(B) SEGLP OF REFERENCE SEGMENTS	PDAUX
C		PDAUX
	DO 35 M=1,MBAG	PDAUX
	IF (LSEG(M)) GO TO 35	PDAUX
	N = N+1	PDAUX
	DO 34 I=1,3	PDAUX
34	SEGLP(I,M) = VAR(I,N)	PDAUX
35	CONTINUE	PDAUX
C		PDAUX
C	(C) WMEG	PDAUX
C		PDAUX

	DO 31 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 31	PDAUX
	N = N+1	PDAUX
	DO 36 I=1,3	PDAUX
	36 WMEG(I,M) = VAR(I,N)	PDAUX
	31 CONTINUE	PDAUX
C		PDAUX
C	(D) SEGLV OF REFERENCE SEGMENTS	PDAUX
C		PDAUX
	DO 38 M=1,MBAG	PDAUX
	IF (LSEG(M)) GO TO 38	PDAUX
	N = N+1	PDAUX
	DO 37 I=1,3	PDAUX
	37 SEGLV(I,M) = VAR(I,N)	PDAUX
	38 CONTINUE	PDAUX
C		PDAUX
C	CALL DAUX ROUTINE TO COMPUTE DERIVATIVES	PDAUX
C		PDAUX
	40 CALL DAUX(0)	PDAUX
C		PDAUX
C	STORE DERIVATIVES FOR INTEGRATING SUBROUTINE.	PDAUX
C		PDAUX
C	(A) DERIVATIVE OF Q	PDAUX
C		PDAUX
	N = 0	PDAUX
	DO 39 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 39	PDAUX
	N = N+1	PDAUX
	CALL CROSS(VAR(1,N),WMEG(1,M),VXT)	PDAUX
	DO 41 I=1,3	PDAUX
	41 DER(I,N) = 0.5*(E1(N)*WMEG(I,M) + VXT(I) )	PDAUX
	39 CONTINUE	PDAUX
	NQUAT = N	PDAUX
C		PDAUX
C	(B) SEGLV OF REFERENCE SEGMENTS	PDAUX
C		PDAUX
	DO 43 M=1,MBAG	PDAUX
	IF (LSEG(M)) GO TO 43	PDAUX
	N = N+1	PDAUX
	DO 42 I=1,3	PDAUX
	42 DER(I,N) = SEGLV(I,M)	PDAUX
	43 CONTINUE	PDAUX
C		PDAUX
C	(C) WMEGD	PDAUX
C		PDAUX
	DO 47 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 47	PDAUX
	N = N+1	PDAUX
	DO 44 I=1,3	PDAUX
	44 DER(I,N) = WMEGD(I,M)	PDAUX



C  
C  
C

[illegible]

51

SUBROUTINE PLEDG(AREAL,BD,PL)		PLEDGD
C	IMPLICIT REAL*8(A-H,O-Z)	HYFIX
	LOGICAL AREAL	PLEDGD
	DIMENSION BD(24),PL(24)	HYFIX
	DIMENSION HAREA(2,2,5),ZC(3,14),X(3),UV(3,2),IV(14)	HYFIX
C	SHARED WITH PLELP-PLSEGF	HYFIX
	COMMON/TEMPVS/DMNT(3,3),DHNT(3,3),DUM1(18),TM(3),R(3),RM(3),	HYFIX
X	DUM2(9),UP(3),VP(3),U(3),V(3),EU(3),EV(3),ET(3),	HYFIX
X	A(2),B(2),CC(2),DUM4(12),TH(3),XH(3),RMD(3),RND(3),	HYFIX
X	APT(2,2,2),AC(2,2),BC(2,2),AFP,E(2,2),DELT,AREA,	HYFIX
X	AB,BB,BT(2),XNC(3),UH(3),P,AMR,FM,T4(3),ALIM(2,2)	HYFIX
	EQUIVALENCE (UV(1,1),U(1))	HYFIX
	EQUIVALENCE (ALIM(1,1),BMIN), (ALIM(1,2),AMIN)	HYFIX
	EQUIVALENCE (ALIM(2,1),BMAX), (ALIM(2,2),AMAX)	HYFIX
	EQUIVALENCE (AC(1,1),BB1), (AC(1,2),AA1)	HYFIX
	EQUIVALENCE (AC(2,1),BB2), (AC(2,2),AA2)	HYFIX
	EQUIVALENCE (BC(1,1),AB1), (BC(1,2),BA1)	HYFIX
	EQUIVALENCE (BC(2,1),AB2), (BC(2,2),BA2)	HYFIX
C	AREA = 0.0	PLEDGD
	AREAL = .FALSE.	PLEDGD
	CALCULATE CENTER OF ELLIPSE IN PLANE	PLEDGD
C	T4 IS VECTOR FROM CENTER OF ELLIPSOID TO CENTER OF ELLIPSE	PLEDGD
	DO 10 I = 1,3	PLEDGD
	T4(I) = FM*XH(I)	HYFIX
	10 XNC(I) = XNC(I) + T4(I)	PLEDGD
C	XNC P1 TO CENTER OF ELLIPSE	PLEDGD
C	PUT PLANE VECTORS IN ELLIPSE SYSTEM TH IS PLANE VECTOR	PLEDGD
	IF (BD(1).LT.0.0) CALL MAT33(BD(8),DMNT,DHNT)	HYPER
	IF (BD(1).LT.0.0) GO TO 20	HYPER
	DO 15 I = 1,3	HYPER
	DO 15 J = 1,3	HYPER
	15 DHNT(I,J) = DMNT(I,J)	HYPER
	20 CALL MAT31(DHNT,PL( 8),UP)	HYPER
	CALL MAT31(DHNT,PL(13),VP)	HYPER
	CALL MAT31(DHNT,PL(18), U)	HYPER
	CALL MAT31(DHNT,PL(21), V)	HYPER
C	U IS P2 - P1, V IS P3 - P1, PLANE VECTOR IS TM	PLEDGD
	CALCULATE CENTER FROM P1 IN U, V COORDINATES	PLEDGD
	B(1) = (UP(1)*XNC(1) + UP(2)*XNC(2) + UP(3)*XNC(3))/PL(12)	PLEDGD
	B(2) = (VP(1)*XNC(1) + VP(2)*XNC(2) + VP(3)*XNC(3))/PL(17)	PLEDGD
	AMIN = -B(1)	HYFIX
	AMAX = 1.0 - B(1)	HYFIX
	BMIN = -B(2)	HYFIX
	BMAX = 1.0 - B(2)	HYFIX
C	GET ELLIPSE EQUATION	PLEDGD
	DO 25 I = 1,2	HYPER
	DO 25 J = 1,2	HYPER
	25 E(I,J) = 0.0	HYPER

IF (BD(1).GT.0.0) GO TO 35	HYPER
C TREAT HYPER AS ELLIPSE FOR FIRST GUESS	HYPER
DO 30 I = 1,3	HYPER
EU(I) = U(I)*BD(I+16)	HYPER
30 EV(I) = V(I)*BD(I+16)	HYPER
C GET INTERSECTION OF PLANE WITH BOX	HYFIX
CALL HYBOX(BD(2),TH,T4,MB,ZC,IV)	HYPER
IF (MB.LT.6) GO TO 140	HYPER
GO TO 40	HYPER
35 CALL MAT31(BD(7),U,EU)	HYPER
CALL MAT31(BD(7),V,EV)	HYPER
40 DO 45 K = 1,3	HYPER
E(1,1) = E(1,1) + U(K)*EU(K)	HYPER
E(1,2) = E(1,2) + V(K)*EU(K)	HYPER
45 E(2,2) = E(2,2) + V(K)*EV(K)	HYPER
DELT = E(1,1)*E(2,2) - E(1,2)**2	PLEDGE
C WHAT ABOUT AMR FOR HYPER?? 1 - FM**P ?	HYFIX
R2D = AMR/DELT	HYFIX
COMPUTE BOUNDS OF ELLIPSOID LOCATION OF MAX AND MIN ALPHA	HYFIX
AA2 = DSQRT(E(2,2)*R2D)	HYFIX
AA1 = -AA2	HYFIX
C BA IS VALUE OF BETA AT AT ALPHA MAX	HYFIX
BA1 = E(1,2)*AA2/E(2,2)	HYFIX
BA2 = -BA1	HYFIX
IF (BD(1).GE.-2.0) GO TO 50	HYPER
CALL HYBND(MB,ZC,IV,UP,-1.,X)	HYPER
CALL HYLIM(AA1,U,BA1,V,FM,XH,X,BD)	HYFIX
50 AMIN = DMAX1(AA1,AMIN)	HYFIX
IF (AMIN.GE.AMAX) GO TO 140	HYFIX
IF (BD(1).GE.-2.0) GO TO 55	HYPER
CALL HYBND(MB,ZC,IV,UP,1.,X)	HYPER
CALL HYLIM(AA2,U,BA2,V,FM,XH,X,BD)	HYFIX
55 AMAX = DMIN1(AA2,AMAX)	HYFIX
IF (AMIN.GE.AMAX) GO TO 140	HYPER
COMPUTE BOUNDS OF ELLIPSOID LOCATION OF MAX AND MIN BETA	HYFIX
BB2 = DSQRT(E(1,1)*R2D)	HYFIX
BB1 = -BB2	HYFIX
C AB IS VALUE OF ALPHA AT AT BETA MAX	HYFIX
AB1 = E(1,2)*BB2/E(1,1)	HYFIX
AB2 = -AB1	HYFIX
IF (BD(1).GE.-2.0) GO TO 60	HYPER
CALL HYBND(MB,ZC,IV,VP,-1.,X)	HYPER
CALL HYLIM(BB1,V,AB1,U,FM,XH,X,BD)	HYFIX
60 BMIN = DMAX1(BB1,BMIN)	HYFIX
IF (BMIN.GE.BMAX) GO TO 140	HYFIX
IF (BD(1).GE.-2.0) GO TO 65	HYPER
CALL HYBND(MB,ZC,IV,VP,1.,X)	HYPER
CALL HYLIM(BB2,V,AB2,U,FM,XH,X,BD)	HYFIX
65 BMAX = DMIN1(BB2,BMAX)	HYFIX
IF (BMIN.GE.BMAX) GO TO 140	HYPER



HAREA(1,1,L+1) = APT(1,1,1)	HYFIX
HAREA(2,1,L+1) = BMIN	HYFIX
HAREA(1,2,L+1) = APT(2,1,1)	HYFIX
HAREA(2,2,L+1) = BMIN	HYFIX
IF (APT(2,1,1).GE.APT(1,1,1)) L = L + 1	HYFIX
HAREA(1,1,L+1) = AMAX	HYFIX
HAREA(2,1,L+1) = APT(1,2,2)	HYFIX
HAREA(1,2,L+1) = AMAX	HYFIX
HAREA(2,2,L+1) = APT(2,2,2)	HYFIX
IF (APT(2,2,2).GE.APT(1,2,2)) L = L + 1	HYFIX
HAREA(1,1,L+1) = APT(2,2,1)	HYFIX
HAREA(2,1,L+1) = BMAX	HYFIX
HAREA(1,2,L+1) = APT(1,2,1)	HYFIX
HAREA(2,2,L+1) = BMAX	HYFIX
IF (APT(2,2,1).GE.APT(1,2,1)) L = L + 1	HYFIX
IF (L.LE.1) GO TO 140	HYFIX
HAREA(1,1,L+1) = HAREA(1,1,1)	HYFIX
HAREA(2,1,L+1) = HAREA(2,1,1)	HYFIX
IF (BD(1).GE.-2) CALL PLREA(L,HAREA,AREA,AB,BB,E,DELT,AMR)	HYFIX
IF (BD(1).LT.-2) CALL HYREA(L,HAREA,AREA,AB,BB)	HYFIX
AREAL = AREA.GT.0.0	HYFIX
IF (.NOT.AREAL) GO TO 140	HYPER
C	HYPER
DO 120 I = 1,3	HYPER
RM(I) = AB*U(I) + BB*V(I) + T4(I)	HYPER
120 RMD(I) = RM(I)	HYPER
COMPUTE POINT ON ELLIPSOID BELOW CENTROID	(CONTACT POINT?)
CONVERT PLANE VECTOR, ET = E*TM	PLEDGE
C TRY TO USE OTHER LOGIC	HYFIX
IF(BD(1).LT.0.0)GO TO 130	HYPER
CALL MAT31(BD(7),TM,ET)	PLEDGE
A2 = TM(1)*ET(1) + TM(2)*ET(2) + TM(3)*ET(3)	PLEDGE
A1 = AB*(TM(1)*EU(1)+TM(2)*EU(2)+TM(3)*EU(3))	HYFIX
1+FM+ BB*(TM(1)*EV(1)+TM(2)*EV(2)+TM(3)*EV(3))	HYFIX
A1 = A1/A2	HYFIX
A0 = (AB**2*E(1,1) + 2.*AB*BB*E(1,2) + BB**2*E(2,2) - AMR)/A2	HYFIX
DISC = A1**2 - A0	PLEDGE
IF(DISC.LT.0.0)DISC = 0.0	PLEDGE
P = A1 + DSQRT(DISC)	PLEDGE
GO TO 140	HYPER
COMPUTE FOR HYPER	HYPER
130 CALL HYVAL(CA,TH,RM,BD,1)	HYFIX
P = -CA	HYFIX
CALL DOT31(BD(8),RMD,RM)	HYPER
140 RETURN	HYPER
END	PLEDGE

	SUBROUTINE PLELP(M,MM,N,NN,NT)	PLELP
C		REV IV 02/07/87HYPER
	IMPLICIT REAL*8(A-H,O-Z)	PLELP
	LOGICAL AREAL	EDGE
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	PLELP
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	PLELP
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	PLELP
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),	NCFORC
	* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF	PLELP
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)	EDGE
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),	PLELP
	* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),	PLELP
	* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),	PLELP
	* KQ1(12),KQ2(12),KQTYPE(12)	PLELP
	COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),	TGMOD7
	* NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)	TGMOD7
	COMMON/TEMPVS/DMNT(3,3),TEMP(3,3),B(3,3),XMN(3),RLN(3),XMM(3),	PLELP
	* TM(3),R(3),RM(3),DMNWN(3),RLM(3),RN(3),VMN(3),VR(3),	PLELP
	* WNM(3),WCM(3),WCN(3),VREL(3),FFM(3),FR(3),TQM(3),	PLELP
	* TQN(3),TQNT(3),T(3),H(3),TH(3),XH(3),RMD(3),RND(3),	EDGE
	* TD(3),TT4(3,4),TT5(3,4),XNC(3),UH(3),P,AMR,FM,CF,	EDGE
	* VRM,VRT,VRTS,VRTEST,TF,ELOSS,MCF,NCF	TGMOD7
	CALL ELTIME(1,21)	PLELP
	CALL DOT33(D(1,1,M),D(1,1,N),DMNT)	PLELP
	DO 10 I = 1,3	PLELP
	10 XMN(I) = SEGLP(I,M) - SEGLP(I,N)	PLELP
	CALL MAT31(D(1,1,M),XMN,XMM)	PLELP
	CALL MAT31(DMNT,PL(1,NN),TM)	PLELP
	CALL MAT31(DMNT,PL(5,NN),TD)	EDGE
	BET = 0.0	EDGE
	J = 3	HYPER
	IF(BD(1,MM).LT.0.0) J = 4	HYPER
	DO 15 I=1,3	EDGE
	J = J + 1	HYPER
	XNC(I) = XMM(I) + BD(J,MM) - TD(I)	HYPER
	15 BET = BET - TM(I)*XNC(I)	EDGE
C		EDGE
C	BET IS FROM CENTER OF FIGURE TO PLANE	EDGE
	IF(BD(1,MM).GT.0.0)GO TO 30	HYPER
C	PUT PLANE VECTOR INTO HYPER	HYPER
	CALL MAT31(BD(8,MM),TM,TH)	HYPER
	CALL MAT31(BD(8,MM),XNC,UH)	HYPER
	DO 20 I = 1,3	HYPER
	XNC(I) = UH(I)	HYPER
	UH(I) = DABS(TH(I))*BD(I+1,MM)/BD(I+19,MM)	HYPER
	R(I) = BD(I+19,MM)/(BD(I+19,MM) - 1.0)	HYPER
	20 RND(I)= UH(I)**R(I)	HYPER
	ALP = HYPEN(BD(1,MM),R,RND)	HYPER
	DO 25 I = 1,3	HYPER
	POW = 1.0/(BD(I+19,MM) - 1.0)	HYPER

	XH(I) = -DSIGN(BD(I+1,MM)*(UH(I)*ALP)**POW,TH(I))	HYPER
25	RND(I) = XH(I)	HYPER
	BTE = TH(1)*XH(1) + TH(2)*XH(2) + TH(3)*XH(3)	HYPER
	FM = BET/BTE	HYPER
	AMR = 1.0 - DABS(FM)**(-BD(1,MM))	HYPER
	GO TO 35	HYPER
C	CODE FOR ELLIPSE XH = E'T	EDGE
C		EDGE
30	CALL MAT31(BD(16,MM),TM,XH)	HYPER
	BTS = TM(1)*XH(1) + TM(2)*XH(2) + TM(3)*XH(3)	EDGE
	BTE = - DSQRT(BTS)	PLELP
	FM = BET/BTS	EDGE
	AMR = 1.0 -BET*FM	EDGE
C		EDGE
35	P = BET - BTE	HYPER
	PSF(1,NPSF) = P	PLELP
	MCF = NTAB(NT+1)	PLELP
	NCF = -MCF	PLELP
	IF(NCF.GT.0)CFQQ(NCF) = -999.	PLELP
	IF(P.LE.0.0) GO TO 85	HYPER
C		EDGE
C	CALL EDGE ROUTINE TO FIND IF ELLIPSOID INTERSECTS FINITE PLANE	EDGE
C	IF IT DOES; AREAL WILL BE TRUE, P WILL BE PENETRATION AT CENTROID	EDGE
C	AND RM WILL BE LOCATION OF CENTROID	EDGE
C	RM IS REFERENCED TO CENTER OF ELLIPSOID	EDGE
C	USE OLD FORMULA FOR ROLL-SLIDE?, I.E. ROLL-SLIDE SHOULDN'T	EDGE
C	CALL PLEDG	EDGE
C		EDGE
	LT = NTAB(NT)	EDGE
	IF(TAB(LT+22).LE.0.0)GO TO 40	HYPER
C		EDGE
	IF (AMR.LE.0.0) GO TO 85	HYPER
	IF (BD(1,MM).LT.0.0.AND.BD(23,MM).NE.0.0) STOP 22	HYPER
	CALL PLEDG(AREAL,BD(1,MM),PL(1,NN))	EDGE
	IF(.NOT.AREAL)GO TO 85	HYPER
	PSF(1,NPSF) = P	EDGE
C		EDGE
40	IF (TAB(LT+22).GT.-2.0.AND.AMR.LE.0.0) GO TO 85	HYPER
	RHO = 0.0	HYPER
	IF(MCF.GT.0)RHO = TAB(MCF+4)	PLELP
	BETE = 1.0 + RHO*P/BTE	HYPER
	IF(BD(1,MM).GT.0.0)BETE = BETE/BTE	HYPER
	IF(BD(1,MM).LT.0.0)CALL DOT31(BD(8,MM),RND,XH)	HYPER
	TRT = P*(1.0 - RHO)	EDGE
	J = 3	HYPER
	IF(BD(1,MM).LT.0.0)J = 4	HYPER
	DO 45 I = 1,3	HYPER
	J = J + 1	HYPER
	IF(TAB(LT+22).LE.0.0)RM(I) = BETE*XH(I)	EDGE
	IF(TAB(LT+22).GT.0.0)RM(I) = RM(I) - TRT*TM(I)	EDGE

	RLM(I) = RM(I) + BD(J,MM)	HYPER
45	RN(I) = RLM(I) + XMM(I)	HYPER
	CALL DOT31(DMNT,RN,RLN)	PLELP
	IF (TAB(LT+22).GT.0.0) GO TO 55	HYPER
	IF (TAB(LT+22).GT.-3.0.AND.TAB(LT+22).LT.0.0) GO TO 55	HYPER
C		EDGE
C	CHECK BOUNDARY USING OLD METHOD	EDGE
	DO 50 I = 8,13,5	HYPER
	IF(PL(I+4,NN).LE.0.0)GO TO 50	HYPER
	DIST = RLN(1)*PL(I,NN)	PLELP
	* + RLN(2)*PL(I+1,NN)	PLELP
	* + RLN(3)*PL(I+2,NN) - PL(I+3,NN)	PLELP
	IF((DIST.LE.0.0).OR.(DIST.GT.PL(I+4,NN))) GO TO 85	HYPER
	50 CONTINUE	HYPER
C		EDGE
55	CALL PLSEGF(M,N,NT)	HYPER
C	DMNWN,VMN,VR,WNM,WCM,WCN,VREL,FFM,FR,TQM,TQN,TQNT,T	EDGE
C	FM,CF,VRM,VRT,VRTS,VRTST,TF,ELOSS	EDGE
C		EDGE
C	STORE RESULTS	EDGE
	DO 60 I = 1,3	HYPER
60	PSF(I+4,NPSF) = RLN(I)	HYPER
	IF(LPMI(N).NE.0) CALL DOT31(DPMI(1,1,N),RLN,PSF(5,NPSF))	EDGE
	IF(MCF.LT.0)GO TO 65	HYPER
	PSF(2,NPSF) = FM	PLELP
	PSF(3,NPSF) = 0.0	PLELP
	TRT = TF**2 - FM**2	PLELP
	IF(TRT.GT.0.0) PSF(3,NPSF) = DSQRT(TRT)	PLELP
	PSF(4,NPSF) = TF	PLELP
	GO TO 85	HYPER
C		PLELP
C	ROLL-SLIDE	PLELP
	REVISED	8/18/85
65	DO 70 I = 1,3	HYPER
70	PSF(I+1,NPSF) = T(I)	HYPER
	IF(BD(1,MM).LT.0.0) STOP 28	HYPER
	CALL CROSS(TM,WNM,TH)	EDGE
	CALL MAT31(BD(16,MM),TH,UH)	EDGE
	TRT = (TM(1)*UH(1) + TM(2)*UH(2) + TM(3)*UH(3))/BTS	EDGE
	DO 75 I = 1,3	HYPER
75	RMD(I) = DABS(BETE)*(UH(I) - TRT*XH(I))	HYPER
	CALL CROSS(DMNWN,TM,TH)	EDGE
	CALL CROSS(WNM,RMD,XNC)	EDGE
	SQQ(NCF) = 0.0	PLELP
	DO 80 I = 1,3	HYPER
80	SQQ(NCF) = SQQ(NCF) + TM(I)*XNC(I) - 2.0*TH(I)*VR(I)	HYPER
	CALL DOT31(D(1,1,M),XNC,RQQ(1,NCF))	EDGE
85	CALL ELTIME(2,21)	HYPER
	RETURN	PLELP
	END	PLELP



SUBROUTINE PLREA(L,H,AREA,AB,BB,E,D,R)		HYFIX
C	IMPLICIT REAL*8(A-H,O-Z)	REV IV 12/11/87HYFIX
	COMPUTES AREA AND CENTROID (TRUE AREA = AREA*!UxV:/6)	PLREA
	C !UxV! IS NEVER COMPUTED !UxV! = UxV.T = AREA OF PARALLELOGRAM	HYFIX
	C THIS ROUTINE WILL ONLY BE CALLED IF THERE IS AN INTERSECTION	PLREA
	DIMENSION H(2,2,5),E(2,2)	HYFIX
	AREA = 0.0	PLREA
	AB = 0.0	PLREA
	BB = 0.0	PLREA
	IF (L.LE.1) GO TO 15	HYFIX
	C = R/DSQRT(D)	HYFIX
	C12 = 2.0*R/D	HYFIX
	C11 = C12*E(1,1)	HYFIX
	C22 = C12*E(2,2)	HYFIX
	C12 = C12*E(1,2)	HYFIX
	DO 10 I = 1,L	HYFIX
	CGMUTE FOR STRAIGHT LINE SEGMENTS	HYFIX
	AR = H(1,1,I)*H(2,2,I) - H(1,2,I)*H(2,1,I)	HYFIX
	IF (AR.EQ.0.0) GO TO 5	HYFIX
	AB = AB + AR*(H(1,1,I) + H(1,2,I))	HYFIX
	BB = BB + AR*(H(2,1,I) + H(2,2,I))	HYFIX
	AREA = AREA + AR	HYFIX
	CGMUTE FOR ELLIPSE	HYFIX
	5 AR = H(1,2,I)*H(2,1,I+1) - H(1,1,I+1)*H(2,2,I)	HYFIX
	IF (AR.EQ.0.0) GO TO 10	HYFIX
	ARC = AR/C	HYFIX
	IF (DABS(ARC).GT.1.0) ARC = DSIGN(1.0DO,ARC)	HYFIX
	AR = C*DASIN(ARC)	HYFIX
	X21 = H(1,1,I+1) - H(1,2,I)	HYFIX
	Y21 = H(2,1,I+1) - H(2,2,I)	HYFIX
	AB = AB + C12*X21 + C22*Y21	HYFIX
	BB = BB - C11*X21 - C12*Y21	HYFIX
	AREA = AREA + AR	HYFIX
	10 CONTINUE	HYFIX
	IF (AREA.LE.0.0) GO TO 15	HYFIX
	AREA = 3.0*AREA	HYFIX
	AB = AB/AREA	PLREA
	BB = BB/AREA	PLREA
C	AREA = AREA/6.0	HYFIX
	15 RETURN	PLREA
	END	PLREA

	SUBROUTINE PLSEGF(M,N,NT)	PLSEGF
		REV III.5 09/03/85TGMOD7
C	IMPLICIT REAL*8 (A-H,O-Z)	PLSEGF
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	PLSEGF
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	PLSEGF
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),	PLSEGF
	* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),	PLSEGF
	* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),	PLSEGF
	* KQ1(12),KQ2(12),KQTYPE(12)	PLSEGF
	COMMON/TEMPVI/ CREST,TTI(3),R1I(3),R2I(3),JSTOP(4,2,30)	PLSEGF
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	DIMENB
C	THIS COMMON/TEMPVS/ IS SHARED BY PLELP, PLSEGF AND SEGSEG.	PLSEGF
	COMMON/TEMPVS/DMNT(3,3),TEMP(3,3),B(3,3),XMN(3),RLN(3),XMM(3),	PLSEGF
	* TM(3),R(3),RM(3),DMNWN(3),RLM(3),RN(3),VMN(3),VR(3),	PLSEGF
	* WMN(3),WCM(3),WCN(3),VREL(3),FFM(3),FR(3),TQM(3),	PLSEGF
	* TQN(3),TQNT(3),T(3),H(3),T1(3),T2(3),RMD(3),RND(3),	PLSEGF
	* TD(3),TT4(3,4),TT5(3,4),T3(3),T4(3),P,AMR,FM,CF,	PLSEGF
	* VRM,VRT,VRTS,VRTST,TF,ELOSS,MCF,NCF,T5(3),T6(3)	TGMOD7
	VRTEST = 2.0	PLSEGF
	CALL MAT31(DMNT,WMEG(1,N),DMNWN)	PLSEGF
	DO 15 I=1,3	PLSEGF
	VMN(I) = SEGLV(I,M) - SEGLV(I,N)	PLSEGF
15	WMN(I) = DMNWN(I) - WMEG(I,M)	PLSEGF
	CALL DOT31(D(1,1,M),TM,T)	PLSEGF
	CALL MAT31(D(1,1,M),VMN,VR)	PLSEGF
	CALL CROSS(WMEG(1,M),RLM,WCM)	PLSEGF
	CALL CROSS(DMNWN,RN,WCN)	PLSEGF
	VRM = 0.0	PLSEGF
	DO 16 I=1,3	PLSEGF
	VR(I) = VR(I) + WCM(I) - WCN(I)	PLSEGF
16	VRM = VRM + VR(I)*TM(I)	PLSEGF
	VRT = 0.0	PLSEGF
	DO 17 I=1,3	PLSEGF
	VREL(I) = VR(I) - VRM*TM(I)	PLSEGF
17	VRT = VRT + VREL(I)**2	PLSEGF
	VRT = DSQRT(VRT)	PLSEGF
	CF = EVALFD (P,NTAB(NT+5),1)	PLSEGF
	LT = NTAB(NT)	PLSEGF
	TAB(LT) = P	PLSEGF
	FM = 1.0	PLSEGF
	PDOT = -VRM	PLSEGF
	ELOSS = 0.0	PLSEGF
	IF (MCF.GT.0) CALL FRCDFL(P,PDOT,NT,1,FM,ELOSS)	PLSEGF
	VRTS = VRT	PLSEGF
	IF (VRT.LT.VRTEST) VRT = VRTEST/(2.0-VRT/VRTEST)	PLSEGF
	FF = -DABS(FM)*CF/VRT	PLSEGF
	IF (NCF.GT.0.AND.KQTYPE(NCF).EQ.6) FF=0.0	PLSEGF
	FS = (VRTS-VRT)/VRT	PLSEGF
	IF (NCF.GT.0.AND.KQTYPE(NCF).EQ.6) FS=0.0	PLSEGF
	TF = 0.0	PLSEGF



	SUBROUTINE PLTXYZ(P,C)	PLTXYZ
		REV III.5 05/30/85VEHICL
C	STORES PLOT CHARACTER (C) INTO PLOTYZ, PLOTXZ AND PLOTXY ARRAYS	PLTXYZ
C	IN VEHICLE REFERENCE FOR POINT (P) GIVEN IN INERTIAL REFERENCE.	PLTXYZ
C		PLTXYZ
	IMPLICIT REAL*8 (A-H,O-Z)	PLTXYZ
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	PLTXYZ
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	PLTXYZ
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	PLTXYZ
	COMMON/VPOSTN/ ZPLT(3),SPLT(3),AXV(3,6),VATAB(6,501,6),	VEHICL
	* VTO(6),VDT(6),TIMEV(6),OMEGV(6),NVTAB(6),INDXV(6)	PLTXYZ
	COMMON/TEMPVS/ DUM(101),PLOTYZ(96,55),PLOTXZ(96,55),PLOTXY(96,55)	PLTXYZ
	LOGICAL*1 C,PLOTYZ,PLOTXZ,PLOTXY	PLTXYZ
	DIMENSION P(3),TMP(3),XYZ(3)	PLTXYZ
	DATA NPLTZ/96/ , NPLTX/55/	PLTXYZ
C		PLTXYZ
C	CONVERT P FROM INERTIAL TO VEHICLE REFERENCE BY	PLTXYZ
C	XYZ = DVEH(P-XCOMP)	PLTXYZ
C		PLTXYZ
	DO 10 I=1,3	PLTXYZ
	10 TMP(I) = P(I) - SEGLP(I,NVEH)	PLTXYZ
	CALL MAT31(D(1,1,NVEH),TMP,XYZ)	PLTXYZ
C		PLTXYZ
C	CONVERT XYZ INTO PLOT CORDINATES IX,IY,IZ AND	PLTXYZ
C	IF WITHIN PLOT LIMITS, STORE C IN PLOTYZ, PLOTXZ AND PLOTXY.	PLTXYZ
C		PLTXYZ
	IX = SPLT(1)*XYZ(1) + ZPLT(1) + 0.5	PLTXYZ
	IZ = SPLT(3)*XYZ(3) + ZPLT(3) + 0.5	PLTXYZ
	IF (IZ.LT.1 .OR. IZ.GT.NPLTZ) GO TO 11	PLTXYZ
	IY = SPLT(2)*XYZ(2) + ZPLT(2) + 0.5	PLTXYZ
	IF (IY.GE.1 .AND. IY.LE.NPLTX) PLOTYZ(IZ,IY) = C	PLTXYZ
	IF (IX.GE.1 .AND. IX.LE.NPLTX) PLOTXZ(IZ,IX) = C	PLTXYZ
	11 IY = -SPLT(3)*XYZ(2) + ZPLT(2) + 0.5	PLTXYZ
	IF (IY.LT.1 .OR. IY.GT.NPLTZ) GO TO 99	PLTXYZ
	IF (IX.GE.1 .AND. IX.LE.NPLTX) PLOTXY(IY,IX) = C	PLTXYZ
	99 RETURN	PLTXYZ
	END	PLTXYZ

SUBROUTINE POSTPR(PRDT)

REV IV

02/01/88MISDOT

CONTROLS GENERATION OF PRINTED TABULAR TIME HISTORIES  
AND PLOTS BY THE VALUE OF NPRT(4) AS FOLLOWS:

VALUE OF NPRT(4)	TIME HISTORIES	PLOTS
+4	**	NO
+3	YES	YES
+2	YES	NO
+1	**	YES
0	**	NO
-1	NO	YES
-2	YES	NO
-3	YES	YES

\*\* TIME HISTORIES WERE PRINTED BY SUBROUTINE OUTPUT.

COMMON/CDINT/ JDTPTS(18),ZZ(1000,3)

NOTE: THIS OVERWRITES COMMON /CDINT/.

COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,  
NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG

REAL\*8 TIME

COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),  
PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF

REAL\*8 PSF,BSF,SSF,BAGSF,PRJNT

COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),  
BLTTTL(5,8),PLTTTL(5,30),BAGTTL(5,6),SEG(30),  
JOINT(30),CGS(30),JS(30)

REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTTL,BAGTTL,SEG,JOINT  
LOGICAL\*1 CGS,JS

COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),

UNITL,UNITM,UNITT,GRAVITY(3),TWOPI

REAL\*8 PI,RADIAN,G,THIRD,EPS,UNITL,UNITM,UNITT,GRAVITY

COMMON/JBARTZ/ MWPL( 30),MWBLT( 8),MWSEG( 30),MWBAG( 6),

MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),

NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)

COMMON/DAMPER/ APSDM(3,20),APSDN(3,20),ASD(5,20),MSDM(20),MSDN(20)

REAL\*8 APSDM,APSDN,ASD

COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),

XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),

NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)

REAL\*8 BAR,BB,BBDOT,PLOSS,XLONG,HTIME

COMMON/RSAGE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),

MSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)

REAL\*8 XSG,DPMI,TDATA,UMSEC,PRDT,TEST1,TEST2,VDT1

REAL\*8 VDT2,R30,R26

NOTE: SUBROUTINES POSTPR & HEDING SHARE THIS COMMON/TEMPVS/.

THE FIRST DIMENSION OF XLAB,YLAB,PLB1 AND PLB2 SHOULD BE THE SAME

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C      AS THE VALUE ASSIGNED TO NW60 WHICH IS THE NUMBER OF WORDS THAT      POSTPR
C      IS NECESSARY TO CONTAIN 60 CONSECUTIVE CHARACTERS DEPENDING ON THEPOSTPR
C      COMPUTER SYSTEM THIS PROGRAM IS OPERATING ON. THE VALUE OF NW60      POSTPR
C      SHOULD BE 15 ON IBM 360 AND 370, 10 ON UNIVAC 1108, 6 ON CDC 6600.POSTPR
C      THE LAST TERM IN FORMAT 13 BELOW SHOULD BE 15A4(IBM), 10A6(UNIVAC)POSTPR
C      OR 6A10(CDC). ALSO, THE FIRST DIMENSION OF PLDATA IN SUBROUTINE      POSTPR
C      HEDING SHOULD BE 97(IBM), 77(UNIVAC) OR 61(CDC).                      REDIM2
C
COMMON/TEMPVS/ TDATA(14,65),HEDATA(470),                                POSTPR
*      X0(20),XN(20),XL(20),XS(20),XLAB(15,20),PLB1(15,20),POSTPR
*      Y0(20),YN(20),YL(20),YS(20),YLAB(15,20),PLB2(15,20),POSTPR
*      NYP(20),MX(2,20),MY(2,10,20),NX(20),NY(20),                POSTPR
*      NXLAB(20),NYLAB(20),NPLB1(20),NPLB2(20),                    POSTPR
*      USEC(45),Z(1000,25),ZTTH(14,45,65)                          MISDOT
LOGICAL LTABH,LPLOT                                                    POSTPR
DATA LPP/45/, NZD1/1000/, NZD2/25/                                  PLTINC
DATA NW60/15/                                                         POSTPR
LTABH = .FALSE.                                                       POSTPR
LPLOT = .FALSE.                                                       POSTPR
NPRT4 = IABS(NPRT(4))                                                  POSTPR
LPLOT = NPRT4.EQ.1 .OR. NPRT4.EQ.3                                     POSTPR
LTABH = NPRT4.EQ.2 .OR. NPRT4.EQ.3                                     POSTPR
IF(NPRT(26).EQ.4) LTABH = .FALSE.                                     TGMOD1
IF(NPRT(26).GE.5) GO TO 99                                           TGMOD1
C
C      READ INPUT CARD H.11 TO CONTROL COMPUTATION OF HIC, HSI & CSI.    WINDOP
C
C      READ (5,11) JDTPTS                                             POSTPR
WRITE(6,700) NPG                                                       POSTPR
NPG=NPG+1                                                             PAGE
700 FORMAT(1H1,122X,'PAGE',15/,2X,                                    PAGE
*          'POSTPROCESSOR CONTROL PARAMETERS',/)                     PAGE
WRITE(6,701)                                                           CHGIII
701 FORMAT(13X,'HIC & HSI POINT',7X,'CSI POINT')                     CHGIII
WRITE(6,702) JDTPTS(1),JDTPTS(2)                                       CHGIII
702 FORMAT(5X,'H.11',10X,I2,17X,I2,/)                                  WINDOP
NDPT = 0                                                              POSTPR
IHIC = 0                                                              TGMOD1
I26 = 0                                                              TGMOD1
ITST1 = 0                                                            TGMOD1
ITST2 = 0                                                            TGMOD1
IF(NPRT(26).LT.0) I26 = IABS(NPRT(26))                                TGMOD1
IF(JDTPTS(1).GT.0.OR.JDTPTS(2).GT.0) IHIC = 1                       TGMOD1
IF(NPRT(30).EQ.0.AND.NPRT(26).EQ.3) ITST1 = 1                       TGMOD1
IF(NPRT(30).LT.I26) ITST2 = 1                                         TGMOD1
IF(IHIC.EQ.1.AND.ITST1.EQ.1) WRITE(6,751)                             TGMOD1
IF(IHIC.EQ.1.AND.ITST2.EQ.1) WRITE(6,752) NPRT(30),I26              TGMOD1
751 FORMAT(3X,'WARNING! LOGIC OF INPUT INDICATES USER ANTICIPATES HIC
* , HSI AND CSI TO BE COMPUTED BASED ON DATA FOR EVERY SUCCESSFUL', TGMOD1
*/,10X,'INTEGRATION STEP, YET DATA WAS STORED (WRITTEN TO TAPE8) EVTGMOD1

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*ERY DT.')
752 FORMAT(3X,'WARNING! LOGIC OF INPUT INDICATES USER ANTICIPATES HICTGMOD1
*, HSI AND CSI TO BE COMPUTED BASED ON DATA FOR EVERY ',I2,/,10X,' TGMOD1
*INTEGER MULTIPLE OF DT, YET DATA WAS STORED (WRITTEN TO TAPE8) EVETGMOD1
*BY ',I2,' INTEGER MULTIPLE OF DT.')
IF(JDTPPTS(1).GT.0.AND.NPRT(26).EQ.2.AND.NPRT(30).LT.1) STOP 91
IF(JDTPPTS(2).GT.0.AND.NPRT(26).EQ.2.AND.NPRT(30).LT.1) STOP 92
IF (JDTPPTS(1).NE.0) NDPT = NDPT + 1
IF (JDTPPTS(2).NE.0) NDPT = NDPT + 1
IF (.NOT.LPLOT .AND. .NOT.LTABH .AND. NDPT.EQ.0) GO TO 99
CALL ELTIME (1,36)
IF (.NOT.LPLOT) GO TO 20

C
C READ INDICES OF VARIABLES TO BE PLOTTED AND
C ARGUMENTS TO SUBROUTINE SLPLOT ON CARDS I.
C
C INPUT CARD I.1
C
C READ (5,11) NPLT , (NYP(K),K=1,NPLT)
11 FORMAT (18I4)
IF(NPLT.GT.0.AND.ITST1.EQ.1) WRITE(6,753)
IF(NPLT.GT.0.AND.ITST2.EQ.1) WRITE(6,754) NPRT(30),I26
753 FORMAT(3X,'WARNING! LOGIC OF INPUT INDICATES USER ANTICIPATES PLOTGMOD1
*TS TO BE COMPUTED BASED ON DATA FOR EVERY SUCCESSFUL INTEGRATION STGMOD1
*TEP',/,10X,'YET DATA WAS STORED (WRITTEN TO TAPE8) EVERY DT.') TGMOD1
754 FORMAT(3X,'WARNING! LOGIC OF INPUT INDICATES USER ANTICIPATES PLOTGMOD1
*TS TO BE COMPUTED BASED ON DATA FOR EVERY ',I2,/,10X,'INTEGER MULTTGMOD1
*PLE OF DT, YET DATA WAS STORED (WRITTEN TO TAPE8) EVERY ',I2,
* ' INTEGER MULTIPLE OF DT.')
IF (NPLT.LE.0) LPLOT = .FALSE.
IF (.NOT.LPLOT) GO TO 20
DO 15 K=1,NPLT
NYPLT = NYP(K)

C
C INPUT CARD I.2.K
C
C READ (5,11) MX(1,K), MX(2,K), (MY(1,J,K), MY(2,J,K), J=1,NYPLT)
C
C INPUT CARD I.3.K
C
C READ (5,12) NX(K), XO(K), XN(K), XL(K), XS(K)
12 FORMAT (I4 , 4X , 4F8.0 )
C
C INPUT CARD I.4.K
C
C READ (5,12) NY(K), YO(K), YN(K), YL(K), YS(K)
C
C INPUT CARD I.5.K
C
C READ (5,13) NXLAB(K), (XLAB(I,K),I=1,NW60)

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13	FORMAT (I4 , 4X , 15A4)	POSTPR
C		POSTPR
C	NOTE - ABOVE FORMAT ASSUMES 4 ALPHANUMERIC CHARACTERS FOR SINGLE	POSTPR
C	PRECISION WORDS ON IBM 360 AND 370 COMPUTERS. THE 15A4 TERM IN THE	POSTPR
C	FORMAT WILL HAVE TO BE CHANGED ON NON-IBM COMPUTERS TO PRODUCE A	POSTPR
C	CONTINUOUS STRING OF 60 CHARACTERS IN CORE MEMORY.	POSTPR
C		POSTPR
C	INPUT CARD I.6.K	POSTPR
C		POSTPR
C	READ (5,13) MYLAB(K), (YLAB(I,K),I=1,NW60)	POSTPR
C		POSTPR
C	INPUT CARD I.7.K	POSTPR
C		POSTPR
C	READ (5,13) MPLB1(K), (PLB1(I,K),I=1,NW60)	POSTPR
C		POSTPR
C	INPUT CARD I.8.K	POSTPR
C		POSTPR
15	READ (5,13) MPLB2(K), (PLB2(I,K),I=1,NW60)	POSTPR
C		CHGIII
C	WRITE OUT PLOTTING CONTROL DATA	CHGIII
C		CHGIII
	WRITE(6,703)	CHGIII
703	FORMAT(4X,'PLOTTING CONTROLS',/)	CHGIII
	WRITE(6,704)	CHGIII
704	FORMAT(12X,'NO. PLOTS',11X,'NO. OF Y VARIABLES PER PLOT')	CHGIII
	WRITE(6,705) NPLT,(NYP(JK),JK=1,NPLT)	CHGIII
705	FORMAT(5X,'I.1',7X,I2,7X,20(I2,2X))	CHGIII
	WRITE(6,706)	CHGIII
706	FORMAT(12X,'MX1 MX2 MY1A MY2A MY1B MY2B MY1C MY2C MY1D MY2D MY1E MCHGIII	CHGIII
	*Y2E MY1F MY2F MY1G MY2G MY1H MY2H MY1I MY2I MY1J MY2J')	CHGIII
	DO 730 IJ=1,NPLT	CHGIII
	WRITE(6,707) IJ,MX(1,IJ),MX(2,IJ),	CHGIII
	* (MY(1,L,IJ),MY(2,L,IJ),L=1,NYP(IJ))	CHGIII
707	FORMAT(5X,'I.2.',I2,2X,I2,2X,I2,2X,20(I2,3X))	CHGIII
730	CONTINUE	CHGIII
	WRITE(6,708)	CHGIII
708	FORMAT(14X,'NX',8X,'X0',9X,'XN',8X,'XL',9X,'XS')	CHGIII
	DO 731 IJ=1,NPLT	CHGIII
	WRITE(6,709) IJ,NX(IJ),X0(IJ),XN(IJ),XL(IJ),XS(IJ)	CHGIII
709	FORMAT(5X,'I.3.',I2,2X,I3,4X,4(F8.3,2X))	CHGIII
731	CONTINUE	CHGIII
	WRITE(6,710)	CHGIII
710	FORMAT(14X,'NY',8X,'Y0',9X,'YN',8X,'YL',9X,'YS')	CHGIII
	DO 732 IJ=1,NPLT	CHGIII
	WRITE(6,711) IJ,NY(IJ),Y0(IJ),YN(IJ),YL(IJ),YS(IJ)	CHGIII
711	FORMAT(5X,'I.4.',I2,2X,I3,4X,4(F8.3,2X))	CHGIII
732	CONTINUE	CHGIII
	WRITE(6,712)	CHGIII
712	FORMAT(12X,'NXLAB',15X,'XLAB')	CHGIII
	DO 733 IJ=1,NPLT	CHGIII



WRITE(6,713) IJ,NXLAB(IJ),(XLAB(L,IJ),L=1,NW60)	CHGIII
713 FORMAT(5X,'1.5.',I2,2X,I3,5X,15A4)	CHGIII
733 CONTINUE	CHGIII
WRITE(6,714)	CHGIII
714 FORMAT(12X,'NYLAB',15X,'YLAB')	CHGIII
DO 734 IJ=1,NPLT	CHGIII
WRITE(6,715) IJ,NYLAB(IJ),(YLAB(L,IJ),L=1,NW60)	CHGIII
715 FORMAT(5X,'1.6.',I2,2X,I3,5X,15A4)	CHGIII
734 CONTINUE	CHGIII
WRITE(6,716)	CHGIII
716 FORMAT(12X,'NPLB1',15X,'PLB1')	CHGIII
DO 735 IJ=1,NPLT	CHGIII
WRITE(6,717) IJ,NPLB1(IJ),(PLB1(L,IJ),L=1,NW60)	CHGIII
717 FORMAT(5X,'1.7.',I2,2X,I3,5X,15A4)	CHGIII
735 CONTINUE	CHGIII
WRITE(6,718)	CHGIII
718 FORMAT(12X,'NPLB2',15X,'PLB2')	CHGIII
DO 736 IJ=1,NPLT	CHGIII
WRITE(6,719) IJ,NPLB2(IJ),(PLB2(L,IJ),L=1,NW60)	CHGIII
719 FORMAT(5X,'1.8.',I2,2X,I3,5X,15A4)	CHGIII
736 CONTINUE	CHGIII
C	POSTPR
C READ TIME HISTORY DATA FROM TAPE 8.	POSTPR
C	POSTPR
20 NPTS = 0	POSTPR
LINES = 0	POSTPR
IF (NPRT(4).GT.0) REWIND 8	POSTPR
READ (8,END=29) NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,NPANEL,	POSTPR
* MNPL,MNBLT,MNSEG,MNBAG,MPL,MBLT,MSEG,MBAG	POSTPR
READ (8,END=29) DATE,COMENT,VPSTTL,BDYTTTL,BLTTTL,PLTTTL,BAGTTL,	POSTPR
* SEG,JOINT,UNITL,UNITM,UNITT,NSG,MSG,XSG,MCG,	ATBIII
* MCGIN,KREF,NHRNSS,NBLTPH,NPTSPB,NSD,MSDM,MSDN	CHGIII
21 READ (8,END=29) NT,UMSEC,((TDATA(I,J),I=1,14),J=1,NT)	POSTPR
R30 = 1.0D0	TGMOD1
IF(NPRT(30).GT.0) R30 = NPRT(30)	TGMOD1
VDT1 = R30*PRDT	TGMOD1
TEST1 = DMOD(UMSEC,VDT1)	TGMOD1
TEST1 = DMIN1(TEST1,DABS(VDT1 -TEST1))	TGMOD1
IF(NPRT(30).GT.0.AND.TEST1.GT.EPS(4)) GO TO 25	TGMOD1
NPTS = NPTS + 1	POSTPR
IF (NPTS.GT.NZD1 .AND. (NDPT.NE.0 .OR. LPLOT) ) STOP 52	ATBIII
ZZ(NPTS,1) = UMSEC	PLTINC
Z(NPTS,1) = UMSEC	PLTINC
IF (NDPT.EQ.0) GO TO 22	POSTPR
C	POSTPR
C STORE DATA FOR HIC, HSI AND CSI.	POSTPR
C	POSTPR
JJ = 1	POSTPR
DO 61 I=1,2	POSTPR
IF (JDTPTS(I).EQ.0) GO TO 61	POSTPR

	JJ = JJ + 1	POSTPR
	JD = JDTPTS(I) - 1	POSTPR
	JE = 4*MOD(JD,3) + 4	POSTPR
	JP = JD/3 + 1	POSTPR
	ZZ(NPTS,JJ) = TDATA(JE,JP)	PLTINC
61	CONTINUE	POSTPR
22	IF (.NOT.LPLOT) GO TO 25	POSTPR
C		POSTPR
C	STORE DATA FOR PLOTTING	POSTPR
C		POSTPR
	JY = 1	PLTINC
	DO 24 K=1,NPLT	POSTPR
	JE = IABS(MX(2,K))	POSTPR
	IF (JE.EQ.0) GO TO 23	POSTPR
	JY = JY + 1	POSTPR
	IF (JY.GT.NZD2) STOP 53	ATBIII
	JP = MX(1,K) - 20	POSTPR
	Z(NPTS,JY) = TDATA(JE,JP)	POSTPR
23	NYPLT = NYP(K)	POSTPR
	DO 24 J=1,NYPLT	POSTPR
	JY = JY + 1	POSTPR
	JP = MY(1,J,K) - 20	POSTPR
	IF (JY.GT.NZD2) STOP 54	ATBIII
	JE = IABS(MY(2,J,K))	POSTPR
	Z(NPTS,JY) = UMSEC	POSTPR
24	IF (JE.NE.0) Z(NPTS,JY) = TDATA(JE,JP)	POSTPR
25	IF (.NOT.LTABH) GO TO 21	POSTPR
C		POSTPR
C	STORE DATA TO PRINT TABULAR TIME HISTORIES	POSTPR
C		POSTPR
	R26 = 1.0D0	TGMOD1
	IF(NPRT(26).LT.0) IFLG = 1	TGMOD1
	IF(IFLG.EQ.1) N26 = IABS(NPRT(26))	TGMOD1
	IF(IFLG.EQ.1) R26 = N26	TGMOD1
	VDT2 = R26*PRDT	TGMOD1
	TEST2 = DMOD(UMSEC,VDT2)	TGMOD1
	TEST2 = DMIN1(TEST2,DABS(VDT2 - TEST2))	TGMOD1
	IF (NPRT(26).LE.0 .AND. TEST2.GT.EPS(4)) GO TO 21	TGMOD1
	LINES = LINES + 1	POSTPR
	NTTH = MOD(LINES-1,LPP) + 1	POSTPR
	USEC(NTTH) = UMSEC	POSTPR
	DO 26 J=1,NT	POSTPR
	DO 26 I=1,14	POSTPR
26	ZTTH(I,NTTH,J) = TDATA(I,J)	POSTPR
	IF (NTTH.EQ.LPP) CALL HEDING (LINES,LPP)	POSTPR
	GO TO 21	POSTPR
29	IF (.NOT.LTABH .OR. LINES.EQ.0) GO TO 30	POSTPR
	IF (NTTH.NE.LPP) CALL HEDING (LINES,LPP)	POSTPR
30	IF (NDPT.NE.0) CALL HICCSI(NPTS)	POSTPR
	IF (.NOT.LPLOT) GO TO 98	POSTPR

C		POSTPR
C	PLOT DATA VIA SUBROUTINE SLPLOT.	POSTPR
C		POSTPR
C	INCLUDE ANY PROGRAM STATEMENTS HERE REQUIRED BY YOUR COMPUTER AND	POSTPR
C	PLOTTING SYSTEMS FOR PLOT INITIALIZATION (E.G., CALL PLOTS).	POSTPR
C		POSTPR
	CALL PLOTS (0.0,0.0,10)	FIXSPT
	JZ = 1	PLTINC
	DO 50 K=1,NPLT	POSTPR
	JX = 1	POSTPR
	IF (MX(2,K).EQ.0) GO TO 42	POSTPR
	JZ = JZ + 1	POSTPR
	JX = JZ	POSTPR
	IF (Z(1,JX).EQ.0.0 .OR. MX(2,K).GE.0) GO TO 42	POSTPR
	DO 41 I=2,NPTS	POSTPR
41	Z(I,JX) = Z(I,JX) - Z(1,JX)	POSTPR
	Z(1,JX) = 0.0	POSTPR
42	NYPLT = NYP(K)	POSTPR
	DO 44 J=1,NYPLT	POSTPR
	JY = JZ + J	POSTPR
	IF (Z(1,JY).EQ.0.0 .OR. MY(2,J,K).GE.0) GO TO 44	POSTPR
	DO 43 I=2,NPTS	POSTPR
43	Z(I,JY) = Z(I,JY) - Z(1,JY)	POSTPR
	Z(1,JY) = 0.0	POSTPR
44	CONTINUE	POSTPR
	NXK = NX(K)	POSTPR
	NYK = NY(K)	POSTPR
	XOK = XO(K)	POSTPR
	YOK = YO(K)	POSTPR
	XNK = XN(K)	POSTPR
	YNK = YN(K)	POSTPR
	XLK = XL(K)	POSTPR
	YLK = YL(K)	POSTPR
	XSK = XS(K)	POSTPR
	YSK = YS(K)	POSTPR
	NXLABK = NXLAB(K)	POSTPR
	NYLABK = NYLAB(K)	POSTPR
	NPLB1K = NPLB1(K)	POSTPR
	NPLB2K = NPLB2(K)	POSTPR
	CALL SLPLOT(Z(1,JX ), NXK, XOK, XNK, XLK, XSK, XLAB(1,K), NXLABK,	POSTPR
	* Z(1,JZ+1), NYK, YOK, YNK, YLK, YSK, YLAB(1,K), NYLABK,	POSTPR
	* NPTS,NYPLT,NZD1,PLB1(1,K),NPLB1K,PLB2(1,K),NPLB2K)	POSTPR
		POSTPR
C		POSTPR
C	INSERT ANY CODE REQUIRED BY YOUR SYSTEM TO ADVANCE PLOT PAGES HERE	POSTPR
C		POSTPR
	IF(NPRT(31).EQ.1) GO TO 444	CHGIII
	X00 = -0.5*(XSK-(XLK-0.5)) + XLK + 3.0	FXPLOT
	Y00 = -0.5*(YSK-(YLK-1.0))	FXPLOT
	CALL PLOT (X00,Y00,-3)	FXPLOT
50	JZ = JZ + NYPLT	POSTPR

444 CONTINUE  
C  
C     INSERT ANY PLOT TERMINATION CODE REQUIRED BY YOUR SYSTEM HERE.  
C  
CALL PLOT(12.0,0.0,999)  
98 CALL ELTIME (2,36)  
99 RETURN  
END

CHGIII  
POSTPR  
POSTPR  
POSTPR  
PECONV  
POSTPR  
POSTPR  
POSTPR



DO 20 I=1,MBAG	PRINT
IF (LPMI(I).EQ.0) GO TO 19	PRINT
CALL DOT33 (DPMI(1,1,I),D(1,1,I),T3)	PRINT
CALL DOT31(DPMI(1,1,I),WMEG(1,I),T1)	FIXPRT
CALL DOT31(DPMI(1,1,I),WMEGD(1,I),T2)	FIXPRT
CALL YPRDEG (T3,YPR)	PRINT
WRITE (6,31) I,SEG(I),YPR,(T1(K),K=1,3),(T2(K),K=1,3)	FIXPRT
GO TO 20	PRINT
19 CALL YPRDEG (D(1,1,I),YPR)	PRINT
WRITE (6,31) I,SEG(I),YPR,(WMEG(K,I),K=1,3),(WMEGD(K,I),K=1,3)	FIXPRT
20 CONTINUE	FIXPRT
WRITE(6,770)	CHGIII
770 FORMAT(//,1X,23X,'(INERTIAL)',27X,'(INERTIAL)',32X,'(INERTIAL)')	CHGIII
WRITE (6,22) UNITL,UNITL,UNITT	PRINT
22 FORMAT(18X,'LINEAR POSITION (' ,A4,' )',	CHGIII
* 13X,'LINEAR VELOCITY (' ,A4,'/' ,A4,' )',	PRINT
* 16X,'LINEAR ACCELERATIONS (G'S)'/	PRINT
* ' SEGMENT',10X,'X',10X,'Y',10X,'Z',	PRINT
* 13X,'X',11X,'Y',11X,'Z',15X,'X',13X,'Y',13X,'Z'//)	PRINT
DO 30 I=1,MBAG	PRINT
DO 29 K=1,3	PRINT
29 T1(K) = SEGLA(K,I)/G	PRINT
30 WRITE (6,31) I,SEG(I),(SEGLP(K,I),K=1,3),(SEGLV(K,I),K=1,3),T1	PRINT
31 FORMAT(13,1X,A4,3X,3F11.4,3X,3F12.5,3X,3F14.6)	PRINT
IF (NSEG.GT.6) WRITE (6,32) NPG	PAGE
IF (NSEG.GT.6) NPG=NPG+1	PAGE
32 FORMAT('1',122X,'PAGE',I5)	PAGE
WRITE(6,775)	CHGIII
775 FORMAT(//,1X,23X,'(INERTIAL)',29X,'(LOCAL)')	CHGIII
WRITE (6,33) UNITL,UNITT,UNITT,UNITM,UNITL	KINETIC
33 FORMAT(18X,'U1 ARRAY (' ,A4,'/' ,A4,'**2)',	KINETIC
* 14X,'U2 ARRAY (RAD/' ,A4,'**2)',	KINETIC
* 25X,'KINETIC ENERGY'/	KINETIC
* 15X,'EXTERNAL LINEAR ACCELERATIONS',	KINETIC
* 8X,'EXTERNAL ANGULAR ACCELERATIONS',	KINETIC
* 22X,'(' ,A4,'-' ,A4,' )'/	KINETIC
* ' SEGMENT',10X,'X',10X,'Y',10X,'Z',13X,'X',11X,'Y',11X,'Z',	KINETIC
* 14X,'LINEAR',7X,'ANGULAR',7X,'TOTAL'//)	KINETIC
DO 80 J=1,3	KINETIC
80 TKE(J)=0.0	KINETIC
DO 34 I=1,NSEG	PRINT
V=SEGLV(1,I)**2+SEGLV(2,I)**2+SEGLV(3,I)**2	KINETIC
SKE(1)=0.5*W(I)*V/G	KINETIC
SKE(2)=0.0	KINETIC
DO 81 J=1,3	KINETIC
81 SKE(2)=SKE(2)+0.5*PHI(J,I)*WMEG(J,I)**2	KINETIC
SKE(3)=SKE(1)+SKE(2)	KINETIC
DO 82 J=1,3	KINETIC
82 TKE(J)=TKE(J)+SKE(J)	KINETIC
IF (LPMI(I).EQ.0) GO TO 73	FIXPRT

CALL DOT31 (DPMI(1,1,I),U2(1,I),T1)	FIXPRT
WRITE (6,61) I,SEG(I),(U1(K,I),K=1,3),	KINETIC
* (T1(K),K=1,3),(SKE(K),K=1,3)	KINETIC
GO TO 34	PRINT
73 CONTINUE	PRINT
WRITE (6,61) I,SEG(I),(U1(K,I),K=1,3),	KINETIC
* (U2(K,I),K=1,3),(SKE(K),K=1,3)	KINETIC
61 FORMAT(13,1X,A4,3X,3(D11.4,1X),3X,3(D12.5,1X),3X,3(D12.5,1X))	KINETIC
34 CONTINUE	FIXPRT
WRITE(6,83) (TKE(K),K=1,3)	KINETIC
83 FORMAT(1X,98X,'TOTAL BODY KINETIC ENERGY'/	KINETIC
* 1X,90X,3(1X,D12.5))	KINETIC
IF (NJNT.LE.0) GO TO 39	PRINT
WRITE(6,776)	CHGIII
776 FORMAT(//,1X,27X,'(INERTIAL)',27X,'(INERTIAL)')	CHGIII
WRITE (6,35) UNITM,UNITL,UNITM,UNITT	PRINT
35 FORMAT(24X,'JOINT FORCES (' ,A4,')',	CHGIII
* 15X,'JOINT TORQUES (' ,2A4,')',	PRINT
* 9X,'RELATIVE ANGULAR'/	PRINT
* ' JOINT IPIN',9X,'X',10X,'Y',10X,'Z',13X,'X',11X,'Y',11X,'Z',	PRINT
* 7X,'VELOCITY (RAD/' ,A4,')'//)	PRINT
DO 36 J=1,NJNT	PRINT
IPINJ = IPIN(J)	PRINT
IF (IABS(IPIN(J)).EQ.4) IPINJ = IEULER(J)	PRINT
DO 137 II=1,3	MISC
137 T1(II)=-TQ(II,J)	MISC
WRITE (6,37) J,JOINT(J),IPINJ,(F(K,J),K=1,3),(T1(K),K=1,3),WJ(J)	MISC
37 FORMAT(13,1X,A4,14,7X,3(D10.3,1X),3X,3(D11.4,1X),3X,F13.3)	FIXPRT
36 CONTINUE	FIXPRT
39 IF (NQ.LE.0) GO TO 99	PRINT
WRITE (6,41)	CHGIII
WRITE (6,47)	CHGIII
47 FORMAT(1X,45X,'(INERTIAL)')	CHGIII
WRITE (6,49) UNITM,UNITL	CHGIII
41 FORMAT(///' OTHER CONSTRAINT FORCES',/)	CHGIII
49 FORMAT(1X,' NO. TYPE SEG1 SEG2',	CHGIII
* 15X,'CONSTRAINT FORCE (' ,A4,')',	PRINT
* 16X,'DISTANCE (' ,A4,')'//)	PRINT
ICH = 0	FIXPRT
DO 50 J=1,NQ	PRINT
IF (KQTYPE(J).NE.5) ICH = 0	FIXPRT
IF (KQTYPE(J).LT.0) GO TO 50	PRINT
IF (KQTYPE(J).EQ.5) ICH = ICH + 1	FIXPRT
IF (ICH.EQ.2) GO TO 50	FIXPRT
M = KQ1(J)	PRINT
N = KQ2(J)	PRINT
CALL DOT31(D(1,1,M),RK1(1,J),T1)	PRINT
CALL DOT31(D(1,1,N),RK2(1,J),T2)	PRINT
S1 = 0.0	PRINT
DO 42 I=1,3	PRINT

HH(I) = SEGLP(I,M)+T1(I) - SEGLP(I,N)-T2(I)	PRINT
42 S1 = S1 + HH(I)**2	PRINT
SQS1 = DSQRT(S1)	PRINT
WRITE (6,43) J,KQTYPE(J),SEG(M),SEG(N),(QQ(I,J),I=1,3),SQS1	PRINT
43 FORMAT(I4,I6,4X,A4,2X,A4,3X,3G15.7,6X,G15.7)	PRINT
50 CONTINUE	PRINT
99 IF (NPRT(28).LE.0) NPRT(28) = -1	PRINT
RETURN	PRINT
END	PRINT



## SUBROUTINE PRIPLT

REV IV 07/24/86SLIP

PRODUCES PRINTER PLOT OF Y-Z PLANE VIEW AND X-Z PLANE VIEW OF  
BODY SEGMENT CGS, JOINTS AND SELECTED POINTS OF VEHICLE COMPONENTS

IMPLICIT REAL\*8 (A-H,O-Z)

COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,

\* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG

COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),

\* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)

COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),

\* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),

\* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)

COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),

\* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),

\* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)

COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)

COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),

\* BLTTTL(5,8),PLTTTL(5,30),BAGTTL(5,6),SEG(30),

\* JOINT(30),CGS(30),JS(30)

COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),

\* XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),

\* NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)

REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTTL,BAGTTL,SEG,JOINT

LOGICAL\*1 CGS,JS

COMMON/TEMPVS/ TEMP1(3),TEMP(3),TEMP2(3),CJOINT(3,30),BSN(2),

\* PLOTYZ(96,55),PLOTXZ(96,55),PLOTXY(96,55)

LOGICAL\*1 PLOTYZ,PLOTXZ,PLOTXY,CHARS(7),BLANK,BCHAR

LOGICAL NPRT5,NPRT6,NPRT7

DATA CHARS/' ','+',',','@','!','\_','-','\*','/', BLANK/' '/

DATA ISTEP/0/ , NPLTI/96/ , NPLTJ/55/

DETERMINE IF PLOTTING IS TO BE DONE FOR THIS TIME STEP.

ISTEP = ISTEP+1

NPRT5 = (NPRT(5).EQ.1)

IF (NPRT(5).GT.1) NPRT5 = (MOD(ISTEP,NPRT(5)).EQ.1)

NPRT6 = (NPRT(6).EQ.1)

IF (NPRT(6).GT.1) NPRT6 = (MOD(ISTEP,NPRT(6)).EQ.1)

NPRT7 = (NPRT(7).EQ.1)

IF (NPRT(7).GT.1) NPRT7 = (MOD(ISTEP,NPRT(7)).EQ.1)

IF (.NOT.NPRT5 .AND. .NOT.NPRT6 .AND. .NOT.NPRT7) GO TO 99

CALL ELTIME(1, 4)

BLANK OUT PLOT ARRAYS.

DO 10 J=1,NPLTJ

PLOTYZ(1,J) = CHARS(6)

PLOTXZ(1,J) = CHARS(6)

PLOTXY(1,J) = CHARS(6)

	DO 10 I=2,NPLTI	PRIPLT
	PLOTYZ(I,J) = BLANK	PRIPLT
	PLOTXZ(I,J) = BLANK	PRIPLT
10	PLOTXY(I,J) = BLANK	PRIPLT
C		PRIPLT
C	PLOT VEHICLE REFERENCE ORIGIN USING SYMBOL(*).	PRIPLT
C		PRIPLT
	CALL PLTXYZ (SEGLP(1,NVEH),CHARS(7))	PRIPLT
C		PRIPLT
C	PLOT CG OF BODY SEGMENTS USING SEGMENT SYMBOLS.	PRIPLT
C		PRIPLT
	DO 20 I=1,NSEG	PRIPLT
20	CALL PLTXYZ(SEGLP(1,I),CGS(I))	PRIPLT
C		PRIPLT
C	COMPUTE AND PLOT JOINT LOCATIONS USING JOINT SYMBOLS.	PRIPLT
C		PRIPLT
	IF (NJNT.EQ.0) GO TO 40	PRIPLT
	DO 31 J=1,NJNT	PRIPLT
	I = IABS(JNT(J))	PRIPLT
	IF (I.LE.0) GO TO 31	PRIPLT
	CALL DOT31(D(1,1,I),SR(1,2*J-1),TEMP)	PRIPLT
	DO 30 L=1,3	PRIPLT
30	CJOINT(L,J) = TEMP(L)+SEGLP(L,I)	PRIPLT
	CALL PLTXYZ (CJOINT(1,J),JS(J))	PRIPLT
31	CONTINUE	PRIPLT
	IF (NPRT(13).NE.0) WRITE (6,32) ((CJOINT(I,J),I=1,3),J=1,NJNT)	PRIPLT
32	FORMAT ('0 JOINT POSITIONS'/(1X,9F14.4))	PRIPLT
C		PRIPLT
C	PLOT BELT ANCHOR, FIXED AND TANGENT POINTS USING SYMBOL(.).	PRIPLT
C		PRIPLT
40	IF (NBLT.LE.0) GO TO 50	PRIPLT
	DO 43 J=1,NBLT	PRIPLT
	IF (MNBLT(J).LE.0) GO TO 43	PRIPLT
	M1 = MBLT(1,1,J)	PRIPLT
	M2 = MBLT(2,1,J)	PRIPLT
	M3 = MBLT(3,1,J)	PRIPLT
	DO 41 I=1,3	PRIPLT
41	TEMP1(I) = BELT(I+6,J) + BD(I+3,M3)	PRIPLT
	CALL DOT31 (D(1,1,M2),TEMP1,TEMP)	PRIPLT
	CALL DOT31 (D(1,1,M1),BELT(1,J),TEMP1)	PRIPLT
	CALL DOT31 (D(1,1,M1),BELT(4,J),TEMP2)	PRIPLT
	DO 42 I=1,3	PRIPLT
	TEMP1(I) = TEMP1(I) + SEGLP(I,M1)	PRIPLT
	TEMP2(I) = TEMP2(I) + SEGLP(I,M1)	PRIPLT
42	TEMP (I) = TEMP (I) + SEGLP(I,M2)	PRIPLT
	CALL PLTXYZ (TEMP1 ,CHARS(1))	PRIPLT
	CALL PLTXYZ (TEMP2 ,CHARS(1))	PRIPLT
	CALL PLTXYZ (TEMP ,CHARS(1))	PRIPLT
	CALL PLTXYZ (TPTS(1,J),CHARS(1))	PRIPLT
	CALL PLTXYZ (TPTS(4,J),CHARS(1))	PRIPLT



67	CALL PLTXYZ (TEMP2,BCHAR)	PRIPLT
68	CONTINUE	PRIPLT
C		PRIPLT
C	PRINT Y-Z , X-Z AND X-Y PLANE VIEW PLOTS.	PRIPLT
C		PRIPLT
80	TMSC = 1000.0*TIME	PRIPLT
	IF (.NOT.NPRT5) GO TO 83	PRIPLT
	WRITE (2,81) TMSC,SEGLP(2,NVEH),SEGLP(3,NVEH)	PRIPLT
81	FORMAT ('1 T=',F10.3,' Y0=',F10.5,' Z0=',F10.5,' Y-Z PLANE')	PRIPLT
	WRITE (2,82) PLOTYZ	PRIPLT
82	FORMAT (2X,96A1)	PRIPLT
83	IF (.NOT.NPRT6) GO TO 85	PRIPLT
	WRITE (2,84) TMSC,SEGLP(1,NVEH),SEGLP(3,NVEH)	PRIPLT
84	FORMAT ('1 T=',F10.3,' X0=',F10.5,' Z0=',F10.5,' X-Z PLANE')	PRIPLT
	WRITE (2,82) PLOTXZ	PRIPLT
85	IF (.NOT.NPRT7) GO TO 87	PRIPLT
	WRITE (2,86) TMSC,SEGLP(1,NVEH),SEGLP(2,NVEH)	PRIPLT
86	FORMAT ('1 T=',F10.3,' X0=',F10.5,' Y0=',F10.5,' X-Y PLANE')	PRIPLT
	WRITE (2,82) PLOTXY	PRIPLT
87	CALL ELTIME(2, 4)	PRIPLT
99	RETURN	PRIPLT
	END	PRIPLT



	SUBROUTINE QUAT(ANG,Q)		QUAT
		REV IV 07/23/86	TWOPI
C	COMPUTES QUATERNIONS FROM YAW, PITCH, ROLL ANGLES IN DEGREES		QUAT
C	IMPLICIT REAL *8(A-H,O-Z)		QUAT
	DIMENSION ANG(3),Q(4),R(4),T(3)		QUAT
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		QUAT
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	A = 0.5*ANG(1)*RADIAN		QUAT
	Q(1) = DCOS(A)		QUAT
	Q(2) = 0.0		QUAT
	Q(3) = 0.0		QUAT
	Q(4) = DSIN(A)		QUAT
	K = 3		QUAT
	DO 10 I = 2,3		QUAT
	A = 0.5*ANG(I)*RADIAN		QUAT
	R(1) = DCOS(A)		QUAT
	R(2) = 0.0		QUAT
	R(3) = 0.0		QUAT
	R(4) = 0.0		QUAT
	R(K) = DSIN(A)		QUAT
	DOT = Q(2)*R(2) + Q(3)*R(3) + Q(4)*R(4)		QUAT
	CALL CROSS(Q(2),R(2),T)		QUAT
	DO 5 J = 2,4		QUAT
5	Q(J) = Q(1)*R(J) + R(1)*Q(J) + T(J-1)		QUAT
	Q(1) = Q(1)*R(1) - DOT		QUAT
10	K = 2		QUAT
	SUM = DSQRT(Q(1)**2 + Q(2)**2 + Q(3)**2 + Q(4)**2)		QUAT
	DO 12 I = 1,4		QUAT
12	Q(I) = Q(I)/SUM		QUAT
	RETURN		QUAT
	END		QUAT

C	DOUBLE PRECISION FUNCTION RCRT(A,PL,Z,IP)	REV 03	07/19/73	RCRT
C				RCRT
C	COMPUTES THE RADIUS OF CURVATURE AT POINT Z OF ELLIPSOID A			RCRT
C	IN THE PLANE PL(I,IP) WHERE			RCRT
C				RCRT
C	A: 3X3 MATRIX DEFINING ELLIPSOID.			RCRT
C	PL: 4X3 MATRIX CONTAINING THREE ORTHONORMAL VECTORS.			RCRT
C	Z: 3 COORDINATES OF POINT ON THE ELLIPSOID			RCRT
C	AS MEASURED FROM CENTER OF ELLIPSOID			RCRT
C	IP: IDENTIFIES THE NORMAL VECTOR OF PLANE IN WHICH THE			RCRT
C	RADIUS OF CURVATURE IS DESIRED.			RCRT
C				RCRT
	IMPLICIT REAL*8 (A-H,O-Z)			RCRT
	DIMENSION A(3,3),PL(4,3),Z(3),T(5)			RCRT
	DO 10 I=1,5			RCRT
10	T(I) = 0.0			RCRT
	M = IP+1			RCRT
	N = IP+2			RCRT
	IF(M.GT.3) M = M-3			RCRT
	IF(N.GT.3) N = N-3			RCRT
	DO 30 I=1,3			RCRT
	S1 = 0.			RCRT
	S2 = 0.			RCRT
	DO 20 J=1,3			RCRT
	S1 = S1+A(I,J)*PL(J,M)			RCRT
20	S2 = S2+A(I,J)*PL(J,N)			RCRT
	T(1) = T(1)+S1*Z(I)			RCRT
	T(2) = T(2)+S2*Z(I)			RCRT
	T(3) = T(3)+S1*PL(I,M)			RCRT
	T(4) = T(4)+S2*PL(I,N)			RCRT
30	T(5) = T(5)+S1*PL(I,N)			RCRT
	W = DSQRT(T(1)**2+T(2)**2)			RCRT
	T(1) = T(1)/W			RCRT
	T(2) = T(2)/W			RCRT
	RCRT = W/(T(3)*T(2)**2-2.0*T(1)*T(2)*T(5)+T(4)*T(1)**2)			RCRT
	IF(RCRT.LT.0.0) RCRT = -RCRT			RCRT
	RETURN			RCRT
	END			RCRT

C	SUBROUTINE ROT (A,L,TH)	REV IV	07/23/86	ROT
C				TWOPI
C	COMPUTES ROTATION MATRIX A FOR ANGLE TH			ROT
C	ABOUT X,Y OR Z AXIS AS L = 1,2, OR 3.			ROT
C				ROT
C	ARGUMENTS:			ROT
C	A: 3X3 ROTATION MATRIX TO BE COMPUTED.			ROT
C	L: 1,2 OR 3 TO ROTATE ABOUT X,Y OR Z AXIS.			ROT
C	TH: ANGLE OF ROTATION IN RADIAN.			ROT
C				ROT
	IMPLICIT REAL*8 (A-H,O-Z)			ROT
	DIMENSION A(3,3)			ROT
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),			ROT
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI			TWOPI
	C=DCOS(TH)			ROT
	S=DSIN(TH)			ROT
	IF (DABS(C) .LT.EPS(8)) C=0.0			CONVER
	IF (DABS(S) .LT.EPS(8)) S=0.0			CONVER
	ONE = 1.0			ROT
	IF (1.0-DABS(C) .LT.EPS(8)) C = DSIGN(ONE,C)			CONVER
	IF (1.0-DABS(S) .LT.EPS(8)) S = DSIGN(ONE,S)			CONVER
	IF (L.EQ.2) S = -S			ROT
	DO 30 I=1,3			ROT
	IF(I.EQ.3)GO TO 20			ROT
	DO 10 J=1,2			ROT
	A(I,J+1)=0.0			ROT
	A(J+1,I)=0.0			ROT
	IF(I+J+L.NE.5)GO TO 10			ROT
	A(I,J+1)=S			ROT
	A(J+1,I)=-S			ROT
	10 CONTINUE			ROT
	20 A(I,I)= C			ROT
	IF(I.EQ.L)A(I,I)=1.0			ROT
	30 CONTINUE			ROT
	RETURN			ROT
	END			ROT



## SUBROUTINE ROTATE

REV IV 02/20/87HYPER

THE PURPOSE OF THIS ROUTINE IS TO TRANSFORM THOSE VARIABLES THAT  
HAVE BEEN SUPPLIED IN LOCAL GEOMETRIC COORDINATES TO PRINCIPAL  
AXES COORDINATES AS INDICATED BY LPMI(I) \* 0 FOR I = 1 TO NSEG.

IMPLICIT REAL\*8 (A-H,O-Z)

COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,

\* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG

COMMON/RSAGE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),

\* NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)

COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),

\* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),

\* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)

COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)

COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),

\* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)

COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),

\* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),

\* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)

COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),

\* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),

\* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),

\* KQ1(12),KQ2(12),KQTYPE(12)

COMMON/DAMPER/ APSDM(3,20),APSDN(3,20),ASD(5,20),MSDM(20),MSDN(20)

COMMON/WINDFR/ WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30),

\* MWSEG(7,30),NFVSEG(6),NFVNT(5),MOWSEG(30,30)

COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),

\* XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),

\* NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)

COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)

COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),

\* FE(3,30),TQE(3,30),CONST(5,30)

COMMON/TEMPVS/ T1(3),T3(3,3),LBD(40),T2(3),T4(3,3)

TRANSFORM DIRECTION COSINE MATRICES D FROM INPUT CARDS G.3.

LTEST = 0

DO 20 J=1,30

IF (J.GT.NSEG) LPMI(J) = 0

IF (LPMI(J).EQ.0) GO TO 20

LTEST = 1

DO 12 I=1,3

T1(I) = WMEG(I,J)

DO 12 K=1,3

12 T3(I,K) = D(I,K,J)

CALL MAT33 (DPMI(1,1,J),T3,D(1,1,J))

CALL MAT31 (DPMI(1,1,J),T1,WMEG(1,J))

20 CONTINUE

IF (LTEST.EQ.0) GO TO 99

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C[illegible]

43	T1(I) = APSDM(I,J)	ROTATE
	CALL MAT31 (DPMI(1,1,KSEG),T1,APSDM(1,J))	ROTATE
44	KSEG = MSDN(J)	ROTATE
	IF (LPMI(KSEG).EQ.0) GO TO 50	ROTATE
	DO 45 I=1,3	ROTATE
45	T1(I) = APSDN(I,J)	ROTATE
	CALL MAT31 (DPMI(1,1,KSEG),T1,APSDN(1,J))	ROTATE
50	CONTINUE	ROTATE
C		FIXROT
C	TRANSFORM QFU AND QFV FROM INPUT CARDS D.9.	FIXROT
C		FIXROT
151	NFORCE = NRVSEG(6)	FIXROT
	IF (NFORCE.LE.0) GO TO 100	WINDROT
	DO 152 J=1,NFORCE	FIXROT
	KSEG = IABS(NRVSEG(J))	FIXROT
	IF (LPMI(KSEG).EQ.0) GO TO 152	FIXROT
	DO 143 I=1,3	FIXROT
	T1(I) = QFU(I,J)	FIXROT
143	T2(I) = QFV(I,J)	FIXROT
	CALL MAT31 (DPMI(1,1,KSEG),T1,QFU(1,J))	FIXROT
	CALL MAT31 (DPMI(1,1,KSEG),T2,QFV(1,J))	FIXROT
152	CONTINUE	FIXROT
C		WINDROT
C	ROTATE WIND FORCE FUNCTIONS	WINDROT
C		WINDROT
100	IF (NWINDF.EQ.0) GOTO 51	WINDROT
	DO 101 I=1,NSEG	WINDROT
	IF (MWSEG(1,I).EQ.0) GOTO 101	WINDROT
	NT = MWSEG(5,I)	WINDROT
	DO 102 J=1,I-1	WINDROT
	IF (NT.EQ.MWSEG(5,J)) GOTO 101	WINDROT
102	CONTINUE	WINDROT
	KT = NTI(NT)	WINDROT
	RK = TAB(KT)	WINDROT
	IF (RK.NE.0) GOTO 101	WINDROT
	NSR = IDINT(TAB(KT+4))	WINDROT
	IF (NSR.EQ.0 .OR. LPMI(NSR).EQ.0) GOTO 101	WINDROT
	NENTRY = TAB(KT+5)	WINDROT
	K1 = KT+6	WINDROT
	K2 = 4*NENTRY+KT+2	WINDROT
	DO 103 K=K1,K2,4	WINDROT
	DO 104 J=1,3	WINDROT
104	T1(J) = TAB(K+J)	WINDROT
103	CALL MAT31(DPMI(1,1,NSR),T1,TAB(K+1))	WINDROT
101	CONTINUE	WINDROT
C		ROTATE
C	CHECK PLANE AND ELLIPSOID ASSIGNMENTS ON INPUT CARDS F.1.	ROTATE
C	TRANSFORM PLANE ARRAYS SET UP FROM INPUT CARD D.1.	ROTATE
C		ROTATE
51	DO 52 J=1,40	ROTATE

	LBD(J) = 0	ROTATE
52	IF (J.LE.NSEG) LBD(J) = J	ROTATE
	IF (NPL.LE.0) GO TO 61	ROTATE
	DO 60 J=1,NPL	ROTATE
	IF (MNPL(J).EQ.0) GO TO 60	ROTATE
	LPL = 0	ROTATE
	KPL = MNPL(J)	ROTATE
	DO 56 I=1,KPL	ROTATE
	M1 = MPL (1,I,J)	ROTATE
	M2 = MPL (2,I,J)	ROTATE
	M3 = MPL (3,I,J)	ROTATE
	IF (LPL.EQ.M1 .OR. LPL.EQ.0) GO TO 54	ROTATE
	WRITE (6,53) J,M1,LPL	ROTATE
53	FORMAT('0 INPUT ERROR HAS BEEN DETECTED IN SUBROUTINE ROTATE.'/	ROTATE
*	' PLANE NO.',I3,' HAS BEEN ASSIGNED TO BOTH SEGMENTS NO.',	ROTATE
*	I3,' AND NO.',I3,'.'/ PROGRAM IS BEING TERMINATED.')	ROTATE
	STOP 43	ROTATE
54	LPL = M1	ROTATE
	IF (LBD(M3).EQ.M2 .OR. LBD(M3).EQ.0) GO TO 55	ROTATE
	WRITE (6,68) M3,M2,LBD(M3)	ROTATE
	STOP 44	ROTATE
55	LBD(M3) = M2	ROTATE
56	CONTINUE	ROTATE
	IF (LPMI(LPL).EQ.0) GO TO 60	ROTATE
	L = 1	EDGE
	DO 59 K=1,6	EDGE
	IF((K.EQ.3).OR.(K.EQ.6)) L = L-1	EDGE
	IF((K.EQ.4).OR.(K.EQ.5)) L = L+1	EDGE
	DO 58 I=1,3	ROTATE
	T1(I) = PL(L,J)	EDGE
58	L=L+1	EDGE
	CALL MAT31 (DPMI(1,1,LPL),T1,PL(L-3,J))	EDGE
59	L=L+1	EDGE
60	CONTINUE	ROTATE
C		ROTATE
C	CHECK ELLIPSOID ASSIGNMENTS ON INPUT CARDS F.2.	ROTATE
C	TRANSFORM BELT(L,J) FOR L=1,9 FROM INPUT CARDS D.3.	ROTATE
C		ROTATE
61	IF (NBLT.LE.0) GO TO 66	ROTATE
	DO 65 J=1,NBLT	ROTATE
	IF (MNBLT(J).EQ.0) GO TO 65	ROTATE
	KBLT = MNBLT(J)	ROTATE
	DO 62 I=1,KBLT	ROTATE
	M1 = MBLT(1,I,J)	ROTATE
	M2 = MBLT(2,I,J)	ROTATE
	M3 = MBLT(3,I,J)	ROTATE
	IF (LBD(M3).EQ.M2 .OR. LBD(M3).EQ.0) GO TO 62	ROTATE
	WRITE (6,68) M3,M2,LBD(M3)	ROTATE
	STOP 45	ROTATE
62	LBD(M3) = M2	ROTATE



C	174 IF(NWINDF.EQ.0) GO TO 74	TGMOD8
	DO 175 J=1,NSEG	TGMOD8
	M1 = IABS(MWSEG(1,J))	TGMOD8
	IF(M1.EQ.0) GO TO 175	TGMOD8
	M2 = MWSEG(2,J)	TGMOD8
	IF(LBD(M2).EQ.M1.OR.LBD(M2).EQ.0) GO TO 172	TGMOD8
	WRITE(6,68) M2,M1,LBD(M2)	TGMOD8
	STOP 48	TGMOD8
	172 LBD(M2) = M1	TGMOD8
	175 CONTINUE	TGMOD8
C		ROTATE
C	CHECK ELLIPSOID ASSIGNMENTS ON INPUT CARDS F.8.	ROTATE
C	TRANSFORM BAR(L,K) FOR L=4,12 FROM INPUT CARDS F.8.D.	ROTATE
C		ROTATE
	74 IF (NHRNSS.EQ.0) GO TO 81	ROTATE
	J1 = 1	ROTATE
	K1 = 1	ROTATE
	DO 80 II=1,NHRNSS	ROTATE
	IF (NBLTPH(II).LE.0) GO TO 80	ROTATE
	J2 = J1 + NBLTPH(II) - 1	ROTATE
	DO 79 JJ=J1,J2	ROTATE
	IF (NPTSPB(JJ).LE.0) GO TO 79	ROTATE
	K2 = K1 + NPTSPB(JJ) - 1	ROTATE
	DO 78 K=K1,K2	ROTATE
	M2 = MOD(IBAR(1,K),100)	ROTATE
	M3 = IBAR(2,K)	ROTATE
	IF (M3.EQ.0) GO TO 88	BUTLER1
	IF (LBD(M3).EQ.M2 .OR. LBD(M3).EQ.0) GO TO 75	ROTATE
	WRITE (6,68) M3,M2,LBD(M3)	ROTATE
	STOP 51	ROTATE
	75 LBD(M3) = M2	ROTATE
	88 IF (LPMI(M2).EQ.0) GO TO 78	BUTLER1
	DO 77 J=3,9,3	ROTATE
	DO 76 I=1,3	ROTATE
	IJ = I+J	ROTATE
	76 T1(I) = BAR(IJ,K)	ROTATE
	77 CALL MAT31 (DPMI(1,1,M2),T1,BAR(J+1,K))	ROTATE
	78 CONTINUE	ROTATE
	K1 = K2+1	ROTATE
	79 CONTINUE	ROTATE
	J1 = J2+1	ROTATE
	80 CONTINUE	ROTATE
C		ROTATE
C	TRANSFORM DATA IN BD ARRAYS FOR ELLIPSOIDS THAT HAVE BEEN ASSIGNED	ROTATE
C		ROTATE
	81 DO 90 J=1,40	ROTATE
	IF (LBD(J).EQ.0) GO TO 90	ROTATE
	KSEG = LBD(J)	ROTATE
	IF (LPMI(KSEG).EQ.0) GO TO 90	ROTATE

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L = 4
IF (BD(1,J).LT.0.0) L = 5
M = 8
DO 82 I=1,3
T1(I) = BD(L,J)
L = L + 1
DO 82 K = 1,3
T3(K,I) = BD(M,J)
82 M = M + 1
CALL MAT31 (DPMI(1,1,KSEG),T1,BD(L-3,J))
IF (BD(1,J).GT.0.0) GO TO 84
CALL MAT33 (DPMI(1,1,KSEG),T3,BD(8,J))
GO TO 90
84 CALL DOTT33 (BD( 7,J),DPMI(1,1,KSEG),T3)
CALL MAT33 (DPMI(1,1,KSEG),T3,BD( 7,J))
CALL DOTT33 (BD(16,J),DPMI(1,1,KSEG),T3)
CALL MAT33 (DPMI(1,1,KSEG),T3,BD(16,J))
90 CONTINUE
99 RETURN
END

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	SUBROUTINE RSTART(IF,IT)		RSTART
		REV IV 07/24/86	SLIP
C	THE FIVE FUNCTIONS OF SUBROUTINE RSTART ARE:		RSTART
C	1. READ INPUT & INITIALIZATION RECORD FROM OLD RESTART TAPE.		RSTART
C	2. WRITE INPUT & INITIALIZATION RECORD ONTO NEW RESTART TAPE.		RSTART
C	3. READ TIME POINT RECORD FROM OLD RESTART TAPE.		RSTART
C	4. READ NEW INPUT DATA FROM INPUT STREAM FOR RESTART.		RSTART
C	5. WRITE TIME POINT RECORD ONTO NEW RESTART TAPE.		RSTART
C			RSTART
	IMPLICIT REAL*8(A-H,O-Z)		RSTART
C			RSTART
C	ALL LABELED COMMON BLOCKS ARE INCLUDED HERE		RSTART
C	TO GIVE A COMPLETE SET FOR REFERENCE		RSTART
C 1	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		RSTART
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJMTF,NPRT(36),NPG		PAGE
	DIMENSION IC1(51)		PAGE
	EQUIVALENCE (IC1(1),NSEG)		RSTART
C 2	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)		RSTART
	DIMENSION RC2(1888)		EDGE
	EQUIVALENCE (RC2(1),PL(1,1))		EDGE
C 3	COMMON/VPOSTN/ ZPLT(3),SPLT(3),AXV(3,6),VATAB(6,501,6),		RSTART
	* VT0(6),VDT(6),TIMEV(6),OMEGV(6),NVTAB(6),INDXV(6)		VEHICL
	DIMENSION RC3(18084),IC3(12)		RSTART
	EQUIVALENCE (RC3(1),ZPLT(1)),(IC3(1),NVTAB(1))		VEHICL
C 4	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		RSTART
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		RSTART
	DIMENSION RC4(900)		RSTART
	EQUIVALENCE (RC4(1),D(1,1,1))		RSTART
C 5	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		RSTART
	* F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	DIMENSION RC5A(1296),RC5B(480)		SLIP
	EQUIVALENCE (RC5A(1),V1(1,1)),(RC5B(1),F(1,1))		RSTART
C 6	COMMON/ABDATA/ ZDEP(3,5),DBR(3,3,5),DPVCTR(3,5),DEPLOY(3,5),		RSTART
	* AB(3,5),B(9,4,5),ZR(3,4,5),BFB(3,4,5),DRR(9,4,5),		RSTART
	* VBAGG(5),VSCS(5),SPRK(5),CK(5),CMASS(5),CYMIN(5),		RSTART
	* CYMOUT(5),BAGPV(5),PD(5),VBAG(5),VOLBP(5),		RSTART
	* PCYV(5),PCYMIN(5),PVBAG(5),TV1(3,4,5),TV2(3,10,5),		RSTART
	* SWITCH(5),PYMOUT(5),SCALE(5),PREVT,IFULL(6)		RSTART
	DIMENSION RC6A(610),RC6B(271)		RSTART
	EQUIVALENCE (RC6A(1),ZDEP(1,1)),(RC6B(1),CYMIN(1))		RSTART
C 7	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),		RSTART
	* BLTTTL(5,8),PLTTTL(5,30),BAGTTL(5,6),SEG(30),		RSTART
	* JOINT(30),CGS(30),JS(30)		RSTART



	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT	RSTART
	LOGICAL*1 CGS,JS	RSTART
	REAL RC7,RC7A,XDTE,XCMENT	RSTART
	DIMENSION RC7(305),RC7A(348),XDTE(3),XCMENT(40)	RSTART
	EQUIVALENCE (RC7(1),VPSTTL(1)),(RC7A(1),DATE(1))	RSTART
C 8	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	RSTART
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
	DIMENSION RC8(35)	TWOPI
	EQUIVALENCE (RC8(1),PI)	RSTART
C 9	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),	RSTART
	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),	SLIP
	* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)	RSTART
	DIMENSION RC9(2460),IC9(150)	RSTART
	EQUIVALENCE (RC9(1),PHI(1,1)),(IC9(1),JNT(1))	SLIP
C 10	COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),	RSTART
	* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),	RSTART
	* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)	RSTART
	DIMENSION IC10(1614)	RSTART
	EQUIVALENCE (IC10(1),MNPL(1))	RSTART
C 11	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),	RSTART
	* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF	NCFORC
	DIMENSION RC11(1240),IC11(9)	RSTART
	EQUIVALENCE (RC11(1),PSF(1,1)),(IC11(1),NPANEL(1))	NCFORC
C 12	COMMON/INTEST/ SGTEST(3,4,30),XTEST(3,120),SEGT(120),REGT(120)	RSTART
	REAL SEGT	RSTART
	DIMENSION RC12(720)	RSTART
	EQUIVALENCE (RC12(1),SGTEST(1,1,1))	RSTART
C 13	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),	RSTART
	* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),	RSTART
	* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),	RSTART
	* KQ1(12),KQ2(12),KQTYPE(12)	RSTART
	DIMENSION RC13(72),IC13(36),RC13A(1212),RC13H(348)	RSTART
	EQUIVALENCE (RC13(1),RK1(1,1)),(IC13(1),KQ1(1)),	RSTART
	* (RC13A(1),A13(1,1,1)),(RC13H(1),HHT(1,1,1))	RSTART
C 14	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	RSTART
	DIMENSION IC14(1304)	DIMENB
	EQUIVALENCE (IC14(1),MXNTI)	BUTLER2
C 15	COMMON/COMAIN/VAR(240),DER(240),DT,H0,HMAX,HMIN,RSTIME,	RSTART
	* ISTEP,NSTEPS,NDINT,NEQ,IRSIN,IRSOUT	RSTART
	DIMENSION RC15(485),IC15(6)	RSTART
	EQUIVALENCE (RC15(1),VAR(1)),(IC15(1),ISTEP)	RSTART
C 16		RSTART

	COMMON/CDINT/ UU(4),GH(3,4),	RSTART
	* E(3,240),FF(5,240),GG(5,240),Y(5,240),U(5,240),	RSTART
	* H,HPRINT,HS,TPRINT,TSTART,ICNT,IDBL,IFLAG	RSTART
C	NOTE: FF REPLACES F FROM SUBROUTINE DINT.	RSTART
	DIMENSION RC16(5541),IC16(3)	RSTART
	EQUIVALENCE (RC16(1),UU(1)),(IC16(1),ICNT)	RSTART
C 17	COMMON/DAMPER/ APSDM(3,20),APSDN(3,20),ASD(5,20),MSDM(20),MSDN(20)	RSTART
	DIMENSION RC17(220),IC17(40)	RSTART
	EQUIVALENCE (RC17(1),APSDM(1,1)),(IC17(1),MSDM(1))	RSTART
C 18	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),	JDRIFT
	* FE(3,30),TQE(3,30),CONST(5,30)	JDRIFT
	DIMENSION RC18(1320)	JDRIFT
	EQUIVALENCE (RC18(1),HIR(1,1,1))	RSTART
C 19	COMMON/TEMPVI/ CREST,TTI(3),RII(3),R2I(3),JSTOP(4,2,30)	RSTART
	DIMENSION RC19(10),IC19(180)	RSTART
	EQUIVALENCE (RC19(1),CREST),(IC19(1),JSTOP(1,1,1))	RSTART
C 20	COMMON/CYDATA/ CYTD(5),CYPA(5),CYSP(5),CYT0(5),CYV0(5),CYCD(5),	RSTART
	* CYK(5),CYR(5),CYAT(5),CYPV(5),CYCD0(5),CYA0(5),	RSTART
	* CYP0(5),CYSS(5),CYL0(5),CYC(5),CYRHO0(5),CYVMAX(5),	RSTART
	* CYORFC(5),CYRHO(5),CYT(5),CYP(5),CYV(5)	RSTART
	DIMENSION RC20A(95),RC20B(20)	RSTART
	EQUIVALENCE (RC20A(1),CYTD(1)),(RC20B(1),CYRHO(1))	RSTART
C 21	COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),	ATBIII
	* NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)	TTHKREF
	DIMENSION RC21(450),IC21(520)	TTHKREF
	EQUIVALENCE (RC21(1),XSG(1,1,1)),(IC21(1),LPMI(1))	RSTART
C 22	COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)	RSTART
	DIMENSION RC22(624),IC22(24)	RSTART
	EQUIVALENCE (RC22(1),HF(1,1,1)),(IC22(1),NFLEX(1,1))	RSTART
C 23	COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),	RSTART
	* XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),	RSTART
	* NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)	RSTART
	DIMENSION RC23(1922),IC23(765)	RSTART
	EQUIVALENCE (RC23(1),BAR(1,1)),(IC23(1),IBAR(1,1))	RSTART
C 24	COMMON/WINDFR/ WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30),	WINDOP
	* MWSEG(7,30),NFVSEG(6),NFVNT(5),MOWSEG(30,30)	WINDOP
	DIMENSION RC24(150),IC24(1151)	WINDOP
	EQUIVALENCE (RC24(1),WTIME(1)),(IC24(1),IWIND(1))	RSTART
C	REAL AOLD4,AAOLD4	RSTART
	DIMENSION COMMON(24),INDEX(3)	RSTART
	DATA COMMON /8HCONTRL ,8HCWTSRF ,8HVPOSTN ,8HSGMNTS ,	RSTART

*	8HCMATRX	,8HABDATA	,8HTITLES	,8HCNSNTS	.	RSTART
*	8HDESCRP	,8HJBARTZ	,8HFORCES	,8HINTEST	.	RSTART
*	8HCSTRNT	,8HTABLES	,8HCOMAIN	,8HCDINT	.	RSTART
*	8HDAMPER	,8HCEULER	,8HTEMPVI	,8HCYDATA	.	RSTART
*	8HRSAVE	,8HFLXBLE	,8HHRNESS	,8HWINDFR	/	RSTART
	DATA BLANK/8H	/				RSTART
	CALL ELTIME(1,25)					RSTART
	GO TO (100,200,300,400,500),IF					RSTART
C						RSTART
C	1. READ INPUT & INITIALIZATION RECORD FROM OLD RESTART TAPE.					RSTART
C						RSTART
	100 READ (IT) IC1, PL, RC3, IC3, NSYM, RC6A, IFULL, XDTE, XCMENr,					RSTART
	* RC7, CGS, JS, RC8, RC9, IC9, IC10, NPANEL, SGTEST,					RSTART
	* RC13, IC13, IC14, DT, H0, HMAX, HMIN, NSTEPS, NDINT,					RSTART
	* RC17, IC17, IEULER, IC19, RC20A, RC21, IC21, HF, IC22,					RSTART
	* RC23, IC23, RC24, IC24					RSTART
	WRITE (6,101) IT,XDTE,XCMENr					RSTART
	101 FORMAT('0 INPUT DATA HAS BEEN READ IN FROM UNIT NO.',I4//					RSTART
	* 10X,3A4//10X,20A4/10X,20A4)					RSTART
	GO TO 999					RSTART
C						RSTART
C	2. WRITE INPUT & INITIALIZATION RECORD ONTO NEW RESTART TAPE.					RSTART
C						RSTART
	200 WRITE (IT) IC1, PL, RC3, IC3, NSYM, RC6A, IFULL, DATE, COMENr,					RSTART
	* RC7, CGS, JS, RC8, RC9, IC9, IC10, NPANEL, SGTEST,					RSTART
	* RC13, IC13, IC14, DT, H0, HMAX, HMIN, NSTEPS, NDINT,					RSTART
	* RC17, IC17, IEULER, IC19, RC20A, RC21, IC21, HF, IC22,					RSTART
	* RC23, IC23, RC24, IC24					RSTART
	GO TO 999					RSTART
C						RSTART
C	3. READ TIME POINT RECORD FROM OLD RESTART TAPE.					RSTART
C						RSTART
	300 READ (IT) TIME, BELT, TPTS, BD, RC4, RC5B, RC6B, IFULL, IPIN,					RSTART
	* RC11, IC11, XTEST, SEGT, REGT, RC13H, KQTYPE, TAB,					RSTART
	* VAR, DER, NEQ, RC16, IC16, IEULER, RC18, IC19, RC20B,					RSTART
	* RC21, IC21, V4, RC23, NL, NPTPLY, WTIME, IWIND					RSTART
	CALL OUTPUT(1)					RSTART
	GO TO 999					RSTART
C						RSTART
C	5. WRITE TIME POINT RECORD ONTO NEW RESTART TAPE.					RSTART
C						RSTART
	500 WRITE (IT) TIME, BELT, TPTS, BD, RC4, RC5B, RC6B, IFULL, IPIN,					RSTART
	* RC11, IC11, XTEST, SEGT, REGT, RC13H, KQTYPE, TAB,					RSTART
	* VAR, DER, NEQ, RC16, IC16, IEULER, RC18, IC19, RC20B,					RSTART
	* RC21, IC21, V4, RC23, NL, NPTPLY, WTIME, IWIND					RSTART
	GO TO 999					RSTART
C						RSTART
C	4. READ NEW INPUT DATA FROM INPUT STREAM FOR RESTART.					RSTART
C						RSTART
	400 READ (5,399) AVAR,INDEX,ITYPE,RR,II,AA,RROLD,IIOLD,AAOLD					RSTART

399	FORMAT(A8,4I4,2(F8.0,I8,A8))	RSTART
	CALL SEARCH(AVAR,INDEX,NCOM,ITEM)	RSTART
	IF (NCOM.LE.0) GO TO 490	RSTART
	IF (NCOM.GT.24) GO TO 999	RSTART
	IF (ITYPE.GT.3) GO TO 490	RSTART
	GO TO ( 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12,	RSTART
	* 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24) , NCOM	RSTART
C	COMMON /CONTRL/	RSTART
1	IF (ITEM.GT.1) GO TO 401	RSTART
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = TIME	RSTART
	TIME = RR	RSTART
	GO TO 492	RSTART
401	IF (ITEM.GT.52) GO TO 490	PAGE
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IC1(ITEM-1)	RSTART
	IC1(ITEM-1) = II	RSTART
	GO TO 494	RSTART
C	COMMON /CNTSRF/	RSTART
2	IF (ITEM.GT.1888) GO TO 490	EDGE
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC2(ITEM)	RSTART
	RC2(ITEM) = RR	RSTART
	GO TO 492	RSTART
C	COMMON /VPOSTN/	RSTART
3	IF (ITEM.GT.18084) GO TO 403	VEHICL
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC3(ITEM)	RSTART
	RC3(ITEM) = RR	RSTART
	GO TO 492	RSTART
403	IF (ITEM.GT.18096) GO TO 490	VEHICL
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IC3(ITEM-18084)	VEHICL
	IC3(ITEM-18084) = II	VEHICL
	GO TO 494	RSTART
C	COMMON /SGMNTS/	RSTART
4	IF (ITEM.GT.900 ) GO TO 404	RSTART
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC4(ITEM)	RSTART
	RC4(ITEM) = RR	RSTART
	GO TO 492	RSTART
404	IF (ITEM.GT.930 ) GO TO 490	RSTART
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = NSYM(ITEM-900)	RSTART
	NSYM(ITEM-900) = II	RSTART
	GO TO 494	RSTART
C	COMMON /CMATRX/	RSTART
5	IF (ITEM.GT.1776) GO TO 490	SLIP
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC5A(ITEM)	RSTART











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[illegible]

	SUBROUTINE SEARCH(AVAR,INDEX,NCOM,ITEM)	REV IV 07/24/86	SEARCH
C			SLIP
C	CALL BY SUBROUTINE RSTART TO COMPUTE NCOM & ITEM FROM AVAR &		SEARCH
C	INDEX. RETURNS NCOM=0 FOR ERROR AND NCOM=50 FOR BLANK.		SEARCH
C			SEARCH
	IMPLICIT REAL*8(A-H,O-Z)		SEARCH
	DIMENSION BVAR(264),KOUNT(25),NDIM(3,264),NJ(3),NK(3),INDEX(3)		SLIP
	DIMENSION C1 ( 17) , NC1 ( 51)		PAGE
	DIMENSION C2 ( 4) , NC2 ( 12)		SEARCH
	DIMENSION C3 ( 10) , NC3 ( 30)		SEARCH
	DIMENSION C4 ( 9) , NC4 ( 27)		SEARCH
	DIMENSION C5 ( 9) , NC5 ( 27)		SLIP
	DIMENSION C6 ( 30) , NC6 ( 90)		SEARCH
	DIMENSION C7 ( 11) , NC7 ( 33)		SEARCH
	DIMENSION C8 ( 10) , NC8 ( 30)		TWOPI
	DIMENSION C9 ( 15) , NC9 ( 45)		SEARCH
	DIMENSION C10( 11) , NC10( 33)		SEARCH
	DIMENSION C11( 10) , NC11( 30)		SEARCH
	DIMENSION C12( 4) , NC12( 12)		SEARCH
	DIMENSION C13( 16) , NC13( 48)		SEARCH
	DIMENSION C14( 7) , NC14( 21)		SEARCH
	DIMENSION C15( 13) , NC15( 39)		SEARCH
	DIMENSION C16( 15) , NC16( 45)		SEARCH
	DIMENSION C17( 5) , NC17( 15)		SEARCH
	DIMENSION C18( 7) , NC18( 21)		SEARCH
	DIMENSION C19( 5) , NC19( 15)		SEARCH
	DIMENSION C20( 23) , NC20( 69)		SEARCH
	DIMENSION C21( 8) , NC21( 24)		CHGIII
	DIMENSION C22( 4) , NC22( 12)		SEARCH
	DIMENSION C23( 12) , NC23( 36)		SEARCH
	DIMENSION C24( 9) , NC24( 27)		WINDOP
C			SEARCH
	EQUIVALENCE (C1 (1),BVAR( 1)) , (NC1 (1),NDIM(1, 1))		SEARCH
	EQUIVALENCE (C2 (1),BVAR( 18)) , (NC2 (1),NDIM(1, 18))		PAGE
	EQUIVALENCE (C3 (1),BVAR( 22)) , (NC3 (1),NDIM(1, 22))		PAGE
	EQUIVALENCE (C4 (1),BVAR( 32)) , (NC4 (1),NDIM(1, 32))		PAGE
	EQUIVALENCE (C5 (1),BVAR( 41)) , (NC5 (1),NDIM(1, 41))		PAGE
	EQUIVALENCE (C6 (1),BVAR( 50)) , (NC6 (1),NDIM(1, 50))		SLIP
	EQUIVALENCE (C7 (1),BVAR( 80)) , (NC7 (1),NDIM(1, 80))		SLIP
	EQUIVALENCE (C8 (1),BVAR( 91)) , (NC8 (1),NDIM(1, 91))		SLIP
	EQUIVALENCE (C9 (1),BVAR(101)) , (NC9 (1),NDIM(1,101))		SLIP
	EQUIVALENCE (C10(1),BVAR(116)) , (NC10(1),NDIM(1,116))		SLIP
	EQUIVALENCE (C11(1),BVAR(127)) , (NC11(1),NDIM(1,127))		SLIP
	EQUIVALENCE (C12(1),BVAR(137)) , (NC12(1),NDIM(1,137))		SLIP
	EQUIVALENCE (C13(1),BVAR(141)) , (NC13(1),NDIM(1,141))		SLIP
	EQUIVALENCE (C14(1),BVAR(157)) , (NC14(1),NDIM(1,157))		SLIP
	EQUIVALENCE (C15(1),BVAR(164)) , (NC15(1),NDIM(1,164))		SLIP
	EQUIVALENCE (C16(1),BVAR(177)) , (NC16(1),NDIM(1,177))		SLIP
	EQUIVALENCE (C17(1),BVAR(192)) , (NC17(1),NDIM(1,192))		SLIP
	EQUIVALENCE (C18(1),BVAR(197)) , (NC18(1),NDIM(1,197))		SLIP

	EQUIVALENCE (C19(1),BVAR(204)) , (NC19(1),NDIM(1,204))	SLIP
	EQUIVALENCE (C20(1),BVAR(209)) , (NC20(1),NDIM(1,209))	SLIP
	EQUIVALENCE (C21(1),BVAR(232)) , (NC21(1),NDIM(1,232))	SLIP
	EQUIVALENCE (C22(1),BVAR(240)) , (NC22(1),NDIM(1,240))	SLIP
	EQUIVALENCE (C23(1),BVAR(244)) , (NC23(1),NDIM(1,244))	SLIP
	EQUIVALENCE (C24(1),BVAR(256)) , (NC24(1),NDIM(1,256))	SLIP
C		SEARCH
	DATA NVAR/264/ , KOM/24/ , BLANK/8H /	SLIP
	DATA KOUNT/1,18,22,32,41,50,80,91,101,116,127,137,141,157,	SLIP
	* 164,177,192,197,204,209,232,240,244,256,265/	SLIP
C		SEARCH
C	1 COMMON/CONTRL/	SEARCH
C		SEARCH
	DATA C1 / 8HTIME ,8HNSEG ,8HNJNT ,8HNPL ,8HNBLT ,	SEARCH
	* 8HNBAG ,8HNVEH ,8HNGRND ,8HNS ,8HNQ ,	SEARCH
	* 8HNSD ,8HNFLX ,8HNNRNS ,8HNWINDF ,8HNJNTF ,	SEARCH
	* 8HNPRT ,8HNP /	PAGE
	DATA NC1 / 0,0,0 , 0,0,0 , 0,0,0 , 0,0,0 , 0,0,0 ,	SEARCH
	* 0,0,0 , 0,0,0 , 0,0,0 , 0,0,0 , 0,0,0 ,	SEARCH
	* 0,0,0 , 0,0,0 , 0,0,0 , 0,0,0 , 0,0,0 ,	SEARCH
	* 36,0,0 , 0,0,0 /	PAGE
C		SEARCH
C	2 COMMON/CNTRF/	SEARCH
C		SEARCH
	DATA C2 / 8HPL ,8HBELT ,8HTPTS ,8HBD /	SEARCH
	DATA NC2 / 24,30,0 , 20,8,0 , 6,8,0 , 24,40,0 /	EDGE
C		SEARCH
C	3 COMMON/VPOSTN/	SEARCH
C		SEARCH
	DATA C3 / 8HZPLT ,8HSPLT ,8HAXV ,8HVATAB ,8HVTO ,	SEARCH
	* 8HVDT ,8HTIMEV ,8HOMEGV ,8HNVTAB ,8HINDXV /	SEARCH
	DATA NC3 / 3,0,0 , 3,0,0 , 3,6,0 , 6,501,6 , 6,0,0 ,	VEHICL
	* 6,0,0 , 6,0,0 , 6,0,0 , 6,0,0 , 6,0,0 /	SEARCH
C		SEARCH
C	4 COMMON/SGMNTS/	SEARCH
C		SEARCH
	DATA C4 / 8HD ,8HWMEG ,8HWMEGD ,8HU1 ,8HU2 ,	SEARCH
	* 8HSEGLP ,8HSEGLV ,8HSEGLA ,8HNSYM /	SEARCH
	DATA NC4 / 3,3,30 , 3,30,0 , 3,30,0 , 3,30,0 , 3,30,0 ,	SEARCH
	* 3,30,0 , 3,30,0 , 3,30,0 , 30,0,0 /	SEARCH
C		SEARCH
C	5 COMMON/CMATRX/	SEARCH
C		SEARCH
	DATA C5 / 8HV1 ,8HV2 ,8HV3 ,8HB12 ,8HA22 ,	SEARCH
	* 8HF ,8HTQ ,8HWJ ,8HA11 /	SLIP
	DATA NC5 / 3,30,0 , 3,30,0 , 3,12,0 , 3,3,60 , 3,3,60 ,	SEARCH
	* 3,30,0 , 3,30,0 , 30,0,0 , 3,3,60 /	SLIP
C		SEARCH
C	6 COMMON/ABDATA/	SEARCH
C		SEARCH

	DATA C6 /	8HZDEP	,8HDBR	,8HDPVCTR	,8HDEPLOY	,8HAB	, SEARCH
	*	8HB	,8HZR	,8HBFB	,8HDDR	,8HVBAGG	, SEARCH
	*	8HVSCS	,8HSPRK	,8HCK	,8HCMASS	,8HCYMIN	, SEARCH
	*	8HCYMOUT	,8HBAGPV	,8HPD	,8HVBAG	,8HVOLBP	, SEARCH
	*	8HPCYV	,8HPCYMIN	,8HPVBAG	,8HTV1	,8HTV2	, SEARCH
	*	8H SWITCH	,8HPYMOUT	,8HSCALE	,8HPREVT	,8HIFULL	/ SEARCH
	DATA NC6 /	3,5,0	, 3,3,5	, 3,5,0	, 3,5,0	, 3,5,0	, SEARCH
	*	9,4,5	, 3,4,5	, 3,4,5	, 9,4,5	, 5,0,0	, SEARCH
	*	5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, SEARCH
	*	5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, SEARCH
	*	5,0,0	, 5,0,0	, 5,0,0	, 3,4,5	, 3,10,5	, SEARCH
	*	5,0,0	, 5,0,0	, 5,0,0	, 0,0,0	, 6,0,0	/ SEARCH
C							SEARCH
C	7	COMMON/TITLES/					SEARCH
C							SEARCH
	DATA C7 /	8HDATE	,8HCOMMENT	,8HVPSTTL	,8HBDYTTL	,8HBLTTTL	, SEARCH
	*	8HPLTTL	,8HBAGTTL	,8HSEG	,8HJOINT	,8HCGS	, SEARCH
	*	8HJS	/				SEARCH
	DATA NC7 /	3,0,0	, 40,0,0	, 20,0,0	, 5,0,0	, 5,8,0	, SEARCH
	*	5,30,0	, 5,6,0	, 30,0,0	, 30,0,0	, 30,0,0	, SEARCH
	*	30,0,0	/				SEARCH
C							SEARCH
C	8	COMMON/CNSNTS/					SEARCH
C							SEARCH
	DATA C8 /	8HPI	,8HRADIAN	,8HG	,8HTHIRD	,8HEPS	, SEARCH
	*	8HUNITL	,8HUNITM	,8HUNITT	,8HGRAVITY	,8HTWOPI	/ TWOPI
	DATA NC8 /	0,0,0	, 0,0,0	, 0,0,0	, 0,0,0	, 24,0,0	, SEARCH
	*	0,0,0	, 0,0,0	, 0,0,0	, 3,0,0	, 0,0,0	/ TWOPI
C							SEARCH
C	9	COMMON/DESCRP/					SEARCH
C							SEARCH
	DATA C9 /	8HPHI	,8HW	,8HRW	,8HSR	,8HHA	, SEARCH
	*	8HHB	,8HRPHI	,8HHT	,8HSPRING	,8HVIS	, SEARCH
	*	8HJNT	,8HJPIN	,8HJSING	,8HJGLOB	,8HJOINTF	/ SEARCH
	DATA NC9 /	3,30,0	, 30,0,0	, 30,0,0	, 4,60,0	, 3,60,0	, SLIP
	*	3,60,0	, 3,30,0	, 3,3,60	, 5,90,0	, 7,90,0	, SEARCH
	*	30,0,0	, 30,0,0	, 30,0,0	, 30,0,0	, 30,0,0	/ SEARCH
C							SEARCH
C	10	COMMON/JBARTZ/					SEARCH
C							SEARCH
	DATA C10/	8HMNPL	,8HMNBTL	,8HMNSEG	,8HMNBAG	,8HMPL	, SEARCH
	*	8HMBLT	,8HMSEG	,8HMBAG	,8HNTPL	,8HNTBLT	, SEARCH
	*	8HNTSEG	/				SEARCH
	DATA NC10/	30,0,0	, 8,0,0	, 30,0,0	, 6,0,0	, 3,5,30	, SEARCH
	*	3,5,8	, 3,5,30	, 3,10,6	, 5,30,0	, 5,8,0	, SEARCH
	*	5,30,0	/				SEARCH
C							SEARCH
C	11	COMMON/FORCES/					SEARCH
C							SEARCH
	DATA C11/	8HPSF	,8HBSF	,8HSSF	,8HBAGSF	,8HPRJNT	, SEARCH

	*	8HNPANEL	,8HNPSF	,8HNBSF	,8HNSSF	,8HNBGSF	/	SEARCH
		DATA NC11/	7,70,0	, 4,20,0	, 10,40,0	, 3,20,0	, 7,30,0	, NCFORC
	*		5,0,0	, 0,0,0	, 0,0,0	, 0,0,0	, 0,0,0	/ SEARCH
C								SEARCH
C	12	COMMON/INTEST/						SEARCH
C								SEARCH
		DATA C12/	8HSGTEST	,8HXTEST	,8HSEGT	,8HREGT	/	SEARCH
		DATA NC12/	3,4,30	, 3,120,0	, 120,0,0	, 120,0,0	/	SEARCH
C								SEARCH
C	13	COMMON/CSTRNT/						SEARCH
C								SEARCH
		DATA C13/	8HA13	,8HA23	,8HB31	,8HB32	,8HHHT	, SEARCH
	*		8HRK1	,8HRK2	,8HQQ	,8HTQQ	,8HRQQ	, SEARCH
	*		8HHQQ	,8HSQQ	,8HCFQQ	,8HKQ1	,8HKQ2	, SEARCH
	*		8HKQTYPE	/				SEARCH
		DATA NC13/	3,3,24	, 3,3,24	, 3,3,24	, 3,3,24	, 3,3,12	, SEARCH
	*		3,12,0	, 3,12,0	, 3,12,0	, 3,12,0	, 3,12,0	, SEARCH
	*		3,12,0	, 12,0,0	, 12,0,0	, 12,0,0	, 12,0,0	, SEARCH
	*		12,0,0	/				SEARCH
C								SEARCH
C	14	COMMON/TABLES/						SEARCH
C								SEARCH
		DATA C14/	8HMXNTI	,8HMXNTB	,8HMXTB1	,8HMXTB2	,8HNTI	, SEARCH
	*		8HNTAB	,8HTAB	/			SEARCH
		DATA NC14/	0,0,0	, 0,0,0	, 0,0,0	, 0,0,0	, 50,0,0	, SEARCH
	*		1250,0,0	, 4500,0,0/				BUTLER2
C								SEARCH
C	15	COMMON/COMAIN/						SEARCH
C								SEARCH
		DATA C15/	8HVAR	,8HDER	,8HDT	,8HHO	,8HHMAX	, SEARCH
	*		8HHMIN	,8HRSTIME	,8HISTEP	,8HNSTEPS	,8HNDINT	, SEARCH
	*		8HNEQ	,8HIRSIN	,8HIRSOUT	/		SEARCH
		DATA NC15/	240,0,0	, 240,0,0	, 0,0,0	, 0,0,0	, 0,0,0	, SEARCH
	*		0,0,0	, 0,0,0	, 0,0,0	, 0,0,0	, 0,0,0	, SEARCH
	*		0,0,0	, 0,0,0	, 0,0,0	/		SEARCH
C								SEARCH
C	16	COMMON/CDINT /						SEARCH
C								SEARCH
		DATA C16/	8HUU	,8HGH	,8HE	,8HFF	,8HGG	, SEARCH
	*		8HY	,8HU	,8HH	,8HHPRINT	,8HHS	, SEARCH
	*		8HTPRINT	,8HTSTART	,8HICNT	,8HIDBL	,8HIFLAG	/ SEARCH
		DATA NC16/	4,0,0	, 3,4,0	, 3,240,0	, 5,240,0	, 5,240,0	, SEARCH
	*		5,240,0	, 5,240,0	, 0,0,0	, 0,0,0	, 0,0,0	, SEARCH
	*		0,0,0	, 0,0,0	, 0,0,0	, 0,0,0	, 0,0,0	/ SEARCH
C								SEARCH
C	17	COMMON/DAMPER/						SEARCH
C								SEARCH
		DATA C17/	8HAPSDM	,8HAPSDN	,8HASD	,8HMSDM	,8HMSDN	/ SEARCH
		DATA NC17/	3,20,0	, 3,20,0	, 5,20,0	, 20,0,0	, 20,0,0	/ SEARCH
C								SEARCH

C 18	COMMON/CEULER/						SEARCH
C							SEARCH
	DATA C18/ 8HIEULER	,8HHIR	,8HANG	,8HANGD	,8HFE		SEARCH
	* 8HTQE	,8HCONST	/				SEARCH
	DATA NC18/ 30,0,0	, 3,3,90	, 3,30,0	, 3,30,0	, 3,30,0		JDRIFT
	* 3,30,0	, 5,30,0	/				JDRIFT
C							SEARCH
C 19	COMMON/TEMPVI/						SEARCH
C							SEARCH
	DATA C19/ 8HCREST	,8HTTI	,8HR1I	,8HR2I	,8HJSTOP	/	SEARCH
	DATA NC19/ 0,0,0	, 3,0,0	, 3,0,0	, 3,0,0	, 4,2,30	/	SEARCH
C							SEARCH
C 20	COMMON/CYDATA/						SEARCH
C							SEARCH
	DATA C20/ 8HCYTD	,8HCYPA	,8HCYSP	,8HCYT0	,8HCYV0		SEARCH
	* 8HCYCD	,8HCYK	,8HCYR	,8HCYAT	,8HCYPV		SEARCH
	* 8HCYCD0	,8HCYAO	,8HCYPO	,8HCYSS	,8HCYL0		SEARCH
	* 8HCYC	,8HCYRHO0	,8HCYVMAX	,8HCYORFC	,8HCYRHO		SEARCH
	* 8HCYT	,8HCYRHP	,8HCYV	/			SEARCH
	DATA NC20/ 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0		SEARCH
	* 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0		SEARCH
	* 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0		SEARCH
	* 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0		SEARCH
	* 5,0,0	, 5,0,0	, 5,0,0	/			SEARCH
C							SEARCH
C 21	COMMON/RSAGE/						SEARCH
C							SEARCH
	DATA C21/ 8HXSG	,8HDPMI	,8HLPMI	,8HNSG	,8HMSG		SEARCH
	* 8HMC	,8HMCIN	,8HKREF	/			CHGIII
	DATA NC21/ 3,20,3	, 3,3,30	, 30,0,0	, 9,0,0	, 20,9,0		WINDOP
	* 1,0,0	, 24,5,0	, 20,9,0	/			TTHKREF
C							SEARCH
C 22	COMMON/FLXBLE/						SEARCH
C							SEARCH
	DATA C22/ 8HHF	,8HB42	,8HV4	,8HNFLEX	/		SEARCH
	DATA NC22/ 4,12,8	, 3,3,24	, 3,8,0	, 3,8,0	/		SEARCH
C							SEARCH
C 23	COMMON/HRNESS/						SEARCH
C							SEARCH
	DATA C23/ 8HBAR	,8HBB	,8HBBDOT	,8HPLOSS	,8HXLONG		SEARCH
	* 8HHTIME	,8HIBAR	,8HNL	,8HNPTSPB	,8HNPTPLY		SEARCH
	* 8HNTHRNS	,8HNBLTPH	/				SEARCH
	DATA NC23/ 15,100,0	, 100,0,0	, 100,0,0	, 2,100,0	, 20,0,0		SEARCH
	* 2,0,0	, 5,100,0	, 2,100,0	, 20,0,0	, 20,0,0		SEARCH
	* 20,0,0	, 5,0,0	/				SEARCH
C							SEARCH
C 24	COMMON/WINDFR/						SEARCH
	DATA C24/ 8HWTIME	,8HQFU	,8HQFV	,8HWF	,8HIWIND		WINDOP
	* 8HMWSEG	,8HNFVSEG	,8HNFVNT	,8HMOWSEG	/		WINDOP
	DATA NC24/ 30,0,0	, 3, 5,0	, 3, 5,0	, 3,30,0	, 30,0,0		WINDOP

	*            7,30,0   ,   6,0,0   ,   5,0,0   ,   30,30,0 /	WINDOP
	NCOM = 50	SEARCH
	IF (AVAR.EQ.BLANK) GO TO 99	SEARCH
C		SEARCH
C	SEARCH FOR VARIABLE NO. IV.	SEARCH
C		SEARCH
	NCOM = 0	SEARCH
	DO 10 IV=1,NVAR	SEARCH
	IF (AVAR.EQ.BVAR(IV)) GO TO 12	SEARCH
10	CONTINUE	SEARCH
	GO TO 99	SEARCH
C		SEARCH
C	SEARCH FOR COMMON NO. IC.	SEARCH
C		SEARCH
12	DO 20 IC=1,KOM	SEARCH
	IF (IV.GE.KOUNT(IC).AND.IV.LT.KOUNT(IC+1)) GO TO 22	SEARCH
20	CONTINUE	SEARCH
	GO TO 99	SEARCH
C		SEARCH
C	COMPUTE ITEM NO. FOR VARIABLE IV IN COMMON IC.	SEARCH
C		SEARCH
22	K1 = KOUNT(IC)	SEARCH
	K2 = IV-1	SEARCH
	ITEM = 1	SEARCH
	IF (K1.EQ.IV) GO TO 25	SEARCH
	DO 24 K=K1,K2	SEARCH
	NI = 1	SEARCH
	DO 23 I=1,3	SEARCH
	IF (NDIM(I,K).NE.0) NI=NI*NDIM(I,K)	SEARCH
23	CONTINUE	SEARCH
24	ITEM = ITEM+NI	SEARCH
25	DO 26 I=1,3	SEARCH
	IF (INDEX(I).EQ.0 .AND. NDIM(I,IV).NE.0) GO TO 99	SEARCH
	IF (NDIM(I,IV).EQ.0 .AND. INDEX(I).GT.1) GO TO 99	SEARCH
	NJ(I) = MAXO(INDEX(I)-1,0)	SEARCH
	NK(I) = MAXO(NDIM(I,IV),1)	SEARCH
	IF (NJ(I).GE.NK(I)) GO TO 99	SEARCH
26	CONTINUE	SEARCH
	ITEM = ITEM+NJ(1)+NJ(2)*NK(1)+NJ(3)*NK(2)*NK(1)	SEARCH
	NCOM = IC	SEARCH
99	RETURN	SEARCH
	END	SEARCH

	SUBROUTINE SEGSEG(M,MM,N,NS,NT)	REV IV	02/07/87	HYPER
C	IMPLICIT REAL*8(A-H,O-Z)			SEGSEG
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)			SEGSEG
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)			EDGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30)			SEGSEG
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)			SEGSEG
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),			NCFORC
*	PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF			SEGSEG
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),			SEGSEG
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),			SEGSEG
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),			SEGSEG
*	KQ1(12),KQ2(12),KQTYPE(12)			SEGSEG
	COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),			TGMOD7
*	NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)			TGMOD7
	COMMON/TEMPVS/DMNT(3,3),TEMP(3,3),B(3,3),XMN(3),RLN(3),XMM(3),			SEGSEG
*	TM(3),R(3),RM(3),DMNWN(3),RLM(3),RN(3),VMN(3),VR(3),			SEGSEG
*	WNM(3),WCM(3),WCN(3),VREL(3),FFM(3),FR(3),TQM(3),			SEGSEG
*	TQN(3),TQNT(3),T(3),H(3),T1(3),T2(3),RMD(3),RND(3),			SEGSEG
*	TD(3),TT4(3,4),TT5(3,4),T3(3),T4(3),P,AMR,FM,CF,			SEGSEG
*	VRM,VRT,VRTS,VRTEST,TF,ELOSS,MCF,NCF,T5(3),T6(3)			TGMOD7
	CALL ELTIME(1,23)			SEGSEG
C	COMPUTATIONS ARE DONE IN M'S REFERENCE SYSTEM			EDGE
C	NN = IABS(NS)			EDGE
	CALL DOT33(D(1,1,M),D(1,1,N),DMNT)			SEGSEG
	DO 10 I = 1,3			SEGSEG
10	XMN(I) = SEGLP(I,M) - SEGLP(I,N)			SEGSEG
	CALL MAT31(D(1,1,M),XMN,XMM)			SEGSEG
	J = 3			HYPER
	IF(BD(1,NN).LT.0.0)J = 4			HYPER
	CALL MAT31(DMNT,BD(J+1,NN),RLN)			HYPER
	J = 3			HYPER
	IF(BD(1,MM).LT.0.0)J = 4			HYPER
	DO 15 I = 1,3			EDGE
	J = J + 1			HYPER
15	R(I) = RLN(I) - XMM(I) - BD(J,MM)			HYPER
	LT = NTAB(NT)			SEGSEG
	TB = 1.0			EDGE
	IF((BD(1,MM).GT.0.0).AND.(BD(1,NN).GT.0.0))GO TO 20			HYPER
C	NEW HYPERELLIPSOID - AT LEAST ONE SURFACE IS A HYPERELLIPSOID			HYPER
	IF (BD(1,MM).LT.0.0.AND.BD(23,MM).NE.0.0) STOP 23			HYPER
	IF (BD(1,NN).LT.0.0.AND.BD(23,NN).NE.0.0) STOP 23			HYPER
C	A HYPERELLIPSOID MUST HAVE IDENTICAL POWERS.			HYPER
C	IF(NS.LT.0) STOP - INTERIOR INTERSECTION NOT OPERATIONAL			HYPER
	IF(NS.LT.0) STOP 38			HYPER
	IF(TAB(LT+23).LE.1.0) CALL HYEST(BD(1,MM),BD(1,NN),TAB(LT+22))			HYPER
	IF(TAB(LT+23).GT.1.0) CALL HYNTR(BD(1,MM),BD(1,NN),TAB(LT+22))			HYPER
	BET = TAB(LT+23)			HYPER
	IF(BET.GT.1.0)TB = 1.0/BET			HYPER



	GO TO 25	HYPER
C	OLD ELLIPSOIDS	HYPER
	20 IF(NS.LT.0.0)TB = -TB	HYPER
	CALL DOTT33(BD(7,NN),DMNT,TEMP)	EDGE
	CALL MAT33(DMNT,TEMP,B)	EDGE
	CALL INTERS(BD(7,MM),B,R,TB,RM,TAB(LT+22),TM)	SEGSEG
C		EDGE
C		EDGE
C		EDGE
	INTERS SOLVES (CA + B)Z = BR, TB = SQRT(Z.AZ)	EDGE
		EDGE
	25 MCF = NTAB(NT+1)	HYPER
	NCF = -MCF	SEGSEG
	IF(NCF.GT.0)CFQQ(NCF) = -999.	SEGSEG
C		EDGE
C	CHECK FOR INTERSECTION	EDGE
C		EDGE
	IF(TB.GE.1.0)GO TO 75	HYPER
	S1 = 0.0	SEGSEG
	S2 = 0.0	SEGSEG
	DO 30 I = 1,3	HYPER
	RI = R(I)	SEGSEG
	IF(NS.LT.0)RI = RM(I) + TB*(RM(I) - R(I))	SEGSEG
	S1 = S1 + RI**2	SEGSEG
30	S2 = S2 + TM(I)**2	HYPER
	AMR = DSQRT(S2)	SEGSEG
	P = (1.0/TB - 1.0)*DSQRT(S1)	SEGSEG
	J = 3	HYPER
	IF(BD(1,MM).LT.0.0)J = 4	HYPER
	DO 35 I = 1,3	HYPER
	J = J + 1	HYPER
	IF((BD(1,MM).LT.0.0).OR.(BD(1,NN).LT.0.0))RM(I) = TB*RM(I)	HYPER
	TM(I) = -TM(I)/AMR	SEGSEG
	T2(I) = RM(I) - R(I)	SEGSEG
	RN(I) = T2(I) + RLN(I)	SEGSEG
35	RLM(I) = RM(I) + BD(J,MM)	HYPER
	CALL DOT31(DMNT,RN,RLN)	SEGSEG
	CALL PLSEGF(M,N,NT)	SEGSEG
C		EDGE
C	STORE PRINT DATA	EDGE
C		EDGE
	SSF(1,NSSF) = P	SEGSEG
	DO 40 I = 1,3	HYPER
	SSF(I+4,NSSF) = RLM(I)	EDGE
40	SSF(I+7,NSSF) = RLN(I)	HYPER
	IF(LPMI(M).NE.0) CALL DOT31(DPMI(1,1,M),RLM,SSF(5,NSSF))	EDGE
	IF(LPMI(N).NE.0) CALL DOT31(DPMI(1,1,N),RLN,SSF(8,NSSF))	EDGE
	IF(MCF.LT.0)GO TO 45	HYPER
	SSF(2,NSSF) = FM	SEGSEG
	TF2FM2 = TF**2 - FM**2	SEGSEG
	IF(TF2FM2.LT.0.0)TF2FM2 = 0.0	SEGSEG
	SSF(3,NSSF) = DSQRT(TF2FM2)	SEGSEG

	SSF(4,NSSF) = TF	SEGSEG
	GO TO 75	HYPER
C		EDGE
C	ROLL-SLIDE	EDGE
45	DO 50 I = 1,3	HYPER
50	SSF(I+1,NSSF) = T(I)	HYPER
	IF((BD(1,MM).LT.0.0).OR.(BD(1,NN).LT.0.0)) STOP 29	HYPER
	ANR = XDY(TM,B,T2)	SEGSEG
	CALL CROSS(TM,WNM,T2)	SEGSEG
	CALL MAT31(B,VR,T1)	SEGSEG
	TB = TM(1)*T1(1) + TM(2)*T1(2) + TM(3)*T1(3)	EDGE
	DO 60 I = 1,3	HYPER
	DO 55 J = 1,3	HYPER
	K = I + 3*(J+1)	SEGSEG
	TT4(I,J) = BD(K,MM)/AMR + B(I,J)/ANR	SEGSEG
55	TT5(I,J) = TT4(I,J)	HYPER
	TT4(I,4) = T2(I) - (T1(I) - TB*TM(I))/ANR	EDGE
60	TT5(I,4) = TM(I)	HYPER
	CALL DSMSOL(TT4,3,3)	SEGSEG
	CALL DSMSOL(TT5,3,3)	SEGSEG
	S1 = TM(1)*TT4(1,4) + TM(2)*TT4(2,4) + TM(3)*TT4(3,4)	EDGE
	S2 = (TM(1)*TT5(1,4) + TM(2)*TT5(2,4) + TM(3)*TT5(3,4))/S1	EDGE
	DO 65 I = 1,3	HYPER
	RMD(I) = TT4(I,4) - S2*TT5(I,4)	EDGE
65	RND(I) = RND(I) + VR(I)	HYPER
	CALL CROSS(DMNWN,RND,T1)	EDGE
	CALL CROSS(WMEG(1,MM),RMD,T2)	EDGE
	CALL MAT31(B,RND,T3)	EDGE
	CALL CROSS(DMNWN,TM,T4)	EDGE
	S1 = TM(1)*T3(1) + TM(2)*T3(2) + TM(3)*T3(3)	EDGE
	SQQ(NCF) = 0.0	SEGSEG
	DO 70 I = 1,3	HYPER
	T1(I) = T1(I) - T2(I)	EDGE
70	SQQ(NCF)=SQQ(NCF)+TM(I)*T1(I)-VR(I)*(T4(I)+(T3(I)-S1*TM(I))/ANR)	HYPER
	CALL DOT31(D(1,1,M),T1,RQQ(1,NCF))	EDGE
75	CALL ELTIME(2,23)	HYPER
	RETURN	SEGSEG
	END	SEGSEG

	SUBROUTINE SETUP1	SETUP1
		REV IV 07/24/86SLIP
C	FOR KK=1 (BEFORE CONTACT ROUTINE IN DAUX)	SETUP1
C	SET UP INITIAL VALUES OF A2 AND B2 ARRAYS FOR THIS TIME POINT.	SETUP1
C	SET UP INITIAL VALUES OF ARRAYS U1,U2 AND V1.	SETUP1
C		SETUP1
	IMPLICIT REAL*8(A-H,O-Z)	SETUP1
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	SETUP1
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),MPG	PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	SETUP1
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	SETUP1
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),	SLIP
	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),	SETUP1
	* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)	SETUP1
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),	SETUP1
	* F(3,30),TQ(3,30),WJ(30),A11(3,3,30)	SLIP
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),	SLIP
	* FE(3,30),TQE(3,30),CONST(5,30)	SLIP
	COMMON/TEMPVS/T(3),S(3),T1(3),T2(3),T3(3),T4(3),T5(3),T6(3),	SETUP1
	* T7(3),T8(3),T9(3),T10(3),T11(3),T12(3),HH(3),	SETUP1
	* TT1(3,3),TT2(3,3),S1,SQS1,S2,S3,S4,V1T,SR2	SLIP
	DATA IFIRST/1/	SLIP
C		SETUP1
	CALL ELTIME(1,10)	SETUP1
	IF (IFIRST.EQ.0) GO TO 15	SLIP
	IF (NJNT.EQ.0) GO TO 15	SLIP
	DO 10 I = 1,NJNT	SLIP
	DO 10 J = 1,3	SLIP
	DO 8 K = 1,3	SLIP
	8 A11(J,K,I) = 0.0	SLIP
	10 A11(J,J,I) = 1.0	SLIP
	IFIRST = 0	SLIP
	15 DO 20 I=1,NGRND	SLIP
C		SETUP1
C	SET EACH U1N = 0	SETUP1
C		SETUP1
	U1(1,I) = 0.0	SETUP1
	U1(2,I) = 0.0	SETUP1
	U1(3,I) = 0.0	SETUP1
C		SETUP1
C	SET EACH U2N = WNX(PHIN*WN)	SETUP1
C		SETUP1
	U2(1,I) = WMEG(2,I)*WMEG(3,I) * (PHI(2,I)-PHI(3,I))	SETUP1
	U2(2,I) = WMEG(1,I)*WMEG(3,I) * (PHI(3,I)-PHI(1,I))	SETUP1
20	U2(3,I) = WMEG(1,I)*WMEG(2,I) * (PHI(1,I)-PHI(2,I))	SETUP1
	IF (NPRT(11).NE.0) WRITE (6,21) ((U2(I,J),I=1,3),J=1,NSEG)	SETUP1
21	FORMAT(' U2 ARRAY'/(1X,1P9D14.4))	SETUP1
	IF (NJNT.LE.0) GO TO 98	SETUP1
	DO 40 J=1,NJNT	SETUP1
	DO 31 K=1,3	SETUP1

	T1(K) = SR(K,2*J-1)	SLIP
	T2(K) = SR(K,2*J )	SLIP
	IF (IABS(IPIN(J)).LT.5) GO TO 31	SLIP
	IF (IEULER(J).EQ.-1) GO TO 31	SLIP
	T1(K) = T1(K) + SR(4,2*J-1)*HT(K,3,2*J-1)	SLIP
31	V1(K,J) = 0.0	SETUP1
	I = IABS(JNT(J))	SETUP1
	IF (I.LE.0) GO TO 40	SETUP1
C		SETUP1
C	FOR EACH JOINT SET	SETUP1
C	B12(2J-1) = B12(J,I ) = -D(I)' * SR(2J-1) X	SETUP1
C	B12(2J ) = B12(J,J+1) = D(J+1)' * SR(2J) X	SETUP1
C		SETUP1
	B12(1,1,2*J-1) = D(3,1,I)*T1(2) - D(2,1,I)*T1(3)	SLIP
	B12(2,1,2*J-1) = D(3,2,I)*T1(2) - D(2,2,I)*T1(3)	SLIP
	B12(3,1,2*J-1) = D(3,3,I)*T1(2) - D(2,3,I)*T1(3)	SLIP
	B12(1,2,2*J-1) = D(1,1,I)*T1(3) - D(3,1,I)*T1(1)	SLIP
	B12(2,2,2*J-1) = D(1,2,I)*T1(3) - D(3,2,I)*T1(1)	SLIP
	B12(3,2,2*J-1) = D(1,3,I)*T1(3) - D(3,3,I)*T1(1)	SLIP
	B12(1,3,2*J-1) = D(2,1,I)*T1(1) - D(1,1,I)*T1(2)	SLIP
	B12(2,3,2*J-1) = D(2,2,I)*T1(1) - D(1,2,I)*T1(2)	SLIP
	B12(3,3,2*J-1) = D(2,3,I)*T1(1) - D(1,3,I)*T1(2)	SLIP
C		SETUP1
	B12(1,1,2*J ) = D(2,1,J+1)*T2(3) - D(3,1,J+1)*T2(2)	SLIP
	B12(2,1,2*J ) = D(2,2,J+1)*T2(3) - D(3,2,J+1)*T2(2)	SLIP
	B12(3,1,2*J ) = D(2,3,J+1)*T2(3) - D(3,3,J+1)*T2(2)	SLIP
	B12(1,2,2*J ) = D(3,1,J+1)*T2(1) - D(1,1,J+1)*T2(3)	SLIP
	B12(2,2,2*J ) = D(3,2,J+1)*T2(1) - D(1,2,J+1)*T2(3)	SLIP
	B12(3,2,2*J ) = D(3,3,J+1)*T2(1) - D(1,3,J+1)*T2(3)	SLIP
	B12(1,3,2*J ) = D(1,1,J+1)*T2(2) - D(2,1,J+1)*T2(1)	SLIP
	B12(2,3,2*J ) = D(1,2,J+1)*T2(2) - D(2,2,J+1)*T2(1)	SLIP
	B12(3,3,2*J ) = D(1,3,J+1)*T2(2) - D(2,3,J+1)*T2(1)	SLIP
C		SETUP1
C	NOTE THAT FOR EACH JOINT	SETUP1
C	A21(M,N) = B12(N,M)	SETUP1
C		SETUP1
C	FOR EACH JOINT SET	SETUP1
C	V1(J) = -D(I)'*W(I)X( W(I)XSR(2J-1) )	SETUP1
C	+D(J+1)'*W(J+1)X( W(J+1)XSR(2J) )	SETUP1
C		SETUP1
	CALL CROSS(WMEG(1,I),T1,T)	SLIP
	CALL CROSS(WMEG(1,I),T,S)	SETUP1
	CALL DOT31(D(1,1,I),S,V1(1,J))	SETUP1
	CALL CROSS(WMEG(1,J+1),T2,T)	SLIP
	CALL CROSS(WMEG(1,J+1),T,S)	SETUP1
	CALL DOT31(D(1,1,J+1),S,T)	SETUP1
	DO 32 K=1,3	SLIP
32	V1(K,J) = T(K) - V1(K,J)	SLIP
	IF (IABS(IPIN(J)).LT.5) GO TO 40	SLIP
	IF (IEULER(J).EQ.-1) GO TO 40	SLIP

CALL DOT31(D(1,1,I),HT(1,3,2*J-1),T4)	SLIP
CALL CROSS(WMEG(1,I),HT(1,3,2*J-1),T5)	SLIP
CALL DOT31(D(1,1,I),T5,T6)	SLIP
V1T = V1(1,J)*T4(1) + V1(2,J)*T4(2) + V1(3,J)*T4(3)	SLIP
SR2 = 2.0*SR(4,2*J)	SLIP
DO 34 K = 1,3	SLIP
V1(K,J) = V1(K,J) - V1T*T4(K) - SR2*T6(K)	SLIP
S1=T4(1)*B12(1,K,2*J-1)+T4(2)*B12(2,K,2*J-1)+T4(3)*B12(3,K,2*J-1)	SLIP
S2=T4(1)*B12(1,K,2*J) +T4(2)*B12(2,K,2*J) +T4(3)*B12(3,K,2*J)	SLIP
DO 33 L = 1,3	SLIP
A11(K,L,J) = -T4(K)*T4(L)	SLIP
B12(L,K,2*J-1) = B12(L,K,2*J-1) - S1*T4(L)	SLIP
33 B12(L,K,2*J) = B12(L,K,2*J) - S2*T4(L)	SLIP
34 A11(K,K,J) = 1.0 + A11(K,K,J)	SLIP
40 CONTINUE	SETUP1
IF (NPRT(11).NE.0) WRITE (6,41) ((V1(I,J),I=1,3),J=1,NJNT)	SETUP1
41 FORMAT(' V1 ARRAY'/(1X,1P9D14.4))	SETUP1
C IF IPIN(M)=1, SET V2(M)=(WN.HN-WM.HM)DN'WNXHN	SETUP1
C	SETUP1
C	SETUP1
DO 50 J=1,NJNT	SETUP1
DO 43 K=1,3	SETUP1
43 V2(K,J) = 0.0	SETUP1
IF (IPIN(J).LT.1) GO TO 50	SLIP
IF (IPIN(J).GT.1.AND.IPIN(J).LT.6) GOTO 50	SLIP
I = IABS(JNT(J))	SETUP1
CALL CROSS (WMEG(1,I),HB(1,2*J-1),T)	SETUP1
CALL DOT31 (D(1,1,I),T,T1)	SETUP1
C CALL CROSS (WMEG(1,J+1),HB(1,2*J),T)	SETUP1
C CALL DOT31 (D(1,1,J+1),T,T2)	SETUP1
S1 = WMEG(1,I)*HB(1,2*J-1)	SETUP1
* + WMEG(2,I)*HB(2,2*J-1)	SETUP1
* + WMEG(3,I)*HB(3,2*J-1)	SETUP1
S2 = WMEG(1,J+1)*HB(1,2*J)	SETUP1
* + WMEG(2,J+1)*HB(2,2*J)	SETUP1
* + WMEG(3,J+1)*HB(3,2*J)	SETUP1
DO 44 K=1,3	SETUP1
C 44 V2(K,J) = S1*T1(K) - S2*T2(K)	SETUP1
44 V2(K,J) = (S1-S2)*T1(K)	SETUP1
50 CONTINUE	SETUP1
98 CALL ELTIME(2,10)	SETUP1
RETURN	SETUP1
END	SETUP1

	SUBROUTINE SETUP2	REV IV 07/24/86	SLIP
C			SETUP2
C	CALLLED BY DAUX AFTER CONTACT ROUTINES AND BY UPDATE PRIOR TO		SETUP2
C	DAUX TO SET UP A2 ARRAY AND (FOR NQ*0) THE A13,A23 AND V3 ARRAYS.		SETUP2
C			SETUP2
	IMPLICIT REAL*8(A-H,O-Z)		SETUP2
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		SETUP2
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		SETUP2
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		SETUP2
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		SETUP2
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		SETUP2
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		SETUP2
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		SETUP2
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		SETUP2
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		SETUP2
*	KQ1(12),KQ2(12),KQTYPE(12)		SETUP2
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		SETUP2
*	UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	LOGICAL*1 FREE		SLIP
	COMMON/TEMPVS/T(3),S(3),T1(3),T2(3),T3(3),T4(3),T5(3),T6(3),		SETUP2
*	T7(3),T8(3),T9(3),T10(3),T11(3),T12(3),HH(3),		SETUP2
*	TT1(3,3),TT2(3,3),S1,SQS1,S2,S3,S4		SETUP2
*	,WCRM(3),RM(3),WCM(3),WWCM(3),WWM(3),RBA(3),BA		SETUP2
*	,WCRN(3),RN(3),WCN(3),WWCN(3),WWN(3),RBAD(3)		SETUP2
*	,IDUM(14290),FREE(30)		SLIP
C			SETUP2
	CALL ELTIME(1,26)		SETUP2
C			SETUP2
C	COMPUTE A22 ARRAY VIA DHHPIN FOR DAUX2 ROUTINES.		SETUP2
C			SETUP2
	IF (NJNT.EQ.0) GO TO 50		SETUP2
	DO 49 M=1,NJNT		SETUP2
	FREE(M) = .TRUE.		SLIP
	N = IABS(JNT(M))		SETUP2
	IF (N.EQ.0) GO TO 49		SETUP2
	IF (IPIN(M).EQ.0) GOTO 49		SLIP
	IF (IPIN(M).GE.2.AND. IPIN(M).LE.5) GO TO 49		SLIP
	FREE(M) = .FALSE.		SLIP
	CALL DHHPIN(A22(1,1,2*M-1),T,N,M,2*M-1)		SETUP2
	CALL DHHPIN(A22(1,1,2*M),T,M+1,M,2*M)		SETUP2
49	CONTINUE		SETUP2
C			PECONV
C	THIS STATEMENT IS NECESSARY FOR THE PROGRAM TO RUN ON THE		PECONV
C	P&E FORTRAN VII O (REV 4) COMPILER		PECONV
C			PECONV
	NNNET = IPIN(M)		PECONV
C			SETUP2

C	SET UP A13,A23 AND V3 ARRAYS FOR DAUX33.	SETUP2
C		SETUP2
50	IF (NQ.EQ.0) GO TO 98	SETUP2
	DO 70 K=1,NQ	SETUP2
	IF (KQTYPE(K).LT.0) GO TO 70	SETUP2
	IF (KQTYPE(K).EQ.5) GO TO 70	SETUP2
	M = KQ1(K)	SETUP2
	N = KQ2(K)	SETUP2
	IF (KQTYPE(K).EQ.2 .OR. KQTYPE(K).EQ.4) GO TO 53	SETUP2
C		SETUP2
C	FOR KQTYPE = 1 OR 3, SET HHT = I	SETUP2
C		SETUP2
	DO 52 J=1,3	SETUP2
	DO 51 I=1,3	SETUP2
51	HHT(I,J,K) = 0.0	SETUP2
52	HHT(J,J,K) = 1.0	SETUP2
	IF (KQTYPE(K).NE.6) GO TO 61	SETUP2
C		SETUP2
C	FOR KQTYPE=6, SET HHT= I-TT'	SETUP2
C		SETUP2
	DO 60 J=1,3	SETUP2
	DO 60 I=1,3	SETUP2
60	HHT(I,J,K) = HHT(I,J,K) - TQQ(I,K)*TQQ(J,K)	SETUP2
	GO TO 61	SETUP2
53	IF (KQTYPE(K).NE.2) GO TO 56	SETUP2
C		SETUP2
C	FOR KQTYPE=2, COMPUTE HH AND HHT.	SETUP2
C		SETUP2
	CALL DOT31(D(1,1,M),RK1(1,K),T1)	SETUP2
	CALL DOT31(D(1,1,N),RK2(1,K),T2)	SETUP2
	S1 = 0.0	SETUP2
	DO 54 I=1,3	SETUP2
	HH(I) = SEGLP(I,M)+T1(I) - SEGLP(I,N)-T2(I)	SETUP2
54	S1 = S1 + HH(I)**2	SETUP2
	SQS1 = DSQRT(S1)	SETUP2
	DO 55 I=1,3	SETUP2
	HH(I) = HH(I)/SQS1	SETUP2
55	IF (DABS(HH(I)).LE.EPS(12)) HH(I) = 0.0	SETUP2
	CALL DOTT31(HH,HH,HHT(1,1,K))	SETUP2
56	IF (KQTYPE(K).NE.4) GO TO 61	SETUP2
C		SETUP2
C	FOR KQTYPE = 4, SET HHT = HHT	SETUP2
C		SETUP2
	CALL DOTT31(HQQ(1,K),HQQ(1,K),HHT(1,1,K))	SETUP2
C		SETUP2
C	SET A13(2K-1) = HHT	SETUP2
C	AND A13(2K) = -HHT	SETUP2
C		SETUP2
61	DO 62 J=1,3	SETUP2
	DO 62 I=1,3	SETUP2

	A13(I,J,2*K-1) = HHT(I,J,K)	SETUP2
62	A13(I,J,2*K ) = -HHT(I,J,K)	SETUP2
C		SETUP2
C	SET A23(2K-1) = (R1X) (D1) A13(2K-1)	SETUP2
C	AND A23(2K) = (R2X) (D2) A13(2K)	SETUP2
C		SETUP2
	CALL MAT33(D(1,1,M),A13(1,1,2*K-1),TT1)	SETUP2
	CALL MAT33(D(1,1,N),A13(1,1,2*K ),TT2)	SETUP2
	DO 63 J=1,3	SETUP2
	CALL CROSS(RK1(1,K),TT1(1,J),A23(1,J,2*K-1) )	SETUP2
63	CALL CROSS(RK2(1,K),TT2(1,J),A23(1,J,2*K ) )	SETUP2
	IF (KQTYPE(K).EQ.4) GO TO 72	SETUP2
C		SETUP2
C	FOR KQTYPE = 1,2 OR 3, SET B31 = A13' AND B32 = A23'	SETUP2
C		SETUP2
	DO 71 I=1,3	SETUP2
	DO 71 J=1,3	SETUP2
	B31(I,J,2*K-1) = A13(J,I,2*K-1)	SETUP2
	B31(I,J,2*K ) = A13(J,I,2*K )	SETUP2
	B32(I,J,2*K-1) = A23(J,I,2*K-1)	SETUP2
71	B32(I,J,2*K ) = A23(J,I,2*K )	SETUP2
	GO TO 76	SETUP2
C		SETUP2
C	FOR KQTYPE = 4, SET B31(2K-1) = HTT	SETUP2
C	B31(2K ) = -HTT	SETUP2
C	B32 = (B31) (D') (RX) '	SETUP2
C		SETUP2
	72 CALL DOTT31(HQQ(1,K),TQQ(1,K),B31(1,1,2*K-1))	SETUP2
	DO 73 I=1,3	SETUP2
	DO 73 J=1,3	SETUP2
73	B31(I,J,2*K) = -B31(I,J,2*K-1)	SETUP2
	CALL DOTT33(D(1,1,M),B31(1,1,2*K-1),B32(1,1,2*K-1))	SETUP2
	CALL DOTT33(D(1,1,N),B31(1,1,2*K ),B32(1,1,2*K ))	SETUP2
	DO 74 J=1,3	SETUP2
	CALL CROSS(RK1(1,K),B32(1,J,2*K-1),TT1(1,J))	SETUP2
74	CALL CROSS(RK2(1,K),B32(1,J,2*K ),TT2(1,J))	SETUP2
	DO 75 I=1,3	SETUP2
	DO 75 J=1,3	SETUP2
	B32(I,J,2*K-1) = TT1(J,I)	SETUP2
75	B32(I,J,2*K ) = TT2(J,I)	SETUP2
C		SETUP2
C	COMPUTE V3 = D2' (W2X(W2XR2)) - D1' (W1X(W1XR1))	SETUP2
C		SETUP2
	76 CALL CROSS(WMEG(1,M),RK1(1,K),T3)	SETUP2
	CALL CROSS (WMEG(1,M),T3,T4)	SETUP2
	CALL DOT31 (D(1,1,M),T4,T5)	SETUP2
	CALL CROSS (WMEG(1,N),RK2(1,K),T6)	SETUP2
	CALL CROSS (WMEG(1,N),T6,T7)	SETUP2
	CALL DOT31 (D(1,1,N),T7,T8)	SETUP2
	DO 64 I=1,3	SETUP2



64	V3(I,K) = T8(I) - T5(I)	SETUP2
	IF (KQTYPE(K).NE.2) GO TO 67	SETUP2
C		SETUP2
C	RECOMPUTE V3 FOR KQTYPE=2.	SETUP2
C		SETUP2
	CALL DOT31 (D(1,1,M),T3,T9 )	SETUP2
	CALL DOT31 (D(1,1,N),T6,T10)	SETUP2
	S2 = 0.0	SETUP2
	DO 65 I=1,3	SETUP2
	T11(I) = SEGLV(I,M)+T9(I) - SEGLV(I,N)-T10(I)	SETUP2
65	S2 = S2 + T11(I)**2	SETUP2
	S3 = HH(1)*V3(1,K) + HH(2)*V3(2,K) + HH(3)*V3(3,K)	SETUP2
	S4 = S3-S2/SQS1	SETUP2
	DO 66 I=1,3	SETUP2
66	V3(I,K) = S4*HH(I)	SETUP2
67	IF (KQTYPE(K).NE.3.AND.KQTYPE(K).NE.6) GO TO 77	SETUP2
C		SETUP2
C	FOR KQTYPE=3 OR 6, ADD R DOT TERM FROM PLELP OR SEGSEG TO V3.	SETUP2
C		SETUP2
	DO 68 I=1,3	SETUP2
68	V3(I,K) = V3(I,K) + RQQ(I,K)	SETUP2
	IF (KQTYPE(K).NE.6) GO TO 70	SETUP2
C		SETUP2
C	FOR KQTYPE=6, SET V3 = (I-TT')(V3+RQQ)	SETUP2
C		SETUP2
	VQQ = V3(1,K)*TQQ(1,K) + V3(2,K)*TQQ(2,K) + V3(3,K)*TQQ(3,K)	SETUP2
	DO 69 I=1,3	SETUP2
69	V3(I,K) = V3(I,K) - VQQ*TQQ(I,K)	SETUP2
77	IF (KQTYPE(K).NE.4) GO TO 70	SETUP2
C		SETUP2
C	FOR KQTYPE = 4, ADD R TERM FROM PLELP OR SEGSEG TO V3.	SETUP2
C		SETUP2
	S3 = TQQ(1,K)*V3(1,K) + TQQ(2,K)*V3(2,K) + TQQ(3,K)*V3(3,K)	SETUP2
	S4 = S3+SQQ(K)	SETUP2
	DO 78 I=1,3	SETUP2
78	V3(I,K) = S4*HQQ(I,K)	SETUP2
70	CONTINUE	SETUP2
C		SETUP2
C	SPECIAL SETUP FOR TENSION ELEMENTS (KQTYPE = 5).	SETUP2
C		SETUP2
	N = 0	SETUP2
79	N = N+1	SETUP2
	IF (N.GE.NQ) GO TO 98	SETUP2
	IF (KQTYPE(N).NE.5) GO TO 79	SETUP2
	DO 81 I=1,3	SETUP2
	DO 80 J=1,3	SETUP2
	A13(I,J,2*N-1) = 0.0	SETUP2
	A13(I,J,2*N ) = 0.0	SETUP2
	A23(I,J,2*N ) = 0.0	SETUP2
	B31(I,J,2*N-1) = 0.0	SETUP2

B31(I,J,2*N ) = 0.0	SETUP2
A13(I,J,2*N+1) = 0.0	SETUP2
A13(I,J,2*N+2) = 0.0	SETUP2
A23(I,J,2*N+1) = 0.0	SETUP2
B31(I,J,2*N+1) = 0.0	SETUP2
B31(I,J,2*N+2) = 0.0	SETUP2
HHT(I,J,N ) = 0.0	SETUP2
80 HHT(I,J,N+1 ) = 0.0	SETUP2
A13(I,I,2*N-1) = 1.0	SETUP2
B31(I,I,2*N-1) = RK1(1,N+1)	SETUP2
B31(I,I,2*N ) = RK1(3,N+1)	SETUP2
A13(I,I,2*N+2) = 1.0	SETUP2
B31(I,I,2*N+1) = RK1(3,N+1)	SETUP2
81 B31(I,I,2*N+2) = RK1(2,N+1)	SETUP2
N1 = KQ1(N)	SETUP2
N2 = KQ2(N)	SETUP2
DO 82 K=1,3	SETUP2
CALL CROSS(RK1(1,N),D(1,K,N1),A23(1,K,2*N-1))	SETUP2
82 CALL CROSS(RK2(1,N),D(1,K,N2),A23(1,K,2*N+2))	SETUP2
DO 83 I=1,3	SETUP2
DO 83 J=1,3	SETUP2
B32(I,J,2*N-1) = RK1(1,N+1)*A23(J,I,2*N-1)	SETUP2
B32(I,J,2*N ) = RK1(3,N+1)*A23(J,I,2*N+2)	SETUP2
B32(I,J,2*N+1) = RK1(3,N+1)*A23(J,I,2*N-1)	SETUP2
83 B32(I,J,2*N+2) = RK1(2,N+1)*A23(J,I,2*N+2)	SETUP2
CALL CROSS(WMEG(1,N1),RK1(1,N),WCRM)	SETUP2
CALL CROSS(WMEG(1,N2),RK2(1,N),WCRN)	SETUP2
CALL DOT31(D(1,1,N1),RK1(1,N),RM)	SETUP2
CALL DOT31(D(1,1,N2),RK2(1,N),RN)	SETUP2
CALL DOT31(D(1,1,N1),WCRM,WCM)	SETUP2
CALL DOT31(D(1,1,N2),WCRN,WCN)	SETUP2
BA = 0.0	SETUP2
DO 84 I=1,3	SETUP2
RBA(I) = SEGLP(I,N2) + RN(I) - SEGLP(I,N1) - RM(I)	SETUP2
RBAD(I) = SEGLV(I,N2) + WCN(I) - SEGLV(I,N1) - WCM(I)	SETUP2
84 BA = BA + RBA(I)**2	SETUP2
BA = DSQRT(BA)	SETUP2
FORCE = 0.0	SETUP2
IF (BA.GT.RK2(3,N+1)) FORCE = RK2(1,N+1)*(1.0-RK2(3,N+1)/BA)	SETUP2
DO 85 I=1,3	SETUP2
V3(I,N) = RK2(2,N+1)*RBAD(I) + FORCE*RBA(I)	SETUP2
85 V3(I,N+1) = -V3(I,N)	SETUP2
CALL CROSS(WMEG(1,N1),WCRM,WWCM)	SETUP2
CALL CROSS(WMEG(1,N2),WCRN,WWCN)	SETUP2
CALL DOT31(D(1,1,N1),WWCM,WWM)	SETUP2
CALL DOT31(D(1,1,N2),WWCN,WWN)	SETUP2
DO 86 I=1,3	SETUP2
V3(I,N ) = V3(I,N ) - RK1(1,N+1)*WWM(I) - RK1(3,N+1)*WWN(I)	SETUP2
86 V3(I,N+1) = V3(I,N+1) - RK1(3,N+1)*WWM(I) - RK1(2,N+1)*WWN(I)	SETUP2
N = N+1	SETUP2

GO TO 79  
98 CALL ELTIME(2,26)  
RETURN  
END

SETUP2  
SETUP2  
SETUP2  
SETUP2

	SUBROUTINE SINPUT		SINPUT
		REV IV 02/20/87	HYPER
C	READS AND PRINTS THE INPUT CARDS THAT DESCRIBE THE PHYSICAL		SINPUT
C	DIMENSIONS OF THE PLANES REPRESENTING THE VEHICLE PANELS AND OF		SINPUT
C	THE RESTRAINT BELTS. ALSO PROCESSES THOSE DATA CARDS THAT DESCRIBES		SINPUT
C	ADDITIONAL CONTACT ELLIPSOIDS, CONSTRAINTS, BODY SEGMENT SYMMETRY		SINPUT
C	OPTIONS AND SPRING DAMPER FUNCTIONS.		SINPUT
C			SINPUT
	IMPLICIT REAL*8 (A-H,O-Z)		SINPUT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		SINPUT
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/CNTRF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)		EDGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		SINPUT
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		SINPUT
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		SINPUT
	* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		SINPUT
	* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		SINPUT
	* KQ1(12),KQ2(12),KQTYPE(12)		SINPUT
	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),		SINPUT
	* BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30),		SINPUT
	* JOINT(30),CGS(30),JS(30)		SINPUT
	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT		SINPUT
	LOGICAL*1 CGS,JS,LP4		HYPER
	COMMON/DAMPER/ APSDM(3,20),APSDN(3,20),ASD(5,20),MSDM(20),MSDN(20)		SINPUT
	COMMON/WINDFR/ WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30),		WINDOP
	* MWSEG(7,30),NFWSEG(6),NFWNT(5),MOWSEG(30,30)		WINDOP
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		SINPUT
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	COMMON/TEMPVS/ P1(3),P2(3),P3(3),P4(3),DE(3,3)		HYPER
	DIMENSION IDYPR(3)		SINPUT
	DATA IDYPR/3,2,1/		SINPUT
	DATA MAXBD/40/		CHGIII
	DATA NPLMAX/30/,NBLTMX/8/,NBAGMX/5/,NELPMX/40/,NQMAX/12/,		MISC
	* NSDMAX/20/,NHRNSM/5/,NWINDM/50/,NJNTFM/50/,NFORCM/5/		MISC
C			SINPUT
C	INPUT CARD D.1		SINPUT
C			SINPUT
	READ (5,11) NPL,NBLT,NBAG,NELP,NQ,NSD,NHRNSS,NWINDF,NJNTF,NFORCES		SINPUT
11	FORMAT(12I6)		SINPUT
	WRITE (6,16) NPG,NPL,NBLT,NBAG,NELP,NQ,NSD,NHRNSS,NWINDF,NJNTF,		PAGE
	* NFORCE		PAGE
	NPG=NPG+1		PAGE
16	FORMAT('1 NPL NBLT NBAG NELP NQ NSD NHRNSS',		PAGE
	* ' NWINDF NJNTF NFORCE',43X,'PAGE',I5/I0I8,40X,'CARD D.1')		PAGE
	IF (NPL.GT.NPLMAX) STOP 65		CHGIII
	IF (NBLT.GT.NBLTMX) STOP 66		MISC
	IF (NBAG.GT.NBAGMX) STOP 67		MISC
	IF (NELP.GT.NELPMX) STOP 68		MISC
	IF (NQ.GT.NQMAX) STOP 69		CHGIII
	IF (NSD.GT.NSDMAX) STOP 70		CHGIII

IF (NHRNSS.GT.NHRNSM) STOP 71	MISC
IF (NWINDF.GT.NWINDM) STOP 72	MISC
IF (NJNTF.GT.NJNTFM) STOP 73	MISC
IF (NFORCE.GT.NFORCM) STOP 74	MISC
IF (NPL.EQ.0) GO TO 15	SINPUT
IPAGE = 0	SINPUT
DO 20 J=1,NPL	SINPUT
C	SINPUT
C READ AND PRINT CARDS D.2.A,D.2.B AND D.2.C FOR THE JTH PLANE.	SINPUT
C	SINPUT
READ (5,23) JJ,(PLTTL(I,J),I = 1,5),P1,P2,P3	SINPUT
23 FORMAT (I4,4X,5A4/(3F12.0))	SINPUT
IF (JJ.NE.J) WRITE (6,24) JJ,J	SINPUT
24 FORMAT (' PLANE INDEX INPUT ERROR','2I4)	SINPUT
IF (JJ.NE.J) STOP 10	SINPUT
IF (MOD(J,7).EQ.1.AND.IPAGE.EQ.0) WRITE (6,12) IPAGE	PAGE
IF (MOD(J,7).EQ.1.AND.IPAGE.EQ.1) WRITE (6,112) IPAGE,NPG	PAGE
IF (MOD(J,7).EQ.1.AND.IPAGE.EQ.1) NPG=NPG+1	PAGE
112 FORMAT(I1,' PLANE INPUTS',109X,'PAGE',15/120X,'CARDS D.2')	PAGE
12 FORMAT(I1,' PLANE INPUTS',106X,'CARDS D.2')	SINPUT
IPAGE = 1	SINPUT
WRITE (6,25) J, (PLTTL(I,J),I = 1,5),P1,P2,P3	SINPUT
25 FORMAT('0 PLANE NO.',I4,4X,5A4//17X,'X',11X,'Y',11X,'Z'/	SINPUT
* ' POINT 1 ' ,3F12.4/	SINPUT
* ' POINT 2 ' ,3F12.4/	SINPUT
* ' POINT 3 ' ,3F12.4)	SINPUT
C	SINPUT
C PROGRAM NOW ASSUMES THE FINITE PLANE IS A PARALLELOGRAM IN SHAPE	SINPUT
C WHERE THE INPUT POINTS P1,P2,P3 ARE 3 OF THE CORNERS SUCH THAT	SINPUT
C EDGE P1-P2 IS LESS THAN 180 DEGREES CLOCKWISE (AS VIEWED BY THE	SINPUT
C OCCUPANT) FROM THE EDGE P1-P3.	SINPUT
C	SINPUT
C SET UP PL ARRAY AS REQUIRED BY SUBROUTINE PLELP	SINPUT
C	SINPUT
C PL(1,J) = A0 NORMAL EQUATION OF JTH PLACE	SINPUT
C PL(2,J) = B0 A0*X + B0*Y + C0*Z = D0	SINPUT
C PL(3,J) = C0	SINPUT
C PL(4,J) = D0	SINPUT
C	SINPUT
C PL(5,J)	SINPUT
C PL(6,J) POINT 1	EDGE
C PL(7,J)	SINPUT
C	SINPUT
C PL(8,J) =A1	SINPUT
C PL(9,J) =B1 NORMAL EQUATION OF 1ST BOUNDARY PLANE	SINPUT
C PL(10,J)=C1 A1*X + B1*Y + C1*Z = D1	SINPUT
C PL(11,J)=D1 AND E1 IS LENGTH OF PLANE FROM BOUNDARY.	SINPUT
C PL(12,J)=E1	SINPUT
C	SINPUT
C PL(13,J)=A2	SINPUT

C	PL(14,J)=B2	NORMAL EQUATION OF 2ND BOUNDARY PLANE	SINPUT
C	PL(15,J)=C2	$A2 \cdot X + B2 \cdot Y + C2 \cdot Z = D2$	SINPUT
C	PL(16,J)=D2	AND E2 IS LENGTH OF PLANE FROM BOUNDARY.	SINPUT
C	PL(17,J)=E2		SINPUT
C			SINPUT
C	PL(18,J)		EDGE
C	PL(19,J)	POINT 2 - POINT 1	EDGE
C	PL(20,J)		EDGE
C			EDGE
C	PL(21,J)		EDGE
C	PL(22,J)	POINT 3 - POINT 1	EDGE
C	PL(23,J)		EDGE
C			EDGE
C	PL(24,J)	NOT CURRENTLY USED	EDGE
	S22 = 0.0		SINPUT
	S23 = 0.0		SINPUT
	S33 = 0.0		SINPUT
	DO 26 I =1,3		SINPUT
	P2(I) = P2(I)-P1(I)		SINPUT
	P3(I) = P3(I)-P1(I)		SINPUT
	PL(I+ 4,J) = P1(I)		EDGE
	PL(I+17,J) = P2(I)		EDGE
	PL(I+20,J) = P3(I)		EDGE
	S22 = S22 + P2(I)*P2(I)		SINPUT
	S23 = S23 + P2(I)*P3(I)		SINPUT
26	S33 = S33 + P3(I)*P3(I)		SINPUT
	S2 = DSQRT(S22)		SINPUT
	S3 = DSQRT(S33)		SINPUT
	CALL CROSS(P2,P3,PL(1,J))		SINPUT
	S1 = 0.0		SINPUT
	DO 27 I=1,3		SINPUT
27	S1 = S1 + PL(I,J)**2		SINPUT
	S1 = DSQRT(S1)		SINPUT
	DO 28 I=1,3		SINPUT
	PL(I,J) = PL(I,J)/S1		SINPUT
	PL(I+7 ,J) = (S33*P2(I) - S23*P3(I)) / (S1*S3)		SINPUT
28	PL(I+12,J) = (S22*P3(I) - S23*P2(I)) / (S1*S2)		SINPUT
	PL( 4,J) = P1(1)*PL( 1,J) + P1(2)*PL( 2,J) + P1(3)*PL( 3,J)		SINPUT
	PL(11,J) = P1(1)*PL( 8,J) + P1(2)*PL( 9,J) + P1(3)*PL(10,J)		SINPUT
	PL(12,J) = P2(1)*PL( 8,J) + P2(2)*PL( 9,J) + P2(3)*PL(10,J)		SINPUT
	PL(16,J) = P1(1)*PL(13,J) + P1(2)*PL(14,J) + P1(3)*PL(15,J)		SINPUT
20	PL(17,J) = P3(1)*PL(13,J) + P3(2)*PL(14,J) + P3(3)*PL(15,J)		SINPUT
15	IF (NBLT.EQ.0) GO TO 35		SINPUT
	DO 30 J=1,NBLT		SINPUT
C			SINPUT
C	READ AND PRINT CARDS D.3.A, D.3.B AND D.3.C FOR THE JTH BELT.		SINPUT
C			SINPUT
	READ (5,13) (BLTTTL(I,J),I = 1,5),(BELT(I,J),I = 1,11)		SINPUT
13	FORMAT (5A4/(6F12.0))		SINPUT
	IF (MOD(J,5).EQ.1) WRITE (6,21) NPG		PAGE

	IF (MOD(J,5).EQ.1) NPG=NPG+1	PAGE
21	FORMAT('1 BELT INPUTS',110X,'PAGE',15/120X,'CARDS D.3')	PAGE
30	WRITE (6,14) J,(BLTTTL(I,J),I = 1,5),(BELT(I,J),I = 1,11)	SINPUT
14	FORMAT('0 BELT NO.',14,4X,5A4//	SINPUT
*	30X,'ANCHOR POINT A',46X,'ANCHOR POINT B'/'	SINPUT
*	2(16X,'X',19X,'Y',19X,'Z',3X)/6F20.3//	SINPUT
*	26X,'FIXED POINT ON SEGMENT',45X,'SLACK(+)'/'	SINPUT
*	16X,'X',19X,'Y',19X,'Z',17X,'BLANK',13X,'LENGTH(-)'/5F20.3)	SINPUT
C		SINPUT
C	CALL AIRBG1 ROUTINE IF REQUIRED FOR AIRBAG INPUT	SINPUT
C		SINPUT
35	IF (NBAG.NE.0) CALL AIRBG1	SINPUT
	IF (NELP.LE.0) GO TO 51	SINPUT
C		SINPUT
C	READ AND PRINT CARDS D.5 FOR ELLIPSOID INPUT, IF ANY.	SINPUT
C	NOTE: NELP IS THE NO. OF ELLIPSOIDS TO BE SUPPLIED HERE, NOT THE	SINPUT
C	NO. OF ELLIPSOIDS IN THE PROGRAM, SINCE THE FIRST NSEG	SINPUT
C	ELLIPSOIDS WERE SUPPLIED ON CARDS B.2.A - B.2.I. HOWEVER	SINPUT
C	THEY MAY BE REPLACED HERE IF DESIRED.	SINPUT
C		SINPUT
	WRITE (6,41) NPG,UNITL,UNITL	PAGE
	NPG=NPG+1	PAGE
41	FORMAT('1 ADDITIONAL ELLIPSOID INPUT',95X,'PAGE',15/120X,	PAGE
*	'CARDS D.5'/17X,'SEMIAXES ('',A4,'')',18X,'OFFSET ('',A4,'')',	PAGE
*	20X,'ROTATION (DEG)',15X,'POWER'/'	HYPER
*	3X,'NO.',2(8X,'X',8X,'Y',8X,'Z',6X),7X,'YAW',7X,'PITCH',5X,	SINPUT
*	'ROLL'//)	SINPUT
	DO 50 MM=1,NELP	SINPUT
	READ (5,42) M,P1,P2,P3,P4	HYPER
42	FORMAT(16,9F6.0,3F4.0)	HYPER
	IF (M.GT.MAXBD) STOP 63	CHGIII
C		CHGIII
C	PREVENT EXTRA ELLIPSOIDS FROM CHANGING AIRBAG ELLIPSOIDS	CHGIII
C		CHGIII
	IF (M.GT.NVEH.AND.M.LT.NGRND) WRITE (6,330)	CHGIII
330	FORMAT(3X,'THE EXTRA CONTACT ELLIPSOID NUMBER IS THE SAME AS AN	CHGIII
	*RBAG ELLIPSOID')	CHGIII
	IF (M.GT.NVEH.AND.M.LT.NGRND) STOP 64	CHGIII
	WRITE (6,43) M,P1,P2,P3,P4	HYPER
43	FORMAT(16,3(3X,3F9.3,3X),3F6.0)	HYPER
	CALL DRCYPR (DE,P3,IDYPR)	SINPUT
	N = 1	HYPER
	LP4 = .FALSE.	HYPER
	DO 39 J = 1,3	HYPER
39	IF (P4(J).GT.2.0) LP4 = .TRUE.	HYPER
	IF (LP4) N = 2	HYPER
	DO 46 I = 1,3	HYPER
	BD(N ,M) = P1(I)	HYPER
	BD(N+3,M) = P2(I)	HYPER
	IF (LP4) GO TO 46	HYPER

	DO 45 J=1,3	SINPUT
	SUM1 = 0.0	SINPUT
	SUM2 = 0.0	SINPUT
	DO 44 L=1,3	SINPUT
	SUM1 = SUM1 + DE(L,I)/P1(L)**2*DE(L,J)	SINPUT
44	SUM2 = SUM2 + DE(L,I)*P1(L)**2*DE(L,J)	SINPUT
	K = 3*I + J + 3	SINPUT
	BD(K ,M) = SUM1	SINPUT
45	BD(K+9,M) = SUM2	SINPUT
46	N = N + 1	HYPER
	IF (.NOT.LP4) GO TO 50	HYPER
	BD(1,M) = -P4(1)	HYPER
	N = 8	HYPER
	DO 48 J = 1,3	HYPER
	BD(J+19,M) = P4(J)	HYPER
	IF (BD(J+19,M).EQ.0.0) BD(J+19,M) = BD(20,M)	HYPER
	BD(J+16,M) = 1.0/BD(J+1,M)**2	HYPER
	DO 48 I = 1,3	HYPER
	BD(N,M) = DE(I,J)	HYPER
48	N = N + 1	HYPER
	BD(23,M) = 0.0	HYPER
	IF (BD(20,M).NE.BD(21,M)) BD(23,M) = 1.0	HYPER
	IF (BD(21,M).NE.BD(22,M)) BD(23,M) = 1.0	HYPER
	IF (BD(22,M).NE.BD(20,M)) BD(23,M) = 1.0	HYPER
50	CONTINUE	SINPUT
C		SINPUT
C	READ AND PRINT CARDS D.6 FOR CONSTRAINT INPUT, IF ANY.	SINPUT
C		SINPUT
	51 IF (NQ.LE.0) GO TO 70	SINPUT
	DO 60 K=1,NQ	SINPUT
	READ (5,52) KQTYPE(K),KQ1(K),KQ2(K), (RK1(I,K),I=1,3)	SINPUT
	* , (RK2(I,K),I=1,3)	SINPUT
	52 FORMAT(3I6,6F6.0)	SINPUT
	IF (K.EQ.1) WRITE (6,53) NPG,UNITL,UNITL	PAGE
	IF (K.EQ.1) NPG=NPG+1	PAGE
	53 FORMAT('1 CONSTRAINT INPUT',105X,'PAGE',I5/120X,'CARDS D.6'/	PAGE
	* ' TYPE SEGMENT SEGMENT POINT ON 1ST SEGMENT ('	SINPUT
	* A4,')', ' POINT ON 2ND SEGMENT (' ,A4,')')/	SINPUT
	* ' NO. NO. 1 NO. 2 X Y Z	SINPUT
	* X Y Z'//)	SINPUT
	WRITE (6,54) KQTYPE(K),KQ1(K),KQ2(K), (RK1(I,K),I=1,3)	SINPUT
	* , (RK2(I,K),I=1,3)	SINPUT
	54 FORMAT(16,2I9,2(6X,3F9.3) )	SINPUT
	60 CONTINUE	SINPUT
C		SINPUT
C	CARD D.7 BODY SEGMENT SYMMETRY INPUT	SINPUT
C		SINPUT
	70 READ (5,71) (NSYM(J),J=1,NSEG)	SINPUT
	71 FORMAT(18I4)	SINPUT
	DO 103 J=1,NSEG	TGMOD2



LJ = NSYM(J)	TGMOD2
IF(IABS(LJ).GT.NSEG) GO TO 107	TGMOD2
IF(LJ) 104,103,105	TGMOD2
105 LK = NSYM(LJ)	TGMOD2
IF(IABS(LK).GT.NSEG) GO TO 107	TGMOD2
IF(LK.NE.J) GO TO 106	TGMOD2
GO TO 103	TGMOD2
104 JJ = -J	TGMOD2
LJ = -LJ	TGMOD2
LK = NSYM(LJ)	TGMOD2
IF(IABS(LK).GT.NSEG) GO TO 107	TGMOD2
IF((LK.NE.JJ).OR.(NSYM(J).EQ.JJ)) GO TO 106	TGMOD2
GO TO 103	TGMOD2
106 STOP 96	TGMOD2
107 STOP 97	TGMOD2
103 CONTINUE	TGMOD2
WRITE(6,72) (J,J=1,NSEG)	SINPUT
WRITE(6,73) (NSYM(J),J=1,NSEG)	SINPUT
72 FORMAT('0 BODY SEGMENT SYMMETRY INPUT',91X,'CARD D.7'//	SINPUT
* ' SEG NO.',3014)	SINPUT
73 FORMAT('0 NSYM(J)',3014)	SINPUT
NSEG1 = NSEG+1	SINPUT
DO 74 J=NSEG1,NGRND	SINPUT
74 NSYM(J) = 0	SINPUT
IF (NSD.LE.0) GO TO 90	SINPUT
C	SINPUT
C	SINPUT
C	SINPUT
CARD D.8 SPRING DAMPERS FUNCTION INPUT.	SINPUT
DO 79 J=1,NSD	SINPUT
79 READ (5,80) MSDM(J),MSDN(J),(APSDM(I,J),I=1,3),	SINPUT
* (APSDN(I,J),I=1,3),(ASD(I,J),I=1,5)	SINPUT
80 FORMAT(2I3,11F6.0)	SINPUT
WRITE (6,81) UNITL	SINPUT
81 FORMAT('0',5X,'SPRING DAMPERS FUNCTION INPUT',82X,'CARDS D.8'//	SINPUT
* 18X,'COORDINATES OF ATTACHMENT POINTS ('A4,')'//	SINPUT
* 5X,'SEGMENT',9X,'SEGMENT M',16X,'SEGMENT N',15X,	SINPUT
* 'SPRING FORCE FUNCTION',12X,'DAMPING FORCE FUNCTION'//	AFREVS
* ' NO. M N',2(6X,'X',7X,'Y',7X,'Z',2X),7X,'D0',9X,'A1',11X,	SINPUT
* 'A2',13X,'B1',10X,'B2' // )	SINPUT
DO 82 J=1,NSD	SINPUT
82 WRITE (6,83) J,MSDM(J),MSDN(J),(APSDM(I,J),I=1,3),	SINPUT
* (APSDN(I,J),I=1,3),(ASD(I,J),I=1,5)	SINPUT
83 FORMAT(13,2I4,2(1X,3F8.2),F11.2,2F12.3,F15.3,F12.3)	SINPUT
C	SINPUT
C	SINPUT
C	CHGIII
CARDS D.9 FORCE AND/OR TORQUE FUNCTIONS.	SINPUT
90 NFVSEG(6)= NFORCE	SINPUT
IF (NFORCE.LE.0) GO TO 99	SINPUT
WRITE (6,91)	SINPUT
91 FORMAT ('0',6X,'FORCE AND/OR TORQUE FUNCTION INPUTS',78X,'CARDS D.CHGIII	

*9'//, 5X,'NO.', 5X,'SEG', 5X,'FCN', 13X,'X', 9X,'Y', 9X,'Z',	CHGIII
* 13X,'YAW', 6X,'PITCH', 6X,'ROLL' //)	SINPUT
DO 95 J=1,NFORCE	SINPUT
READ (5,92) NFVSEG(J),NFVNT(J),P1,P2	SINPUT
92 FORMAT (2I6,6F10.0)	SINPUT
WRITE (6,93) J,NFVSEG(J),NFVNT(J),P1,P2	SINPUT
93 FORMAT (3I8,6X,3F10.3,6X,3F10.3)	SINPUT
CALL DRCYPR (DE,P2,IDYPR)	SINPUT
DO 94 I=1,3	SINPUT
94 QFU(I,J) = DE(1,I)	FIXSPT
95 CALL CROSS (P1,QFU(1,J),QFV(1,J))	SINPUT
99 RETURN	SINPUT
END	SINPUT

```

SUBROUTINE SLPLOT (X, NX, XO, XN, XL, XSIZE, XLAB, NXLB,      SLPLOT
*                Y, NY, YO, YN, YL, YSIZE, YLAB, NYLB,      SLPLOT
*                NPTS, NYY, NDY, PLAB1, NPLB1, PLAB2, NPLB2) SLPLOT

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REV III.2 08/08/84REVIII

#### ARGUMENTS:

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X(NPTS)      - ARRAY OF NPTS ABSCISSAS TO BE PLOTTED.      SLPLOT
Y(NDY,NYY)   - ARRAY OF NPTS*NY Y ORDINATES TO BE PLOTTED. SLPLOT
NX,NY        - POSITIVE - NO. OF LINEAR SUBDIVISIONS.      SLPLOT
              - NEGATIVE - NO. OF LOGARITHMIC DECADES.      SLPLOT
XO,YO        - AXES ORIGINS (POWER OF TEN IF NX,NY NEGATIVE). SLPLOT
XN,YN        - AXES END VALUES (REQUIRED IF NX,NY POSITIVE). SLPLOT
XL,YL        - LENGTH (INCHES) OF X,Y AXES.                SLPLOT
XSIZE,YSIZE  - PAPER SIZE (INCHES) IN X,Y DIRECTIONS.      SLPLOT
XLAB,YLAB    - X,Y AXES LABELS (ALPHANUMERIC ARRAYS).      SLPLOT
NXLB,NYLB    - NO. OF CHARACTERS IN X,Y LABELS.            SLPLOT
NPTS         - NO. OF POINTS IN X ARRAY AND EACH Y ARRAY.  SLPLOT
NYY          - NO. OF Y ARRAYS TO BE PLOTTED VS. X ARRAY.  SLPLOT
NDY          - FIRST DIMENSION OF Y ARRAY IN CALLING ROUTINE. SLPLOT
              (NDY MUST BE .GE. NPTS)                      SLPLOT
PLAB1,PLAB2  - 1ST & 2ND LINES OF PLOT ID LABELS (ALPHANUMERIC). SLPLOT
NPLB1,NPLB2  - NO. OF CHARACTERS IN PLOT ID LABELS.        SLPLOT

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NOTE: PLOTS WILL BE TRUNCATED AS FOLLOWS:

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NX,NY POSITIVE - XO,YO .LE. X,Y .LE. XN,YN                SLPLOT
NX,NY NEGATIVE - XO,YO .LE. X,Y .LE. XN*10**(-NX),YO*10**(-NY) SLPLOT

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DIMENSION X(NPTS),Y(NDY,NYY),XLAB(1),YLAB(1),PLAB1(1),PLAB2(1) SLPLOT

NOTE: THIS ROUTINE HAS BEEN WRITTEN FOR THE PLOTTING FACILITIES AT CALSPAN. THE FOLLOWING ITEMS ARE KNOWN TO BE CONTRARY TO THE NORMAL CALCOMP PROCEDURES AND SHOULD BE EXAMINED BY USERS AT OTHERS COMPUTER SYSTEMS AND CHANGES MADE ACCORDINGLY.

1. AT CALSPAN THE PLOTTED CHARACTERS GENERATED BY SUBROUTINE SYMBOL HAVE A WIDTH OF 6/7 TIMES THE HEIGHT. FOR THE CALCOMP ROUTINES THE WIDTH IS EQUAL TO THE HEIGHT. THE STATEMENT 'WIDTHF = 6.0/7.0' SHOULD BE CHANGED TO 'WIDTHF = 1.0'.
2. THE ONLY INITIALIZATION REQUIRED AT CALSPAN IS THE STATEMENT 'CALL PLOT (0.0,0.0,0)' TO ESTABLISH A NEW PAGE, INCLUDING THE FIRST PAGE. THIS IS FOLLOWED BY 'CALL PLOT (XO,YO,-3)' TO SET THE PLOT ORIGIN ON THE PAGE. PROPER PLOT INITIALIZATION SHOULD BE DONE HERE AND IN SUBROUTINE POSTPR (AFTER STATEMENT NO. 30) AS REQUIRED BY THE USER'S PLOTTING FACILITY.
3. THE STATEMENT 'CALL NEWPEN(2)' SHOULD BE EXAMINED OR DELETED.
4. THE STATEMENT 'CALL EFPLLOT' AFTER STATEMENT NO. 50 IN POSTPR IS REQUIRED AT CALSPAN TO CLOSE OUT THE PLOT FILES. THIS

C	SHOULD BE CHANGED TO CONFORM TO THE REQUIREMENTS OF THE	SLPLOT
C	USER'S PLOTTING FACILITIES.	SLPLOT
C		SLPLOT
C	5. THE NECESSARY JOB CONTROL LANGUAGE FOR PLOTTING IS NECESSARY.	SLPLOT
C		SLPLOT
C	6. THE ONLY CALCOMP ROUTINES NEEDED ARE SYMBOL, NUMBER AND PLOT.	SLPLOT
C		SLPLOT
	LOGICAL NXPOS,NXNEG,NYPOS,NYNEG	SLPLOT
	DATA HN/0.07/, HL/0.105/	SLPLOT
	WIDTHF = 1.0	REDIMN
	WN = WIDTHF*HN	SLPLOT
	WL = WIDTHF*HL	SLPLOT
C	** PLOT PAGE INITIALIZATION **	SLPLOT
	CALL PLOT (0.0,0.0,-3)	CHANGE
	XP = 0.5*(XSIZE-(XL-0.5))	SLPLOT
	YP = 0.5*(YSIZE-(YL-1.0))	SLPLOT
	CALL PLOT (XP,YP,-3)	SLPLOT
	NXPOS = NX.GT.0	SLPLOT
	NXNEG = NX.LT.0	SLPLOT
	NYPOS = NY.GT.0	SLPLOT
	NYNEG = NY.LT.0	SLPLOT
C	** PLOT AXES AND ID LABELS. **	SLPLOT
	XP = 0.0	SLPLOT
	YP = 0.0	SLPLOT
	IF (NOT.NXPOS) GO TO 12	SLPLOT
C	** LINEAR X AXIS **	SLPLOT
	CALL LINAXS (XP, YP, 0.0, NX, XL)	SLPLOT
	XB = XL/(XN-X0)	SLPLOT
C	** LINEAR X AXIS NUMERICS **	SLPLOT
	DX = XL/FLOAT(NX)	SLPLOT
	EX = X0	SLPLOT
	DD = (XN-X0)/FLOAT(NX)	SLPLOT
	ND = 0.99 - ALOG10(ABS(DD))	SLPLOT
	IF (ND.LE.0) ND = -1	SLPLOT
	IX = 0	SLPLOT
	YC = YP - 2.0*HN	SLPLOT
11	AX = ABS(EX)	SLPLOT
	NF = 0	SLPLOT
	IF (AX.GE.10.0) NF = ALOG10(AX)	SLPLOT
	NS = 0	SLPLOT
	IF (EX.LT.0.0) NS = 1	SLPLOT
	SP = NS+NF+2+ND	SLPLOT
	XC = XP - 0.5*SP*WN	SLPLOT
	CALL NUMBER (XC, YC, HN, EX, 0.0, ND)	SLPLOT
	XP = XP + DX	SLPLOT
	EX = EX + DD	SLPLOT
	IX = IX + 1	SLPLOT
	IF (ABS(EX).GT.ABS(0.1*DD)) GO TO 18	SLPLOT
	IF (IX.GT.NX) GO TO 12	SLPLOT
	CALL PLOT (XP, YP+YL,3)	SLPLOT

	CALL PLOT (XP, YP, 2)	SLPLOT
18	IF (IX.LE.NX) GO TO 11	SLPLOT
12	IF (.NOT.NXNEG) GO TO 14	SLPLOT
C	** LOG X AXIS **	SLPLOT
	CALL LOGAXS (XP, YP, 0.0, -NX, XL)	SLPLOT
	XB = XL/ALOG(10.0**(-NX))	SLPLOT
	XA = -XB*ALOG(X0)	SLPLOT
C	** LOG X AXIS NUMERICS **	SLPLOT
	DX = XL/FLOAT(-NX)	SLPLOT
	EX = ALOG10(X0)	SLPLOT
	IX = 0	SLPLOT
13	CALL NUMBER (XP-1.0*WN, YP-2.5*HN, HN, 10.0, 0.0, -1)	SLPLOT
	CALL NUMBER (XP+1.0*WN, YP-2.0*HN, HN, EX, 0.0, -1)	SLPLOT
	XP = XP + DX	SLPLOT
	EX = EX + 1.0	SLPLOT
	IX = IX - 1	SLPLOT
	IF (IX.GE.NX) GO TO 13	SLPLOT
14	IF (NXLB.LE.0) GO TO 15	SLPLOT
C	** X AXIS LABEL **	SLPLOT
	XPX = (XL-FLOAT(NXLB)*WL)/2.0	SLPLOT
	YPX = YP-4.0*HN-HL	SLPLOT
	CALL SYMBOL(XPX, YPX, HL, XLAB, 0.0, NXLB)	SLPLOT
15	IF (NPLB1.LE.0) GO TO 16	SLPLOT
C	** PLOT LABEL - 1ST LINE **	SLPLOT
	XP1 = (XL-FLOAT(NPLB1)*WL)/2.0	SLPLOT
	YP1 = YP-4.0*HN-4.0*HL	SLPLOT
	CALL SYMBOL (XP1, YP1, HL, PLAB1, 0.0, NPLB1)	SLPLOT
16	IF (NPLB2.LE.0) GO TO 20	SLPLOT
C	** PLOT LABEL - 2ND LINE **	SLPLOT
	XP2 = (XL-FLOAT(NPLB2)*WL)/2.0	SLPLOT
	YP2 = YP-4.0*HN-6.0*HL	SLPLOT
	CALL SYMBOL (XP2, YP2, HL, PLAB2, 0.0, NPLB2)	SLPLOT
20	XP = 0.0	SLPLOT
C	** COMPLETE AXIS GRID **	SLPLOT
	IF (NYPOS) CALL LINAXS (XL, YP, 90.0, NY, YL)	SLPLOT
	IF (NYNEG) CALL LOGAXS (XL, YP, 90.0, -NY, YL)	SLPLOT
	IF (NXPOS) CALL LINAXS (XL, YL, 180.0, NX, XL)	SLPLOT
	IF (NXNEG) CALL LOGAXS (XL, YL, 180.0, -NX, -XL)	SLPLOT
	IF (.NOT.NYPOS) GO TO 22	SLPLOT
C	** LINEAR Y AXIS **	SLPLOT
	CALL LINAXS (XP, YL, -90.0, NY, YL)	SLPLOT
	YB = YL/(YN-Y0)	SLPLOT
C	** LINEAR Y AXIS NUMERICS **	SLPLOT
	DY = YL/FLOAT(NY)	SLPLOT
	EY = Y0	SLPLOT
	DD = (YN-Y0)/FLOAT(NY)	SLPLOT
	ND = 0.99 - ALOG10(ABS(DD))	SLPLOT
	IF (ND.LE.0) ND = -1	SLPLOT
	IY = 0	SLPLOT
	XC = XP - 1.0*HN	SLPLOT

21	AY = ABS(EY)	SLPLOT
	NF = 0	SLPLOT
	IF (AY.GE.10.0) NF = ALOG10(AY)	SLPLOT
	NS = 0	SLPLOT
	IF (EY.LT.0.0) NS = 1	SLPLOT
	SP = NS+NF+2+ND	SLPLOT
	YC = YP - 0.5*SP*WN	SLPLOT
	CALL NUMBER (XC, YC, HN, EY, 90.0, ND)	SLPLOT
	YP = YP + DY	SLPLOT
	EY = EY + DD	SLPLOT
	IY = IY + 1	SLPLOT
	IF (ABS(EY).GT.ABS(0.1*DD)) GO TO 19	SLPLOT
	IF (IY.GT.NY) GO TO 22	SLPLOT
	CALL PLOT (XP+XL, YP, 3)	SLPLOT
	CALL PLOT (XP, YP, 2)	SLPLOT
19	IF (IY.LE.NY) GO TO 21	SLPLOT
22	IF (.NOT.NYNEG) GO TO 24	SLPLOT
C	** LOG Y AXIS **	SLPLOT
	CALL LOGAXS (XP, YL, -90.0, -NY, -YL)	SLPLOT
	YB = YL/ALOG(10.0*(-NY))	SLPLOT
	YA = -YB*ALOG(Y0)	SLPLOT
C	** LOG Y AXIS NUMERICS **	SLPLOT
	DY = YL/FLOAT(-NY)	SLPLOT
	EY = ALOG10(Y0)	SLPLOT
	IY = 0	SLPLOT
23	CALL NUMBER (XP-1.0*HN, YP-1.0*WN, HN, 10.0, 90.0, -1)	SLPLOT
	CALL NUMBER (XP-1.5*HN, YP+1.0*WN, HN, EY, 90.0, -1)	SLPLOT
	YP = YP + DY	SLPLOT
	EY = EY + 1.0	SLPLOT
	IY = IY - 1	SLPLOT
	IF (IY.GE.NY) GO TO 23	SLPLOT
24	IF (NYLB.LE.0) GO TO 25	SLPLOT
C	** Y AXIS LABEL **	SLPLOT
	XPY = XP-4.0*HN	SLPLOT
	YPY = (YL-FLOAT(NYLB)*WL)/2.0	SLPLOT
	CALL SYMBOL(XPY, YPY, HL, YLAB, 90.0, NYLB)	SLPLOT
25	CONTINUE	SLPLOT
C	** PLOT DATA ARRAYS **	SLPLOT
	NSYM = 24	SLPLOT
	IS = NPTS/NSYM	SLPLOT
	IF (IS.EQ.0) IS = 1	VARTTH
	XOMIN = X0/1000.0	SLPLOT
	YOMIN = Y0/1000.0	SLPLOT
	DO 40 J=1,NYY	SLPLOT
	IPEN = 3	SLPLOT
	DO 39 I=1,NPTS	SLPLOT
	X1 = X2	SLPLOT
	Y1 = Y2	SLPLOT
	IF (NXPOS) X2 = XB*(X(I) -X0)	SLPLOT
	IF (NYPOS) Y2 = YB*(Y(I,J)-Y0)	SLPLOT

	IF (NXNEG) X2 = XA + XB*ALOG(AMAX1(X(I) ,XOMIN))	SLPLOT
	IF (NYNEG) Y2 = YA + YB*ALOG(AMAX1(Y(I,J),YOMIN))	SLPLOT
	IF (Y2.LT.0.0 .OR. Y2.GT.YL) GO TO 33	SLPLOT
	IF (X2.LT.0.0 .OR. X2.GT.XL) GO TO 33	SLPLOT
	IF (IPEN.EQ.3) GO TO 33	SLPLOT
	CALL PLOT (X2,Y2,IPEN)	SLPLOT
C	**      PLOT NYSM SYMBOLS      **	SLPLOT
	IF (NYY.EQ.1 .OR. MOD(I,IS).NE.0) GO TO 39	SLPLOT
	IF (MOD((I/IS)-1,NYY)+1.EQ.J) CALL SYMBOL (X2,Y2,0.14,J,0.0,-2)	SLPLOT
	GO TO 39	SLPLOT
33	IF (I.EQ.1) GO TO 39	SLPLOT
	DX = X2 - X1	SLPLOT
	IF (DX.NE.0.0) GO TO 34	SLPLOT
	AX0 = 1.0	SLPLOT
	AXL = 0.0	SLPLOT
	IF (X1.GE.0.0) AX0 = 0.0	SLPLOT
	IF (X1.LE.XL ) AXL = 1.0	SLPLOT
	GO TO 35	SLPLOT
34	AX0 = -X1 /DX	SLPLOT
	AXL = (XL-X1)/DX	SLPLOT
35	AX1 = AMIN1(AX0,AXL)	SLPLOT
	AX2 = AMAX1(AX0,AXL)	SLPLOT
	DY = Y2 - Y1	SLPLOT
	IF (DY.NE.0.0) GO TO 36	SLPLOT
	AY0 = 1.0	SLPLOT
	AYL = 0.0	SLPLOT
	IF (Y1.GE.0.0) AY0 = 0.0	SLPLOT
	IF (Y1.LE.YL ) AYL = 1.0	SLPLOT
	GO TO 37	SLPLOT
36	AY0 = -Y1 /DY	SLPLOT
	AYL = (YL-Y1)/DY	SLPLOT
37	AY1 = AMIN1(AY0,AYL)	SLPLOT
	AY2 = AMAX1(AY0,AYL)	SLPLOT
	A1 = AMAX1(AX1,AY1,0.0)	SLPLOT
	A2 = AMIN1(AX2,AY2,1.0)	SLPLOT
	IF (A1.GE.A2 ) GO TO 39	SLPLOT
	XP = X1 + A1*DX	SLPLOT
	YP = Y1 + A1*DY	SLPLOT
	CALL PLOT(XP,YP,IPEN)	SLPLOT
	IPEN = 2	SLPLOT
	XP = X1 + A2*DX	SLPLOT
	YP = Y1 + A2*DY	SLPLOT
	CALL PLOT(XP,YP,IPEN)	SLPLOT
	IF (A2.NE.1.0) IPEN = 3	SLPLOT
39	CONTINUE	SLPLOT
40	CONTINUE	SLPLOT
	RETURN	SLPLOT
	END	SLPLOT

C

SUBROUTINE SOLVA(R,AA11,AA22,AA12)

REV III.2 08/08/84REVIII

IMPLICIT REAL\*8 (A-H,O-Z)

DIMENSION R(2,3)

A11=R(1,1)\*\*2

A12=2.0\*R(2,1)\*R(1,1)

A13=R(2,1)\*\*2

A21=R(1,2)\*\*2

A22=2.0\*R(2,2)\*R(1,2)

A23=R(2,2)\*\*2

A31=R(1,3)\*\*2

A32=2.0\*R(2,3)\*R(1,3)

A33=R(2,3)\*\*2

DEL=A11\*(A22\*A33-A23\*A32)-A12\*(A21\*A33-A23\*A31)+

\* A13\*(A21\*A32-A22\*A31)

AA11=((A22-A12)\*(A33-A23)-(A23-A13)\*(A32-A22))/DEL

AA12=((A23-A13)\*(A31-A21)-(A21-A11)\*(A33-A23))/DEL

AA22=((A21-A11)\*(A32-A22)-(A22-A12)\*(A31-A21))/DEL

RETURN

END

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C	SUBROUTINE SOLVR(A1,A2,A3,A4,A5,A6,A7,A8,P,RX,RZ)	SOLVR
		REV III.2 08/08/84REVIII
C	IMPLICIT REAL*8 (A-H,O-Z)	SOLVR
C		SOLVR
C	*****	SOLVR
C		SOLVR
C	THIS SUBROUTINE WILL SOLVE A SET OF SIMULTANEOUS EQUATIONS	SOLVR
C	TO FIND COMPONETS OF VECTOR R THAT SATISFY THE PROPERTIES NEEDED	SOLVR
C	TO DETERMINE THE EQUATION OF THE PROJECTED ELLIPSE.	SOLVR
C		SOLVR
C	SEE WRITEUP.	SOLVR
C		SOLVR
C	*****	SOLVR
	DIMENSION P(3)	SOLVR
	B=A1*P(1)+A2*P(2)+A3*P(3)	SOLVR
	D=A4*P(1)+A5*P(2)+A6*P(3)	SOLVR
	T1=A7*(D/B)**2+A6-2.0*A8*D/B	SOLVR
	T2=2.0*A7*D/(B)**2-2.0*A8/B	SOLVR
	T3=A7*(1/B)**2-1	SOLVR
	RZ=(-T2+DSQRT(T2**2-4.0*T1*T3))/(2.0*T1)	SOLVR
	RX=-D*RZ/B-1.0/B	SOLVR
	RETURN	SOLVR
	END	SOLVR

	SUBROUTINE SPDAMP	SPDAMP
		REV IV 07/24/86SLIP
C	COMPUTES THE SPRING AND VISCOUS FORCE OF A SPRING DAMPER BETWEEN	SPDAMP
C	SPECIFIED POINTS ON SELECTED SEGMENTS AND ADDS THE RESULTING	SPDAMP
C	FORCE AND TORQUE TO THE U1 AND U2 ARRAYS.	SPDAMP
C		SPDAMP
	IMPLICIT REAL*8(A-H,O-Z)	SPDAMP
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	SPDAMP
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	SPDAMP
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	SPDAMP
	COMMON/DAMPER/ APSDM(3,20),APSDN(3,20),ASD(5,20),MSDM(20),MSDN(20)	SPDAMP
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	BUTLER2
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),	NCFORC
	* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF	SPDAMP
	COMMON/TEMPVS/DELM(3),DELN(3),DD(3),DEL,T1(3),T2(3),T3(3),T4(3),	SPDAMP
	* DUNIT(3),DV(3),DMV,DDO,FS,FD,TOTF(3),	SPDAMP
	* T5(3),T6(3),T7(3),T8(3)	SPDAMP
	CALL ELTIME(1,32)	SPDAMP
	NBSFO = NBSF	SPDAMP
	DO 90 I=1,NSD	SPDAMP
	M = MSDM(I)	SPDAMP
	N = MSDN(I)	SPDAMP
C		SPDAMP
C	COMPUTE VECTOR AND ITS MAGNITUDE BETWEEN THE SPECIFIED POINTS.	SPDAMP
C		SPDAMP
	CALL DOT31 (D(1,1,M),APSDM(1,I),DELM)	SPDAMP
	CALL DOT31 (D(1,1,N),APSDN(1,I),DELN)	SPDAMP
	DEL = 0.0	SPDAMP
	DO 10 K=1,3	SPDAMP
	DD(K) = SEGLP(K,M)+DELM(K)-SEGLP(K,N)-DELN(K)	SPDAMP
10	DEL = DEL+DD(K)**2	SPDAMP
	IF (DEL.LE.0.0) GO TO 90	SPDAMP
	DEL = DSQRT(DEL)	SPDAMP
C		SPDAMP
C	COMPUTE RELATIVE VELOCITY AND ITS COMPONENT ON VECTOR LINE.	SPDAMP
C		SPDAMP
	CALL CROSS(WMEG(1,M),APSDM(1,I),T1)	SPDAMP
	CALL CROSS(WMEG(1,N),APSDN(1,I),T2)	SPDAMP
	CALL DOT31 (D(1,1,M),T1,T3)	SPDAMP
	CALL DOT31 (D(1,1,N),T2,T4)	SPDAMP
	DO 20 K=1,3	SPDAMP
	DUNIT(K) = DD(K)/DEL	SPDAMP
20	DV(K) = SEGLV(K,M)+T3(K)-SEGLV(K,N)-T4(K)	SPDAMP
	DMV = DUNIT(1)*DV(1)+DUNIT(2)*DV(2)+DUNIT(3)*DV(3)	SPDAMP
C		SPDAMP
C	COMPUTE SPRING AND VISCOUS FORCE AND THE COMPONENTS	SPDAMP
C	ALONG THE UNIT VECTOR	SPDAMP
C		SPDAMP
	FS = 0.0	SPDAMP



	SUBROUTINE SPLINE (X,Y,F,N,L)		SPLINE
		REV 19	05/14/79SPLINE
C			SPLINE
C	ROUTINE TO FIT A SET OF POLYNOMIALS OF DEGREE L		SPLINE
C	TO A SET OF GIVEN DATA POINTS (X(I),Y(I),I=1,N)		SPLINE
C			SPLINE
C	FUNCTION IS OF FORM:		SPLINE
C			SPLINE
C	$Y = F(2,K) + F(3,K)*DX + F(4,K)*DX**2 + F(5,K)*DX**3$		SPLINE
C			SPLINE
C	WHERE: $DX = XX - F(1,K)$		SPLINE
C	$F(1,K) \leq XX \leq F(1,K+1)$ ; (SETS K)		SPLINE
C	IF $(XX.GT.F(1,N))$ ; USE K=N, CONSTANT FIT TO Y(N)		SPLINE
C	IF $(XX.LT.F(1,1))$ ; EXTRAPOLATED FIT FOR K=1		SPLINE
C			SPLINE
C	$F(1,I) = X(I)$ , $I=1,N$		SPLINE
C	$F(2,I) = Y(I)$ , $I=1,N$		SPLINE
C			SPLINE
C	DEGREE L	CONTINUITY	SPLINE
C	0 $F(3,I) = F(4,I) = F(5,I) = 0$ , $I=1,N$	NONE	SPLINE
C	1 $F(4,I) = F(5,I) = 0$ , $I=1,N$	Y	SPLINE
C	2 $F(5,I) = 0$ , $I=1,N$	Y,Y'	SPLINE
C	3 CUBIC SPLINE	Y,Y',Y''	SPLINE
C			SPLINE
C	$F(K,N)=0$ FOR K=3,5 IN ALL CASES		SPLINE
C			SPLINE
C	FOR L=2 AND L=3 THE CHANGES IN THE L'TH DERIVATIVES ARE MINIMIZED		SPLINE
C			SPLINE
C	SPECIAL CASES:		SPLINE
C	N=1 ; TREATED AS L=0		SPLINE
C	N=2 ; TREATED AS L=MIN(L,1)		SPLINE
C	L<0 ; TREATED AS L=0		SPLINE
C	L>3 ; TREATED AS L=3		SPLINE
C			SPLINE
C	STORAGE REQUIRED X(N),Y(N),F(5,N); SET BY CALLING PROGRAM		SPLINE
C			SPLINE
C	USAGE:		SPLINE
C	ALL COMPUTATIONS AND REAL VARIABLES ARE DOUBLE PRECISION		SPLINE
C	GIVEN: L,N, (X(I),Y(I),I=1,N)		SPLINE
C	CALL SPLINE (X,Y,F,N,L) ; SETS F		SPLINE
C			SPLINE
CC			SPLINE
CC	TO EVALUATE FUNCTION AND DERIVATIVES AT POINT XX		SPLINE
CC			SPLINE
C	DO 10 K=1,N		SPLINE
C	IF (K.EQ.N) GO TO 11		SPLINE
C	IF (XX.LT.F(1,K+1)) GO TO 11		SPLINE
C	10 CONTINUE		SPLINE
C	11 $DX = XX - F(1,K)$		SPLINE
C	$YY = F(2,K) + DX*(F(3,K)+DX*(F(4,K)+DX*F(5,K)))$		SPLINE

C	YD = F(3,K) + DX*(2.0*F(4,K)+3.0*DX*F(5,K))	SPLINE
C	YDD = 2.0*F(4,K) + 6.0*DX*F(5,K)	SPLINE
C	YDDD = 6.0*F(5,K)	SPLINE
C	YDDDD = 0.0	SPLINE
CC		SPLINE
CC	FUNCTIONAL VALUE IN YY, DERIVATIVES IN YD'S	SPLINE
CC	REPEAT FOR NEXT VALUE OF XX	SPLINE
C		SPLINE
C	AUTHOR: DR. JOHN T. FLECK	SPLINE
C		SPLINE
	IMPLICIT REAL*8 (A-H,O-Z)	SPLINE
	DIMENSION X(N),Y(N),F(5,N),C(2,3)	SPLINE
	DO 20 I=1,N	SPLINE
	F(1,I) = X(I)	SPLINE
	DO 10 K=2,5	SPLINE
10	F(K,I) = 0.0	SPLINE
	IF (L.LT.3) F(2,I) = Y(I)	SPLINE
20	IF (L.GT.0 .AND. I.LT.N) F(3,I) = (Y(I+1)-Y(I))/(X(I+1)-X(I))	SPLINE
	IF (L.LT.2 .OR. N.LT.3) GO TO 99	SPLINE
	IF (L.GE.3) GO TO 50	SPLINE
	D1 = X(2) - X(1)	SPLINE
	SS = 0.0	SPLINE
	DS = 0.0	SPLINE
	DO 30 I=3,N	SPLINE
	F(4,I-1) = F(3,I-1) - F(3,I-2) - F(4,I-2)	SPLINE
	DX1 = X(I) - X(I-1)	SPLINE
	DX2 = X(I-1) - X(I-2)	SPLINE
	DD = D1/DX1 + D1/DX2	SPLINE
	SS = SS + DD*DD	SPLINE
	DS = DS + DD*(F(4,I-1)/DX1 - F(4,I-2)/DX2)	SPLINE
30	D1 = -D1	SPLINE
	F(4,I) = DS/SS	SPLINE
	DX = (X(2)-X(1))*F(4,I)	SPLINE
	F(3,I) = F(3,I) - DX	SPLINE
	DO 40 I=3,N	SPLINE
	XX = F(4,I-1) - DX	SPLINE
	F(3,I-1) = F(3,I-1) - XX	SPLINE
	F(4,I-1) = XX/(X(I)-X(I-1))	SPLINE
40	DX = -DX	SPLINE
	GO TO 99	SPLINE
C		SPLINE
C	CUBIC SPLINE	SPLINE
C		SPLINE
50	DO 51 I=2,N	SPLINE
	IF (I.EQ.N) GO TO 51	SPLINE
	F(4,I) = 3.0*(F(3,I)-F(3,I-1))	SPLINE
	F(5,I) = 2.0*(X(I+1)-X(I-1))	SPLINE
51	F(3,I-1) = 0.0	SPLINE
	F(2,N) = -1.0	SPLINE
	F(3,1) = -1.0	SPLINE

[illegible]

	DOUBLE PRECISION FUNCTION SPRNGF(T,D,ZD,SPR,JSTOP)	SPRNGF
C		REV IV 07/23/86TWOPI
C	COMPUTES NONLINEAR SPRING TORQUE FOR JOINTS AS A FUNCTION OF ANGLE	SPRNGF
C	ACTUALLY ROUTINE RETURNS TORQUE/ABS(SIN THETA)	SPRNGF
C		SPRNGF
C	ARGUMENTS:	SPRNGF
C	T : COS THETA WHERE THETA IS ANGLE OF JOINT (0<THETA<PI)	SPRNGF
C	D : ABS(SIN THETA)	SPRNGF
C	ZD : -THETA DOT * SIN THETA	SPRNGF
C	SPR : ARRAY OF 5 VALUES DESCRIBING FUNCTION EVALUATION	SPRNGF
C	JSTOP : INDICATOR TO BE SET TO ONE IF JOINT IS IN STOP	SPRNGF
C		SPRNGF
	IMPLICIT REAL*8 (A-H,O-Z)	SPRNGF
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	SPRNGF
*	UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
	DIMENSION SPR(5)	SPRNGF
C		SPRNGF
C	RESET T=1 IF T>1 (HAD & HBD IN VISPR)	SPRNGF
C		SPRNGF
	IF (T.GT.1.0) T = 1.0	SPRNGF
	IF (T.LT.-1.0) T = -1.0	SPRNGF
	Z = DACOS(T)	SPRNGF
	U = EPS(1)*D	SPRNGF
	Q = 0.0	SPRNGF
	IF (D.NE.0.0) Q = -ZD/U	SPRNGF
	IF (Q.GT.1.0) Q = 1.0	SPRNGF
	IF (Q.LT.-1.0) Q = -1.0	SPRNGF
	X = 0.5*(1.0+SPR(4) + Q*(1.0-SPR(4)) )	SPRNGF
	Y = 0.0	SPRNGF
	IF (D.NE.0.0) Y = Z/D	SPRNGF
	Q = 1.0	SPRNGF
	IF (DABS(Z).LT.EPS(4)) Y = DSIGN(Q,Z)	SPRNGF
	SPRNGF = Y*SPR(1)	SPRNGF
	JSTOP = 0	SPRNGF
	IF (SPR(5).GT.0.0) GO TO 10	SPRNGF
	SPRNGF = X*SPRNGF	SPRNGF
	GO TO 11	SPRNGF
10	IF (Z.LT.SPR(5)) GO TO 11	SPRNGF
	JSTOP = 1	SPRNGF
	Z = Z-SPR(5)	SPRNGF
	SPRNGF = SPRNGF + X/D*(SPR(2)+Z*SPR(3))*Z**2	SPRNGF
11	CONTINUE	SPRNGF
	RETURN	SPRNGF
	END	SPRNGF





	SUBROUTINE UNIT1(IND)	UNIT1
		REV IV 02/20/87HYPER
C	THIS SUBROUTINE REPLACES THE PROGRAM CODE THAT PREVIOUSLY WAS	UNIT1
C	NEAR THE END OF THE MAIN PROGRAM TO WRITE ON UNIT 1 THAT DATA	UNIT1
C	USED FOR VARIOUS PLOTTING PROGRAMS (E.G. BUBBLE MAN PLOT).	UNIT1
C		UNIT1
C	THIS SUBROUTINE IS WRITTEN TO GENERATE UNIT 1 IN SUCH A MANNER	UNIT1
C	TO BE COMPATIBLE WITH THE INPUT REQUIREMENTS FOR THE AAMRL VIEW	UNIT1
C	PROGRAM THAT IS NOW BEING DISTRIBUTED ON THE CVS PROGRAM TAPES.	UNIT1
C		UNIT1
C	ARGUMENTS:	UNIT1
C	IND = 0: CALL IS FROM THE MAIN PROGRAM	UNIT1
C	* 0: CALL IS FROM SUBROUTINE EQUILB	UNIT1
C		UNIT1
	IMPLICIT REAL*8 (A-H,O-Z)	UNIT1
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	UNIT1
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	UNIT1
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	UNIT1
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)	EDGE
	COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),	UNIT1
*	MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),	UNIT1
*	NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)	UNIT1
	COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),	UNIT1
*	NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)	TTHKREF
	COMMON/TEMPVS/ XD(3,3,30),XSEGLP(3,30),XPL(17,30),XBD(24,40),	UNIT1
*	T1(3),T3(3,3)	FIXWBS
	REAL XTIME,XD,XSEGLP,XPL,XBD	UNIT1
	DATA IFIRST/0/	UNIT1
	IF (NPRT(1).EQ.0) GO TO 99	UNIT1
	IF (IFIRST.NE.0) GO TO 20	UNIT1
	IFIRST = 1	UNIT1
C		UNIT1
C	FIRST TIME IN ROUTINE, WRITE STATIC DATA ON OUTPUT UNIT 1.	UNIT1
C	DATA MUST BE CONVERTED TO SINGLE PRECISION FOR VIEW PROGRAM.	UNIT1
C		UNIT1
	DO 11 J=1,30	UNIT1
	DO 11 I=1,17	FIXWBS
11	XPL(I,J) = PL(I,J)	FIXWBS
	DO 12 J=1,40	UNIT1
	K = 1	HYPER
	IF (BD(1,J).LT.0.0) K = 2	HYPER
	DO 12 I=1,24	UNIT1
	XBD(I,J) = BD(K,J)	HYPER
12	K = K + 1	HYPER
	WRITE (1) NSEG,NPL,XPL,XBD,MPL	UNIT1
	GOTO 99	EDGE
C		UNIT1
C	WRITE TIME POINT DATA ON OUTPUT UNIT 1.	UNIT1
C	DATA MUST BE CONVERTED TO SINGLE PRECISION FOR VIEW PROGRAM.	UNIT1

C

```
20  XTIME = TIME
    DO 22 K=1,30
    DO 22 J=1,3
    DO 21 I=1,3
21  XD(I,J,K) = D(I,J,K)
22  XSEGLP(J,K) = SEGLP(J,K)
    DO 25 K=1,NSEG
    IF (LPMI(K).EQ.0) GO TO 25
    CALL DOT33 (DPMI(1,1,K),D(1,1,K),T3)
    DO 24 I=1,3
    DO 24 J=1,3
24  XD(I,J,K) = T3(I,J)
25  CONTINUE
    WRITE (1) XTIME,XSEGLP,XD
99  RETURN
    END
```

```
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
```

	SUBROUTINE UPDATE(I)		UPDATE
		REV IV 07/24/86	SLIP
	CALLED BY SUBROUTINE DINT		UPDATE
			UPDATE
	(I=1) AT THE START OF A NEW STEP TO SETUP ANY NEW CONDITIONS		UPDATE
	TO BE VALID FOR ENTIRE INTEGRATION STEP		UPDATE
	A. UPDATE FORCE DEFLECTION FUNCTIONS(SUBROUTINE UPDFDC)		UPDATE
	B. TEST FOR LOCKED JOINTS		UPDATE
	NOTE: ARGUMENT I WILL BE SET TO -1 TO RESET INTEGRATOR.		UPDATE
			UPDATE
	(I=2) AT THE END OF EACH SUCCESSFUL INTEGRATION STEP TO		UPDATE
	COMPLETE CALCULATIONS FOR OUTPUT (SUBROUTINE AIRBG3).		UPDATE
			UPDATE
	IMPLICIT REAL*8(A-H,O-Z)		UPDATE
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		UPDATE
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		UPDATE
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		UPDATE
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		UPDATE
	* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		UPDATE
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		UPDATE
	* F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),		UPDATE
	* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),		UPDATE
	* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)		UPDATE
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)		UPDATE
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),		NCFORC
	* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF		UPDATE
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		UPDATE
	* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		UPDATE
	* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		UPDATE
	* KQ1(12),KQ2(12),KQTYPE(12)		UPDATE
	COMMON/TEMPVI/ CREST,TTI(3),RII(3),R2I(3),JSTOP(4,2,30)		UPDATE
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),		JDRIFT
	* FE(3,30),TQE(3,30),CONST(5,30)		JDRIFT
	COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),		UPDATE
	* XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),		UPDATE
	* NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)		UPDATE
	DIMENSION TQTEST(3),LOCK(8,3),T(3)		UPDATE
	DATA LOCK/-8, 6, 5, 7,-3,-2,-4, 1,		UPDATE
	* 6,-8, 4,-3, 7,-1,-5, 2,		UPDATE
	* 5, 4,-8,-2,-1, 7,-6, 3/		UPDATE
			UPDATE
	CALL AIRBG3 FOR AIRBAG, IF ANY.		UPDATE
			UPDATE
	IF (NBAG.NE.0) CALL AIRBG3(I)		UPDATE
	IF (I.EQ.2) GO TO 42		UPDATE
	CALL ELTIME (1,7)		UPDATE
	IF (NPL.LE.0) GO TO 13		UPDATE

C		UPDATE
C	CALL UPDFDC FOR EACH ALLOWED PLANE-SEGMENT CONTACT.	UPDATE
C		UPDATE
	NPSF = 0	UPDATE
	DO 12 J=1,NPL	UPDATE
	NK = MNPL(J)	UPDATE
	IF (NK.LE.0) GO TO 12	UPDATE
	DO 11 K = 1, NK	UPDATE
	NPSF = NPSF+1	UPDATE
	NT = NTPL(K,J)	UPDATE
	NF = NTAB(NT+5)	UPDATE
	CALL UPDFDC(NT)	UPDATE
	IF (NT.GT.0.OR.TAB(NF+3).EQ.0.0) GO TO 11	UPDATE
	CALL IMPULS(1,K,J)	UPDATE
	I = -1	UPDATE
	11 CONTINUE	UPDATE
	12 CONTINUE	UPDATE
	13 IF (NBLT.LE.0) GO TO 16	UPDATE
C		UPDATE
C	CALL UPDFDC FOR EACH ALLOWED BELT-SEGMENT CONTACT.	UPDATE
C		UPDATE
	DO 15 J=1,NBLT	UPDATE
	NK = MNBLT(J)	UPDATE
	IF (NK.LE.0) GO TO 15	UPDATE
	DO 14 K = 1,NK	UPDATE
	NT = NTBLT(K,J)	UPDATE
	NF = NTAB(NT+5)	UPDATE
	NT6 = NT+6	UPDATE
	CALL UPDFDC(NT)	UPDATE
C		UPDATE
C	AND FOR 2ND FUNCTION, IF FULL BELT FRICTION.	UPDATE
C		UPDATE
	14 IF (NF.NE.0) CALL UPDFDC(NT6)	UPDATE
	15 CONTINUE	UPDATE
C		UPDATE
C	CALL UPDFDC FOR EACH ALLOWED SEGMENT-SEGMENT CONTACT.	UPDATE
C		UPDATE
	16 NSSF = 0	UPDATE
	DO 18 J=1,NSEG	UPDATE
	NK = MNSEG(J)	UPDATE
	IF (NK.LE.0) GO TO 18	UPDATE
	DO 17 K = 1,NK	UPDATE
	NSSF = NSSF+1	UPDATE
	NT = NTSEG(K,J)	UPDATE
	NF = NTAB(NT+5)	UPDATE
	CALL UPDFDC(NT)	UPDATE
	IF (NT.GT.0.OR.TAB(NF+3).EQ.0.0) GO TO 17	UPDATE
	CALL IMPULS(3,K,J)	UPDATE
	I = -1	UPDATE
	17 CONTINUE	UPDATE

18	CONTINUE	UPDATE
	IF (NHRNSS.LE.0) GO TO 71	UPDATE
C		UPDATE
C	CALL UPDFDC FOR EACH BELT OF HARNESS-BELT SYSTEMS.	UPDATE
C		UPDATE
	CALL HPTURB	UPDATE
	J1 = 1	UPDATE
	K1 = 1	UPDATE
	DO 70 II=1,NHRNSS	UPDATE
	IF (NBLTPH(II).LE.0) GO TO 70	UPDATE
	J2 = J1 + NBLTPH(II) - 1	UPDATE
	DO 69 J=J1,J2	UPDATE
	IF (NPTPLY(J).LE.0) GO TO 69	UPDATE
	NT = NTHRNS(J)	UPDATE
	CALL UPDFDC(NT)	UPDATE
	K2 = K1 + NPTPLY(J) - 1	UPDATE
	DO 68 K=K1,K2	UPDATE
	KI = NL(1,K)	UPDATE
	NT = IBAR(3,KI)	UPDATE
	CALL UPDFDC(NT)	UPDATE
68	CONTINUE	UPDATE
	K1 = K2+1	UPDATE
69	CONTINUE	UPDATE
	J1 = J2+1	UPDATE
70	CONTINUE	UPDATE
71	IF (NJNT.LE.0) GO TO 37	UPDATE
C		UPDATE
C	CHECK FOR IMPULSE ON JOINT STOPS	UPDATE
C	TO BE CALLED IF IN JOINT STOP (JSTOP(1)=1) THIS TIME STEP	UPDATE
C	BUT NOT IN IN JOINT STOP (JSTOP(2)=0) AT PREVIOUS TIME.	UPDATE
C		UPDATE
	DO 21 K=1,NJNT	UPDATE
	IF (JNT(K).EQ.0) GO TO 21	UPDATE
	IF (IABS(IPIN(K)).NE.4 .AND. VISC(7,3*K-2).EQ.0.0) GO TO 20	UPDATE
	DO 19 J=1,3	UPDATE
	K3J = 3*K-3+J	UPDATE
	IF (IABS(IPIN(K)).NE.4) K3J=3*K-2	UPDATE
	IF (IABS(IPIN(K)).EQ.4 .AND. VISC(7,K3J).EQ.0.0) GO TO 19	UPDATE
	IF (JSTOP(J,1,K).NE.1.OR.JSTOP(J,2,K).NE.0) GO TO 19	UPDATE
	CALL IMPULS(4,J,K)	UPDATE
	I = -1	UPDATE
19	JSTOP(J,2,K) = JSTOP(J,1,K)	UPDATE
20	IF (IGLOB(K).EQ.0) GO TO 21	UPDATE
	NT = IGLOB(K)	UPDATE
	MT = NTAB(NT+5)	UPDATE
	NT1 = NTAB(NT+2)	UPDATE
	NTAB(NT+2) = 0	UPDATE
	CALL UPDFDC(NT)	UPDATE
	NT = IABS(NT)	UPDATE
	NTAB(NT+2) = NT1	UPDATE



IPINJ = -IPIN(J)	UPDATE
WRITE (6,27) TMSEC,J,IPINJ,IPIN(J)	UPDATE
27 FORMAT('0 AT TIME =',F9.3,' MSEC, IPIN(' ,12,	BUTLER1
* ' ) HAS BEEN CHANGED FROM',13,' TO',13)	BUTLER1
28 CONTINUE	UPDATE
C	UPDATE
C TEST TO LOCK OR UNLOCK EULER JOINTS AXES.	UPDATE
C USE SAME TEST AS ABOVE BUT ON EACH AXIS SERARATELY.	UPDATE
C	UPDATE
C IF LOCK(IEULER,K) IS NEGATIVE, AXIS K IS LOCKED;	UPDATE
C TO UNLOCK AXIS SET IEULER TO -LOCK(IEULER,K).	UPDATE
C	UPDATE
C IF LOCK(IEULER,K) IS POSITIVE, AXIS K IS UNLOCKED;	UPDATE
C TO LOCK AXIS SET IEULER TO LOCK(IEULER,K).	UPDATE
C	UPDATE
DO 36 J=1,NJNT	UPDATE
IF (IABS(IPIN(J)).NE.4) GO TO 36	UPDATE
JEULER = IEULER(J)	UPDATE
CALL DOT31(HIR(1,1,J),TQ(1,J),TQTEST)	UPDATE
DO 31 K=1,3	UPDATE
K3J = 3*J-3+K	UPDATE
NLOCK = LOCK(JEULER,K)	UPDATE
IF (NLOCK.GT.0) GO TO 29	UPDATE
IF (VISC(4,K3J).EQ.0.0) GO TO 31	UPDATE
IF (DABS(TQTEST(K)).LE.VISC(4,K3J)) GO TO 31	UPDATE
JEULER = -NLOCK	UPDATE
HA(K,2*J-1) = TQTEST(K)	UPDATE
GO TO 31	UPDATE
29 IF (HA(K,2*J).EQ.0.0) HA(K,2*J-1) = 0.0	UPDATE
IF (VISC(5,K3J).EQ.0.0) GO TO 30	UPDATE
IF (DABS(TQTEST(K)).LT.VISC(5,K3J)) JEULER = NLOCK	UPDATE
GO TO 31	UPDATE
30 IF (VISC(6,K3J).EQ.0.0) GO TO 31	UPDATE
IF (DABS(ANGD(K,J)).LT.VISC(6,K3J)) JEULER = NLOCK	UPDATE
31 CONTINUE	UPDATE
IF (JEULER.EQ.IEULER(J)) GO TO 36	UPDATE
TMSEC = 1000.0*TIME	UPDATE
WRITE (6,32) TMSEC,J,IEULER(J),JEULER	UPDATE
32 FORMAT('0 AT TIME =',F9.3,' MSEC, IEULER(' ,12,	BUTLER1
* ' ) HAS BEEN CHANGED FROM',13,' TO',13)	BUTLER1
IF (JEULER.EQ.8) GO TO 35	UPDATE
IF (IEULER(J).EQ.7) GO TO 35	UPDATE
IF (IEULER(J).EQ.6 .AND. (JEULER.EQ.2.OR.JEULER.EQ.1)) GO TO 35	UPDATE
IF (IEULER(J).EQ.5 .AND. (JEULER.EQ.3.OR.JEULER.EQ.1)) GO TO 35	UPDATE
IF (IEULER(J).EQ.4 .AND. (JEULER.EQ.3.OR.JEULER.EQ.2)) GO TO 35	UPDATE
MODE = -1	UPDATE
K = JEULER	UPDATE
IF (K.GT.3) GO TO 33	UPDATE
IF (K.EQ.2) GO TO 34	UPDATE
K4 = 4-K	UPDATE

	CALL CROSS (HIR(1,K4,J),HIR(1,2,J),T)	UPDATE
	IEULER(J) = 8	UPDATE
	IPIN(J) = 4	UPDATE
	CALL IMPLS2(MODE,J,T)	UPDATE
	I = -1	UPDATE
	GO TO 35	UPDATE
33	MODE = 1	UPDATE
	K = K-3	UPDATE
	IF (K.GT.3) MODE=0	UPDATE
34	IEULER(J) = 8	UPDATE
	IPIN(J) = 4	UPDATE
	CALL IMPLS2(MODE,J,HIR(1,K,J))	UPDATE
	I = 1	UPDATE
35	IEULER(J) = JEULER	UPDATE
	IPIN(J) = 4	UPDATE
	IF (IEULER(J).NE.8) IPIN(J) = -4	UPDATE
C	GET SINE AND COSINE OF NUTATION IF IEULER GOES TO STATE 2	JDRIFT
	CALL EJOINT(-1,J)	JDRIFT
	IF(JEULER.NE.2) GOTO 36	JDRIFT
	TQM=ANG(2,J)+CONST(2,J)	JDRIFT
	CONST(4,J) = DCOS(TQM)	JDRIFT
	CONST(5,J) = DSIN(TQM)	JDRIFT
36	CONTINUE	UPDATE
	DO 90 J = 1,NJNT	SLIP
	IF (IABS(IPIN(J)).LE.4) GO TO 90	SLIP
	IF (IEULER(J).GE.0) GO TO 90	SLIP
	IF (CONST(1,J).EQ.0.0.AND.CONST(2,J).EQ.0.0) GO TO 90	SLIP
	M = JNT(J)	SLIP
	FTEST = XDY(HT(1,3,2*J-1),D(1,1,M),F(1,J))	SLIP
	IF (FTEST.GE.CONST(1,J).AND.FTEST.LE.CONST(2,J)) GO TO 90	SLIP
	IEULER(J) = 0	SLIP
	TMSEC = 1000.0*TIME	SLIP
	WRITE (6,88) TMSEC,J	SLIP
88	FORMAT(/'0 AT TIME =',F9.3,' MSEC, JOINT ',I3,' HAS BEEN',	SLIP
	* ' UNLOCKED AND ALLOWED TO SLIP.'/)	SLIP
90	CONTINUE	SLIP
C	F IS THE FORCE ON SEGMENT J+1, - F IS ON SEGMENT M	SLIP
C		UPDATE
37	IF (NQ.LE.0) GO TO 41	UPDATE
	DO 40 K=1,NQ	UPDATE
	IF (KQTYPE(K).LT.3) GO TO 40	UPDATE
	IF (KQTYPE(K).GT.4) GO TO 40	UPDATE
	IF (CFQQ(K).LT.0.0) KQTYPE(K) = -KQTYPE(K)	UPDATE
	IF (CFQQ(K).LT.0.0) GO TO 39	UPDATE
C		UPDATE
C	TEST IF ROLLING CONSTRAINT SHOULD BE SLIDING AND VICE VERSA.	UPDATE
C		UPDATE
	QN = -XDY(TQQ(1,K),HHT(1,1,K),QQ(1,K))	UPDATE
	IF (NPRT(24).NE.0) WRITE (6,38) KQTYPE(K),KQ1(K),KQ2(K),	UPDATE
	* (RK1(II,K),II=1,3),(RK2(II,K),II=1,3),	UPDATE



*	((HHT(II,J,K),J=1,3),II=1,3),	UPDATE
*	(QQ(II,K),II=1,3),(TQQ(II,K),II=1,3),(RQQ(II,K),II=1,3),	UPDATE
*	(HQQ(II,K),II=1,3),SQQ(K),CFQQ(K),QN	UPDATE
38	FORMAT('0 UPDATE ROLL-SLIDE TEST'/(2X,9G14.6))	UPDATE
	IF (QN.LT.0.0) KQTYPE(K) = -4	UPDATE
	IF (QN.LT.0.0) GO TO 39	UPDATE
	QDOTQ = QQ(1,K)**2 + QQ(2,K)**2 + QQ(3,K)**2	UPDATE
	QT = DSQRT(QDOTQ-QN**2)	UPDATE
	IF (KQTYPE(K).EQ.3 .AND. QT.LE.CFQQ(K)*QN) GO TO 40	UPDATE
	IF (KQTYPE(K).EQ.4 .AND. QT.GE.0.9*CFQQ(K)*QN) GO TO 40	UPDATE
	KQTYPE(K) = 7-KQTYPE(K)	UPDATE
39	CALL OUTPUT(0)	UPDATE
	CALL SETUP2	UPDATE
	CALL DAUX(K)	UPDATE
	IF (NPRT(24).NE.0) CALL OUTPUT(1)	UPDATE
	IF (NPRT( 3).NE.0) CALL PRINT (6HUPDATE)	UPDATE
	I = -1	UPDATE
40	CONTINUE	UPDATE
41	CALL ELTIME(2,7)	UPDATE
42	RETURN	UPDATE
	END	UPDATE

	SUBROUTINE UPDFDC (M)	UPDFDC
		REV III.2 08/08/84REVIII
C	UPDATE FORCE DEFLECTION CURVE DEFINITION THAT IS DEFINED	UPDFDC
C	IN LOCATION M OF NTAB ARRAY. SUBROUTINE ASSUMES THAT	UPDFDC
C	A SUCCESSFUL INTEGRATION STEP HAS JUST BEEN COMPLETED AND	UPDFDC
C	WILL COMPUTE ENTIRE CURVE DEFINITION TO BE VALID FOR NEXT STEP.	UPDFDC
C		UPDFDC
	IMPLICIT REAL*8(A-H,O-Z)	UPDFDC
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	DIMENB
	L = NTAB(M)	UPDFDC
	IF (L.EQ.0) GO TO 99	UPDFDC
	D = TAB(L)	UPDFDC
	IF (D.LT.0.0) D = 0.0	UPDFDC
	DLAST = TAB(L+1)	UPDFDC
	IF (D.EQ.DLAST) GO TO 99	UPDFDC
	DCUBIC = TAB(L+6)	UPDFDC
	IF (D.EQ.DCUBIC) GO TO 98	UPDFDC
	AREA = TAB(L+2)	UPDFDC
	RLAST = TAB(L+3)	UPDFDC
	GLAST = TAB(L+4)	UPDFDC
	DG = TAB(L+5)	UPDFDC
	DGO = DG	UPDFDC
	DREF = TAB(L+7)	UPDFDC
	DMAX = TAB(L+8)	UPDFDC
	DINER = TAB(L+9)	UPDFDC
	FDMAX = TAB(L+10)	UPDFDC
	DCO = TAB(L+18)	UPDFDC
	LQ = L+11	UPDFDC
	LC = L+14	UPDFDC
	IF (NTAB(M+1).LT.0) GO TO 98	UPDFDC
	IF (D-DCUBIC) 10,98,20	UPDFDC
C		UPDFDC
C	D < DCUBIC, DEFINE NEW CUBIC	UPDFDC
C	$Y(X) = A0 + A1*(X-X1) + A2*(X-X1)**2 + A3*(X-X1)**3$	UPDFDC
C	WHOSE DERIVATIVE IS	UPDFDC
C	$Y'(X) = A1 + 2*A2*(X-X1) + 3*A3*(X-X1)**2$	UPDFDC
C		UPDFDC
10	X1 = DMAX1 (D,DG)	UPDFDC
	X2 = DREF	UPDFDC
C		UPDFDC
C	IF INERTIAL SPIKE EXISTS AND IF DIMAX < DREF , DROP INERTIAL SPIKE	UPDFDC
	NI = NTAB(M+2)	UPDFDC
	IF (NI.GT.0.AND.TAB(NI+3).GT.0.0.AND.DREF.GT.TAB(NI+3))NTAB(M+2)=0	UPDFDC
	DX = X2-X1	UPDFDC
	X = X1-DG	UPDFDC
	$Y1 = TAB(LQ) + X*(TAB(LQ+1)+X*TAB(LQ+2))$	UPDFDC
	$Y1P = TAB(LQ+1)+2.0*X*TAB(LQ+2)$	UPDFDC
	X2DOT = 0.0	UPDFDC
	CALL FRCDL (X2,X2DOT,M,0,Y2P,ELOSS)	UPDFDC
	CALL FRCDL (X2,X2DOT,M,1,Y2 ,ELOSS)	UPDFDC

	DCUBIC = X1	UPDFDC
	DC0 = DCUBIC	UPDFDC
C		UPDFDC
C	A0 = Y(X1) (THE VALUE OF THE QUADRATIC AT X1)	UPDFDC
C	A1 = Y'(X1) (THE DERIVATIVE OF THE QUADRATIC AT X1)	UPDFDC
C		UPDFDC
	A0 = Y1	UPDFDC
	A1 = Y1P	UPDFDC
C		UPDFDC
C	SOLVE SIMULTANEOUSLY FOR A2 AND A3	UPDFDC
C	$A2*(X2-X1)**2 + A3*(X2-X1)**3 = Y(X2)-A0-A1*(X2-X1)$	UPDFDC
C	$2*A2*(X2-X1) + 3*A3*(X2-X1)**2 = Y'(X2)-A1$	UPDFDC
C		UPDFDC
	R13 = (Y2 - Y1 -Y1P*DX)/DX**2	UPDFDC
	R23 = (Y2P - Y1P)/DX	UPDFDC
	A2 = 3.0*R13 - R23	UPDFDC
	A3 = (R23 - 2.0*R13)/DX	UPDFDC
C		UPDFDC
C	IF LOCAL MINIMUM OF CUBIC (ABSCISSA VALUE WHERE Y'(X) = 0)	UPDFDC
C	LIES BETWEEN DCUBIC AND DREF AND IS NEGATIVE, THEN REPLACE	UPDFDC
C	CUBIC DEFINITION WITH STRAIGHT LINE BETWEEN (X1,Y1) AND (X2,Y2).	UPDFDC
C		UPDFDC
	IF (A3.NE.0.0) GO TO 14	UPDFDC
	R2 = -0.5*A1/A2	UPDFDC
	GO TO 15	UPDFDC
14	A33 = 3.0*A3	UPDFDC
	DISC = A2**2-A1*A33	UPDFDC
	IF (DISC.LT.0.0) GO TO 13	UPDFDC
	SQDISC = DSQRT(DISC)	UPDFDC
	R1 = (-A2+SQDISC)/A33	UPDFDC
	IF (R1.LE.0.0.OR.R1.GE.DX) GO TO 11	UPDFDC
	FR1 = A0+R1*(A1+R1*(A2+R1*A3))	UPDFDC
	IF (FR1.LT.0.0) GO TO 12	UPDFDC
11	R2 = (-A2-SQDISC)/A33	UPDFDC
15	IF (R2.LE.0.0.OR.R2.GE.DX) GO TO 13	UPDFDC
	FR2 = A0+R2*(A1+R2*(A2+R2*A3))	UPDFDC
	IF (FR2.GE.0.0) GO TO 13	UPDFDC
12	A0 = Y1	UPDFDC
	A1 = (Y2-Y1)/DX	UPDFDC
	A2 = 0.0	UPDFDC
	A3 = 0.0	UPDFDC
13	TAB(LC) = A0	UPDFDC
	TAB(LC+1) = A1	UPDFDC
	TAB(LC+2) = A2	UPDFDC
	TAB(LC+3) = A3	UPDFDC
	TAB(L+6) = DCUBIC	UPDFDC
	TAB(L+18) = DC0	UPDFDC
	GO TO 98	UPDFDC
20	IF (D-DREF) 21,21,30	UPDFDC
C		UPDFDC

C	DCUBIC < D < DREF, DEFINE NEW QUADRATIC FROM CUBIC CURVE.	UPDFDC
C		UPDFDC
21	X = D-DC0	UPDFDC
	Y2 = TAB(LC)+X*(TAB(LC+1)+X*(TAB(LC+2)+X*TAB(LC+3)))	UPDFDC
	X1 = DCUBIC - DG	UPDFDC
	AREA = X1*(TAB(LQ)+X1*(TAB(LQ+1)/2.0+X1*TAB(LQ+2)/3.0))	UPDFDC
	* + X*(TAB(LC)+X*(TAB(LC+1)/2.0+X*(TAB(LC+2)/3.0+X*TAB(LC+3)/4.0))	UPDFDC
	X = DCUBIC - DC0	UPDFDC
	IF (X.NE.0.0) AREA = AREA	UPDFDC
	* - X*(TAB(LC)+X*(TAB(LC+1)/2.0+X*(TAB(LC+2)/3.0+X*TAB(LC+3)/4.0))	UPDFDC
	GO TO 31	UPDFDC
C		UPDFDC
C	DREF < D, DEFINE NEW QUADRATIC FROM BASE CURVE.	UPDFDC
C		UPDFDC
C	IF DINER < D , REMOVE INFERTIAL SPIKE	UPDFDC
C		UPDFDC
30	IF (NTAB(M+2).GT.0 .AND. D.GE.DINER) NTAB(M+2) = 0	UPDFDC
	NR = NTAB(M+3)	UPDFDC
	RLAST = 1.0	UPDFDC
	IF (NR.GT.0 ) RLAST = EVALFD(D,NR,1)	UPDFDC
	IF (RLAST.NE.1.0) GO TO 39	UPDFDC
C		UPDFDC
C	R = 1, USE BASE CURVE FOR UNLOADING	UPDFDC
C		UPDFDC
	DG = 0.0	UPDFDC
	DCUBIC = 0.0	UPDFDC
	DREF = 0.0	UPDFDC
	A0 = 0.0	UPDFDC
	A1 = 0.0	UPDFDC
	A2 = 0.0	UPDFDC
	GO TO 32	UPDFDC
39	NG = NTAB(M+4)	UPDFDC
	GLAST = 0.0	UPDFDC
	IF (NG.GT.0 ) GLAST = EVALFD(D,NG,1)	UPDFDC
	NB = NTAB(M+1)	UPDFDC
	D0 = TAB(NB)	UPDFDC
	DG = D0 + GLAST*(D-D0)	UPDFDC
	Y2 = EVALFD(D, NB,1)	UPDFDC
	NI = NTAB(M+2)	UPDFDC
	IF (NI.GT.0) Y2 = Y2+EVALFD(D,NI,1)	UPDFDC
	AREA = EVALFD(D,NB,2)	UPDFDC
	DREF = D	UPDFDC
31	DCUBIC = D	UPDFDC
	X1 = DG	UPDFDC
	X2 = D	UPDFDC
	DX = X2-X1	UPDFDC
	Y1 = 0.0	UPDFDC
	RAREA = RLAST*AREA	UPDFDC
C		UPDFDC
C	COMPUTE UNLOADING QUADRATIC COEFFICIENTS SUCH THAT	UPDFDC



	SUBROUTINE VEHPOS	REV IV 07/23/86	TWOPI	VEHPOS
C				
C	COMPUTES COMPONENTS OF VEHICLE ACCELERATIONS ONLY AS A FUNCTION			VEHPOS
C	OF TIME USING DATA AND TABLES PRODUCED BY SUBROUTINE VINPUT.			VEHPOS
C				VEHPOS
	IMPLICIT REAL*8 (A-H,O-Z)			VEHPOS
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,			VEHPOS
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG			PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),			VEHPOS
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)			VEHPOS
	COMMON/VPOSTN/ ZPLT(3),SPLT(3),AXV(3,6),VATAB(6,501,6),			VEHICL
	* VTO(6),VDT(6),TIMEV(6),OMEGV(6),NVTAB(6),INDXV(6)			VEHPOS
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),			VEHPOS
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI			TWOPI
	DIMENSION AX(3)			VEHPOS
	T = TIME			VEHPOS
	M = 1			VEHPOS
15	DO 16 I=1,3			VEHPOS
16	AX(I) = AXV(I,M)			VEHPOS
	ATO = VTO(M)			VEHPOS
	ADT = VDT(M)			VEHPOS
	VTIME = TIMEV(M)			VEHPOS
	OMEG = OMEGV(M)			VEHPOS
	NATAB = NVTAB(M)			VEHPOS
	K = INDXV(M)			VEHPOS
	IF(NATAB.NE.0) GO TO 20			VEHPOS
C				VEHPOS
C	HALF-SINE WAVE DECELERATION			VEHPOS
C				VEHPOS
	IF(T.GT.VTIME) T=VTIME			VEHPOS
	WT = OMEG*T			VEHPOS
	SWT = DSIN(WT)			VEHPOS
	DO 10 I=1,3			VEHPOS
	AW = AX(I)*OMEG			VEHPOS
	SEGLA(I,K) = -AW*OMEG*SWT			VEHPOS
10	WMEGD(I,K) = 0.0			VEHPOS
	GO TO 99			VEHPOS
20	IF (NATAB.LT.0) GO TO 30			VEHPOS
C				VEHPOS
C	UNIDIRECTIONAL DECELERATION			VEHPOS
C				VEHPOS
	IF (T.LT.VTIME) GO TO 21			VEHPOS
C				VEHPOS
C	TIME POINT EXCEEDS TABLE, USE LAST VALUES OF ACCELERATION.			VEHPOS
C				VEHPOS
	ACO = VATAB(1,NATAB,M)			VEHPOS
	GO TO 25			VEHPOS
C				VEHPOS
C	USE QUADRATIC INTERPOLATION FROM TABLES FOR CURRENT VALUE OF			VEHPOS
C	TIME TO BE CONSISTENT WITH SIMPSON INTEGRATION OF TABLES.			VEHPOS

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C
21 J = 0.5*(T-ATO)/ADT + 1.0
   XK = T/ADT -DFLOAT(2*J-1)
   X1 = XK+1.0
   X3 = XK-1.0
   ACO = 0.5*XK*X3*VATAB(1,2*J-1,M)
   *   -      X3*X1*VATAB(1,2*J  ,M)
   *   + 0.5*XK*X1*VATAB(1,2*J+1,M)
C
C      COMPONENTS OF VEHICLE ACCELERATION.
C
25 DO 29 I=1,3
   SEGLA(I,K) = -G*AX(I)*ACO
29 WMEGD(I,K) = 0.0
   GO TO 99
C
C      OMNIDIRECTIONAL DECELERATION
C
30 J = (TIME-ATO)/ADT + 1.0
   IF (J.GE.-NATAB) GO TO 32
C
C      INTERPOLATION FROM VINPUB TABLES OF COMPONENTS OF VEHICLE
C      LINEAR AND ANGULAR ACCELERATION.
C
   TJ      = ATO + DFLOAT(J-1)*ADT
   DLT      = TIME-TJ
   R1 = DLT/ADT
   R2 = 1.0-R1
   DO 31 I=1,3
   SEGLA(I,K) =      -G*(VATAB(I  ,J+1,M)*R1 + VATAB(I  ,J,M)*R2)
31 WMEGD(I,K) = RADIANT*(VATAB(I+3,J+1,M)*R1 + VATAB(I+3,J,M)*R2)
   GO TO 99
C
C      TIME POINT EXCEEDS TABLE, USE LAST VALUES OF ACCELERATION.
C
32 J = - NATAB
   DO 33 I=1,3
   SEGLA(I,K) =      -G*VATAE(I  ,J,M)
33 WMEGD(I,K) = RADIANT*VATAB(I+3,J,M)
99 M = M+1
   IF (M.LE.6 .AND. INDXV(M).NE.0) GO TO 15
   RETURN
   END

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	SUBROUTINE VINPUT	REV IV 07/24/86SLIP	VINPUT
C			
C	PERFORMS CARD INPUT AND COMPUTES DATA AND TABLES REQUIRED BY		VINPUT
C	SUBROUTINE VEHPOS TO INTEGRATE THE CRASH VEHICLE MOTION FOR ONE OF		VINPUT
C	THREE PERMISSABLE OPTIONS:		VINPUT
C	(1) HALF SINE-WAVE LINEAR DECELERATION IMPULSE		VINPUT
C	(2) UNIDIRECTIONAL LINEAR DECELERATION TABULAR INPUT		VINPUT
C	(3) OMNIDIRECTIONAL LINEAR AND ANGULAR ACCELERATION TABULAR		VINPUT
C	INPUT (6 DEGREES OF FREEDOM VEHICLE MOTION)		VINPUT
C			VINPUT
	IMPLICIT REAL*8 (A-H,O-Z)		VINPUT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		VINPUT
	* NS,NQ,NSD,NFLX,NHRSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		VINPUT
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		VINPUT
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		VINPUT
	* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		VINPUT
	COMMON/VPOSTN/ ZPLT(3),SPLT(3),AXV(3,6),VATAB(6,501,6),		VEHICL
	* VTO(6),VDT(6),TIMEV(6),OMEGV(6),NVTAB(6),INDXV(6)		VINPUT
	COMMON/TEMPVS/ X0(3),XDOT0(3),XCOMP(3),XVCOMP(3),ANGLE(3),		VINPUT
	* ATAB(15,501),DVEH(3,3),VMEG(3),VMEGD(3),		VEHICL
	* XACOMP(3),THET(3),AX(3),F(5,101),XYZ(103,6),TT(103),		CHGIII
	* VIPS,VMPH,ATO,ADT,VTIME,OMEG,NATAB		VINPUT
	* ,SP(5,101,4),Q1(101,4),A1(3),W1(4),QD(4),QC(4)		JTF984
	COMMON/INTEST/ SGTEST(3,4,30),XTEST(3,120),SEGT(120),REGT(120)		VINPUT
	REAL SEGT		VINPUT
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		VINPUT
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),		VINPUT
	* BLTTTL(5,8),PLTTTL(5,30),BAGTTL(5,6),SEG(30),		VINPUT
	* JOINT(30),CGS(30),JS(30)		VINPUT
	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTTL,BAGTTL,SEG,JOINT		VINPUT
	LOGICAL*1 CGS,JS		VINPUT
	DIMENSION IDYPR(3)		VINPUT
	REAL VEH(6),GRND		VINPUT
	DATA VEH/4HVEH1,4HVEH2,4HVEH3,4HVEH4,4HVEH5,4HVEH /,GRND/4HGRND/		VINPUT
	DATA IDYPR/3,2,1/		VINPUT
	DATA MXTAB2/99/,MXTAB3/501/,MXTAB4/101/		MISC
C			VINPUT
C	READ AND PRINT CONTENTS OF CARDS C.1 AND C.2		VINPUT
C			VINPUT
	NVEH = NSEG		VINPUT
	NVH = 0		VINPUT
	DO 11 I=1,6		VINPUT
	11 INDXV(I) = 0		VINPUT
	12 READ (5,13) VPSTTL		VINPUT
	13 FORMAT (20A4)		VINPUT
	READ(5,14) ANGLE,VIPS,VTIME,X0,NATAB,ATO,ADT,MSEG		VINPUT
	14 FORMAT(8F6.0,I6,2F6.0,I6)		VINPUT



	INTAB = IABS(NATAB)	CHGIII
	IF (NATAB.GT.0.AND.INTAB.GT.MXTAB2) STOP 79	MISC
	WRITE (6,15) NPG,VPSTTL,ANGLE,VIPS,VTIME,X0,NATAB,ATO,ADT,MSEG	PAGE
	NPG = NPG+1	PAGE
15	FORMAT('1 VEHICLE DECELERATION INPUTS',94X,'PAGE',15/120X,	PAGE
	* 'CARDS C'/3X,20A4//	PAGE
	* 7X,'YAW',9X,'PITCH',7X,'ROLL',8X,'VIPS',8X,'VTIME',7X,'X0(X)',	VINPUT
	* 7X,'X0(Y)',7X,'X0(Z)',2X,'NATAB',6X,'ATO',9X,'ADT',4X,'MSEG'/	VINPUT
	* 8F12.3,15,2X,2F12.6,15)	VINPUT
	DA1 = ANGLE(1)*RADIAN	VINPUT
	DA2 = ANGLE(2)*RADIAN	VINPUT
	AX(3) = DCOS(DA2)	VINPUT
	AX(1) = DCOS(DA1)*AX(3)	VINPUT
	AX(2) = DSIN(DA1)*AX(3)	VINPUT
	AX(3) = DSIN(DA2)	VINPUT
	IF(NATAB.NE.0) GO TO 18	VINPUT
C		VINPUT
C	HALF-SINE WAVE DECELERATION	VINPUT
C		VINPUT
	OMEG = PI/VTIME	VINPUT
	AT = 0.5*VIPS/OMEG	VINPUT
	IF (VIPS.LT.0.0) VIPS = 0.0	VINPUT
	DO 16 I=1,3	VINPUT
	XACOMP(I) = 0.0	VINPUT
	XDOT0(I) = VIPS*AX(I)	VINPUT
16	AX(I) = AT*AX(I)	VINPUT
	WRITE (6,17) VIPS,UNITL,UNITT,ANGLE,VTIME,UNITT	VINPUT
17	FORMAT('0 PASSENGER COMPARTMENT DISPLACEMENT HISTORY'/	VINPUT
	* ' ANALYTICAL HALF-SINE WAVE DECELERATION'/	VINPUT
	* ' VO=',F8.3,1X,A4,'/',A4,', OBLIQUE ANGLES =',3F7.2,	VINPUT
	* ' DEGREES, TIME DURATION =',F7.3,1X,A4//)	VINPUT
	GO TO 28	VINPUT
18	IF (NATAB.LT.0) GO TO 31	VINPUT
C		VINPUT
C	FOR UN ISECTIONAL VEHICLE MOTION	VINPUT
C	READ L1 AR DECELERATION TABLES FROM CARDS C.3	VINPUT
C		VINPUT
	READ (5,19) (ATAB(1,I),I=1,NATAB)	VINPUT
19	FORMAT (12F6.0)	VINPUT
C		VINPUT
C	EXTEND TABLE IF NECESSARY SUCH THAT NATAB IS ODD AND	VINPUT
C	LAST ENTRY NEED NOT BE ZERO. IF TABLE SIZE IS EXCEEDED ON TIME,	VINPUT
C	VALUE OF LAST ENTRY WILL BE USED.	VINPUT
C		VINPUT
	IF (MOD(NATAB,2).EQ.1) GO TO 20	VINPUT
	ATAB(1,NATAB+1) = ATAB(1,NATAB)	VINPUT
	NATAB = NATAB+1	VINPUT
20	VTIME = ADT * DFLOAT(NATAB-1)	VINPUT
C		VINPUT
C	USING SIMPSON'S INTEGRATION, COMPUTE VELOCITY AND DISPLACEMENT	VINPUT

C	TABLE FOR NATAB EQUALLY SPACED (ADT) TIME POINTS.	VINPUT
C	FOR I=1,NATAB	VINPUT
C	ATAB(1,I) = LINEAR DECELERATION (G'S)	VINPUT
C	ATAB(2,I) = LINEAR VELOCITY (L UNITS/T UNITS)	VINPUT
C	ATAB(3,I) = LINEAR DISPLACEMENT (L UNITS)	VINPUT
C		VINPUT
	ATAB(2,1) = VIPS	VINPUT
	ATAB(3,1) = 0.0	VINPUT
	DA1 = ADT/3.0	VINPUT
	DA2 = ADT/12.0	VINPUT
	UNITS = -G	VINPUT
	DO 22 J=2,3	VINPUT
	DO 21 I=2,NATAB,2	VINPUT
	F1 = ATAB(J-1,I-1) * UNITS	VINPUT
	F2 = ATAB(J-1,I) * UNITS	VINPUT
	F3 = ATAB(J-1,I+1) * UNITS	VINPUT
	ATAB(J,I) = ATAB(J,I-1) + DA2*(5.0*F1+8.0*F2-F3)	VINPUT
21	ATAB(J,I+1) = ATAB(J,I-1) + DA1*(F1+4.0*F2+F3)	VINPUT
22	UNITS = 1.0	VINPUT
C		VINPUT
C	PRINT TABLES	VINPUT
C		VINPUT
	WRITE (6,23) (UNITL,UNITT,UNITL,I=1,2)	VINPUT
23	FORMAT('0 UNIDIRECTIONAL VEHICLE POSITION TABLES'//	VINPUT
	* 2(' TIME ACC VELOCITY POSITION ')/	VINPUT
	* 2(' (MSEC) (G) ('.A4, '/' .A4, ')',5X, '(' .A4, ')',4X)/)	VINPUT
	DO 26 J=1,50	VINPUT
	IF (J.GT.NATAB) GO TO 26	VINPUT
	T1 = (ATO + DFLOAT(J-1)*ADT)*1000.0	VINPUT
	IF (J+50.LE.NATAB) GO TO 25	VINPUT
	WRITE (6,24) T1,(ATAB(I,J),I=1,3)	VINPUT
24	FORMAT(2(F11.5,F10.2,F13.4,F13.5,3X))	VINPUT
	GO TO 26	VINPUT
25	T2 = (ATO + DFLOAT(J+49)*ADT)*1000.0	VINPUT
	WRITE (6,24) T1,(ATAB(I,J),I=1,3),T2,(ATAB(I,J+50),I=1,3)	VINPUT
26	CONTINUE	VINPUT
C		VINPUT
C	INITIALIZATION	VINPUT
C		VINPUT
	DO 27 I=1,3	VINPUT
	XACOMP(I) = -G*AX(I)*ATAB(1,1)	VINPUT
27	XDOT0(I) = VIPS*AX(I)	VINPUT
28	DO 30 I=1,3	VINPUT
	DO 29 J=1,3	VINPUT
29	DVEH(I,J) = 0.0	VINPUT
	DVEH(I,I) = 1.0	VINPUT
	VMEGD(I) = 0.0	VINPUT
30	VMEG(I) = 0.0	VINPUT
	GO TO 64	VINPUT
C		VINPUT

C	FOR OMNIDIRECTIONAL (6 DEGREES OF FREEDOM) VEHICLE MOTION	VINPUT
C	READ LINEAR DECELERATION AND ANGULAR ACCELERATION TABLES	VINPUT
C	FROM CARDS C.2.B AND C.4.	CHGIII
C		VINPUT
	31 MATAB = -NATAB	VINPUT
	READ (5,32) LTYPE,LFIT,NPTS,(VMEG(I),I=1,3)	VINPUT
	32 FORMAT (3I6,22X,3F10.0)	VINPUT
	IF (MATAB.GT.MXTAB3) STOP 80	MISC
	IF (LTYPE.EQ.2.AND.LFIT.LT.1) STOP 82	CHGIII
	IF (LTYPE.EQ.1.AND.LFIT.LT.2) STOP 83	VEHICL
	IF (LTYPE.GT.0) GO TO 34	VINPUT
	READ (5,33) ((ATAB(I,J),I=1,3),(ATAB(I,J),I=10,12),J=1,MATAB)	VINPUT
	33 FORMAT (10X,6F10.0)	VINPUT
	ISKIP = 0	VINPUT
	GO TO 46	VINPUT
C		CHGIII
C	FOR SPLINE FIT VEHICLE MOTION	CHGIII
C	READ DATA FROM CARDS C.5.	CHGIII
C		CHGIII
	34 LPTS = LTYPE-1 + NPTS	VINPUT
	IF (NPTS.GT.MXTAB3) STOP 84	MISC
	READ (5,35) (TT(1),(XYZ(I,J),J=1,6),I=1,LPTS)	VINPUT
	35 FORMAT (7F10.0)	VINPUT
	WRITE (6,36) LTYPE,LFIT,NPTS	CHGIII
	36 FORMAT ('O SPLINE FIT TABULAR INPUT'//	CHGIII
	* 3X,'LTYPE =' ,I6,' LFIT =' ,I6,' NPTS =' ,I6/)	CHGIII
	IF (LTYPE.EQ.2) WRITE(6,701) UNITL,UNITT,TT(1),(XYZ(1,J),J=1,6)	CHGIII
	IF (LTYPE.EQ.3) WRITE(6,702) UNITL,UNITT,TT(1),(XYZ(1,J),J=1,6).	CHGIII
	* UNITL,UNITT,UNITT,UNITT,TT(2),(XYZ(2,J),J=1,6)	CHGIII
	701 FORMAT(32X,'INITIAL LINEAR POSITION (' ,A4,')',17X,'INITIAL ANGULACHGIII	
	*R POSITION (DEG)' ,/,3X,'TIME(' ,A4,')=' ,F9.4,3X,2('X=' ,F10.3,2X,	JTF984
	* 'Y=' ,F10.3,2X,'Z=' ,F10.3,8X),/)	CHGIII
	702 FORMAT(32X,'INITIAL LINEAR POSITION (' ,A4,')',17X,'INITIAL ANGULACHGIII	
	*R POSITION (DEG)' ,/,3X,'TIME(' ,A4,')=' ,F9.4,3X,2('X=' ,F10.3,2X,	JTF984
	* 'Y=' ,F10.3,2X,'Z=' ,F10.3,8X),/,30X,'INITIAL LINEAR VELOCITY (' ,CHGIII	
	* A4,')',12X,'INITIAL ANGULAR VELOCITY (DEG/' ,A4,')',	CHGIII
	*/,3X,'TIME(' ,A4,')=' ,F9.4,3X,2('X=' ,F10.2,2X,'Y=' ,	CHGIII
	* F10.2,2X,'Z=' ,F10.2,8X),/)	CHGIII
	IF (LTYPE.EQ.1) WRITE(6,703) UNITL,UNITT	CHGIII
	IF (LTYPE.EQ.2) WRITE(6,704) UNITL,UNITT,UNITT,UNITT	CHGIII
	IF (LTYPE.EQ.3) WRITE(6,705) UNITT,UNITT	VEHICL
	703 FORMAT(29X,'LINEAR POSITION (' ,A4,')',21X,'ANGULAR POSITION (DECHGIII	
	*G)' ,/,5X,'TIME(' ,A4,')',11X,'X',11X,'Y',11X,'Z',18X,'YAW',8X,	VEHICL
	*'PITCH',8X,'ROLL')	VEHICL
	704 FORMAT(26X,'LINEAR VELOCITY (' ,A4,')',16X,	CHGIII
	* 'ANGULAR VELOCITY (DEG/' ,A4,')',/,5X,'TIME(' ,A4,')',	CHGIII
	* 11X,2('X',11X,'Y',11X,'Z',19X))	CHGIII
	705 FORMAT(26X,'LINEAR DECELERATION (G'S)',15X,	VEHICL
	* 'ANGULAR ACCELERATION (DEG/' ,A4,')**2)' ,/,5X,'TIME(' ,A4,')',	CHGIII
	* 11X,2('X',11X,'Y',11X,'Z',19X))	CHGIII

IF (LTYPE.EQ.1) WRITE(6,706) (TT(I),(XYZ(I,J),J=1,6),I=1,LPTS)	CHGIII
IF (LTYPE.EQ.2) WRITE(6,706) (TT(I),(XYZ(I,J),J=1,6),I=2,LPTS)	CHGIII
IF (LTYPE.EQ.3) WRITE(6,706) (TT(I),(XYZ(I,J),J=1,6),I=3,LPTS)	CHGIII
706 FORMAT(1X,F12.5,6X,3F12.3,8X,3F12.3)	CHGIII
DO 37 I=1,3	VINPUT
XO(I) = XYZ(1,I)	VINPUT
XDOTO(I) = XYZ(2,I)	VINPUT
VMEG(I) = XYZ(2,I+3)	VINPUT
37 ANGLE(I) = XYZ(1,I+3)	JTF984
IMJ = 6	JTF984
IF(LTYPE.EQ.1)IMJ = 3	JTF984
DO 45 II=1,IMJ	JTF984
CALL SPLINE (TT(LTYPE),XYZ(LTYPE,II),F,NPTS,LFIT)	VINPUT
I = II	VINPUT
IF (II.GT.3) I = II + 6	VINPUT
IF(LTYPE.EQ.1) XDOTO(I) = F(3,1)	JTF984
UNITS = 1.0	JTF984
IF (LTYPE.LT.3 .AND. II.LE.3) UNITS = -1.0/G	VINPUT
K1 = 1	VINPUT
DO 45 J=1,MATAB	VINPUT
TTT = ATO + DFLOAT(J-1)*ADT	VINPUT
DO 39 L=K1,NPTS	JTF984
K = L	JTF984
IF (TTT.LT.F(1,L+1)) GO TO 40	VINPUT
39 CONTINUE	VINPUT
40 K1 = K	VINPUT
DX = TTT - F(1,K)	VINPUT
IF (LTYPE-2) 41,42,43	BUTLER1
41 ACC = 2.0*F(4,K) + 6.0*DX*F(5,K)	VINPUT
GO TO 44	VINPUT
42 ACC = F(3,K) + DX*(2.0*F(4,K)+3.0*DX*F(5,K))	VINPUT
GO TO 44	VINPUT
43 ACC = F(2,K) + DX*(F(3,K)+DX*(F(4,K)+DX*F(5,K)))	VINPUT
44 ATAB(I,J) = ACC*UNITS	VINPUT
45 CONTINUE	VINPUT
ISKIP = 1	VINPUT
IF(LTYPE.NE.1)GO TO 46	JTF984
C CODE FOR OMEGA ROUTINE: COMPUTE ATAB(I,J),I=10,11,12 J = 1,MATAB	JTF984
DO 80 I = 1,NPTS	JTF984
DO 91 K = 1,3	JTF984
91 A1(K) = XYZ(I,K+3)	JTF984
CALL QUAT(A1,W1)	JTF984
DO 76 K = 1,4	JTF984
76 Q1(I,K) = W1(K)	JTF984
IF(I.EQ.1)GO TO 80	JTF984
TA = 0.0	JTF984
TB = 0.0	JTF984
DO 77 K = 1,4	JTF984
TA = TA + DABS(Q1(I,K) - Q1(I-1,K))	JTF984
77 TB = TB + DABS(Q1(I,K) + Q1(I-1,K))	JTF984

IF(TA.LE.TB)GO TO 80	JTF984
DO 78 K = 1,4	JTF984
78 Q1(I,K) = -Q1(I,K)	JTF984
80 CONTINUE	JTF984
DO 82 K = 1,4	JTF984
82 CALL SPLINE(TT,Q1(1,K),SP(1,1,K),NPTS,LFIT)	JTF984
DO 90 J = 1,MATAB	JTF984
TTT = ATO + DFLOAT(J-1)*ADT	JTF984
K1 = 1	JTF984
DO 83 L = K1,NPTS	JTF984
K = L	JTF984
83 IF(TTT.LT.SP(1,L+1,1))GO TO 84	JTF984
84 K1 = K	JTF984
DX = TTT - SP(1,K,1)	JTF984
DO 85 L = 1,4	JTF984
W1(L) = SP(2,K,L)+DX*(SP(3,K,L)+DX*(SP(4,K,L)+DX*SP(5,K,L)))	JTF984
QD(L) = 2.0*SP(4,K,L) + 6.0*DX*SP(5,K,L)	JTF984
85 IF(J.EQ.1)QC(L) = SP(3,K,L)+DX*(2.0*SP(4,K,L)+DX*3.0*SP(5,K,L))	MISC
CCC = 2.0/RADIAN	JTF984
IF(J.GT.1)GO TO 88	JTF984
CALL CROSS(QC(2),W1(2),A1)	JTF984
DO 86 K = 1,3	JTF984
86 VMEG(K) = CCC*(W1(1)*QC(K+1) - QC(1)*W1(K+1) + A1(K))	JTF984
CALL DRCQUA(DVEH,W1)	JTF984
CALL YPRDEG(DVEH,ANGLE)	JTF984
88 CALL CROSS(QD(2),W1(2),QC(2))	JTF984
DO 89 K = 2,4	JTF984
89 ATAB(K+8,J) = CCC*(W1(1)*QD(K)-QD(1)*W1(K) + QC(K))	JTF984
90 CONTINUE	JTF984
46 DO 55 J=1,MATAB	VINPUT
IF (MOD(J,45).NE.1) GO TO 49	VINPUT
C PRINT PAGE HEADING AT START OF EACH 45 TIME POINTS.	VINPUT
C	VINPUT
C	VINPUT
IPAGE = (J-1)/45 + 1	VINPUT
IF (ISKIP.EQ.1) WRITE (6,75) NPG	PAGE
IF (ISKIP.EQ.1) NPG=NPG+1	PAGE
75 FORMAT('1',122X,'PAGE',I5)	PAGE
WRITE (6,48) VPSTTL,IPAGE,UNITL,UNITT,UNITL	PAGE
48 FORMAT('0 VEHICLE LINEAR TIME HISTORY',3X,20A4,3X,	PAGE
* 'PAGE NO.',I3//	VINPUT
* 4X,'TIME',12X,'LINEAR DECELERATIONS (G''S)',	VINPUT
* 11X,'LINEAR VELOCITIES ('.A4, '/' ,A4,')',	VINPUT
* 11X,'LINEAR DISPLACEMENTS ('.A4,')' /	VINPUT
* 3X,'(MSEC)',3(11X,'X',11X,'Y',11X,'Z',3X) / )	VINPUT
ISKIP = 1	VINPUT
49 IF (J.GT.1) GO TO 52	VINPUT
C	VINPUT
C INTEGRATION INITIALIZATION FOR TIME = 0.	VINPUT
C	VINPUT

	DO 50 I=1,3	VINPUT
	ATAB(I+6,J) = XO(I)	VINPUT
50	ATAB(I+12,J) = VMEG(I)	JTF984
	CALL DRCYPR (DVEH,ANGLE,IDYPR)	VINPUT
	DO 51 I=1,3	VINPUT
	IF (LTYPE.EQ.0) XDOT0(I) = VIPS*DVEH(1,I)	VINPUT
51	ATAB(I+3,J) = XDOT0(I)	VINPUT
	GO TO 54	VINPUT
52	DO 53 I=1,3	VINPUT
C		VINPUT
C	INTEGRATE LINEAR VELOCITY AND DISPLACEMENT.	VINPUT
C		VINPUT
	ATAB(I+3,J) = ATAB(I+3,J-1)-G*ADT/2.0*(ATAB(I,J-1)+ATAB(I,J))	VINPUT
53	ATAB(I+6,J) = ATAB(I+6,J-1)	VINPUT
	* +ADT*(ATAB(I+3,J-1)-G*ADT/6.0*(2.0*ATAB(I,J-1)+ATAB(I,J)))	VINPUT
54	T1 = (ATO + DFLOAT(J-1)*ADT)*1000.0	VINPUT
55	WRITE(6,56) T1,(ATAB(I,J),I=1,9)	VINPUT
56	FORMAT(F9.3,3(3X,3F12.3))	VINPUT
	DO 61 J=1,MATAB	VINPUT
	IF (MOD(J,45).NE.1) GO TO 58	VINPUT
C		VINPUT
C	PRINT PAGE HEADING AT START OF EACH 45 TIME POINTS.	VINPUT
C		VINPUT
	IPAGE = (J-1)/45 + 1	VINPUT
	WRITE (6,57) VPSTTL,NPG,IPAGE,UNITT,UNITT	PAGE
	NPG=NPG+1	PAGE
57	FORMAT('1 VEHICLE ANGULAR TIME HISTORY',3X,20A4,10X,'PAGE',15/	PAGE
	* 116X,'PAGE NO.',I3/	PAGE
	* 4X,'TIME', 7X,'ANGULAR ACCELERATIONS (DEG/','A4,'**2)',	VINPUT
	* 7X,'ANGULAR VELOCITIES (DEG/','A4,'')',	VINPUT
	* 11X,'ANGULAR DISPLACEMENTS (DEG)' /	VINPUT
	* 3X,'(MSEC)',2(11X,'X',11X,'Y',11X,'Z',3X),	VINPUT
	* 10X,'YAW',8X,'PITCH',8X,'ROLL' /)	VINPUT
58	IF(J.EQ.1) GO TO 60	VINPUT
C		VINPUT
C	INTEGRATE ANGULAR VELOCITY AND DISPLACEMENT.	VINPUT
C		VINPUT
	DO 59 I=1,3	VINPUT
	ATAB(I+12,J) = ATAB(I+12,J-1)+(ATAB(I+9,J-1)+ATAB(I+9,J))*ADT/2.0	VINPUT
59	THET(I) = ADT*(ATAB(I+12,J-1)+(2.0*ATAB(I+9,J-1)+ATAB(I+9,J))*ADT	VINPUT
	*/6.0)*RADIAN	VINPUT
	CALL DSETD(DVEH,THET,THT)	VINPUT
60	CALL YPRDEG(DVEH,THET)	VINPUT
	T1 = (ATO + DFLOAT(J-1)*ADT)*1000.0	VINPUT
61	WRITE (6,56) T1,(ATAB(I,J),I=10,15),THET	VINPUT
C		VINPUT
C	PROGRAM INITIALIZATION FOR TIME = 0.	VINPUT
C		VINPUT
	CALL DRCYPR (DVEH,ANGLE,IDYPR)	VINPUT
	DO 63 I=1,3	VINPUT

[illegible]

	SEG(NVEH) = VEH(6)	VINPUT
C		VINPUT
C	SET UP SEGMENT DATA FOR GROUND	VINPUT
C		VINPUT
	NGRND = NVEH+1	VINPUT
	IF (NGRND.GT.30 .OR. NVH.GT.6) STOP 7	VINPUT
	SEG(NGRND) = GRND	VINPUT
	J = NGRND	VINPUT
	ISING(J) = -1	VINPUT
	W(J) = 0.0	VINPUT
	RW(J) = 0.0	VINPUT
	DO 74 I=1,3	VINPUT
	DO 73 K=1,3	VINPUT
	D(I,K,J) = 0.0	VINPUT
73	SGTEST(I,K,J) = 0.0	VINPUT
	D(I,I,J) = 1.0	VINPUT
	SGTEST(I,4,J) = 0.0	VINPUT
	SEGLP(I,J) = 0.0	VINPUT
	SEGLV(I,J) = 0.0	VINPUT
	SEGLA(I,J) = 0.0	VINPUT
	WMEG (I,J) = 0.0	VINPUT
	WMEGD(I,J) = 0.0	VINPUT
	PHI (I,J) = 0.0	VINPUT
74	RPHI (I,J) = 0.0	VINPUT
	RETURN	VINPUT
	END	VINPUT



C	DOUBLE PRECISION FUNCTION VISCOS(ZD,VISC,HA)	REV 19	10/23/78	VISCOS
C				VISCOS
C	COMPUTES SUM OF COULOMB AND VISCOUS TORQUES			VISCOS
C	AT JOINTS AS A FUNCTION OF THETA DOT.			VISCOS
C	ACTUALLY ROUTINE RETURNS SUM/ZD.			VISCOS
C				VISCOS
C	ARGUMENTS:			VISCOS
C	ZD : !THETA DOT! WHERE THETA IS THE ANGLE OF THE JOINT.			VISCOS
C	VISC: ARRAY OF 5 VALUES DESCRIBING FUNCTION EVALUATION.			VISCOS
C				VISCOS
	IMPLICIT REAL*8 (A-H,O-Z)			VISCOS
	DIMENSION VISC(5)			VISCOS
	Z = ZD			VISCOS
	IF (ZD.LT.VISC(3)) Z = VISC(3)/(2.0-ZD/VISC(3))			VISCOS
	HA = (Z-ZD)/Z			VISCOS
	VISCOS = VISC(1)+VISC(2)/Z			VISCOS
	RETURN			VISCOS
	END			VISCOS

	SUBROUTINE VISPR(IJ,NJ)	REV IV	02/01/88	MISDOT	VISPR
C					VISPR
C	COMPUTES VISCOS AND SPRING TORQUES AT THE JOINTS				VISPR
C	AND ADDS THEM TO THE U2 ARRAY.				VISPR
C	ARGUMENTS:				VISPR
C	NJ = 0 - REGULAR COMPUTATION FOR ALL JOINTS				VISPR
C	* 0 - COMPUTE ONLY FOR JOINT NJ IMPULSE				VISPR
C					VISPR
C	IJ = 1 IMPULSE FOR FLEXURE ONLY				VISPR
C	= 2 IMPULSE FOR TORSION ONLY				VISPR
C	= 4 IMPULSE FOR GLOBALGRAPHIC ONLY				VISPR
C					VISPR
	IMPLICIT REAL*8 (A-H,O-Z)				VISPR
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,				VISPR
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG				PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),				VISPR
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)				VISPR
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),				SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),				VISPR
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)				VISPR
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),				VISPR
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)				SLIP
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),				NCFORC
*	PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF				VISPR
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),				JDRIFT
*	FE(3,30),TQE(3,30),CONST(5,30)				JDRIFT
	COMMON/TEMPVI/ CREST,TTI(3),R1I(3),R2I(3),JSTOP(4,2,30)				VISPR
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),				VISPR
*	UNITL,UNITM,UNITT,GRAVITY(3),TWOPI				TWOPI
	COMMON/TEMPVS/ T3(3),T6(3),T7(3),T8(3),T9(3),				VISPR
*	WIJ(3),ANGL(3),DH1(3,3),HD3(3,3),				VISPR
*	HAD,HBD,WIJM,CV,CSA,CSB,TQC				VISPR
	IF (NJNT.LE.0) GO TO 99				VISPR
	CALL ELTIME(1,13)				VISPR
	IF (NPRT(12).NE.0) WRITE (6,11) TIME,NPG				PAGE
	IF (NPRT(12).NE.0) NPG=NPG+1				PAGE
11	FORMAT('1 VISPR COMPUTATIONS FOR TIME =',F12.6,80X,'PAGE',I5)				PAGE
	J1 = 1				VISPR
	J2 = NJNT				VISPR
	IF (NJ.EQ.0) GO TO 13				VISPR
	J1 = NJ				VISPR
	J2 = NJ				VISPR
13	DO 90 J=J1,J2				VISPR
	DO 12 L=1,3				VISPR
	T3(L) = 0.0				VISPR
	T6(L) = 0.0				VISPR
	ANGL(L) = 0.0				VISPR
12	TQ(L,J) = 0.0				VISPR
	WJ(J) = 0.0				VISPR

C		VISPR
C	DO NOT COMPUTE TORQUES FOR NULL, LOCKED OR EULER JOINTS.	VISPR
C		VISPR
	I = IABS(JNT(J))	VISPR
	IF (I.LE.0) GO TO 90	VISPR
	CALL DOT33 (D(1,1,J+1),HT(1,1,2*J),HIR(1,1,J))	VISPR
	IF (IABS(IPIN(J)).EQ.4) GO TO 90	SLIP
C		VISPR
C	ZERO T1-T9 ARRAYS AND HAD,HBD,WIJM,CV,CS4,CSB AND TQC.	VISPR
C		VISPR
	WIJM = 0.0	VISPR
	HAC = 0.0	BUTLER1
	CV = 0.0	VISPR
	CSA = 0.0	VISPR
	CSB = 0.0	VISPR
	TQC = 0.0	VISPR
	CALL DOT33 (D(1,1,I),HT(1,1,2*J-1),DH1)	VISPR
	CALL DOT33 (DH1,HIR(1,1,J),HD3)	VISPR
	DO 220 L=1,3	TGMOD6
	DO 220 K=1,3	TGMOD6
	IF(DABS(HD3(L,K)).LT.EPS(10)) HD3(L,K) = 0.D0	TGMOD6
220	CONTINUE	TGMOD6
	HAD = HD3(3,3)	VISPR
	IF (HAD.GT. 1.0) HAD = 1.0	VISPR
	IF (HAD.LT.-1.0) HAD = -1.0	VISPR
	ANGL(1) = DACOS(HAD)	VISPR
	IF ((HD3(2,3).NE.0.0 .OR. HD3(1,3).NE.0.0).AND.IABS(IPIN(J)).NE.7) SLIP	SLIP
	*ANGL(2) = DATAN2(HD3(2,3),HD3(1,3))	VISPR
	ANGL(3) = DATAN2(HD3(2,1)-HD3(1,2),HD3(1,1)+HD3(2,2))	VISPR
	IF(NPRT(12).NE.0.AND.IPIN(J).LT.0) WRITE (6,739) J,I,ANGL,	TGMOD6
	*((D(L,K,J+1),K=1,3),(HT(L,K,2*J),K=1,3),(HIR(L,K,J),K=1,3),L=1,3),	TGMOD6
	*((D(L,K,I),K=1,3),(HT(L,K,2*J-1),K=1,3),(DH1(L,K),K=1,3),L=1,3),	TGMOD6
	* ((HD3(L,K),K=1,3),L=1,3)	TGMOD6
739	FORMAT(1H0,'J= ',I2,1X,'I= ',I2,3(2X,D14.7),/,	TGMOD6
	* 2(3(9(1X,D13.6),/),/),3(3(2X,D18.12),/))	TGMOD6
	IF (IPIN(J).LT.0) GO TO 41	VISPR
	IF (NJ.NE.0.AND.IJ.EQ.4) GO TO 27	VISPR
C		VISPR
C	CONVERT TO INERTIAL REFERENCE SYSTEM	VISPR
C	T1= D(I)'*HA(NJ) T4=D(J+1)'*HA(MJ)	VISPR
C	T3= D(I)'*WMEG(I) T6=D(J+1)'*WMEG(J+1)	VISPR
C		VISPR
C	HAD = COS TA = T1.T4	VISPR
C	WIJ = T3-T6	VISPR
C	WJ = !WIJ!	VISPR
C		VISPR
	DO 20 L=1,3	VISPR
	DO 15 M=1,3	VISPR
	T3(L) = T3(L)+ D(M,L,I)* WMEG(M,I)	VISPR
15	T6(L) = T6(L)+ D(M,L,J+1)* WMEG(M,J+1)	VISPR

	WIJ(L) = T3(L) - T6(L)	VISPR
20	WIJM = WIJM + WIJ(L)**2	VISPR
	WIJM = DSQRT(WIJM)	VISPR
	IF (WIJM.LE.EPS(12)) WIJM = 0.0	MISDOT
	WJ(J) = WIJM	VISPR
C		VISPR
C	T7 = T1 X T4	VISPR
C	HAC = !T7!	VISPR
C		VISPR
	CALL CROSS (DH1(1,3),HIR(1,3,J),T7)	VISPR
	HACC = T7(1)**2 + T7(2)**2 + T7(3)**2	VISPR
	HAC = DSQRT(HACC)	VISPR
C		VISPR
C	COMPUTE CV, THE MAGNITUDE OF VISCOUS AND COULOMB TORQUE/WIJM	VISPR
C	RA = +SGN TA DOT = -WIJ.T7	VISPR
C	AND CSA, THE MAGNITUDE OF FLEXURE TORQUE/HAC	VISPR
C		VISPR
	CV = VISCOS(WIJM,VISC(1,3*J-2),HA2)	VISPR
	IF (NJ.EQ.0) HA(2,2*J) = HA2	VISPR
	CREST = VISC(7,3*J-2)	VISPR
	RA = -(WIJ(1)*T7(1) + WIJ(2)*T7(2) + WIJ(3)*T7(3))	VISPR
	IF (HAC.LT.EPS(12)) RA=0.0	MISDOT
	IF (HAC.GE.EPS(12)) RA=RA/HAC	MISDOT
	JSTP = 0	VISPR
	IF (IPIN(J).EQ.7) GOTO 25	SLIP
	IF (JOINTF(J).EQ.0) CSA = EFUNCT(ANGL(1),RA,SPRING(1,3*J-2),JSTP)	VISPR
	IF (JOINTF(J).NE.0) CSA = FNTERP(ANGL(1),ANGL(2),JOINTF(J))	VISPR
	IF (HAC.LT.EPS(12)) CSA=0.0	MISDOT
	IF (HAC.GE.EPS(12)) CSA=CSA/HAC	MISDOT
25	IF (NJ.EQ.0) JSTOP(1,1,J) = JSTP	SLIP
	IF (IPIN(J).EQ.1) GO TO 34	VISPR
	IF (IPIN(J).EQ.6) GOTO 34	SLIP
C		VISPR
C	RB = +SGN TB DOT = -WIJ.T8	VISPR
C	COMPUTE CSB, THE MAGNITUDE OF TORSIONAL TORQUE/HBC	VISPR
C		VISPR
	RB = -(WIJ(1)*HIR(1,3,J) + WIJ(2)*HIR(2,3,J) + WIJ(3)*HIR(3,3,J))	VISPR
	CSB = EFUNCT(ANGL(3),RB,SPRING(1,3*J-1),JSTP)	VISPR
	IF (NJ.EQ.0) JSTOP(2,1,J) = JSTP	VISPR
	IF (NJ.GT.0) GO TO 34	VISPR
C		VISPR
C	COMPUTE EFFECT OF GLOBALGRAPHIC JOINT STOP (IPIN=3)	VISPR
C		VISPR
27	IF (IPIN(J).NE.3) GO TO 34	VISPR
	CALL GLOBAL (J,HD3(1,3),DH1,TQC,T9,ANGL)	VISPR
C		VISPR
C	COMPUTE TOTAL TORQUE IN INERTIAL REFERENCE BY	VISPR
C	TQ = -CV*WIJ + CSA*T7 + CSB*T8 + TQC*T9	VISPR
C		VISPR
34	IF (NJ.EQ.0) GO TO 35	JDRIFT

CV = 0.0	VISPR
IF (IJ.NE.1) CSA = 0.0	VISPR
IF (IJ.NE.2) CSB = 0.0	VISPR
IF (IJ.NE.4) TQC = 0.0	VISPR
35 IF (HA(2,2*J).EQ.0.0) GO TO 36	JDRIFT
CALL MAT31 (HIR(1,1,J),HA(1,2*J-1),TQ(1,J))	VISPR
DO 38 L=1,3	VISPR
38 TQ(L,J) = HA(2,2*J)*TQ(L,J)	VISPR
36 DO 37 L=1,3	VISPR
TQ(L,J) = TQ(L,J) -CV*WIJ(L) +CSA*T7(L) +CSB*HIR(L,3,J) +TQC*T9(L)	VISPR
37 TTI(L) = TQ(L,J)	VISPR
IF (NPRT(12).NE.0) WRITE (6,39)	VISPR
* J, CV, CSA, CSB, HAC, RA, RB, (TQ(L,J), L=1,3),	VISPR
* WIJ, T7, ANGL, DH1, HD3,	VISPR
* ((HIR(L,K,J), L=1,3), K=1,3)	VISPR
39 FORMAT (1H0,I3,3F14.3,6F14.6/(4X,9F14.6))	VISPR
C	VISPR
C ADD TORQUE CONVERTED TO LOCAL REFERENCE BY	VISPR
C U2I = U2I + DI*TQ	VISPR
C U2J = U2J - DJ*TQ	VISPR
C	VISPR
DO 40 L=1,3	VISPR
DO 40 M=1,3	VISPR
U2(L,I) = U2(L,I) + D(L,M,I)*TQ(M,J)	VISPR
40 U2(L,J+1) = U2(L,J+1) - D(L,M,J+1)*TQ(M,J)	VISPR
C	VISPR
C STORE DATA FOR OUTPUT ROUTINE INTO PRJNT ARRAY.	VISPR
C	VISPR
41 PRJNT(1,J) = IPIN(J)	VISPR
PRJNT(2,J) = ANGL(1)	VISPR
PRJNT(3,J) = ANGL(2)	VISPR
PRJNT(4,J) = ANGL(3)	VISPR
PRJNT(5,J) = (CSA*HAC)**2 + CSB**2	VISPR
PRJNT(6,J) = (CV*WIJM)**2	VISPR
PRJNT(7,J) = TQ(1,J)**2 + TQ(2,J)**2 + TQ(3,J)**2	VISPR
90 CONTINUE	VISPR
CALL ELTIME(2,13)	VISPR
99 RETURN	VISPR
END	VISPR

	SUBROUTINE WINDY(MMM,MM,N,NN,NT)	WINDY
		REV IV 07/23/86TWOPI
C	COMPUTES FORCES AND TORQUES ADDING THEM TO THE U1 AND U2 ARRAYS	WINDY
C	OF WIND BLAST FORCES DETERMINED BY FUNCTION STORED IN TAB(NT)	WINDY
C	ON ELLIPSOID (MM) ATTACHED TO BODY SEGMENT (M) WHICH EXTENDS	WINDY
C	THROUGH THE INTERSECTING PLANE (NN) ATTACHED TO SEGMENT (N).	WINDY
C		WINDY
	IMPLICIT REAL*8 (A-H,O-Z)	WINDY
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	WINDY
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	WINDY
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	WINDY
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	DIMENB
	COMMON/WINDFR/ WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30),	WINDOP
	* MWSEG(7,30),NFVSEG(6),NFVNT(5),MOWSEG(30,30)	WINDOP
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)	EDGE
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	WINDY
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
	COMMON/TEMPVS/ DMNT(3,3),XMN(3),XMM(3),TM(3),BET,BTS,P,FT(3),	WINDOP
	* FF(3),AF(3),FAF,TF,BREF,SCALE,TRACER,AREA,RLM(3),	WINDOP
	* TQM(3),RM(3),DD(3,3),DDD(3,3),R(3,3),DVP(3,3),	WINDOP
	* SI(3,15),R2(2,3),TTF(3),FFT(3),AM(3,3),VP(3),	WINDOP
	* SS(3),SM(3),SN1(3),AS(3),BTE,XNORM,TEMP,	WINDOP
	* X,Y,AI(3,3,15),RYC,AMDA1,AMDA2,B1,B2,RXC	WINDOP
		WINDOP
	MMM=0 CALCULATE NFORCE	WINDOP
	MMM>0 WIND FORCE CALCULATED USING ENTIRE AREA METHOD	WINDOP
	MMM<0 WIND FORCE CALCULATED USING GRID METHOD	WINDOP
	(ALLOWS BLOCKING SEGMENTS)	WINDOP
		WINDOP
	DATA NSTEPS/4/	WINDOP
	CALL ELTIME(1,37)	WINDY
	M=IABS(MMM)	WINDOP
	IF (MMM.EQ.0) GO TO 50	WINDOP
		WINDY
	COMPUTE PENETRATION DISTANCE; IF NEGATIVE, RETURN.	WINDY
		WINDY
	CALL DOTT33 (D(1,1,M),D(1,1,N),DMNT)	WINDY
	DO 10 I=1,3	WINDY
	10 XMN(I) = SEGLP(I,M) - SEGLP(I,N)	WINDY
	CALL MAT31 (D(1,1,M),XMN,XMM)	WINDY
	CALL MAT31 (DMNT,PL(1,NN),TM)	WINDY
	BET = PL(4,NN)	WINDY
	DO 11 I=1,3	WINDY
	11 BET = BET - TM(I)*(BD(I+3,MM)+XMM(I))	WINDY
	CALL MAT31 (BD(16,MM),TM,RM)	WINDY
	BTS = TM(1)*RM(1) + TM(2)*RM(2) + TM(3)*RM(3)	WINDY
	BTE = -DSQRT(BTS)	WINDY
	P = BET - BTE	WINDY
	IF (P.LT.0.0) GO TO 99	WINDY

C		WINDY
C	FETCH OR STORE INITIAL PENETRATION TIME.	WINDY
C		WINDY
	IWIND(M) = M	WINDY
	IF (TIME.LE.WTIME(M)) WTIME(M) = TIME	WINDY
	FTIME = TIME - WTIME(M)	WINDY
C		WINDY
C	GET DRAG COEFFICIENT CD FROM TABLE NTC FOR TIME = FTIME.	WINDOP
C		WINDOP
	CD=1.0	WINDOP
	NTC=MWSEG(6,M)	WINDOP
	IF (NTC.EQ.0) GOTO 20	WINDOP
	KT=NTI(NTC)	WINDOP
	NENTRY=TAB(KT+5)	WINDOP
	K1=KT+10	WINDOP
	K2=4*NENTRY+KT+2	WINDOP
	IF (NENTRY.EQ.1) GOTO 18	WINDOP
	DO 17 K=K1,K2,4	WINDOP
	IF (FTIME.GT.TAB(K)) GOTO 17	WINDOP
	KK=K	WINDOP
	R1=(TAB(K)-FTIME)/(TAB(K)-TAB(K-4))	WINDOP
	GOTO 19	WINDOP
17	CONTINUE	WINDOP
18	KK=K2	WINDOP
	R1=0.0	WINDOP
19	R22=1.0-R1	WINDOP
	K=KK+1	WINDOP
	CD=R22*TAB(K)+R1*TAB(K-4)	WINDOP
C		WINDOP
C	GET FORCE VECTOR FT	WINDOP
C		WINDOP
C	RK=0 TIME DEPENDENT WIND FORCE FROM TABLE	WINDOP
C	RK=0 VELOCITY DEPENDENT WIND FORCE	WINDOP
C		WINDOP
20	KT = NTI(NT)	WINDOP
	RK=TAB(KT)	WINDOP
	IF (RK.EQ.0.0) GOTO 13	WINDOP
	C=TAB(KT+1)	WINDOP
	PR=TAB(KT+2)	WINDOP
	NSV=IDINT(TAB(KT+3))	WINDOP
	NSR=IDINT(TAB(KT+4))	WINDOP
	DO 12 I=1,3	WINDOP
	V=SEGLV(I,NSV)-SEGLV(I,NSR)	WINDOP
12	FT(I)=DSIGN(0.5D0,-V)*CD*RK*PR*V**2/C**2	WINDOP
	GOTO 14	WINDOP
13	NSR=IDINT(TAB(KT+4))	WINDOP
	NENTRY = TAB(KT+5)	WINDY
	K1 = KT+10	WINDY
	K2 = 4*NENTRY + KT+2	WINDY
	IF (NENTRY.EQ.1) GO TO 31	WINDY

	DO 30 K=K1,K2,4	WINDY
	IF (FTIME.GT.TAB(K)) GO TO 30	WINDY
	KK = K	WINDY
	R1 = (TAB(K)-FTIME)/(TAB(K)-TAB(K-4))	WINDY
	GO TO 32	WINDY
30	CONTINUE	WINDY
31	KK = K2	WINDY
	R1 = 0.0	WINDY
32	R22= 1.0 - R1	WINDOP
	DO 33 I=1,3	WINDY
	K= KK+I	WINDY
33	FT(I)=(R22*TAB(K) + R1*TAB(K-4))*CD	WINDOP
	IF (NSR.EQ.0) GOTO 14	WINDOP
	CALL DOT31(D(1,1,NSR),FT,FF)	WINDOP
	DO 21 I=1,3	WINDOP
21	FT(I)=FF(I)	WINDOP
14	IF (MMM.LT.0) GOTO 15	WINDOP
C		WINDY
C	COMPUTE PRESENTED AREA TO WIND FORCE.	WINDY
C		WINDY
	CALL MAT31 (D(1,1,M),FT,FF)	WINDY
	CALL MAT31 (BD(7,MM),FF,AF)	WINDY
	FAF = FF(1)*AF(1) + FF(2)*AF(2) + FF(3)*AF(3)	WINDY
	IF (FAF.LE.0.0) GO TO 99	WINDY
	TF = TM(1)*FF(1) + TM(2)*FF(2) + TM(3)*FF(3)	WINDY
	BREF=0.0	CCWIND
	TEMP=BTS-TF*TF/FAF	CCWIND
	IF(TEMP.GT.0.0) BREF =DSQRT(TEMP)	CCWIND
	SCALE = (-BET+BREF)/(-BTE+BREF)	WINDY
	IF (SCALE.GE.1.0) GO TO 99	WINDY
	IF (SCALE.LT.0.0) SCALE = 0.0	WINDY
	TRACER = (BD( 7,MM)-AF(1)**2/FAF)*(BD(11,MM)-AF(2)**2/FAF)	WINDY
*	+ (BD( 7,MM)-AF(1)**2/FAF)*(BD(15,MM)-AF(3)**2/FAF)	WINDY
*	+ (BD(11,MM)-AF(2)**2/FAF)*(BD(15,MM)-AF(3)**2/FAF)	WINDY
*	- (BD( 8,MM)-AF(1)*AF(2)/FAF)**2	WINDY
*	- (BD( 9,MM)-AF(1)*AF(3)/FAF)**2	WINDY
*	- (BD(12,MM)-AF(2)*AF(3)/FAF)**2	WINDY
	AREA = (1.0-SCALE**2) * PI / DSQRT(TRACER)	WINDY
C		WINDY
C	ADD FORCE AND TORQUES TO U1 AND U2 ARRAYS FOR SEGMENT M.	WINDY
C		WINDY
	SCALE = SCALE/BTE	WINDY
	DO 36 I=1,3	WINDY
	RLM(I) = RM(I)*SCALE + BD(I+3,MM)	WINDY
	FT (I) = FT(I)*AREA	WINDY
36	FF (I) = FF(I)*AREA	WINDY
	CALL CROSS (RLM,FF,TQM)	WINDY
	DO 39 I=1,3	WINDY
	WF(I,M)=FT(I)	WINDOP
	U1(I,M) = U1(I,M) + FT(I)	WINDY



39	U2(I,M) = U2(I,M) + TQM(I)	WINDY
	IF (NPRT(14).NE.0) WRITE (6,41) TIME,M,P,AREA,FT,TQM	WINDY
41	FORMAT(' WIND FORCE',F14.6,I6,2F10.3,3X,3F12.5,3X,3F12.5)	WINDY
	GO TO 99	WINDY
C		WINDY
C	USE GRID TO CALCULATE WIND FORCE	WINDOP
C	VP - ORIGIN OF WIND	WINDOP
C		WINDOP
15	AREAT=0.0	WINDOP
	DO 16 I=1,3	WINDOP
	TTF(I)=0.0	WINDOP
	TQM(I)=0.0	WINDOP
16	VP(I) = -FT(I)*10000.0	WINDOP
	TEMP=FT(1)**2+FT(2)**2+FT(3)**2	WINDOP
	IF (TEMP.EQ.0.0) GOTO 99	WINDOP
	CALL MAT31(D(1,1,M),FT,FF)	WINDOP
	TEMP = 0.0	WINDOP
	IF (FT(1).NE.0.0.OR.FT(2).NE.0.0) GOTO 150	WINDOP
C		WINDOP
C	CALCULATE DIRECTION COSINE MATRIX FOR VP COORD. SYS.	WINDOP
C		WINDOP
	DO 140 I=1,3	WINDOP
	DO 140 J=1,3	WINDOP
140	DVP(I,J)=0.0	WINDOP
	DVP(1,2)=1.0	WINDOP
	DVP(2,1)=1.0	WINDOP
	DVP(3,3)=-1.0	WINDOP
	GO TO 141	WINDOP
150	CONTINUE	WINDOP
	DO 110 I=1,3	WINDOP
110	TEMP=TEMP+FT(I)*FT(I)	WINDOP
	TEMP = DSQRT(TEMP)	WINDOP
	KNORM = DSQRT(FT(1)*FT(1)/TEMP**2+FT(2)*FT(2)/TEMP**2)	WINDOP
	DVP(1,1) = FT(2)/(KNORM*TEMP)	WINDOP
	DVP(1,2) = -FT(1)/(KNORM*TEMP)	WINDOP
	DVP(1,3) = 0.0	WINDOP
	DVP(2,1) = FT(1)*FT(3)/(KNORM*TEMP*TEMP)	WINDOP
	DVP(2,2) = FT(2)*FT(3)/(KNORM*TEMP*TEMP)	WINDOP
	DVP(2,3) = -KNORM	WINDOP
	DO 130 I=1,3	WINDOP
130	DVP(3,I) = FT(I)/TEMP	WINDOP
141	CONTINUE	WINDOP
	MOELP = MWSEG(7,M)	WINDOP
C		WINDOP
C	PROJECT MM ELLIPSOID UNTO VP-PLANE	WINDOP
C	AS - PROJECTED ELLIPSE MATRIX	WINDOP
C		WINDOP
	CALL DOTT33(D(1,1,M),DVP,DD)	WINDOP
	CALL MAT33(BD(7,MM),DD,DDD)	WINDOP
	CALL DOT33(D(1,1,M),DDD,DD)	WINDOP

	CALL MAT33(DVP,DD,AM)	WINDOP
	DO 101 K=1,3	WINDOP
101	SS(K)=SEGLP(K,M)+BD(K+3,MM)-VP(K)	WINDOP
	CALL MAT31(DVP,SS,SM)	WINDOP
	DO 114 K=1,3	WINDOP
	IF (DABS(SM(K)).LT.EPS(5)) SM(K)=DSIGN(EPS(5),SM(K))	WINDOP
114	CONTINUE	WINDOP
	CALL SOLVR(AM(1,1),AM(2,1),AM(3,1),AM(1,3),AM(2,3),AM(3,3),	WINDOP
	* AM(1,1),AM(1,3),SM,R(1,1),R(3,1))	WINDOP
	CALL SOLVR(AM(1,2),AM(2,2),AM(3,2),AM(1,3),AM(2,3),AM(3,3),	WINDOP
	* AM(2,2),AM(2,3),SM,R(2,2),R(3,2))	WINDOP
	CALL SOLVR(AM(1,1)+AM(1,2),AM(2,1)+AM(2,2),AM(3,1)+AM(3,2),	WINDOP
	* AM(1,3),AM(2,3),AM(3,3),AM(1,1)+2.0*AM(1,2)+AM(2,2),	WINDOP
	* AM(1,3)+AM(2,3),SM,R(1,3),R(3,3))	WINDOP
	R(2,1)=0.0	WINDOP
	R(1,2)=0.0	WINDOP
	R(2,3)=R(1,3)	WINDOP
	DO 102 K=1,3	WINDOP
	DO 102 J=1,2	WINDOP
102	R2(J,K)=R(J,K)	WINDOP
	CALL SOLVA(R2,AS(1),AS(2),AS(3))	WINDOP
C		WINDOP
C	GET MAJOR & MINOR AXES OF PROJECTED ELLIPSE	WINDOP
C		WINDOP
	TEMP=(AS(1)+AS(2))*2-4.0*(AS(1)*AS(2)-AS(3))*2)	WINDOP
	IF (TEMP.LT.0.0) TEMP=0.0	WINDOP
	TEMP = DSQRT(TEMP)	WINDOP
	AMDA1=(AS(1)+AS(2)+TEMP)/2.0	WINDOP
	AMDA2=(AS(1)+AS(2)-TEMP)/2.0	WINDOP
	R2(1,1)=AS(3)	WINDOP
	R2(2,1)=AMDA1-AS(1)	WINDOP
	R2(1,2)=AMDA2-AS(2)	WINDOP
	R2(2,2)=AS(3)	WINDOP
	AMDA1=DABS(AMDA1)	WINDOP
	AMDA2=DABS(AMDA2)	WINDOP
	B1=DSQRT(1.0/(AMDA1*(R2(1,1)**2+R2(1,2)**2)))	WINDOP
	B2=DSQRT(1.0/(AMDA2*(R2(2,1)**2+R2(2,2)**2)))	WINDOP
	R2(1,1)=R2(1,1)*B1	WINDOP
	R2(1,2)=R2(1,2)*B2	WINDOP
	R2(2,1)=R2(2,1)*B1	WINDOP
	R2(2,2)=R2(2,2)*B2	WINDOP
C		WINDOP
C	GET BLOCKING ELLIPSOIDS IN VP COORD. SYS.	WINDOP
C		WINDOP
	DO 103 MI=1,MOELP	WINDOP
	I=MOWSEG(M,MI*2-1)	WINDOP
	II=MOWSEG(M,MI*2)	WINDOP
	CALL DOTT33(D(1,1,I),DVP,DD)	WINDOP
	CALL MAT33(BD(7,II),DD,DDD)	WINDOP
	CALL DOT33(D(1,1,I),DDD,DD)	WINDOP

	CALL MAT33(DVP,DD,AI(1,1,MI))	WINDOP
	DO 104 K=1,3	WINDOP
104	SS(K)=SEGLP(K,I)+BD(K+3,II)-VP(K)	WINDOP
	CALL MAT31(DVP,SS,SI(1,MI))	WINDOP
	DO 115 K=1,3	WINDOP
	IF (DABS(SI(K,MI)).LT.EPS(6)) SI(K,MI)=DSIGN(EPS(6),SI(K,MI))	WINDOP
115	CONTINUE	WINDOP
103	CONTINUE	WINDOP
C		WINDOP
C	SET-UP GRID AND CHECK EACH RECTANGLE CENTER POINT	WINDOP
C		WINDOP
	AREA=DSQRT((R2(1,1)**2+R2(2,1)**2)*(R2(1,2)**2+R2(2,2)**2))	WINDOP
	AREA=AREA/NSTEPS**2	WINDOP
	IN=2*NSTEPS+1	WINDOP
	DO 105 I=1,IN	WINDOP
	RXC=R2(1,1)-R2(1,1)*(I-1)/NSTEPS	WINDOP
	RYC=R2(2,1)-R2(2,1)*(I-1)/NSTEPS	WINDOP
	DO 106 J=1,IN	WINDOP
	RM(1)=(RXC-R2(1,2)*(NSTEPS-J+1)/NSTEPS)*0.9999	WINDOP
	RM(2)=(RYC-R2(2,2)*(NSTEPS-J+1)/NSTEPS)*0.9999	WINDOP
	TM(1)=AM(3,3)	WINDOP
	TM(2)=2.0*(RM(1)*AM(1,3)+RM(2)*AM(2,3))	WINDOP
	TM(3)=RM(1)**2*AM(1,1)+RM(2)**2*AM(2,2)+2.0*RM(1)*RM(2)*AM(1,2)-1.	WINDOP
	TEMP=TM(2)**2-4.0*TM(1)*TM(3)	WINDOP
	IF (TEMP.LT.0.0) GOTO 106	WINDOP
	B1=(DSQRT(TEMP)-TM(2))/(2.0*TM(1))	WINDOP
	B2=-(DSQRT(TEMP)+TM(2))/(2.0*TM(1))	WINDOP
	RM(3)=B1	WINDOP
	IF (B2.LT.B1) RM(3)=B2	WINDOP
	SN1(1)=RM(1)+SM(1)	WINDOP
	SN1(2)=RM(2)+SM(2)	WINDOP
	SN1(3)=RM(3)+SM(3)	WINDOP
	CALL DOT31(DVP,SN1,XMM)	WINDOP
C		WINDOP
C	CHECK FOR PENETRATION	WINDOP
C		WINDOP
	DO 107 K=1,3	WINDOP
107	XMN(K)=VP(K)-SEGLP(K,N)+XMM(K)	WINDOP
	CALL MAT31(D(1,1,N),XMN,XMM)	WINDOP
	BET=PL(4,NN)	WINDOP
	BTS=PL(1,NN)*XMM(1)+PL(2,NN)*XMM(2)+PL(3,NN)*XMM(3)	WINDOP
	IF (BTS.GT.BET) GOTO 106	WINDOP
C		WINDOP
C	CHECK FOR BLOCKING ELLIPSOIDS	WINDOP
C		WINDOP
	DO 109 IM=1,MOELP	WINDOP
	X=SN1(1)-SI(1,IM)	WINDOP
	Y=SN1(2)-SI(2,IM)	WINDOP
	TM(1)=AI(3,3,IM)	WINDOP
	TM(2)=2.0*(AI(1,3,IM)*X+AI(2,3,IM)*Y)	WINDOP

	TM(3)=AI(1,1,IM)*X**2+AI(2,2,IM)*Y**2+2.0*AI(1,2,IM)*X*Y-1.0	WINDOP
	TEMP=TM(2)**2-4.0*TM(1)*TM(3)	WINDOP
	IF (TEMP.LT.0.0) GOTO 109	WINDOP
	B1=(-TM(2)+DSQRT(TEMP))/(2.0*TM(1))	WINDOP
	B2=(-TM(2)-DSQRT(TEMP))/(2.0*TM(1))	WINDOP
	IF (B2.LT.B1) B1=B2	WINDOP
	SNZ=B1+SI(3,IM)	WINDOP
	IF (SNZ.LT.SN1(3)) GOTO 106	WINDOP
109	CONTINUE	WINDOP
	CALL DOT31(DVP,RM,SS)	WINDOP
	CALL MAT31(D(1,1,M),SS,RM)	WINDOP
C		WINDOP
C	SUM FORCES & TORQUES	WINDOP
C		WINDOP
	AREAT=AREAT+AREA	WINDOP
	DO 111 K=1,3	WINDOP
	TTF(K)=FT(K)*AREA+TTF(K)	WINDOP
	RM(K)=RM(K)+BD(K+3,MM)	WINDOP
111	FFT(K)=FF(K)*AREA	WINDOP
	CALL CROSS(RM,FFT,TM)	WINDOP
	DO 112 K=1,3	WINDOP
112	TQM(K)=TQM(K)+TM(K)	WINDOP
106	CONTINUE	WINDOP
105	CONTINUE	WINDOP
C		WINDOP
C	ADD FORCE & TORQUE TO U1 & U2 ARRAYS FOR SEGMENT M	WINDOP
C		WINDOP
	IF (NPRT(14).NE.0) WRITE(6,200) TIME,M,AREAT,TTF,TQM	WINDOP
200	FORMAT(' WIND FORCE',F14.6,I6,13X,F10.3,3F12.5,3X,3F12.5)	WINDOP
	DO 113 I=1,3	WINDOP
	WF(I,M)=TTF(I)	WINDOP
	U1(I,M)=U1(I,M)+TTF(I)	WINDOP
113	U2(I,M)=U2(I,M)+TQM(I)	WINDOP
	GO TO 99	WINDOP
C		WINDOP
C	M = 0: CALCULATE FORCE FUNCTIONS.	WINDOP
C		WINDY
50	NFORCE = NFVSEG(6)	WINDY
	DO 60 J=1,NFORCE	WINDY
	NFS = IABS(NFVSEG(J))	WINDY
	NFT = IABS(NFVNT(J))	WINDY
	KFT = NTI(NFT)	WINDY
	FRCE = EVALFD(TIME,KFT,1)	WINDY
	IF (NFVSEG(J).GT.0) GO TO 52	WINDY
	DO 51 I=1,3	WINDY
51	U2(I,NFS) = U2(I,NFS) + FRCE*QFU(I,J)	WINDY
	GO TO 60	WINDY
52	CALL DOT31 (D(1,1,NFS),QFU(1,J),TM)	WINDY
	DO 53 I=1,3	WINDY
	U1(I,NFS) = U1(I,NFS) + FRCE*TM(I)	WINDY

53  $U2(I,NFS) = U2(I,NFS) + FRCE * QFV(I,J)$   
60 CONTINUE  
99 CALL ELTIME (2,37)  
RETURN  
END

WINDY  
WINDY  
WINDY  
WINDY  
WINDY

	DOUBLE PRECISION FUNCTION XDY(X,D,Y)		XDY
C		REV IV	07/23/86JTF786
C	FUNCTION ROUTINE TO COMPUTE X.DY OR Y.D'X		XDY
C			XDY
	IMPLICIT REAL*8(A-H,O-Z)		XDY
	DIMENSION X(3),D(3,3),Y(3)		XDY
	XDY = 0.0		XDY
	DO 10 I=1,3		XDY
10	XDY = XDY + X(I)*(D(I,1)*Y(1)+D(I,2)*Y(2)+D(I,3)*Y(3))		JTF786
	RETURN		XDY
	END		XDY

	SUBROUTINE YPRDEG(D,A)		YPRDEG
C		REV IV	11/26/86YPRFIX
C	COMPUTES YAW PITCH AND ROLL IN DEGREES AND PLACES THEM		YPRDEG
C	INTO THE A ARRAY FOR A GIVEN DIRECTION COSINE MATRIX D.		YPRDEG
C			YPRDEG
C	ASSUMES D = D(R)D(P)D(Y) , WHERE		YPRDEG
C			YPRDEG
C	1 0 0 CP 0 -SP CY SY 0		YPRDEG
C	D(R) = 0 CR SR ,D(P) = 0 1 0 AND D(Y) = -SY CY 0		YPRDEG
C	0 -SR CR SP 0 CP 0 0 1		YPRDEG
C			YPRDEG
	IMPLICIT REAL*8(A-H,O-Z)		YPRDEG
	DIMENSION A(3),D(3,3)		YPRDEG
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		YPRDEG
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	IF (DABS(D(1,1)).LE.EPS(15).AND.DABS(D(1,2)).LE.EPS(15))GOTO10		YPRFIX
	IF (DABS(D(2,3)).LE.EPS(15).AND.DABS(D(3,3)).LE.EPS(15))GOTO10		YPRFIX
	YAW = DATAN2(D(1,2),D(1,1))		YPRDEG
	ROLL = DATAN2(D(2,3),D(3,3))		YPRDEG
	GO TO 11		YPRDEG
10	YAW = DATAN2(-D(2,1),D(2,2))		YPRDEG
	ROLL = 0.0		YPRDEG
11	PITCH = -DASIN(D(1,3))		YPRDEG
	IF (DABS(ROLL).LE.0.5*PI) GO TO 20		YPRDEG
	IF (DABS(YAW ).LE.0.5*PI) GO TO 20		YPRDEG
	PITCH = DSIGN(PI-DABS(PITCH),PITCH)		YPRDEG
	YAW = DATAN2(-D(1,2),-D(1,1))		YPRDEG
	ROLL = DATAN2(-D(2,3),-D(3,3))		YPRDEG
20	A(1) = YAW/RADIAN		YPRDEG
	A(2) = PITCH/RADIAN		YPRDEG
	A(3) = ROLL/RADIAN		YPRDEG
	RETURN		YPRDEG
	END		YPRDEG

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